

CS 484/684

# Computational Vision

---

- Web page: [cs.uwaterloo.ca/~yboykov/Courses/cs484/](https://cs.uwaterloo.ca/~yboykov/Courses/cs484/)
  - announcements, assignments (text), code samples/libraries, **syllabus**
  - lecture notes
  
- LEARN
  - assignments collection/grading

CS 484/684

# Computational Vision

---

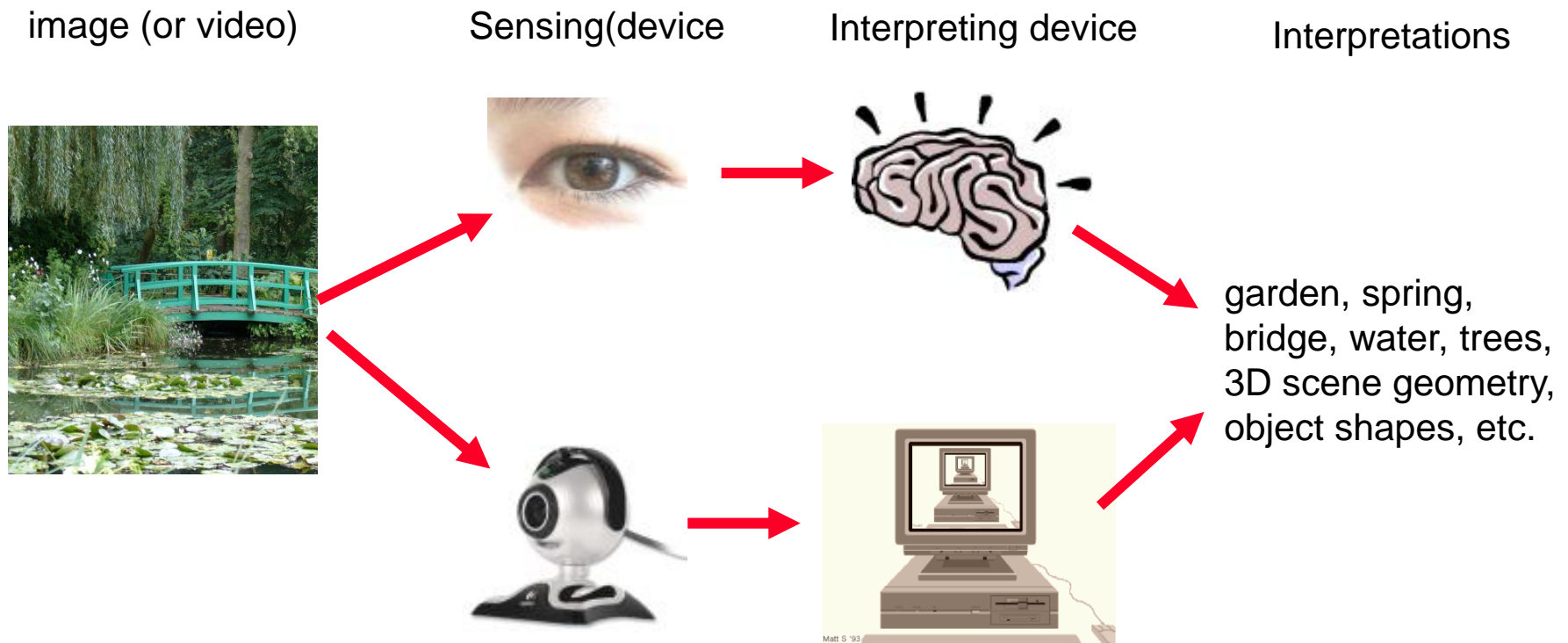
## □ Today

- Overview of computer vision applications

CS 484/684

# Computational Vision

## What is (computer) vision?



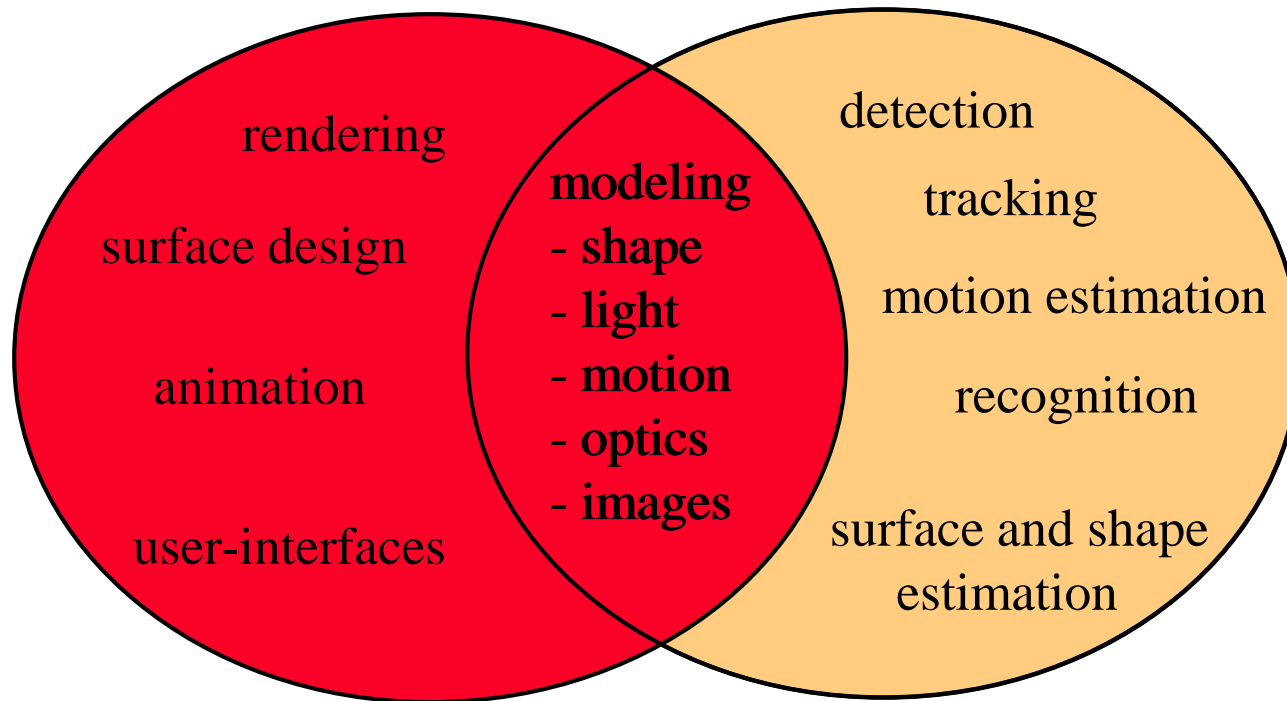
Source: Fei-Fei Li

CS 484/684

# Computational Vision

---

What is it related to?



**Computer Graphics**  
 (Image Rendering)

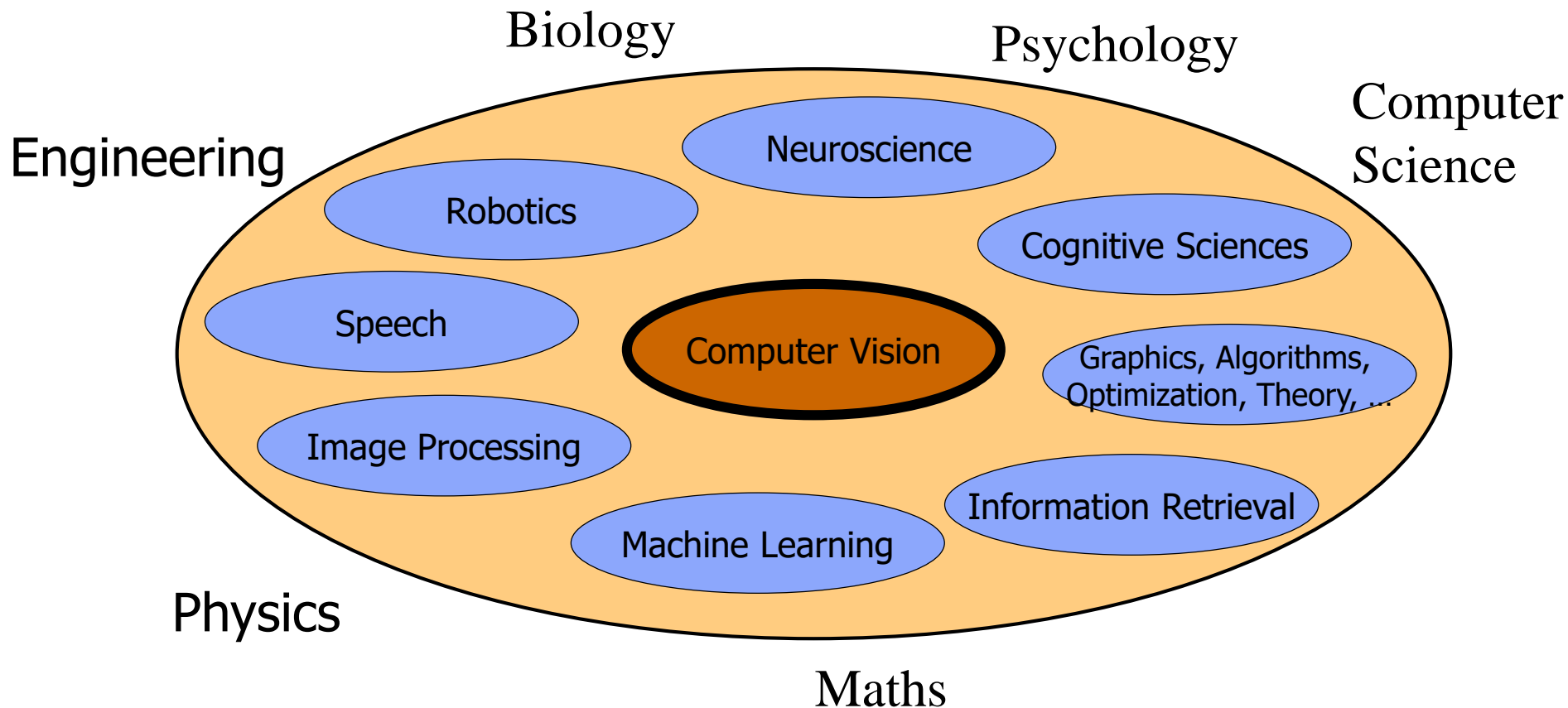
**Computer Vision**  
 (Image Analysis)

Source: S. Seitz

CS 484/684

# Computational Vision

Interdisciplinary area, maths are important



Source: Fei-Fei Li

CS 484/684

# Computational Vision

## The goal of computer vision?

To bridge the gap between pixels and “meaning”



What we see

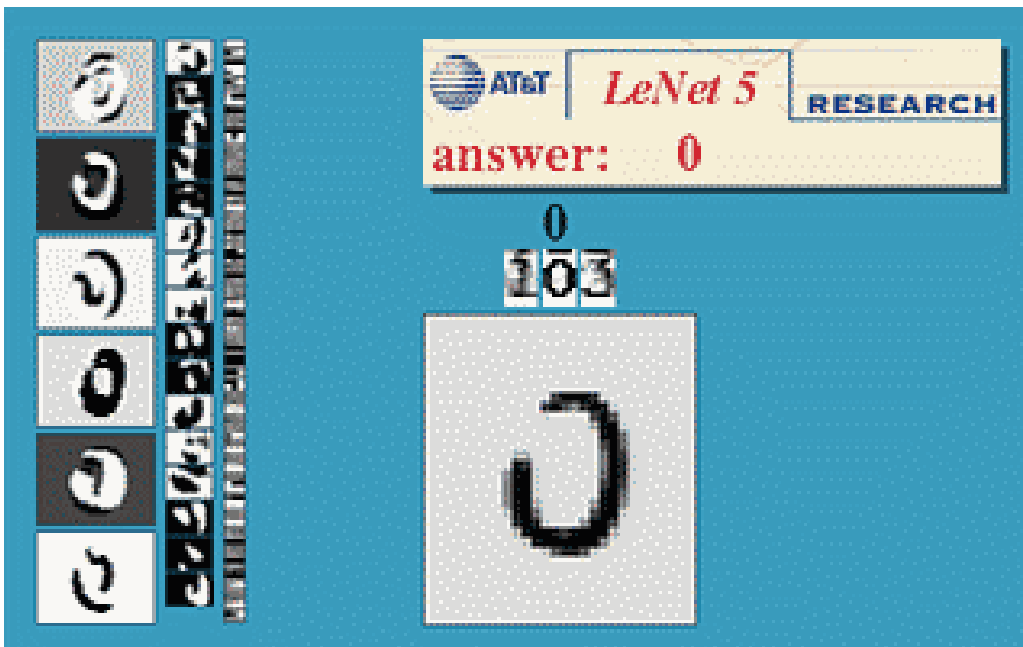
0	3	2	5	4	7	6	9	8
3	0	1	2	3	4	5	6	7
2	1	0	3	2	5	4	7	6
5	2	3	0	1	2	3	4	5
4	3	2	1	0	3	2	5	4
7	4	5	2	3	0	1	2	3
6	5	4	3	2	1	0	3	2
9	6	7	4	5	2	3	0	1
8	7	6	5	4	3	2	1	0

What a computer sees

CS 484/684

# Computational Vision

## Optical character recognition



early 90's



must be older

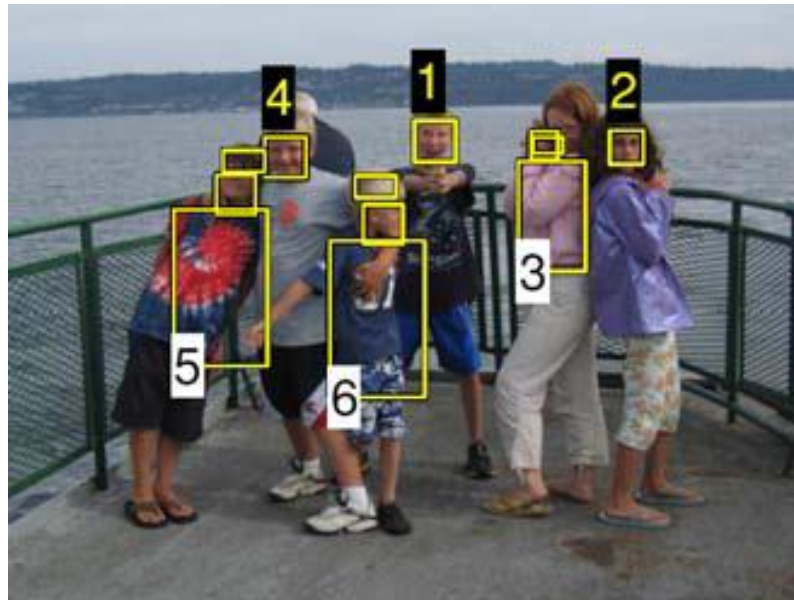
Source: S. Seitz

CS 484/684

# Computational Vision

---

## Object Detection



face detection around 00's



CS 484/684

# Computational Vision

---

## Object Detection



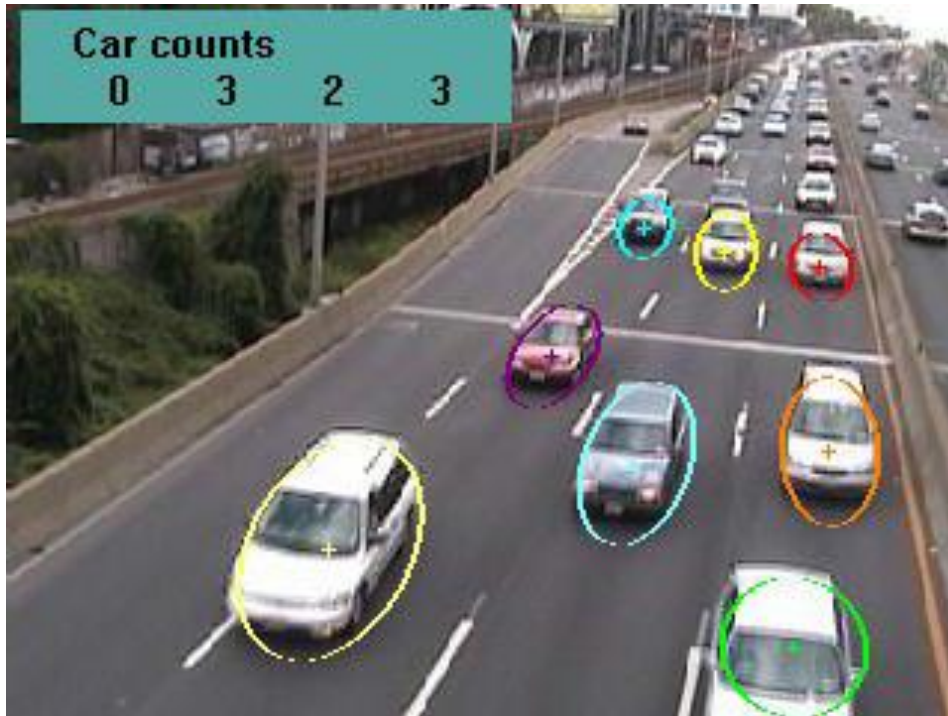
and now

CS 484/684

# Computational Vision

---

Object Detection and tracking:

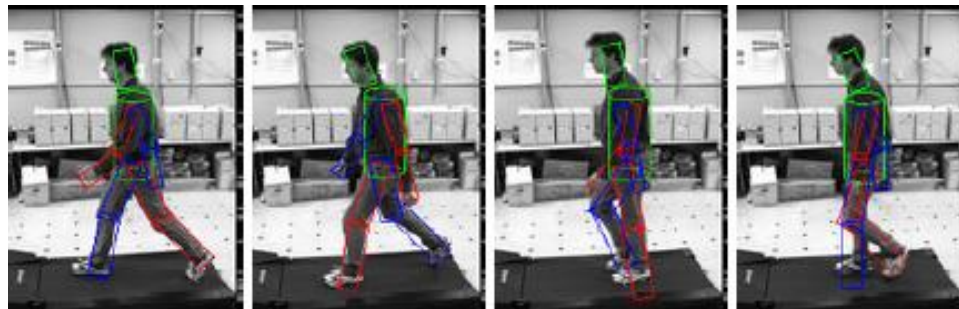


CS 484/684

# Computational Vision

---

Object Detection and tracking:



tracking pictorial structures

CS 484/684

# Computational Vision

---

Segmentation (pixel accurate labeling):



2D model

CS 484/684

# Computational Vision

---

Segmentation ?



CS 484/684

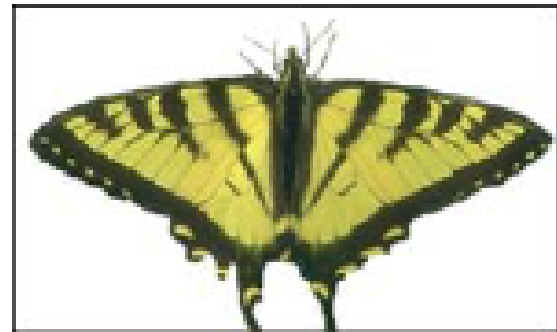
# Computational Vision

---

User-assisted Segmentation (photo/video editing):



Livewire 1995



Graph cut 2001-2004

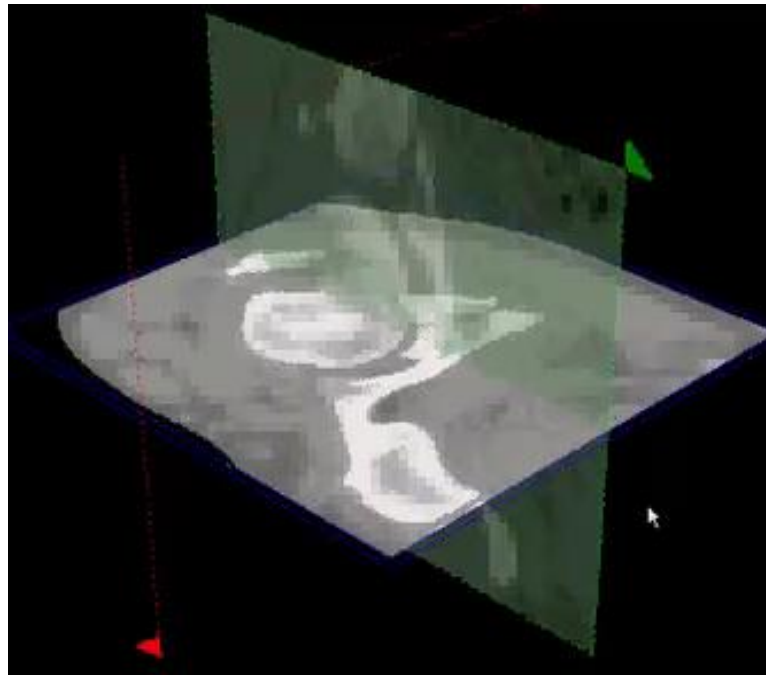


CS 484/684

# Computational Vision

---

## Segmentation in Medical Imaging:



3D object extraction

Graph cut 2001

CS 484/684

# Computational Vision

---

## Combining Detection and Segmentation



Source: "CityScapes" data set

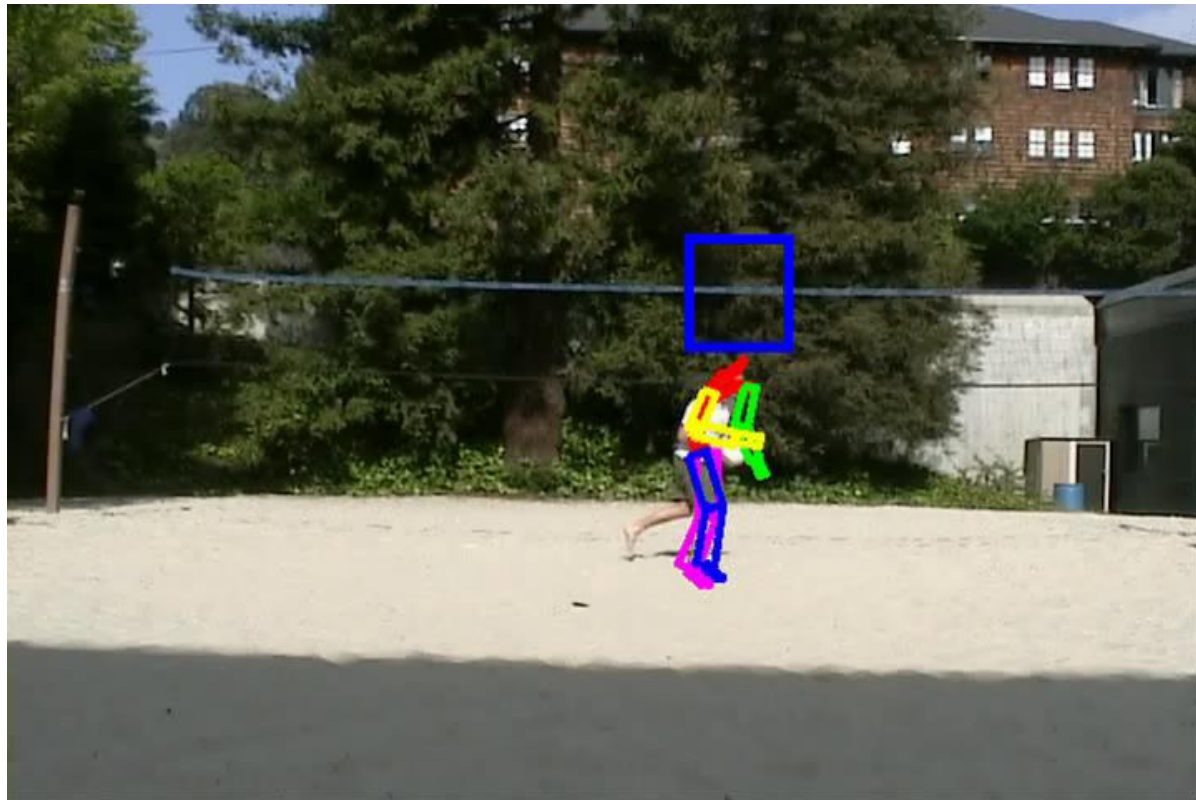


CS 484/684

# Computational Vision

---

Activity recognition:



Bottom-up tracker

CS 484/684

# Computational Vision

---

## Vision-based interaction (gaming)



Microsoft Kinect  
2010



Assistive technologies

Source: S. Seitz

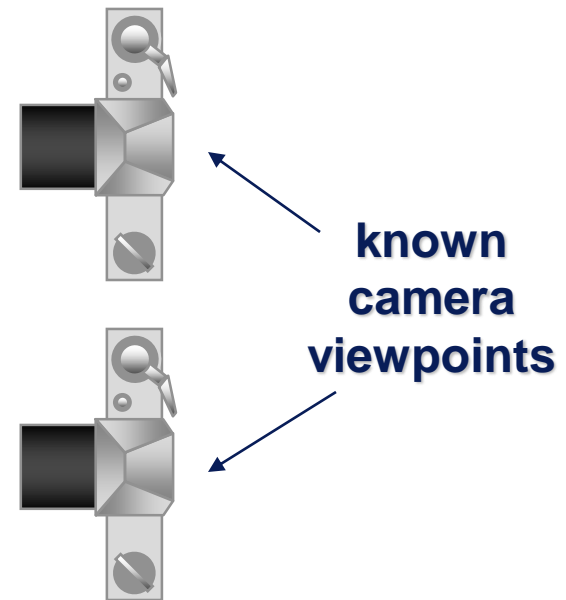
CS 484/684

# Computational Vision

---

## □ Stereo Reconstruction from Photo Images

- Shape from two (or more) images
- Biological motivation



CS 484/684

# Computational Vision

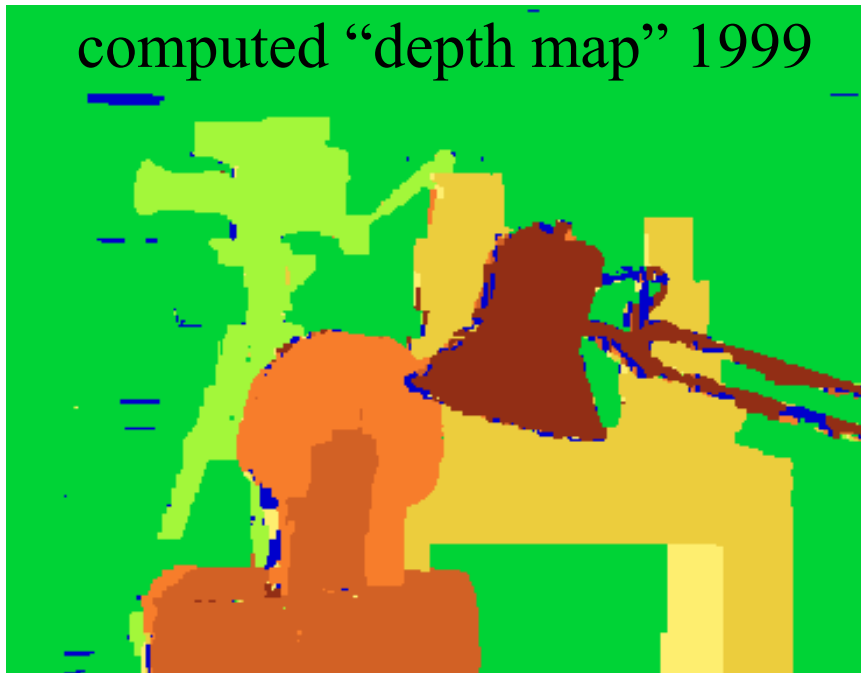
---



CS 484/684

# Computational Vision

---



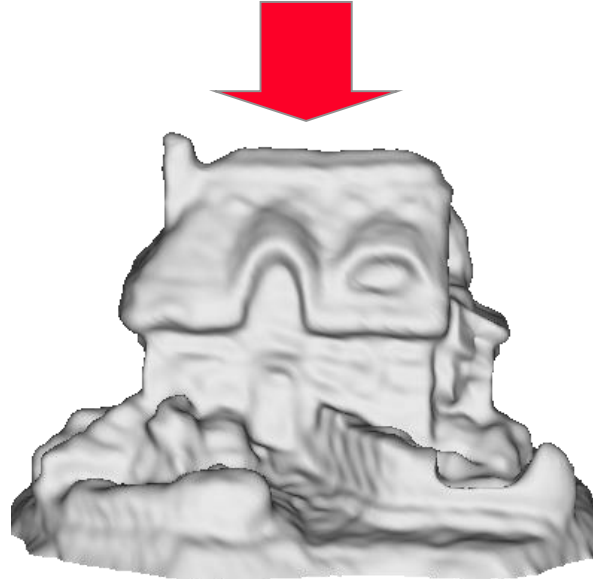
CS 484/684

# Computational Vision

---



More than  
2 images



3D model 2005



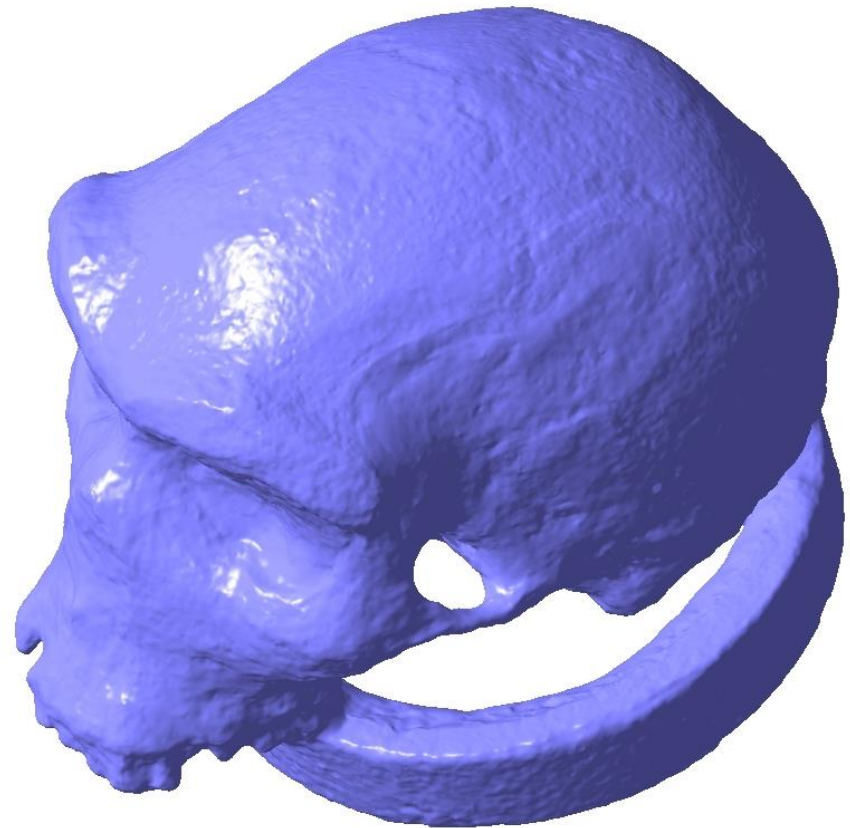
CS 484/684

# Visual Computing

---



multi-view reconstruction  
from high resolution cameras

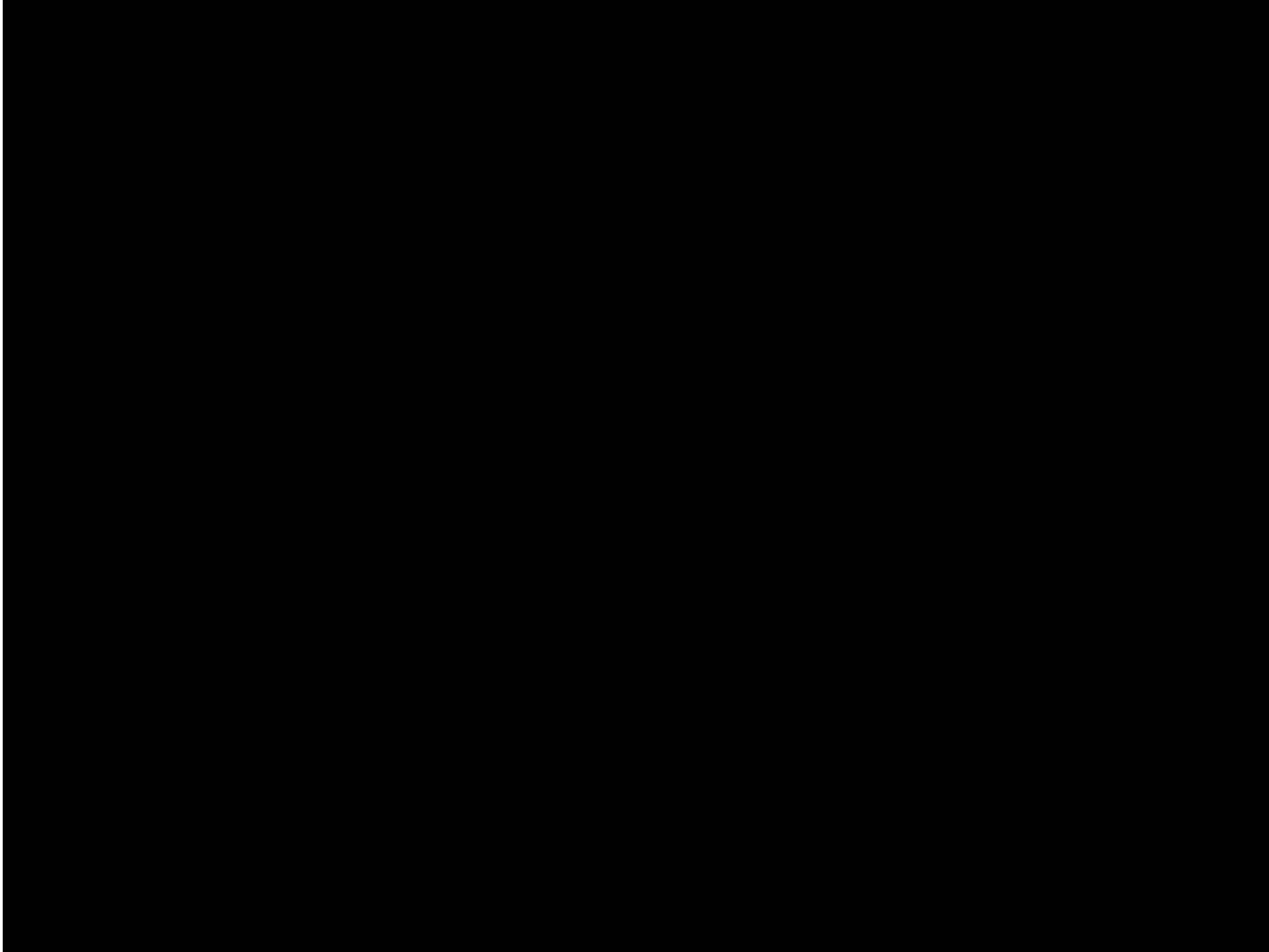


3D model  
2006

CS 484/684

# Computational Vision

---



Structure from Motion

(video from Carl Olsson)

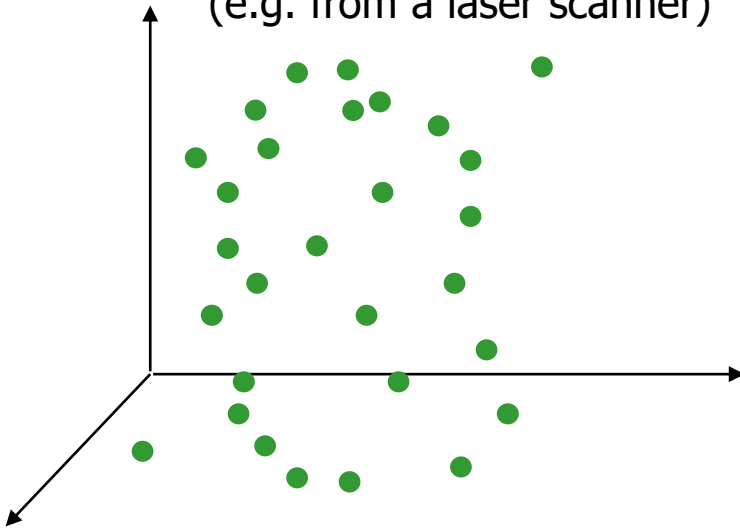


CS 484/684

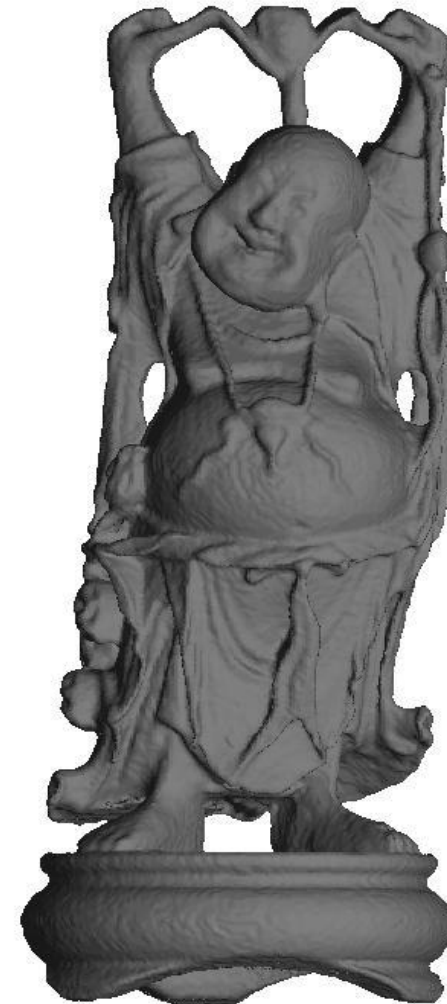
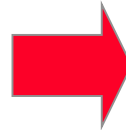
# Computational Vision

---

a cloud of 3D points  
(e.g. from a laser scanner)



surface fitting:



3D model:

CS 484/684

# Computational Vision

---



Multiple views



feature detection +  
plane fitting

CS 484/684

# Computational Vision

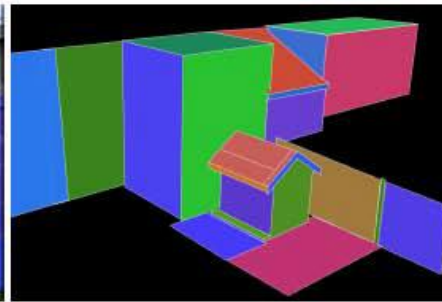
---



Input Photographs



2D Sketching Interface



Geometric Model



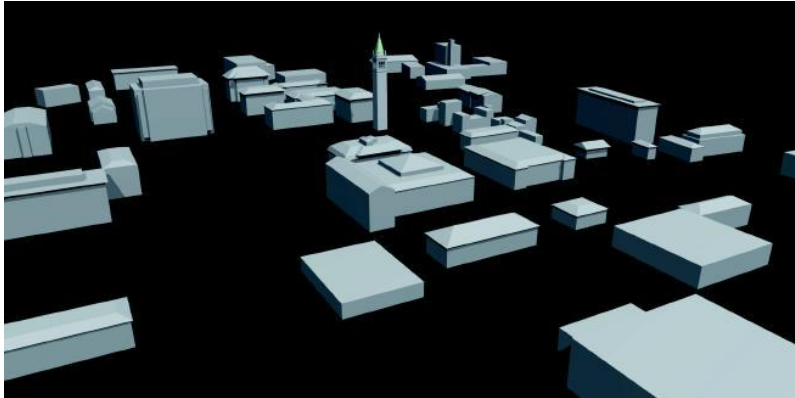
Texture-mapped model

3D model constructed from 9 images

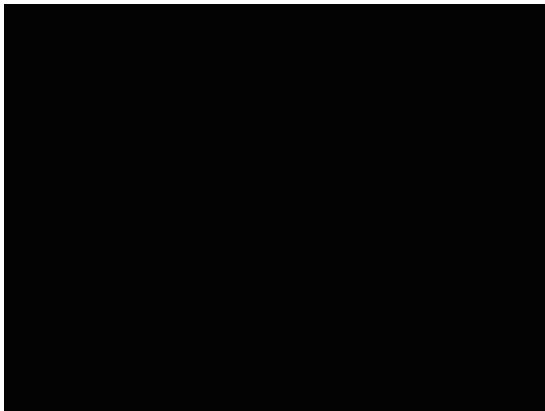
CS 484/684

# Computational Vision

---



3D Scene Reconstruction:



Debevec, Taylor, and Malik, SIGGRAPH 1996



CS 484/684

# Computational Vision

---

3D Scene Reconstruction:  
From a single view!!!



Courtesy  
Creminisi et al.

CS 484/684

# Computational Vision

---

3D Scene Reconstruction:  
From a single view!!!



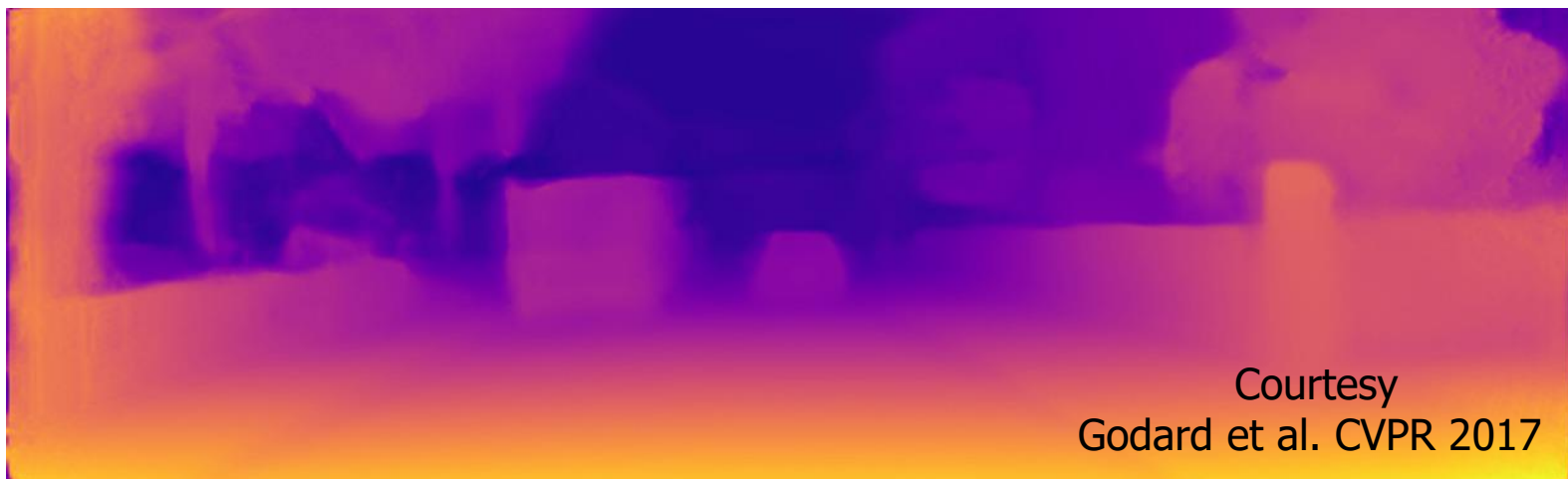
Courtesy  
Creminisi et al.

CS 484/684

# Computational Vision

---

3D Scene Reconstruction:  
From a single view!!!



Courtesy  
Godard et al. CVPR 2017

CS 484/684

# Computational Vision

---

Vision for robotics (e.g. space exploration)



NASA's Mars Exploration Rover Spirit captured this westward view from atop a low plateau where Spirit spent the closing months of 2007.

Vision system solves the following tasks:

- panorama stitching
- 3D terrain modelling
- position tracking
- obstacle detection

Source: S. Seitz