Neural Networks - Part 1

Wenhu Chen

Lecture 19

Readings: RN 21.1, PM 7.5.

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Outline

Learning Goals

Introduction to Artificial Neural Networks

Introduction to Perceptrons

Limitations of Perceptrons

Recurrent Neural Network

Revisiting Learning Goals

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Learning Goals

- Describe the simple mathematical model of a neuron.
- Describe desirable properties of an activation function.
- Distinguish feedforward and recurrent neural networks.
- Learn a perceptron that represents a simple logical function.
- Determine the logical function represented by a perceptron.
- Explain why a perceptron cannot represent the XOR function.
- Understanding recurrent neural networks.



Introduction to Artificial Neural Networks

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Learning complex relationships

Image interpretation, speech recognition, and translation.

- The relationship between inputs and outputs can be extremely complex.
- How can we build a model to learn such complex relationships?

 \rightarrow We need a model that can learn complex relationships, that can be learned efficiently, and does not overfit the data.

Humans can learn complex relationships well.

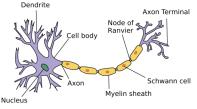
Can we build a model that mimics the human brain?

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Human brains

- ► A brain is a set of densely connected neurons.
- Components of a neuron: dendrites, soma, axon, synapse
 - Dendrites receive input signals from other neurons.
 - Soma controls activity of the neuron.
 - Axon sends output signals to other neurons.
 - Synapses are the links between neurons.
- Depending on the input signals, the neuron performs computations and decides to fire or not.

 \rightarrow Conventional models of neurons have few complex components. Neural networks have many simple components.



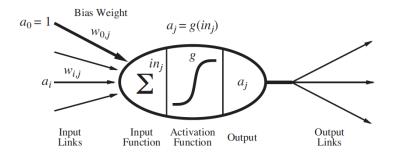
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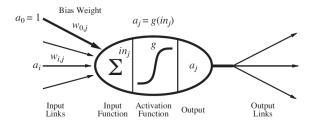
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A simple mathematical model of a neuron

- McCulloch and Pitts 1943.
- A linear classfier it "fires" when a linear combination of its inputs exceeds some threshold.



A simple mathematical model of a neuron



- Neuron j computes a weighted sum of its input signals. in_j = ∑ⁿ_{i=0} w_{ij}a_i.
- ▶ Neuron *j* applies an activation function *g* to the weighted sum to derive the output. $a_j = g(in_j) = g(\sum_{i=0}^n w_{ij}a_i)$.

 \rightarrow Neuron *i* sends input signal a_i to neuron *j*. The link between *i* and *j* has weight w_{ij} , which is the strength of the connection. The neuron has a dummy input $a_0 = 1$ with an associated weight w_{0j} .

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Desirable Properties of The Activation Function

What are some desirable properties of the activation function?

It should be nonlinear.

 \rightarrow Complex relationships are often nonlinear. Combining linear functions will not give us a nonlinear function. We can interleave linear and nonlinear functions to represent complex relationships.

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It should mimic the behaviour of real neurons.

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It should be differentiable almost everywhere.

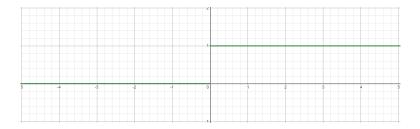
→ We learn a neural network using optimization algorithms such as gradient descent. Many such optimization algorithms require a function to be differentiable. CS 486/686: Intro to Al Lecturer: Wenhu Chen Slides: Alice Gao / Blake Vanberlo 9 / 38

Common activation functions

Step function: g(x) = 1 if x > 0. g(x) = 0 if $x \le 0$.

Simple to use, but not differentiable.

Not used in practice, but useful to explain concepts.



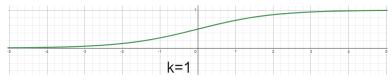
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Common activation functions (continued)

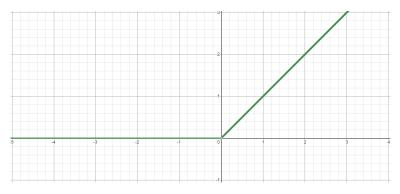
- Sigmoid function: $g(x) = \frac{1}{1 + e^{-kx}}$.
 - For very large or very small x, g(x) is very close to 1 or 0.
 - Can approximate the step function by tuning k. As k increases, the sigmoid function becomes steeper and is closer to the step function. Usually in practice k = 1.
 - Differentiable.
 - ▶ Vanishing gradient problem: when x is very large or very small, g(x) responds little to changes in x. The network does not learn further or learns very slowly.
 - Computationally expensive.



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Common activation functions (continued)

- Rectified linear unit (ReLU): g(x) = max(0, x).
 - Computationally efficient; network converges quickly.
 - Differentiable.
 - The dying ReLU problem: when inputs approach 0 or are negative, the gradient becomes 0 and the network cannot learn.

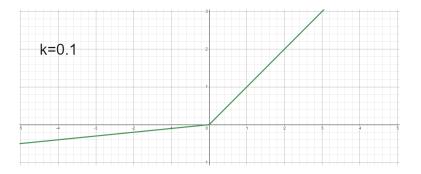


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Common activation functions (continued)

• Leaky ReLU: $g(x) = max(0, x) + k \cdot min(0, x)$

 \rightarrow Small positive slope k in the negative area. Enables learning for negative input values.



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Connecting the neurons together into a network

Feedforward network

- Forms a directed acyclic graph (no loops).
- Have connections only in one direction.
- Represents a function of its inputs.

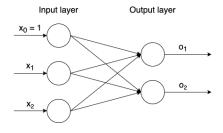
Recurrent network

- Feeds its outputs back into its inputs.
- Can support short-term memory. For the given inputs, the behaviour of the network depends on its initial state, which may depend on previous inputs.
- The model is more interesting, but more difficult to understand and to learn.

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Perceptrons

- Single-layer feedforward neural network
- The inputs are connected directly to the outputs.
- Can represent some logical functions, e.g. AND, OR, and NOT.
 - \rightarrow A big deal at the time. People believed that AI is solved if computers could perform formal logical reasoning.



 \rightarrow Learn the perceptron for each output separately.

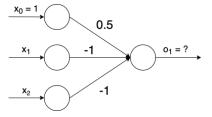
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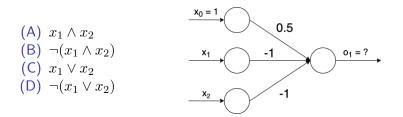
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Q #1: Consider the following perceptron, where the activation function is the step function. $(g(x) = 1 \text{ if } x > 0. g(x) = 0 \text{ if } x \le 0.)$. Which of the following logical functions does the perceptron compute?

(A) $x_1 \land x_2$ (B) $\neg(x_1 \land x_2)$ (C) $x_1 \lor x_2$ (D) $\neg(x_1 \lor x_2)$



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 \rightarrow (D) is correct. This perceptron computes a NOR gate.

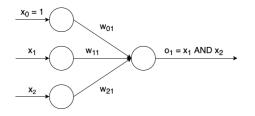
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Q: Learning a perceptron for the AND function

Q #2: Consider the perceptron below where the activation function is the step function $(g(x) = 1 \text{ if } x > 0. g(x) = 0 \text{ if } x \le 0.)$. What should the weights w_{01} , w_{11} and w_{21} be such that the perceptron represents an AND function?



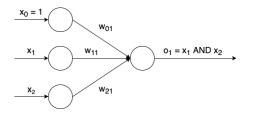
x_1	x_2	o_1
0	0	0
0	1	0
1	0	0
1	1	1

(A)
$$w_{01} = -1$$
. $w_{11} = 0.5$. $w_{21} = 0.5$
(B) $w_{01} = 0.5$. $w_{11} = -1$. $w_{21} = 1$
(C) $w_{01} = 1.5$. $w_{11} = -1$. $w_{21} = -1$
(D) $w_{01} = -1.5$. $w_{11} = 1$. $w_{21} = 1$

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(D) $w_{01} = -1.5$. $w_{11} = 1$. $w_{21} = 1$

ightarrow (D) is correct. $(-1.5)x_0 + 1x_1 + 1x_2 \ge 0$. CS 486/686: Intro to Al Lecturer: Wenhu Chen Slides: Alice Gao / Blake Vanberlo 18 / 38

Q #3: What does h_1 compute?

 $h_1 = g(x_1 + x_2 - 0.5)$ where g(x) = 1 if x > 0 and g(x) = 0 if $x \le 0$. (A) $(x_1 \lor x_2)$ (B) $(x_1 \land x_2)$ (C) $(\neg(x_1 \lor x_2))$ (D) $(\neg(x_1 \land x_2))$

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Q #3: What does h_1 compute?

 $h_1 = q(x_1 + x_2 - 0.5)$ where g(x) = 1 if x > 0 and g(x) = 0 if $x \le 0$. (A) $(x_1 \lor x_2)$ (B) $(x_1 \wedge x_2)$ (C) $(\neg(x_1 \lor x_2))$ (D) $(\neg (x_1 \land x_2))$ \rightarrow (A) is the correct answer. This perceptron computes an OR gate.

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Q #4: What does h_2 compute?

 $h_2 = g(-x_1 - x_2 + 1.5)$ where g(x) = 1 if x > 0 and g(x) = 0 if $x \le 0$. (A) $(x_1 \lor x_2)$ (B) $(x_1 \land x_2)$ (C) $(\neg(x_1 \lor x_2))$ (D) $(\neg(x_1 \land x_2))$

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Q #4: What does h_2 compute?

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Limitations of perceptrons

 Perceptrons: An introduction to computational geometry. Minsky and Papert. MIT Press. Cambridge MA 1969.

 \rightarrow Marvin Minsky (founder of MIT AI lab)

Seymour Papert (director of the lab).

Results:

- XOR cannot be represented using perceptrons. We need a deeper network.
- No one knew how to train deeper networks.
- Led to the first AI winter.

 \rightarrow This approach was a dead end. A freeze to funding and publications.

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Why can't a perceptron represent XOR?

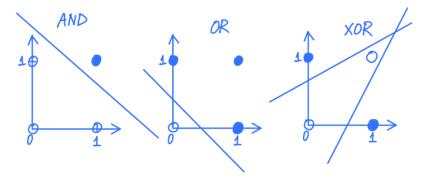
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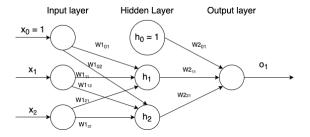
 \rightarrow Intuition: a perceptron is a linear classifier. XOR is not linearly separable.



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XOR as a 2-Layer Neural Network

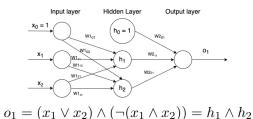
Can you come up with the weights such that the following network represents the XOR function?



 \rightarrow Hint: Start by converting XOR to logical formula composed of logical operations that can be represented by a perceptron: $o_1 = (x_1 \lor x_2) \land (\neg(x_1 \land x_2)) = h_1 \land h_2$

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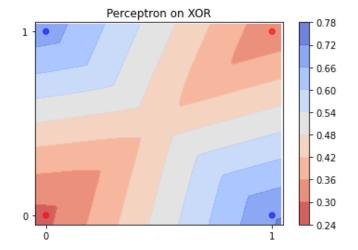
XOR as a 2-Layer Neural Network



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XOR function

The decision boundary of XOR network:



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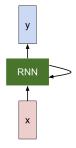
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Recurrent Neural Network

We can process a sequence of vectors x by applying a recurrence formula at every time step:

We need to maintain a state variable h_t to keep track of the history of all the seen information.

$$h_t = f_W(h_{t-1}, x_t) \quad y_t = f_Y(h_t)$$

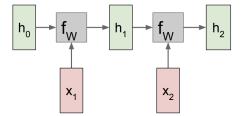


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Vanilla Recurrent Neural Network

$$h_t = f_W(h_{t-1}, x_t)$$

$$h_t = tanh(W_{hh}h_{t-1} + W_{xh}x_t); \quad y_t = W_{hy}h_t$$



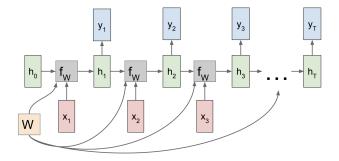
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Vanilla Recurrent Neural Network

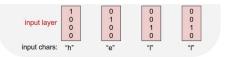
Proceed from $x_1 \cdots x_n$, the weights of the transition is being shared among all the transitions.



Example: Character-level Language Model

Vocabulary: [h,e,l,o]

Example training sequence: "hello"



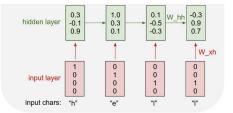
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Example: Character-level Language Model

$$h_t = anh(W_{hh}h_{t-1}+W_{xh}x_t)$$

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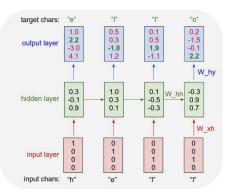
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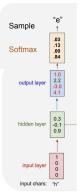
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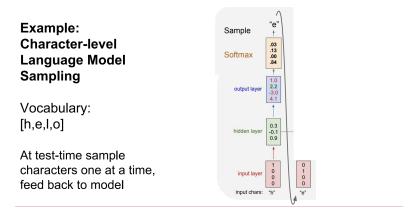


Example: Character-level Language Model Sampling

Vocabulary: [h,e,l,o]

At test-time sample characters one at a time, feed back to model





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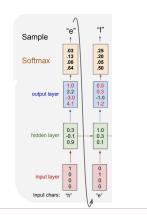
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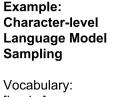
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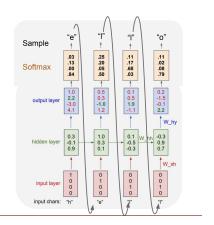
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