## **Distributed Database Management Systems**

### Outline

- Introduction
- Distributed DBMS Architecture
- Distributed Database Design
- Distributed Query Processing
- Distributed Concurrency Control
- Distributed Reliability Protocols

### **Outline**

- Introduction
  - What is a distributed DBMS
  - Problems
  - Current state-of-affairs
- Distributed DBMS Architecture
- Distributed Database Design
- Distributed Query Processing
- Distributed Concurrency Control
- Distributed Reliability Protocols

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### **Motivation**



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# What is a Distributed Database System?

A distributed database (DDB) is a collection of multiple, *logically interrelated* databases distributed over a *computer network*.

A distributed database management system (D–DBMS) is the software that manages the DDB and provides an access mechanism that makes this distribution transparent to the users.

Distributed database system (DDBS) = DDB + D–DBMS

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### What is not a DDBS?

- A timesharing computer system
- A loosely or tightly coupled multiprocessor system
- A database system which resides at one of the nodes of a network of computers - this is a centralized database on a network node

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### **Centralized DBMS on a Network**



### **Distributed DBMS Environment**



### **Implicit Assumptions**



- relational data model
- D-DBMS is a full-fledged DBMS
  - ➡ not remote file system, not a TP system

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### **Distributed DBMS Promises**

- Transparent management of distributed, fragmented, and replicated data
- Improved reliability/availability through distributed transactions
- Improved performance
- Basier and more economical system expansion

### **Transparency**

- Transparency is the separation of the higher level semantics of a system from the lower level implementation issues.
- Fundamental issue is to provide

#### data independence

#### in the distributed environment

- >> Network (distribution) transparency
- Replication transparency
- - horizontal fragmentation: selection
  - vertical fragmentation: projection
  - hybrid

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### Example

EMP			ASG			
ENO	ENAME	TITLE	ENO	PNO	RESP	DUR
E1 E2 E3 E4 E5 E6 E7 E8	J. Doe M. Smith A. Lee J. Miller B. Casey L. Chu R. Davis J. Jones	Elect. Eng. Syst. Anal. Mech. Eng. Programmer Syst. Anal. Elect. Eng. Mech. Eng. Syst. Anal.	E1 E2 E3 E3 E3 E4 E5 E6 E7 E7	P1 P2 P3 P4 P2 P2 P2 P4 P3 P5	Manager Analyst Analyst Consultant Engineer Programmer Manager Manager Engineer Engineer	12 24 6 10 48 18 24 48 36 23
			E8	P3	Manager	40

PRO	l		PAY	
PNO	PNAME	BUDGET	TITLE	SAL
P1 P2 P3 P4	Instrumentation Database Develop. CAD/CAM Maintenance	150000 135000 250000 310000	Elect. Eng. Syst. Anal. Mech. Eng. Programmer	40000 34000 27000 24000

### **Transparent Access**



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### **Distributed Database – User View**





### Potentially Improved Performance

- Proximity of data to its points of use
  - Requires some support for fragmentation and replication
- Parallelism in execution
  - Inter-query parallelism
  - Intra-query parallelism

### **Parallelism Requirements**

- Have as much of the data required by each application at the site where the application executes
  - **Full replication**
- How about updates?
  - Updates to replicated data requires implementation of distributed concurrency control and commit protocols

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### **System Expansion**

- Issue is database scaling
- Emergence of microprocessor and workstation technologies
  - Demise of Grosh's law
  - Client-server model of computing
- Data communication cost vs telecommunication cost

### **Distributed DBMS Issues**

#### Distributed Database Design

- how to distribute the database
- ➡ replicated & non-replicated database distribution
- a related problem in directory management

#### Query Processing

- convert user transactions to data manipulation instructions
- optimization problem
- min{cost = data transmission + local processing}

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**Distributed DBMS Issues** 

#### Concurrency Control

- synchronization of concurrent accesses
- consistency and isolation of transactions' effects
- deadlock management

#### Reliability

- how to make the system resilient to failures
- atomicity and durability

### **Relationship Between Issues**



Outline

- Introduction
- Distributed DBMS Architecture
- Distributed Database Design
  - Fragmentation
  - Data Placement
- Distributed Query Processing
- Distributed Concurrency Control
- Distributed Reliability Protocols

### **Design Problem**

- In the general setting :
  - Making decisions about the placement of data and programs across the sites of a computer network as well as possibly designing the network itself.
- In Distributed DBMS, the placement of applications entails
  - placement of the distributed DBMS software; and
  - » placement of the applications that run on the database

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### **Distribution Design**

#### Top-down

- mostly in designing systems from scratch
- mostly in homogeneous systems

#### Bottom-up

when the databases already exist at a number of sites



### **Distribution Design Issues**

- Why fragment at all?
- How to fragment?
- 8 How much to fragment?
- O How to test correctness?
- 6 How to allocate?
- **6** Information requirements?

### **Fragmentation**

Can't we just distribute relations?

- What is a reasonable unit of distribution?
  - relation
    - views are subsets of relations ⇒ locality
    - extra communication
  - fragments of relations (sub-relations)
    - concurrent execution of a number of transactions that access different portions of a relation
    - views that cannot be defined on a single fragment will require extra processing
    - semantic data control (especially integrity enforcement) more difficult

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### Fragmentation Alternatives – Horizontal

PROJ<sub>1</sub> : projects with budgets less than \$200,000

FROJ				
PNO	PNAME	BUDGET	LOC	
P1	Instrumentation	150000	Montreal	
P2	Database Develop.	135000	New York	
P3	CAD/CAM	250000	New York	
P4	Maintenance	310000	Paris	
P5	CAD/CAM	500000	Boston	

PROJ<sub>2</sub> : projects with budgets greater than or equal to \$200,000

PROJ<sub>1</sub>

PNO	PNAME	BUDGET	LOC
P1	Instrumentation	150000	Montreal
P2	Database Develop.	135000	New York

PROJ <sub>2</sub>	
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PNO	PNAME	BUDGET	LOC
P3	CAD/CAM	250000	New York
P4	Maintenance	310000	Paris
P5	CAD/CAM	500000	Boston

# Fragmentation Alternatives – Vertical

- PROJ<sub>1</sub>: information about project budgets
- PROJ<sub>2</sub>: information about project names and locations

PROJ

PNO	PNAME	BUDGET	LOC
P1	Instrumentation	150000	Montreal
P2	Database Develop.	135000	New York
P3	CAD/CAM	250000	New York
P4	Maintenance	310000	Paris
P5	CAD/CAM	500000	Boston

PROJ <sub>1</sub>				
PNO	BUDGET			
P1 P2 P3 P4 P5	150000 135000 250000 310000 500000			

PROJ <sub>2</sub>	
-------------------	--

PNO	PNAME	LOC
P1	Instrumentation	Montreal
P2	Database Develop.	New York
P3	CAD/CAM	New York
P4	Maintenance	Paris
P5	CAD/CAM	Boston

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**Degree of Fragmentation** 



Finding the suitable level of partitioning within this range

### **Correctness of Fragmentation**

#### Completeness

Decomposition of relation R into fragments R<sub>1</sub>, R<sub>2</sub>, ..., R<sub>n</sub> is complete iff each data item in R can also be found in some R<sub>i</sub>

#### Reconstruction

If relation *R* is decomposed into fragments *R*<sub>1</sub>, *R*<sub>2</sub>, ..., *R<sub>n</sub>*, then there should exist some relational operator ∇ such that

$$R = \nabla_{1 \le i \le n} R_i$$

#### Disjointness

If relation R is decomposed into fragments R<sub>1</sub>, R<sub>2</sub>, ..., R<sub>n</sub>, and data item d<sub>i</sub> is in R<sub>i</sub>, then d<sub>i</sub> should not be in any other fragment R<sub>k</sub> (k ≠ j).

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### **Allocation Alternatives**

- Non-replicated
  - partitioned : each fragment resides at only one site

#### Replicated

- fully replicated : each fragment at each site
- partially replicated : each fragment at some of the sites

#### Rule of thumb:

If  $\frac{\text{read - only queries}}{\text{update queries}} \ge 1$  replication is advantageous, otherwise replication may cause problems

### **Fragmentation**

Horizontal Fragmentation (HF)

- Primary Horizontal Fragmentation (PHF)
- Derived Horizontal Fragmentation (DHF)
- Vertical Fragmentation (VF)
- Hybrid Fragmentation (HF)

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### Primary Horizontal Fragmentation

Definition :

 $R_j = \sigma_{F_i}(R), 1 \le j \le w$ 

where  $F_i$  is a selection formula.

Therefore,

A horizontal fragment  $R_i$  of relation R consists of all the tuples of R which satisfy a predicate  $p_i$ .

 $\downarrow$ 

Given a set of predicates M, there are as many horizontal fragments of relation R as there are predicates.

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### **PHF – Example**



Two candidate relations : PAY and PROJ

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### **PHF – Example**

PAY <sub>1</sub>	
TITLE	SAL
Mech. Eng.	27000
Programmer	24000

PAY <sub>2</sub>	
TITLE	SAL
Elect. Eng.	40000
Syst. Anal.	34000

### PHF – Example

PRO	.OJ <sub>1</sub>			PROJ <sub>2</sub>				
PNO	PNAME	BUDGET	LOC		PNO	PNAME	BUDGET	LOC
P1	Instrumentation	150000	Montreal		P2	Database Develop.	135000	New York
PRO	I.				PRO	.l.		

 $OJ_4$ 

 $OJ_6$ 

PNO	PNAME	BUDGET	LOC	PNO	PNAME	BUDGET	LOC
P3	CAD/CAM	250000	New York	P4	Maintenance	310000	Paris

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### **PHF – Correctness**

#### Completeness

Since the set of predicates is complete and minimal, the selection predicates are complete

#### Reconstruction

→ If relation *R* is fragmented into  $F_R = \{R_1, R_2, ..., R_r\}$ 

$$R = \bigcup_{\forall Ri \in FR} R_i$$

#### Disjointness

Predicates that form the basis of fragmentation should be mutually exclusive.

### Derived Horizontal Fragmentation

Defined on a member relation of a link according to a selection operation specified on its owner.

- Each link is an equijoin.
- Equijoin can be implemented by means of semijoins.



**DHF – Definition** 

Given a link *L* where owner(L)=S and member(L)=R, the derived horizontal fragments of *R* are defined as

 $R_i = R \bowtie_F S_i, 1 \le i \le w$ 

where w is the maximum number of fragments that will be defined on R and

 $S_i = \sigma_{F_i}(S)$ 

where  $F_i$  is the formula according to which the primary horizontal fragment  $S_i$  is defined.

### **DHF – Example**

Given link  $L_1$  where owner( $L_1$ )=SKILL and member( $L_1$ )=EMP EMP<sub>1</sub> = EMP  $\bowtie$  SKILL<sub>1</sub>

 $EMP_2 = EMP \bowtie SKILL_2$ 

where

 $SKILL_1 = \sigma_{SAL \le 30000}(SKILL)$ 

$$SKILL_2 = \sigma_{SAL>30000}(SKILL)$$

EMP<sub>1</sub>

ENO	ENAME	TITLE
E3	A. Lee	Mech. Eng.
E4	J. Miller	Programmer
E7	R. Davis	Mech. Eng.

2		
ENO	ENAME	TITLE
E1	J. Doe	Elect. Eng.
E2	M. Smith	Syst. Anal.
E5	B. Casey	Syst. Anal.
E6	L. Chu	Elect. Eng.
E8	J. Jones	Syst. Anal.

EMP<sub>2</sub>

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### **DHF – Correctness**

#### Completeness

**Referential integrity** 

→ Let *R* be the member relation of a link whose owner is relation *S* which is fragmented as  $F_S = \{S_1, S_2, ..., S_n\}$ . Furthermore, let A be the join attribute between *R* and *S*. Then, for each tuple *t* of *R*, there should be a tuple *t* of *S* such that

*t*[*A*]=*t*'[*A*]

Reconstruction

Same as primary horizontal fragmentation.

- Disjointness
  - Simple join graphs between the owner and the member fragments.

### **Vertical Fragmentation**

Has been studied within the centralized context

- design methodology
- physical clustering
- More difficult than horizontal, because more alternatives exist.

Two approaches :

- grouping
  - attributes to fragments
- splitting
  - relation to fragments

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**Vertical Fragmentation** 

- Overlapping fragments
  - 🗯 grouping
- Non-overlapping fragments
  - splitting
  - We do not consider the replicated key attributes to be overlapping.
- Advantage:
  - Easier to enforce functional dependencies (for integrity checking etc.)

### **VF – Correctness**

A relation *R*, defined over attribute set *A* and key *K*, generates the vertical partitioning  $F_R = \{R_1, R_2, ..., R_r\}$ .

#### Completeness

The following should be true for A:

 $A = \bigcup A_{R_i}$ 

#### Reconstruction

Reconstruction can be achieved by

 $R = \bowtie_{K} R_{i} \forall R_{i} \in F_{R}$ 

#### Disjointness

- TID's are not considered to be overlapping since they are maintained by the system
- Duplicated keys are not considered to be overlapping

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### **Fragment Allocation**

Problem Statement

Given

- $F = \{F_1, F_2, ..., F_n\}$
- $S = \{S_1, S_2, \dots, S_m\}$  network sites
- $Q = \{q_1, q_2, ..., q_a\}$  applications

Find the "optimal" distribution of *F* to *S*.

#### Optimality

- Minimal cost
  - Communication + storage + processing (read & update)

fragments

- Cost in terms of time (usually)
- Performance

Response time and/or throughput

- Constraints
  - Per site constraints (storage & processing)

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#### **General Form**

min(Total Cost)

subject to

response time constraint

storage constraint

processing constraint

#### **Decision Variable**

 $x_{ij} = \begin{cases} 1 \text{ if fragment } F_i \text{ is stored at site } S_j \\ 0 \text{ otherwise} \end{cases}$ 

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### **Allocation Model**

Total Cost

 $\sum_{\text{all queries}} \text{query processing cost } + \sum_{\text{all sites}} \sum_{\text{all fragments}} \text{cost of storing a fragment at a site}$ 

Storage Cost (of fragment  $F_j$  at  $S_k$ )

(unit storage cost at  $S_k$ ) \* (size of  $F_j$ ) \* $x_{jk}$ 

Query Processing Cost (for one query)

processing component + transmission component

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#### Query Processing Cost

Processing component

access cost + integrity enforcement cost + concurrency control cost

Access cost

 $\sum_{\text{all sites}} \sum_{\text{all fragments}} (\text{no. of update accesses+ no. of read accesses}) *$ 

 $x_{ij}$  \*local processing cost at a site

Integrity enforcement and concurrency control costs

Can be similarly calculated

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**Allocation Model** 

#### Query Processing Cost

#### Transmission component

cost of processing updates + cost of processing retrievals

Cost of updates

$$\sum_{\text{all sites}} \sum_{\text{all fragments}} \text{update message cost} +$$

 $\sum_{\text{all sites}} \sum_{\text{all fragments}} \text{acknowledgment cost}$ 

Retrieval Cost

∑<sub>all fragments</sub> min<sub>all sites</sub>(cost of retrieval command +

cost of sending back the result)

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### **Allocation Model**

- Solution Methods
  - **FAP** is NP-complete
  - **DAP** also NP-complete

#### Heuristics based on

- single commodity warehouse location (for FAP)
- knapsack problem
- branch and bound techniques
- network flow

Attempts to reduce the solution space

- assume all candidate partitionings known; select the "best" partitioning
- ignore replication at first

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### Outline

- Introduction
- Distributed DBMS Architecture
- Distributed Database Design
- Distributed Query Processing
  - Query Processing Methodology
  - Distributed Query Optimization
- Distributed Concurrency Control
- Distributed Reliability Protocols

### **Query Processing**



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### **Query Processing Components**

- Query language that is used
  - SQL: "intergalactic dataspeak"
- Query execution methodology
  - The steps that one goes through in executing high-level (declarative) user queries.

#### Query optimization

How do we determine the "best" execution plan?

### **Selecting Alternatives**

```
select ENAME
FROM EMP, ASG
where EMP, ENO = ASG, ENO
AND DUR > 37
Strategy 1
\Pi_{ENAME}(\sigma_{DUR>37 \land EMP.ENO=ASG, ENO}(EMP \times ASG))
Strategy 2
\Pi_{ENAME}(EMP \bowtie O(\sigma_{DUR>37}(ASG)))
```

Strategy 2 avoids Cartesian product, so is "better"

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What is the Problem?

<u>Site 1</u>	<u>Site 2</u>	<u>Site 3</u>	<u>Site 4</u>	<u>Site 5</u>
ASG <sub>1</sub> =σ <sub>ENO≤"E3</sub> (ASG)	$ASG_2 = \sigma_{ENO s^{e}E3^{e}}(ASG)$	EMP <sub>1</sub> =σ <sub>ENO≤"E3"</sub> (EMP)	$EMP_2 = \sigma_{ENO}(EMP)$	Result



### **Cost of Alternatives**

#### Assume:

	<i>size</i> (EMP) = 400, <i>size</i> (ASG) = 1000	
1011	tuple access cost = 1 unit; tuple transfer cost = 10 units	
Stra	ategy 1	
0	produce ASG': (10+10)*tuple access cost	20
0	transfer ASG' to the sites of EMP: (10+10)*tuple transfer cost	200
8	produce EMP': (10+10) *tuple access cost*2	40
4	transfer EMP' to result site: (10+10) *tuple transfer cost	200
	Total cost	460
Stra	ategy 2	
0	transfer EMP to site 5:400*tuple transfer cost	4,000
2	transfer ASG to site 5 :1000*tuple transfer cost	10,000
8	produce ASG':1000*tuple access cost	1,000
4	join EMP and ASG':400*20*tuple access cost	8,000
	Total cost	23,000
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### **Query Optimization Objectives**

#### Minimize a cost function

I/O cost + CPU cost + communication cost

These might have different weights in different distributed environments

#### Wide area networks

- communication cost will dominate
  - low bandwidth
  - low speed
  - high protocol overhead
- most algorithms ignore all other cost components

#### Local area networks

- communication cost not that dominant
- total cost function should be considered

#### Can also maximize throughput

### Query Optimization Issues – Types of Optimizers

#### Exhaustive search

- cost-based
- 🗯 optimal
- combinatorial complexity in the number of relations

#### Heuristics

- 🗯 not optimal
- regroup common sub-expressions
- perform selection, projection first
- replace a join by a series of semijoins
- reorder operations to reduce intermediate relation size

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### Query Optimization Issues – Optimization Granularity

- Single query at a time
  - cannot use common intermediate results
- Multiple queries at a time
  - efficient if many similar queries
  - decision space is much larger

### Query Optimization Issues – Optimization Timing

#### Static

- $\rightarrow$  compilation  $\Rightarrow$  optimize prior to the execution
- $\blacksquare$  difficult to estimate the size of the intermediate results  $\Rightarrow$  error propagation
- -can amortize over many executions
- **₩**R\*

#### Dynamic

- run time optimization
- exact information on the intermediate relation sizes
- have to reoptimize for multiple executions
- **Distributed INGRES**

#### Hybrid

- if the error in estimate sizes > threshold, reoptimize at run time
- MERMAID

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### **Query Optimization Issues – Statistics**

- Relation
  - cardinality
  - size of a tuple
  - fraction of tuples participating in a join with another relation

#### Attribute

- cardinality of domain
- actual number of distinct values

#### Common assumptions

- mindependence between different attribute values
- uniform distribution of attribute values within their domain

### Query Optimization Issues – Decision Sites

#### Centralized

- single site determines the "best" schedule
- simple
- > need knowledge about the entire distributed database

#### Distributed

- cooperation among sites to determine the schedule
- meed only local information
- cost of cooperation

#### Hybrid

- one site determines the global schedule
- each site optimizes the local subqueries

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### Query Optimization Issues – Network Topology

- Wide area networks (WAN) point-to-point
  - characteristics
    - low bandwidth
    - low speed
    - high protocol overhead
  - communication cost will dominate; ignore all other cost factors
  - global schedule to minimize communication cost
  - > local schedules according to centralized query optimization
- Local area networks (LAN)
  - communication cost not that dominant
  - total cost function should be considered
  - broadcasting can be exploited (joins)
  - special algorithms exist for star networks

### **Distributed Query Processing Methodology**



### **Step 1 – Query Decomposition**

Input : Calculus query on global relations

- Normalization
  - manipulate query quantifiers and qualification
- Analysis
  - detect and reject "incorrect" queries
  - possible for only a subset of relational calculus
- Simplification
  - eliminate redundant predicates
- Restructuring
  - ➡ calculus query ⇒ algebraic query
  - more than one translation is possible
  - we transformation rules

### **Normalization**

- Lexical and syntactic analysis
  - check validity (similar to compilers)
  - check for attributes and relations
  - type checking on the qualification
- Put into normal form
  - Conjunctive normal form
    - $(p_{11} \lor p_{12} \lor \ldots \lor p_{1n}) \land \ldots \land (p_{m1} \lor p_{m2} \lor \ldots \lor p_{mn})$
  - Disjunctive normal form

 $(p_{11} \land p_{12} \land \ldots \land p_{1n}) \lor \ldots \lor (p_{m1} \land p_{m2} \land \ldots \land p_{mn})$ 

- OR's mapped into union
- AND's mapped into join or selection

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### Analysis

- Refute incorrect queries
- Type incorrect
  - If any of its attribute or relation names are not defined in the global schema
  - If operations are applied to attributes of the wrong type
- Semantically incorrect
  - Components do not contribute in any way to the generation of the result
  - Only a subset of relational calculus queries can be tested for correctness
  - Those that do not contain disjunction and negation
  - To detect
    - connection graph (query graph)
    - join graph

### Simplification

- Why simplify?
  - Remember the example
- How? Use transformation rules
  - elimination of redundancy
    - idempotency rules
      - $p_1 \land \neg (p_1) \Leftrightarrow \mathsf{false}$  $p_1 \land (p_1 \lor p_2) \Leftrightarrow p_1$

 $p_1 \land (p_1 \lor p_2) \Leftrightarrow p_1$  $p_1 \lor \text{false} \Leftrightarrow p_1$ 

- ...
- application of transitivity
- use of integrity rules

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### Simplification – Example

TITLE
EMP
EMP.ENAME = "J. Doe"
( <b>NOT</b> (EMP.TITLE = "Programmer")
(EMP.TITLE = "Programmer"
<pre>EMP.TITLE = "Elect. Eng.")</pre>
<b>NOT</b> (EMP.TITLE = "Elect. Eng."))
$\Downarrow$
TITLE
EMP
EMP.ENAME = "J. Doe"





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### **Restructuring – Transformation Rules**

- Commutativity of binary operations
  - $\implies R \times S \Leftrightarrow S \times R$

  - $\blacksquare R \cup S \Leftrightarrow S \cup R$
- Associativity of binary operations
  - $\implies (R \times S) \times T \Leftrightarrow R \times (S \times T)$
  - $\implies (R \bowtie S) \bowtie T \Leftrightarrow R \bowtie (S \bowtie T)$
- Idempotence of unary operations
  - ▶  $\Pi_{A'}(\Pi_{A'}(\mathsf{R})) \Leftrightarrow \Pi_{A'}(\mathsf{R})$
- Commuting selection with projection

### Restructuring – Transformation Rules

- Commuting selection with binary operations
  - $\Rightarrow \sigma_{p(A)}(R \times S) \Leftrightarrow (\sigma_{p(A)}(R)) \times S$
  - $\Longrightarrow \sigma_{\rho(A_i)}(R \bowtie_{A_i,B_k)} S) \Leftrightarrow (\sigma_{\rho(A_i)}(R)) \bowtie_{A_i,B_k)} S$

$$\twoheadrightarrow \sigma_{\rho(A_i)}(R \cup T) \Leftrightarrow \sigma_{\rho(A_i)}(R) \cup \sigma_{\rho(A_i)}(T)$$

where  $A_i$  belongs to R and T

#### Commuting projection with binary operations

- $\Longrightarrow \Pi_{C}(R \Join_{A_{j},B_{k})} S) \Leftrightarrow \Pi_{A'}(R) \Join_{A_{j},B_{k}} \Pi_{B'}(S)$

$$\blacksquare \Pi_{\mathcal{C}}(\mathcal{R} \cup \mathcal{S}) \Leftrightarrow \Pi_{\mathcal{C}}(\mathcal{R}) \cup \Pi_{\mathcal{C}}(\mathcal{S})$$

where R[A] and S[B];  $C = A' \cup B'$  where  $A' \subseteq A$ ,  $B' \subseteq B$ 

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### **Example**



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### **Equivalent Query**



### Restructuring



### **Step 2 – Data Localization**

Input: Algebraic query on distributed relations

- Determine which fragments are involved
- Localization program

  - optimize

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### **Example**



### **Provides Parallellism**



### **Eliminates Unnecessary Work**



### **Reduction for PHF**



### **Reduction for PHF**

- Reduction with join
  - Possible if fragmentation is done on join attribute
  - Distribute join over union

 $(R_1 \cup R_2) \bowtie S \Leftrightarrow (R_1 \bowtie S) \cup (R_2 \bowtie S)$ 

• Given  $R_i = \sigma_{p_i}(R)$  and  $R_j = \sigma_{p_j}(R)$ 

 $R_{i} \bowtie R_{j} = \phi \text{ if } \forall x \text{ in } R_{i}, \forall y \text{ in } R_{j}: \neg(p_{i}(x) \land p_{j}(y))$ 

### **Reduction for PHF**



### **Reduction for PHF**

- Reduction with join Example
  - Distribute join over unions
  - Apply the reduction rule



### **Reduction for VF**



### Step 3 – Global Query Optimization

Input: Fragment query

- Find the *best* (not necessarily optimal) global schedule
  - Minimize a cost function
  - Distributed join processing
    - Bushy vs. linear trees
    - Which relation to ship where?
    - Ship-whole vs ship-as-needed
  - Decide on the use of semijoins
    - Semijoin saves on communication at the expense of more local processing.
  - Join methods
    - nested loop vs ordered joins (merge join or hash join)

### **Cost-Based Optimization**

#### Solution space

- The set of equivalent algebra expressions (query trees).
- Cost function (in terms of time)
  - I/O cost + CPU cost + communication cost
  - These might have different weights in different distributed environments (LAN vs WAN).
  - Can also maximize throughput
- Search algorithm
  - How do we move inside the solution space?
  - Exhaustive search, heuristic algorithms (iterative improvement, simulated annealing, genetic,...)

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### **Query Optimization Process**



### Search Space



**Search Space** 



### **Search Strategy**

- How to "move" in the search space.
- Deterministic
  - Start from base relations and build plans by adding one relation at each step
  - >>> Dynamic programming: breadth-first
- Randomized
  - Search for optimalities around a particular starting point
  - Trade optimization time for execution time
  - → Better when > 5-6 relations
  - Simulated annealing
  - Iterative improvement

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### **Cost Functions**

- Total Time (or Total Cost)
  - Reduce each cost (in terms of time) component individually
  - Do as little of each cost component as possible
  - Optimizes the utilization of the resources



Response Time

- Do as many things as possible in parallel
- May increase total time because of increased total activity

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### **Total Cost**

Summation of all cost factors

Total cost = CPU cost + I/O cost + communication cost

CPU cost = unit instruction cost \* no.of instructions

I/O cost = unit disk I/O cost \* no. of disk I/Os

communication cost = message initiation + transmission

### **Total Cost Factors**

#### Wide area network

- message initiation and transmission costs high
- local processing cost is low (fast mainframes or minicomputers)
- ➡ ratio of communication to I/O costs = 20:1

#### Local area networks

- communication and local processing costs are more or less equal
- 🗯 ratio = 1:1.6

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### **Response Time**

Elapsed time between the initiation and the completion of a query

Response time = CPU time + I/O time + communication time					
CPU time = unit instruction time * no. of sequential instruction					
I/O time = unit I/O time * no. of sequential I/Os					
communication ti	ime = unit msg initiation time * sequential msg + unit transmission time * no sequential bytes	no. of ). of			



### **Optimization Statistics**

- Primary cost factor: size of intermediate relations
- Make them precise  $\Rightarrow$  more costly to maintain
  - For each relation  $R[A_1, A_2, ..., A_n]$  fragmented as  $R_1, ..., R_r$ 
    - length of each attribute: *length*(*Ai*)
    - the number of distinct values for each attribute in each fragment: card(∏<sub>Ai</sub>R<sub>i</sub>)
    - maximum and minimum values in the domain of each attribute: min(A<sub>i</sub>), max(A<sub>i</sub>)
    - the cardinalities of each domain: card(dom[A<sub>i</sub>])
    - the cardinalities of each fragment: card(R<sub>i</sub>)
  - Selectivity factor of each operation for relations
    - For joins

$$SF_{\bowtie}(R,S) = \frac{card(R\bowtie S)}{card(R) * card(S)}$$

## Intermediate Relation Sizes

#### Selection

size(R) = card(R) \* length(R) $card(\sigma_F(R)) = SF_{\sigma}(F) * card(R)$ where

$$S F_{\sigma}(A = value) = \frac{1}{card(\prod_{A}(R))}$$
$$S F_{\sigma}(A > value) = \frac{max(A) - value}{max(A) - min(A)}$$
$$S F_{\sigma}(A < value) = \frac{value - max(A)}{max(A) - min(A)}$$

$$SF_{\sigma}(p(A_{i}) \land p(A_{j})) = SF_{\sigma}(p(A_{i})) * SF_{\sigma}(p(A_{j}))$$
$$SF_{\sigma}(p(A_{i}) \lor p(A_{j})) = SF_{\sigma}(p(A_{i})) + SF_{\sigma}(p(A_{j})) - (SF_{\sigma}(p(A_{i})) * SF_{\sigma}(p(A_{j})))$$
$$SF_{\sigma}(A \in value) = SF_{\sigma}(A = value) * card(\{values\})$$

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### **Intermediate Relation Sizes**

#### Projection

 $card(\Pi_A(R))=card(R)$ 

#### **Cartesian Product**

 $card(R \times S) = card(R) * card(S)$ 

#### Union

upper bound:  $card(R \cup S) = card(R) + card(S)$ lower bound:  $card(R \cup S) = max{card(R), card(S)}$ 

#### Set Difference

upper bound: card(R-S) = card(R)lower bound: 0

### **Intermediate Relation Size**

Join

Special case: A is a key of R and B is a foreign key of S;

 $card(R \bowtie_{A=B} S) = card(S)$ 

More general:

 $card(R \bowtie S) = SF_{\bowtie} * card(R) * card(S)$ 

#### Semijoin

 $card(R \bowtie_A S) = SF_{\bowtie}(S.A) * card(R)$ 

where

 $SF_{\bowtie}(R \bowtie_{A} S) = SF_{\bowtie}(S.A) = \frac{card(\prod_{A}(S))}{card(dom[A])}$ 

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### **System R Algorithm**

 Simple (i.e., mono-relation) queries are executed according to the best access path

#### execute joins

- **2.1** Determine the possible ordering of joins
- **2.2** Determine the cost of each ordering
- 2.3 Choose the join ordering with minimal cost

### **System R Algorithm**

For joins, two alternative algorithms :

Nested loops

 for each tuple of *external* relation (cardinality n<sub>1</sub>)
 for each tuple of *internal* relation (cardinality n<sub>2</sub>)
 join two tuples if the join predicate is true
 end
 Complexity: n<sub>1</sub>\*n<sub>2</sub>

 Merge join

 sort relations
 merge relations
 Complexity: n<sub>1</sub>+ n<sub>2</sub> if relations are previously sorted and equijoin

System R Algorithm – Example

Names of employees working on the CAD/CAM

project

Assume

- EMP has an index on ENO,
- ASG has an index on PNO,
- PROJ has an index on PNO and an index on PNAME



### System R Example (cont'd)

#### Ochoose the best access paths to each relation

- EMP: sequential scan (no selection on EMP)
- ASG: sequential scan (no selection on ASG)
- PROJ: index on PNAME (there is a selection on PROJ based on PNAME)

#### Determine the best join ordering

- ▶ EMP ⋈ ASG ⋈ PROJ
- ➡ ASG ⋈PROJ ⋈EMP
- ➡ PROJ ⋈ ASG ⋈ EMP
- ➡ ASG ⋈ EMP ⋈ PROJ
- ▶ EMP × PROJ⊠ASG
- ▶ PROJ × EMP ⋈ ASG
- Select the best ordering based on the join costs evaluated according to the two methods

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#### System R Algorithm Alternatives PROJ ASG EMP EMP ⋈ ASG $\mathsf{EMP} \times \mathsf{PROJASG} \bowtie \mathsf{EMP} \mathsf{ASG} \bowtie \mathsf{PROJ} \mathsf{PROJ} \bowtie \mathsf{ASG} \mathsf{PROJ} \times \mathsf{EMP}$ pruned pruned pruned pruned (ASG<sup>I</sup> EMP)<sup>I</sup> PROJ (PROJ ⋈ ASG)⋈ EMP Best total join order is one of ((ASG ⋈ EMP) ⋈ PROJ) ((PROJ ⋈ASG) ⋈EMP)

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### **System R Algorithm**

- ((PROJ ⋈ASG)⋈EMP) has a useful index on the select attribute and direct access to the join attributes of ASG and EMP
- Therefore, chose it with the following access methods:
  - ➡ select PROJ using index on PNAME
  - > then join with ASG using index on PNO
  - ➡ then join with EMP using index on ENO

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### Join Ordering in Fragment Queries

- Ordering joins
  - Distributed INGRES
  - ➡ System R\*
- Semijoin ordering
  - msdd-1 🗰

### **Join Ordering**



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### Join Ordering – Example



### Join Ordering – Example

Execution alternatives:

- 1. EMP → Site 2 Site 2 computes EMP'=EMP $\checkmark$ ASG EMP' → Site 3 Site 3 computes EMP $\triangleright \checkmark$  PROJ
- 3. ASG → Site 3 Site 3 computes ASG'=ASG $\bowtie$  PROJ ASG' → Site 1 Site 1 computes ASG' $\bowtie$  EMP
- 5. EMP  $\rightarrow$  Site 2 PROJ  $\rightarrow$  Site 2 Site 2 computes EMP  $\bowtie$  PROJ  $\bowtie$  ASG

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ASG → Site 1
 Site 1 computes EMP'=EMP⊠ASG
 EMP' → Site 3
 Site 3 computes EMP'⊠PROJ

4. PROJ  $\rightarrow$  Site 2 Site 2 computes PROJ'=PROJ $\bowtie$  ASG PROJ'  $\rightarrow$  Site 1 Site 1 computes PROJ' $\bowtie$  EMP

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### **Semijoin Algorithms**

- Consider the join of two relations:
  - ➡ R[A] (located at site 1)
  - ➡ S[A] (located at site 2)

#### Alternatives:

- 1 Do the join  $R \bowtie_A S$
- 2 Perform one of the semijoin equivalents

$$R\bowtie_A S \Leftrightarrow (R\bowtie_A S)\bowtie_A S$$

$$\Leftrightarrow R \bowtie_A (S \bowtie_A R)$$

 $\Leftrightarrow (R \bowtie_A S) \bowtie_A (S \bowtie_A R)$ 

### **Semijoin Algorithms**

- Perform the join
  - send R to Site 2
  - $\rightarrow$  Site 2 computes  $R \bowtie_A S$
- Consider semijoin  $(R \bowtie_A S) \bowtie_A S$ 
  - $\implies$   $S' \leftarrow \prod_A(S)$
  - $\blacksquare S' \rightarrow Site 1$
  - ⇒ Site 1 computes  $R' = R \bowtie_A S'$
  - $\Rightarrow R' \rightarrow Site 2$
  - $\blacksquare$  Site 2 computes  $R' \bowtie_A S$

#### Semijoin is better if

 $size(\Pi_A(S)) + size(R \bowtie_A S)) < size(R)$ 

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### **Distributed Query Processing**

Algorithms	Opt. Timing	Objective Function	Opt. Factors	Network Topology	Semijoin	Stats	Fragments
Dist. INGRES	Dynamic	Resp. time or Total time	Msg. Size, Proc. Cost	General or Broadcast	No	1	Horizontal
R*	Static	Total time	No. Msg., Msg. Size, IO, CPU	General or Local	No	1, 2	No
SDD-1	Static	Total time	Msg. Size	General	Yes	1,3,4, 5	No

1: relation cardinality; 2: number of unique values per attribute; 3: join selectivity factor; 4: size of projection on each join attribute; 5: attribute size and tuple size

### **R\* Algorithm**

- Cost function includes local processing as well as transmission
- Considers only joins
- Exhaustive search
- Compilation
- Published papers provide solutions to handling horizontal and vertical fragmentations but the implemented prototype does not

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### **R\* Algorithm**

#### Performing joins

Ship whole

- > larger data transfer
- ➡ smaller number of messages
- better if relations are small

#### Fetch as needed

- number of messages = O(cardinality of external relation)
- data transfer per message is minimal
- better if relations are large and the selectivity is good

### R\* Algorithm – Vertical Partitioning & Joins

#### Move outer relation tuples to the site of the inner relation

- (a) Retrieve outer tuples
- (b) Send them to the inner relation site
- (c) Join them as they arrive

Total Cost = cost(retrieving qualified outer tuples)

- + no. of outer tuples fetched \* cost(retrieving qualified inner tuples)
- + msg. cost \* (no. outer tuples fetched \* avg. outer tuple size) / msg. size

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### R\* Algorithm – Vertical Partitioning & Joins

#### 2. Move inner relation to the site of outer relation

cannot join as they arrive; they need to be stored

- Total Cost = cost(retrieving qualified outer tuples)
  - + no. of outer tuples fetched \* cost(retrieving matching inner tuples from temporary storage)
  - + cost(retrieving qualified inner tuples)
  - + cost(storing all qualified inner tuples in temporary storage)
  - + msg. cost \* (no. of inner tuples fetched \* avg. inner tuple size) / msg. size

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### R\* Algorithm – Vertical Partitioning & Joins

#### 3. Move both inner and outer relations to another site

Total cost = cost(retrieving qualified outer tuples)

- + cost(retrieving qualified inner tuples)
- + cost(storing inner tuples in storage)
- + msg. cost \* (no. of outer tuples fetched \* avg. outer tuple size) / msg. size
- + msg. cost \* (no. of inner tuples fetched \* avg. inner tuple size) / msg. size
- + no. of outer tuples fetched \* cost(retrieving inner tuples from temporary storage)

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R\* Algorithm – Vertical Partitioning & Joins

#### 4. Fetch inner tuples as needed

- (a) Retrieve qualified tuples at outer relation site
- (b) Send request containing join column value(s) for outer tuples to inner relation site
- (c) Retrieve matching inner tuples at inner relation site
- (d) Send the matching inner tuples to outer relation site
- (e) Join as they arrive
  - Total Cost = cost(retrieving qualified outer tuples)
    - + msg. cost \* (no. of outer tuples fetched)
    - + no. of outer tuples fetched \* (no. of inner tuples fetched \* avg. inner tuple size \* msg. cost / msg. size)
    - + no. of outer tuples fetched \* cost(retrieving matching inner tuples for one outer value)

### **Step 4 – Local Optimization**

Input: Best global execution schedule

- Select the best access path
- Use the centralized optimization techniques

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