

Scalable Virtual Ray Lights Rendering for Participating Media

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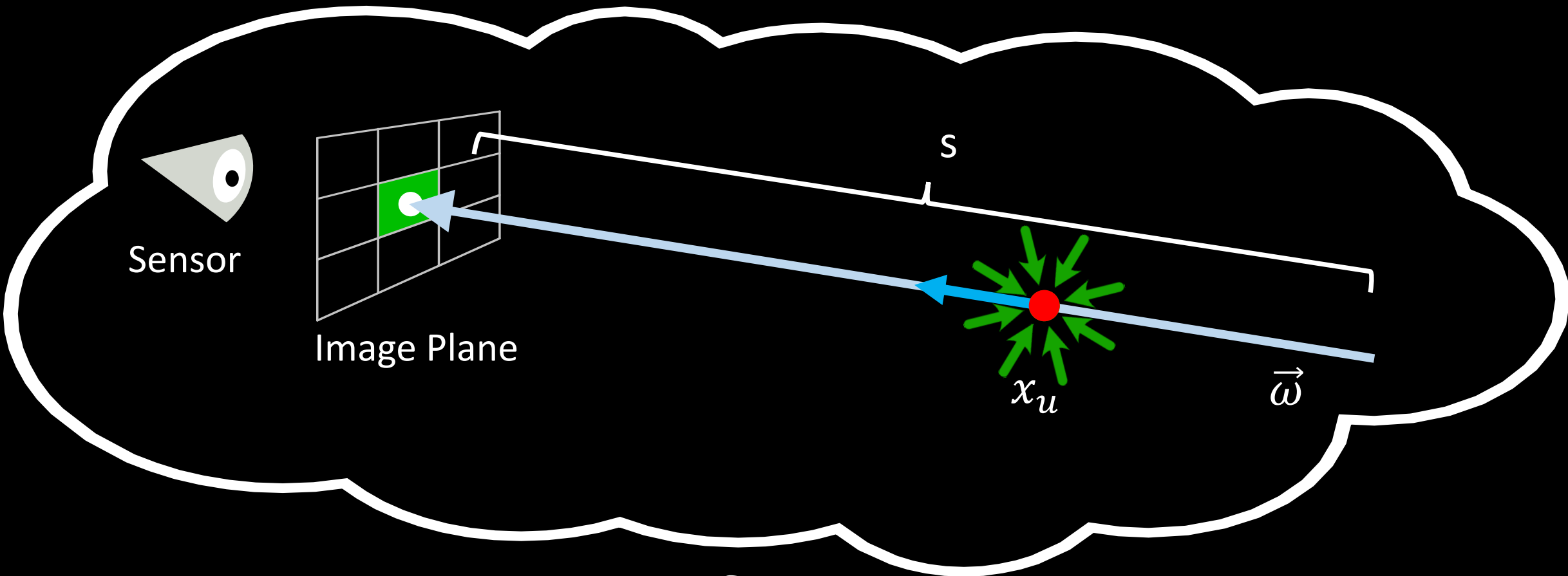
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MOTIVATION: Surface and Volume interaction



MOTIVATION: Volume interaction only



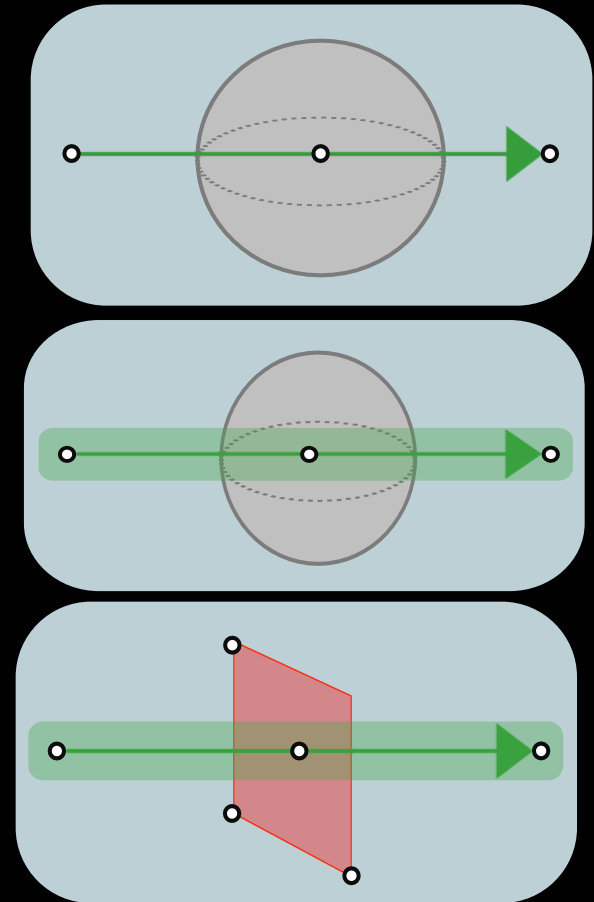


$$L_m(x, \vec{\omega}) = \int_0^s T_r(u) L_i(x_u, \vec{\omega}) du$$

- Path tracing / Bidirectional path tracing

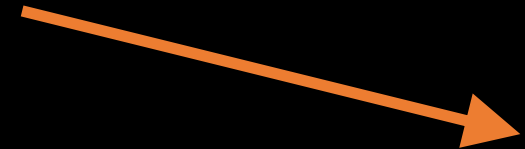
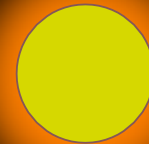
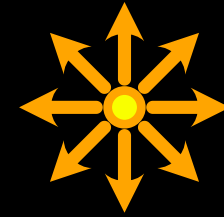
VOLUMETRIC RENDERING: Many techniques

- Path tracing / Bidirectional path tracing
- Density estimation:
 - Volumetric Photon Mapping
 - Photon Beam
 - Photon Planes
 - “Higher-order geometric primitives”

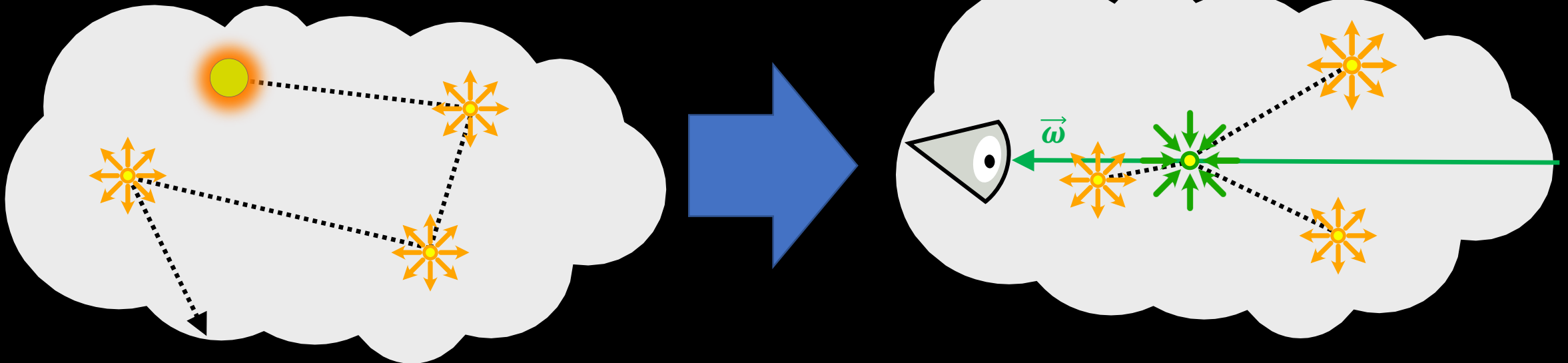


VOLUMETRIC RENDERING: Many techniques

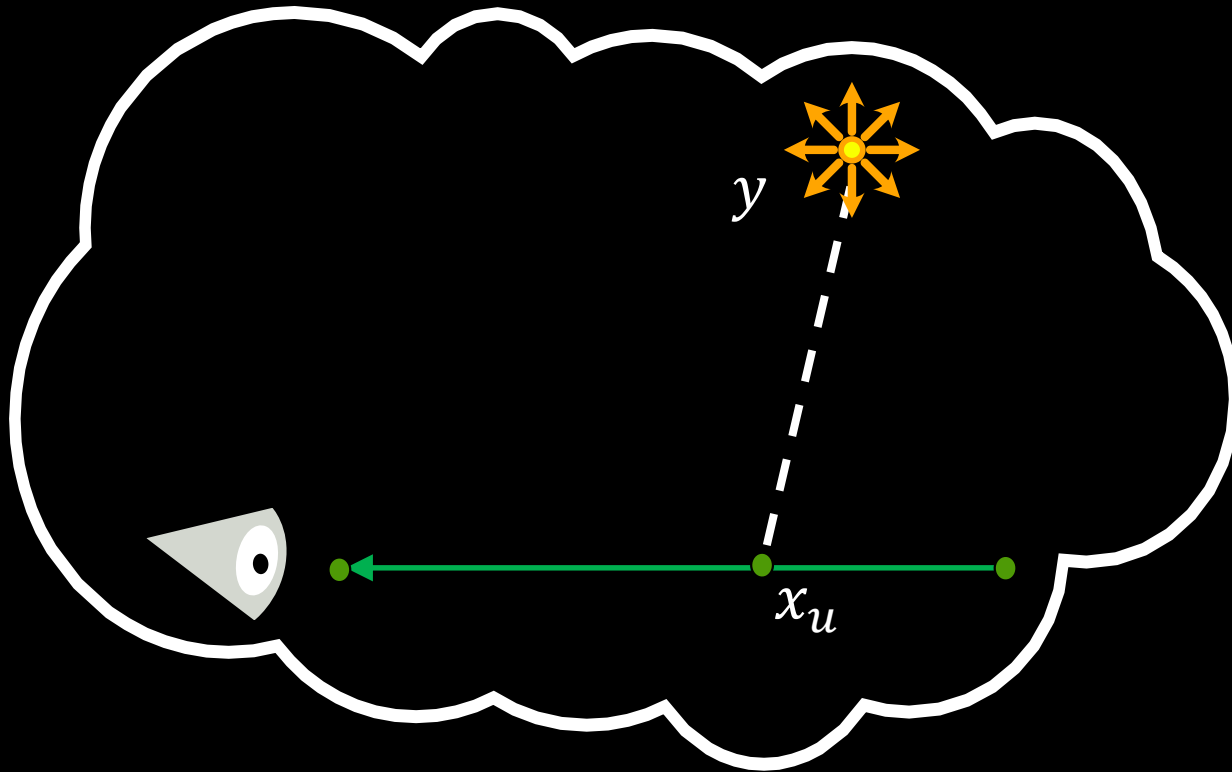
- Path tracing / Bidirectional path tracing
- Density estimation:
 - Volumetric Photon Mapping
 - Photon Beam
 - Photon Planes
 - “Higher-order geometric primitives”
- Many lights:
 - Virtual point lights
 - Virtual spherical lights
 - **Virtual ray lights**
 - “Higher-order geometric primitives”



- Many-light techniques have been introduced in “instant radiosity” [Keller et al. 1997]
- Indirect illumination as a sum of direct illumination of virtual lights

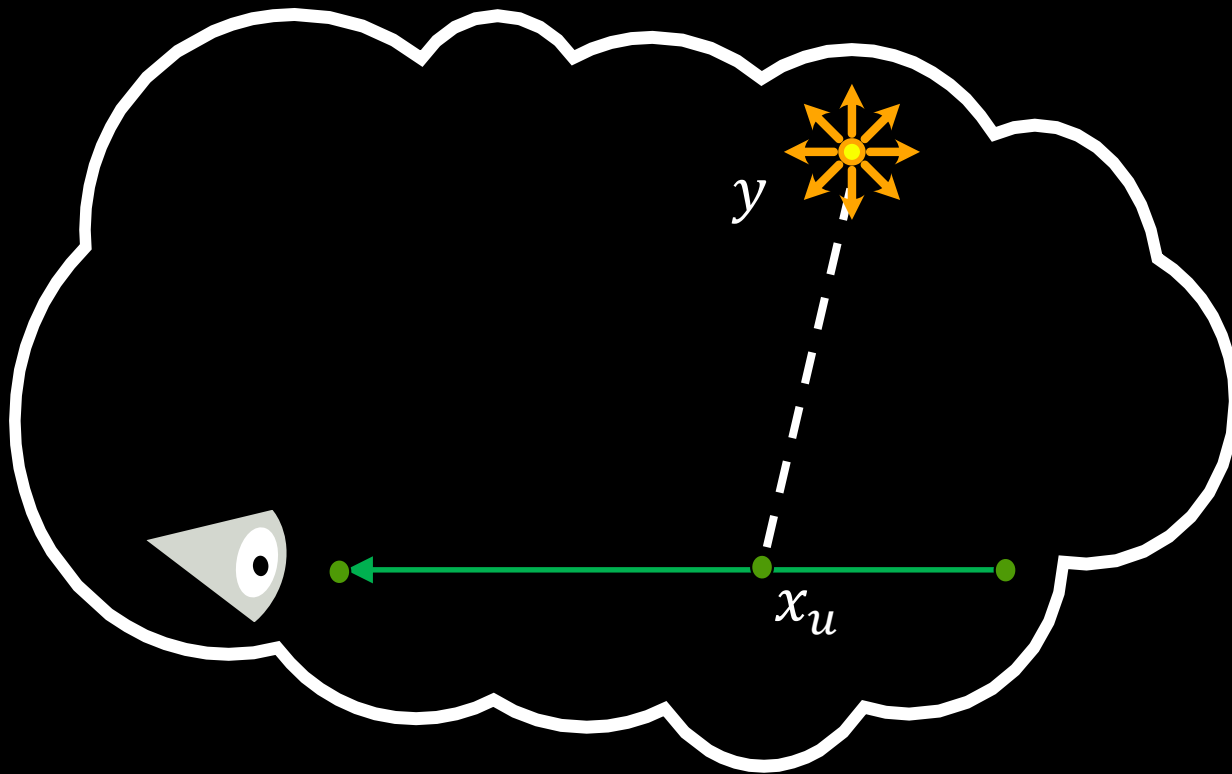


Virtual point light contribution



$$L_m^{VPL} = \frac{VPL(y, x_u)}{|y - x_u|^2 p(x_u)}$$

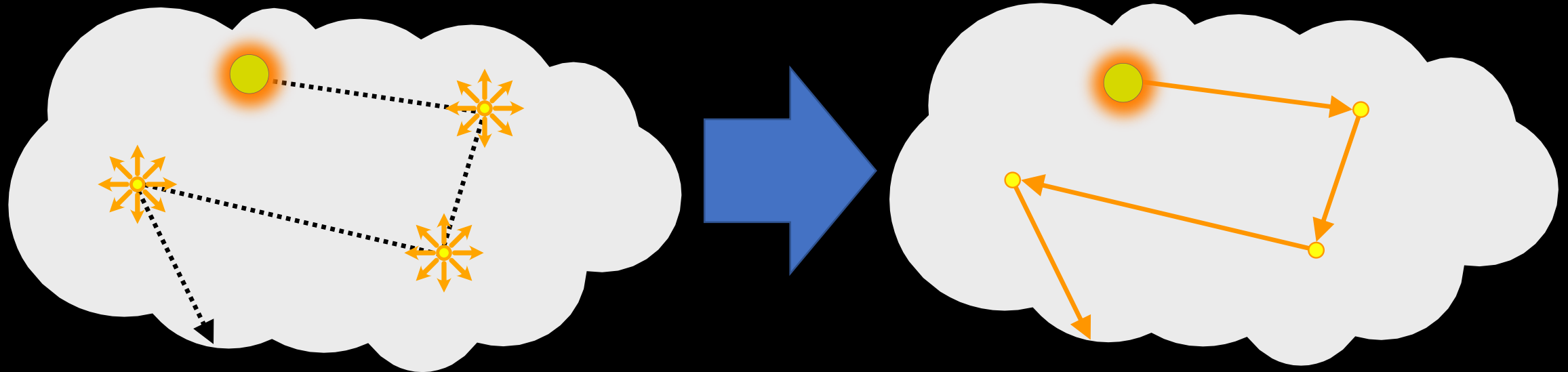
Virtual point light contribution



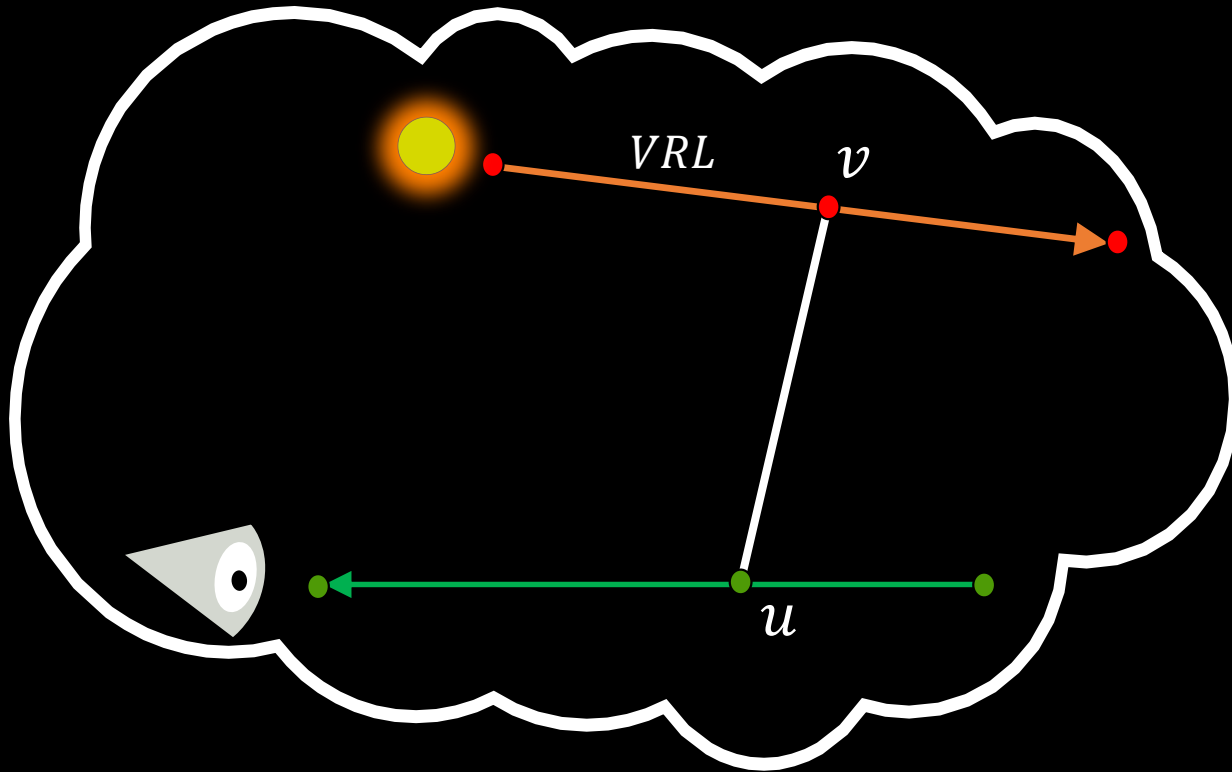
$$L_m^{VPL} = \frac{VPL(y, x_u)}{|y - x_u|^2 p(x_u)}$$

$$\propto \frac{1}{|y - x_u|^2}$$

- VPL vs. short VRL

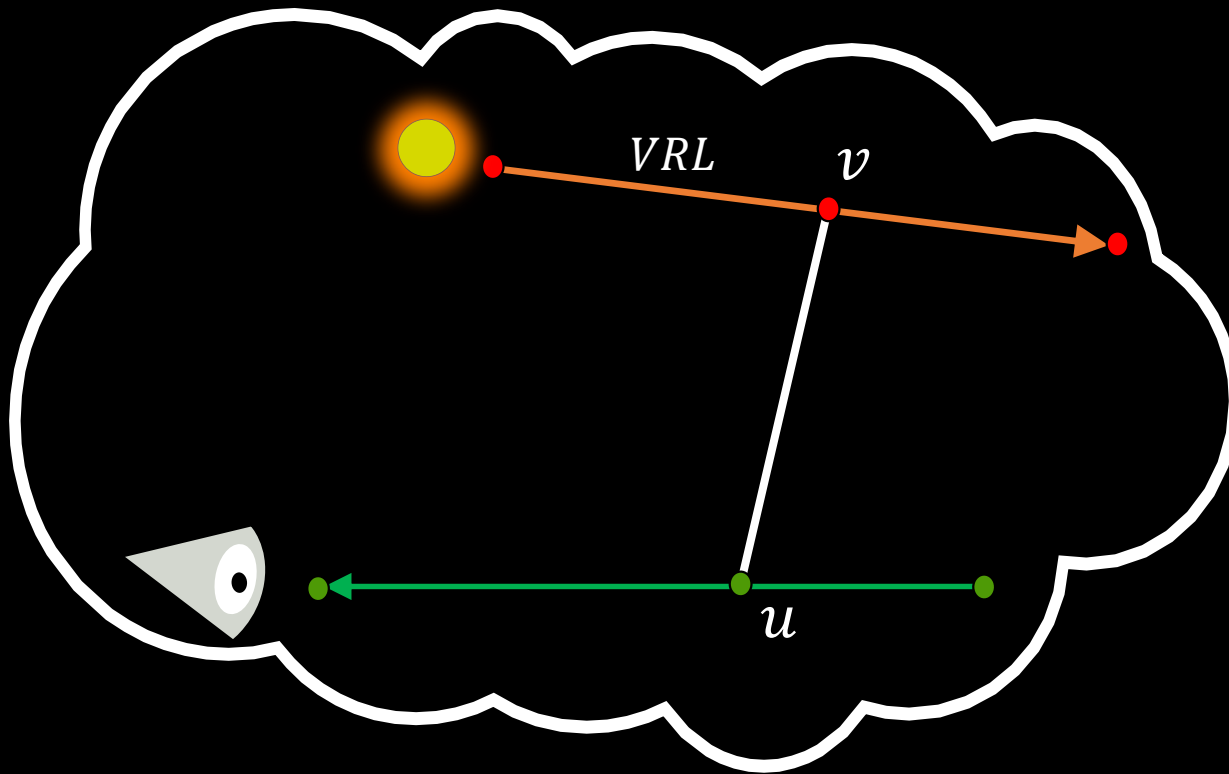


Virtual ray lights contribution



$$L_m^{VRL} = \int_0^s \int_0^t \frac{VRL(u, v)}{w(u, v)^2} dv du$$

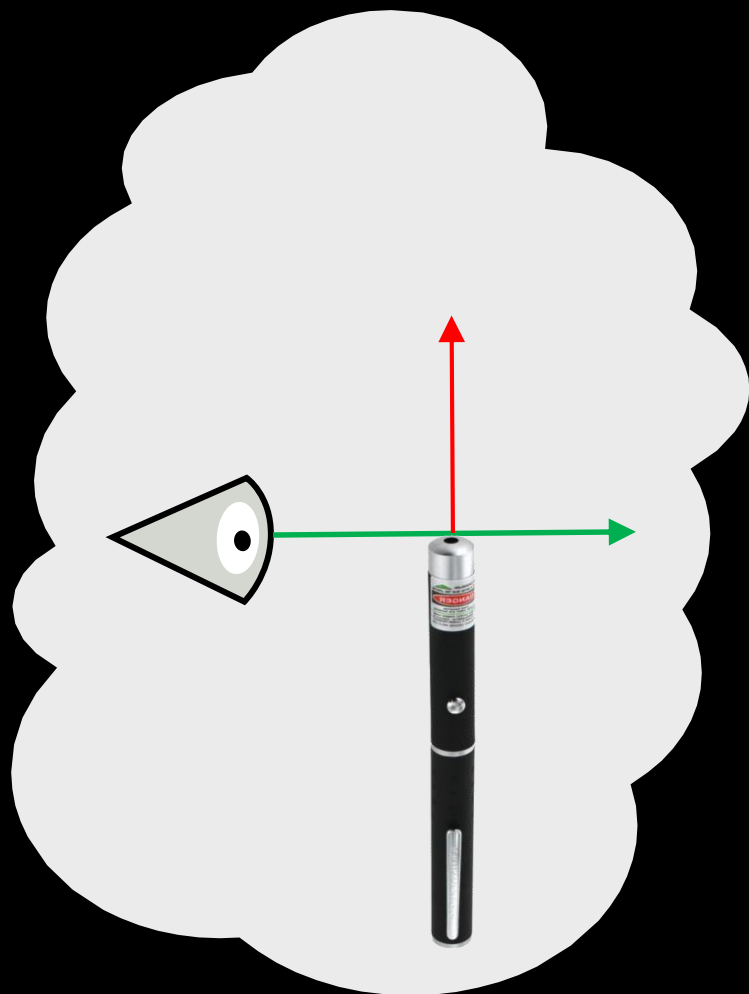
Virtual ray lights contribution



$$L_m^{VRL} = \frac{VRL(u, v)}{w(u, v)^2 p(u, v)}$$

$$p(u, v) \propto w(u, v)^{-2}$$

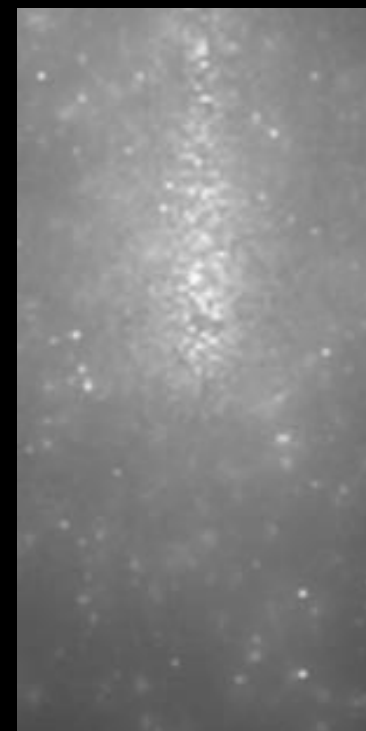
MANY LIGHTS: VRL vs. VPL



VRL



VPL



Equal rendering time

Realistic rendering :

- Unmanageable amount of virtual lights
- Cost linear with lights

Realistic rendering:

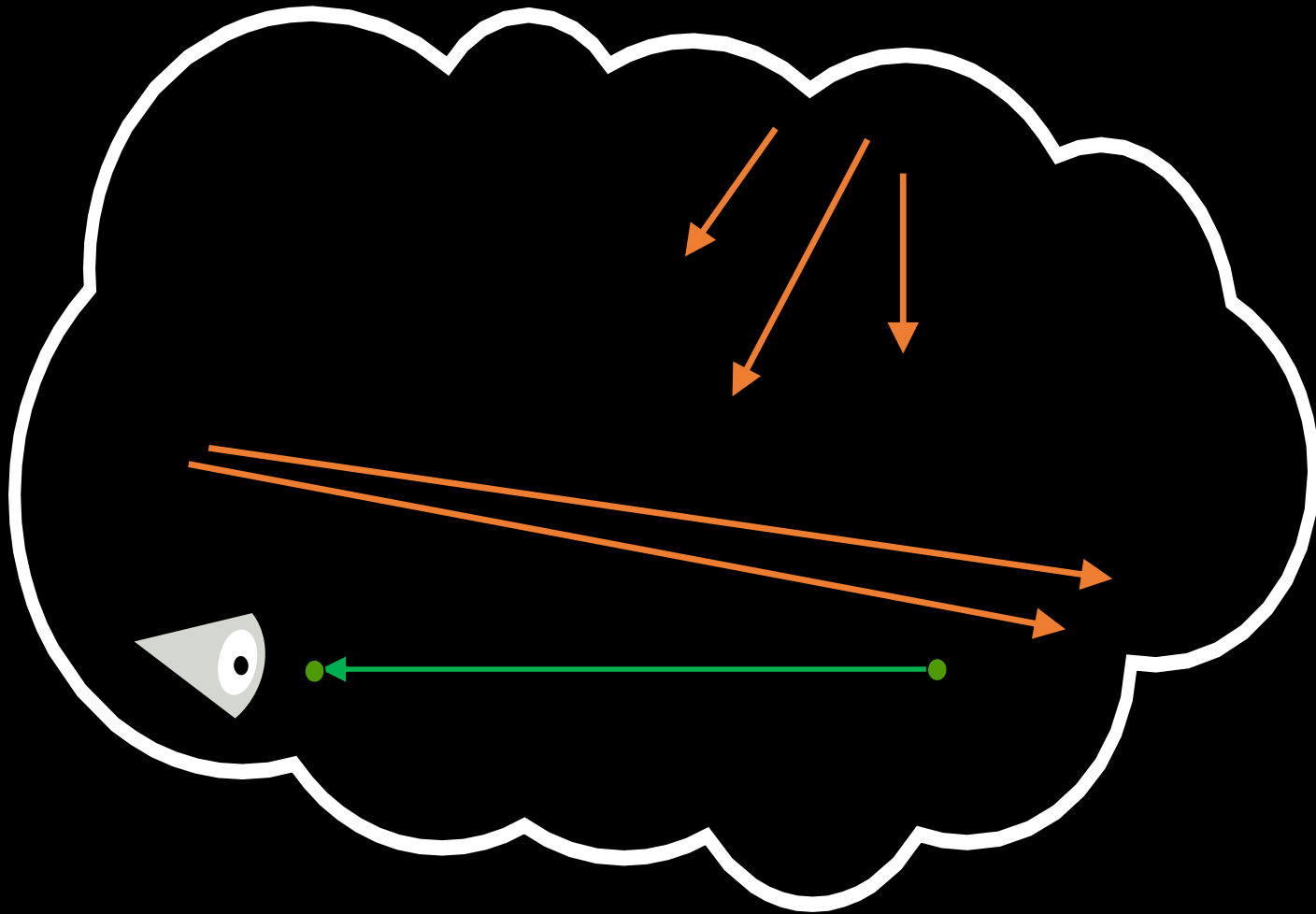
- Unmanageable amount of virtual lights
- Cost linear with lights

Aim:

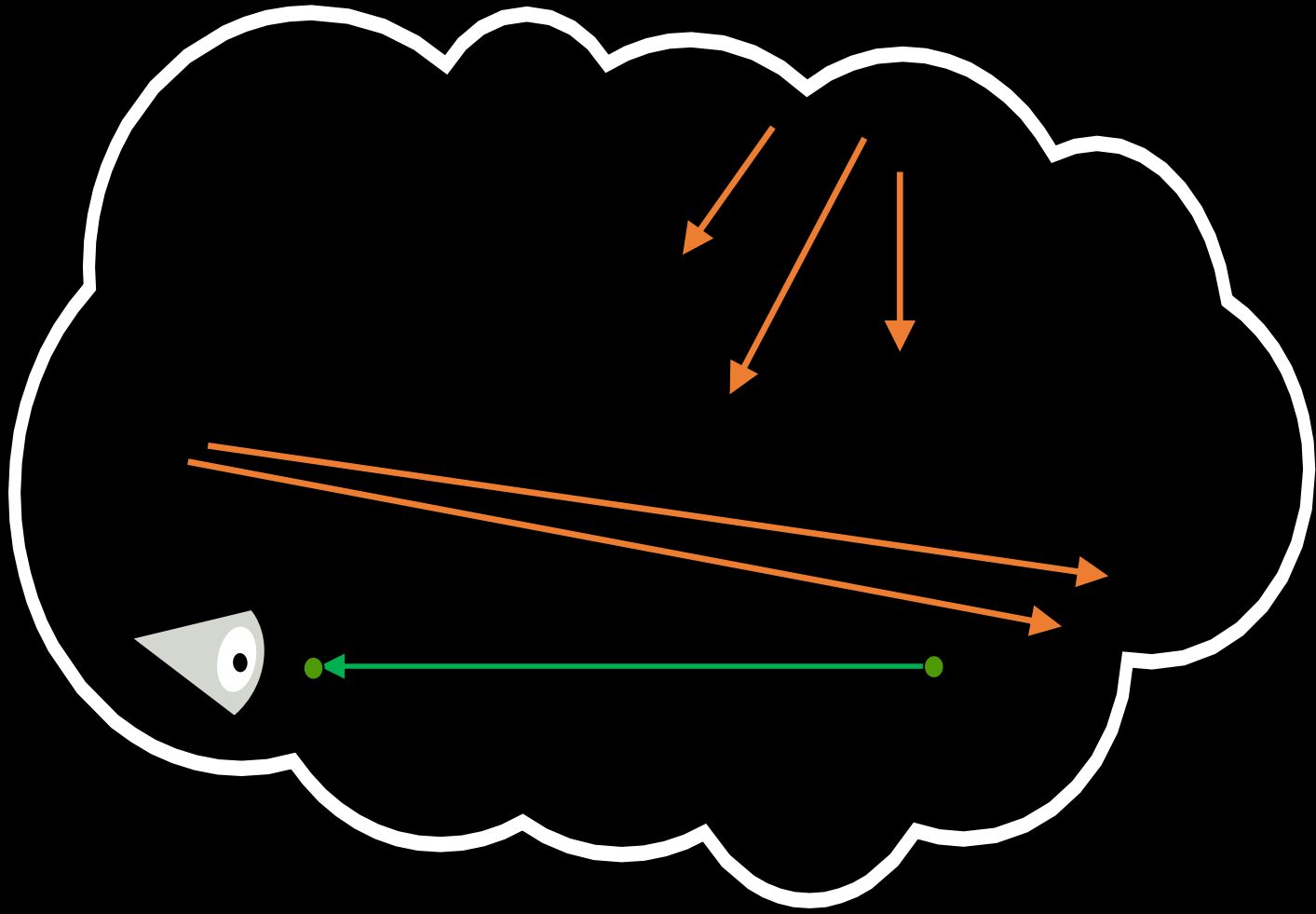
- Sub-linear cost
- Scalable methods

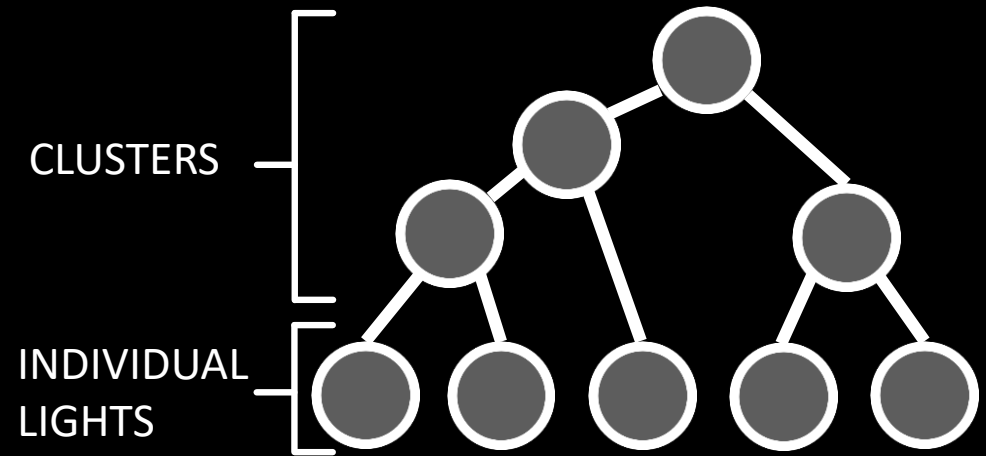
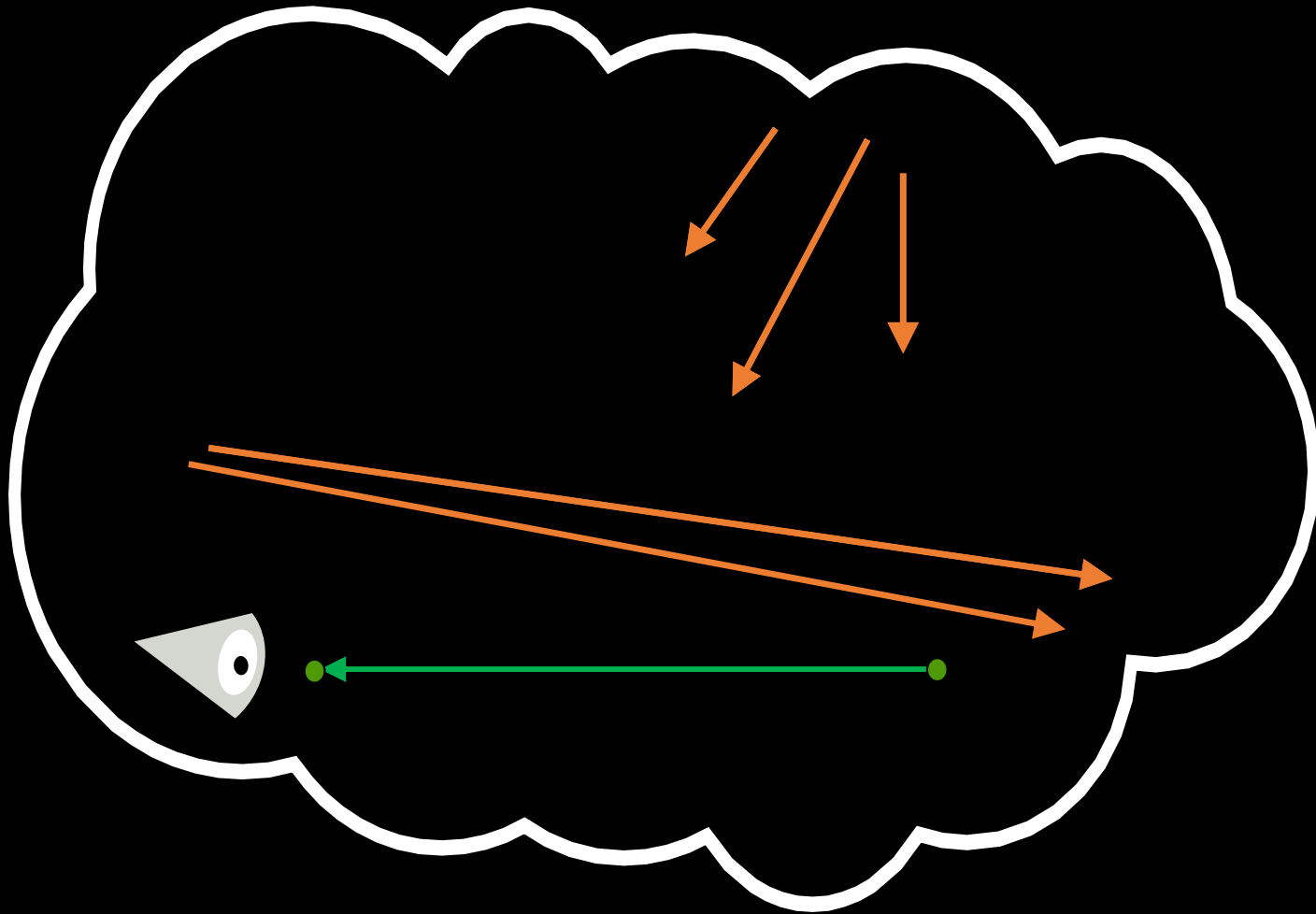
[Walter et al. 2005][Walter et al. 2006][Walter et al. 2012]

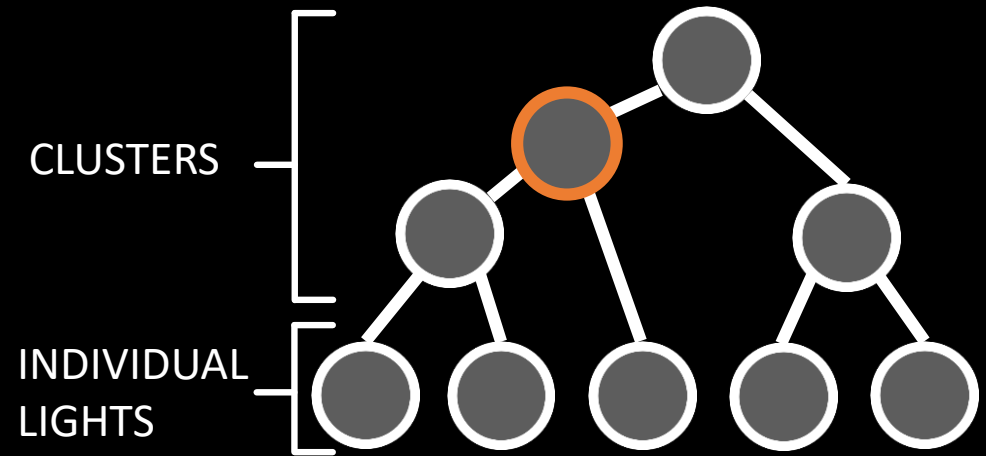
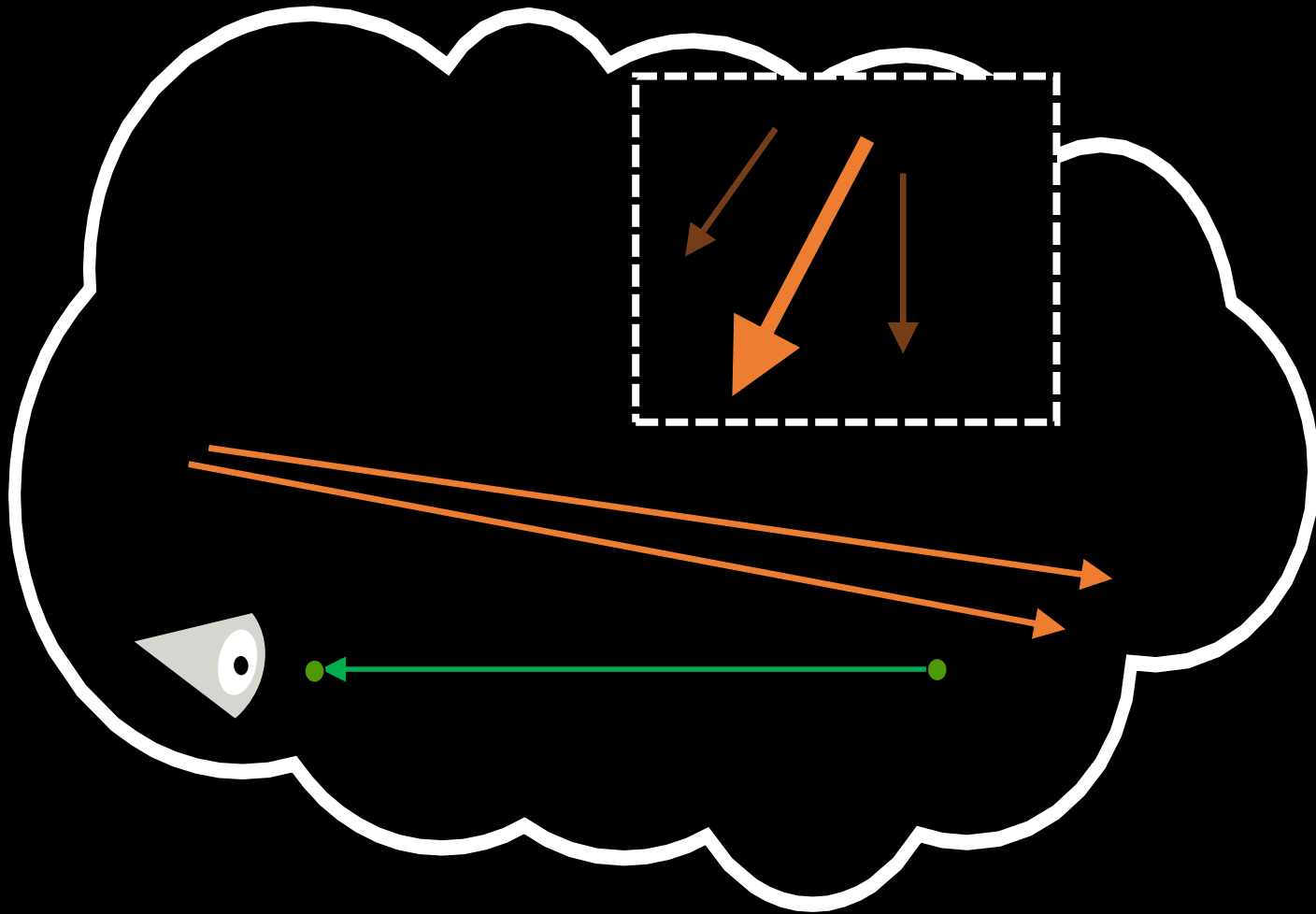
[Hasan et al. 2007][Ou et al. 2011][Bus et al. 2015]



SCALABILITY







Previous works have already explored a combination of VRLs with scalable techniques:

- Adaptive light-slice for virtual ray light [Frederickx et al. 2015]
- Adaptive matrix column sampling and completion for rendering participating media [Huo et al. 2016]

Our solution: Upper bound

$$\frac{VRL(u,v)}{w(u,v)^2 p(u,v)} < B$$

$$B=?$$

Our solution: Upper bound

$$\frac{\Phi f(u,v) T_r(u) T_r(w(u,v))}{w(u,v)^2 p(u,v)} < B$$

$\Phi f(u,v)$: Constant within the VRL cluster

Our solution: Upper bound

$$\frac{\Phi f(u,v) T_r(u) T_r(w(u,v))}{w(u,v)^2 p(u,v)} < B$$

$\Phi f(u,v)$: Constant within the VRL cluster

$T_r(u)$: Impossible to control, assuming worst case $\Rightarrow 1$

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$$\frac{\Phi f(u, v) T_r(u) T_r(w(u, v))}{w(u, v)^2 p(u, v)} < B$$

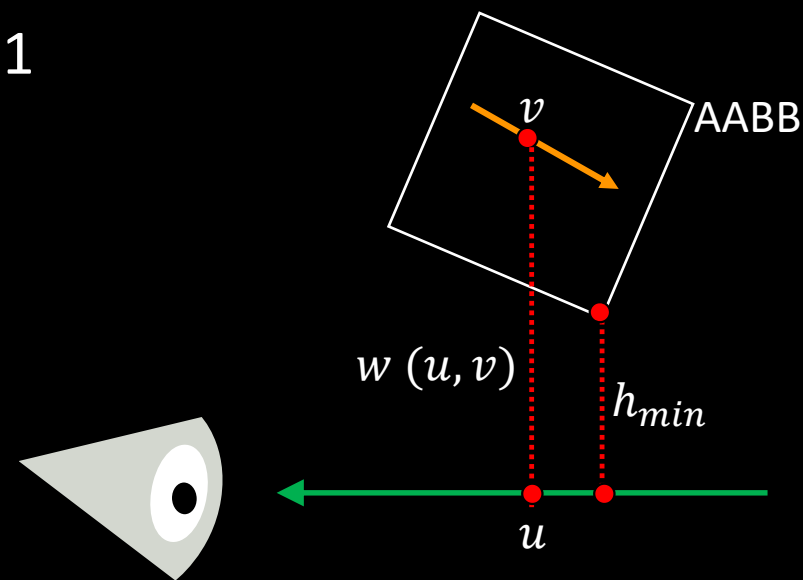
$\Phi f(u, v)$: Constant within the VRL cluster

$T_r(u)$: Impossible to control, assuming worst case $\Rightarrow 1$

$T_r(w(u, v))$: Based on the min distance

$$\Rightarrow h_{min} \leq w_k(u, v)$$

$$\Rightarrow T_r(w(u, v)) < T_r(h_{min})$$



$$\frac{\Phi f(u, v) T_r(u) T_r(w(u, v))}{w(u, v)^2 p(u, v)} < B$$

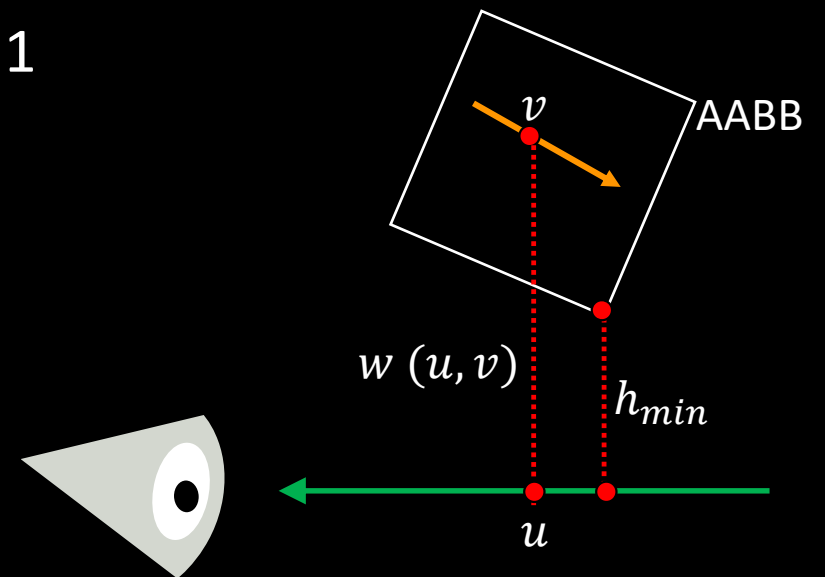
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Our solution: Upper bound

$$\begin{aligned} & w_k(u, v)^2 p(u, v) \\ = & w_k(u, v)^2 p(u|v) p(v) \end{aligned}$$

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Worst case when VRL and sensor ray are parallel.

$p(v) < \frac{1}{L_{max}}$, with L_{max} the maximum length inside the cluster.

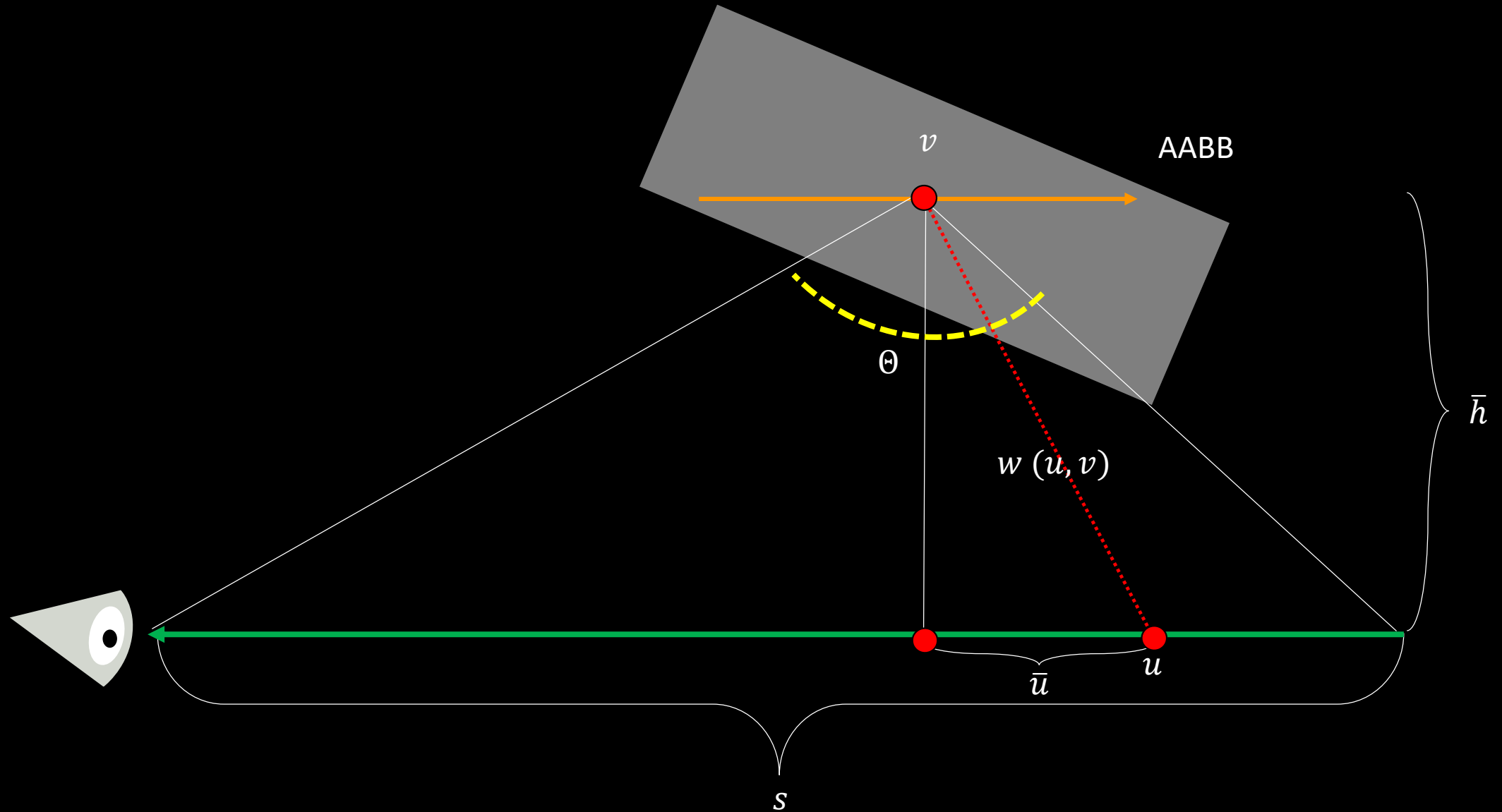
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Worst case when VRL and sensor ray are parallel.

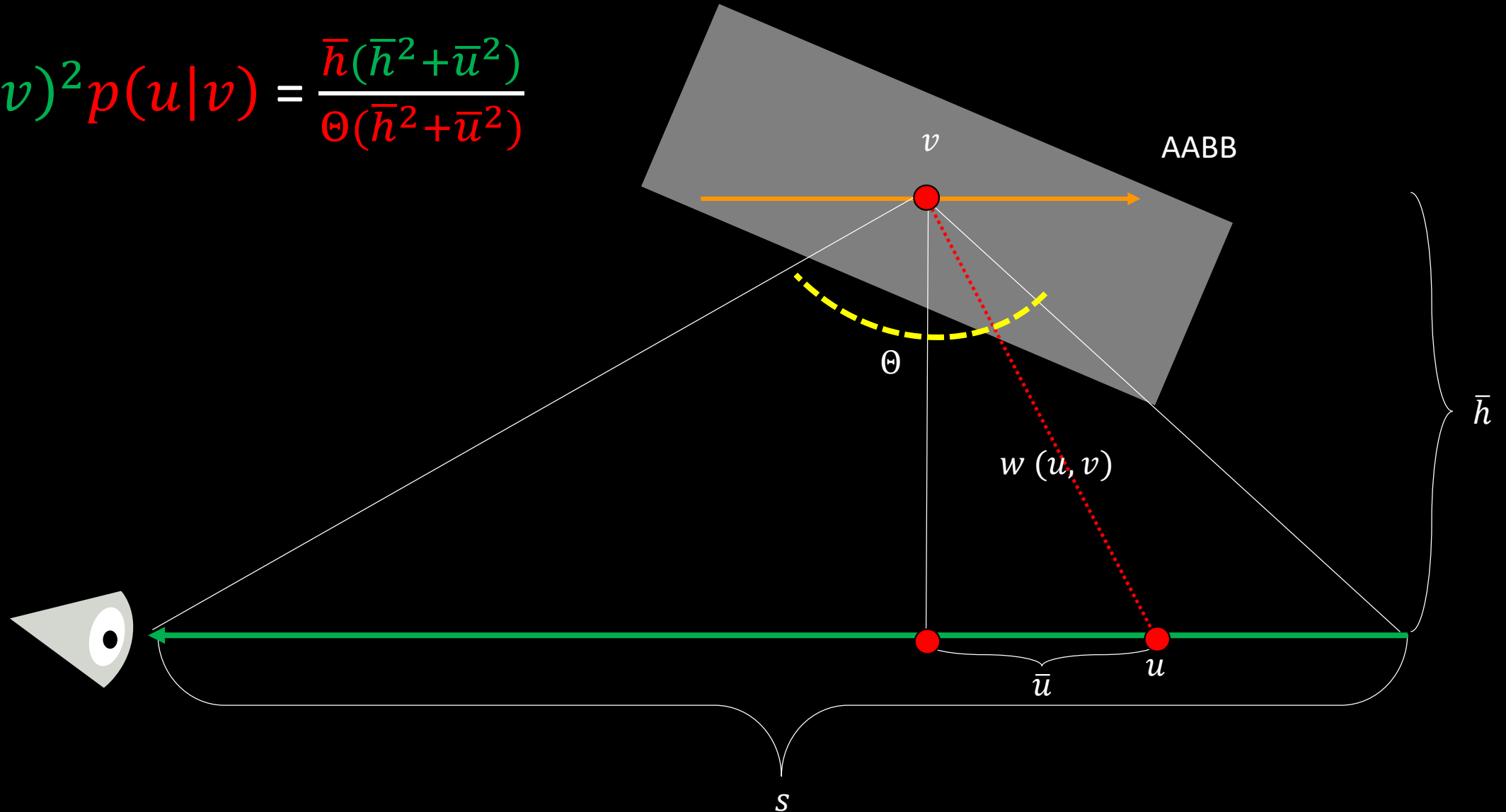
$p(v) < \frac{1}{L_{max}}$, with L_{max} the maximum length inside the cluster.

Our solution: Upper bound



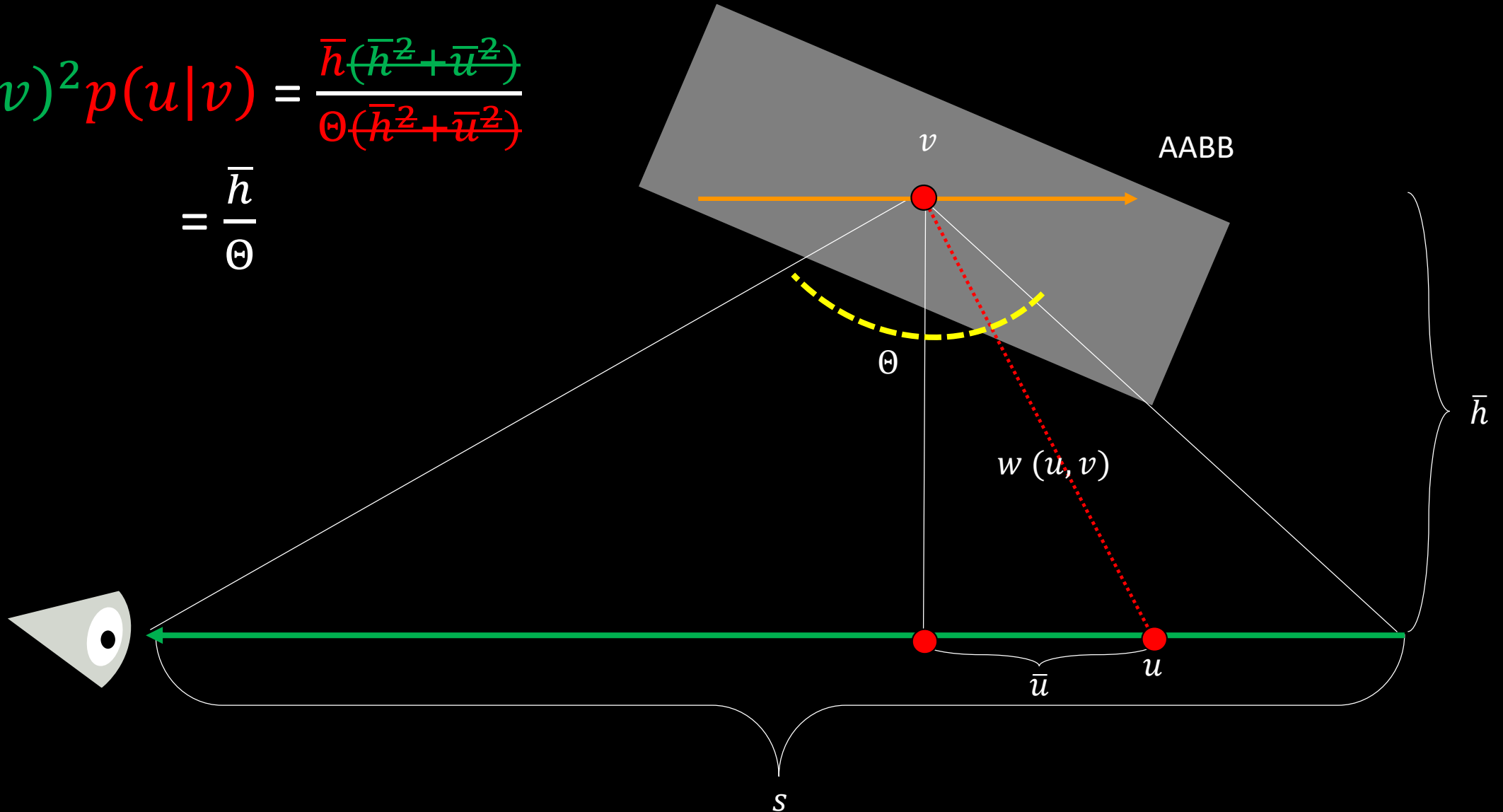
Our solution: Upper bound

$$w(u, v)^2 p(u|v) = \frac{\bar{h}(\bar{h}^2 + \bar{u}^2)}{\Theta(\bar{h}^2 + \bar{u}^2)}$$



Our solution: Upper bound

$$w(u, v)^2 p(u|v) = \frac{\bar{h}(\bar{h}^2 + \bar{u}^2)}{\Theta(\bar{h}^2 + \bar{u}^2)}$$
$$= \frac{\bar{h}}{\Theta}$$

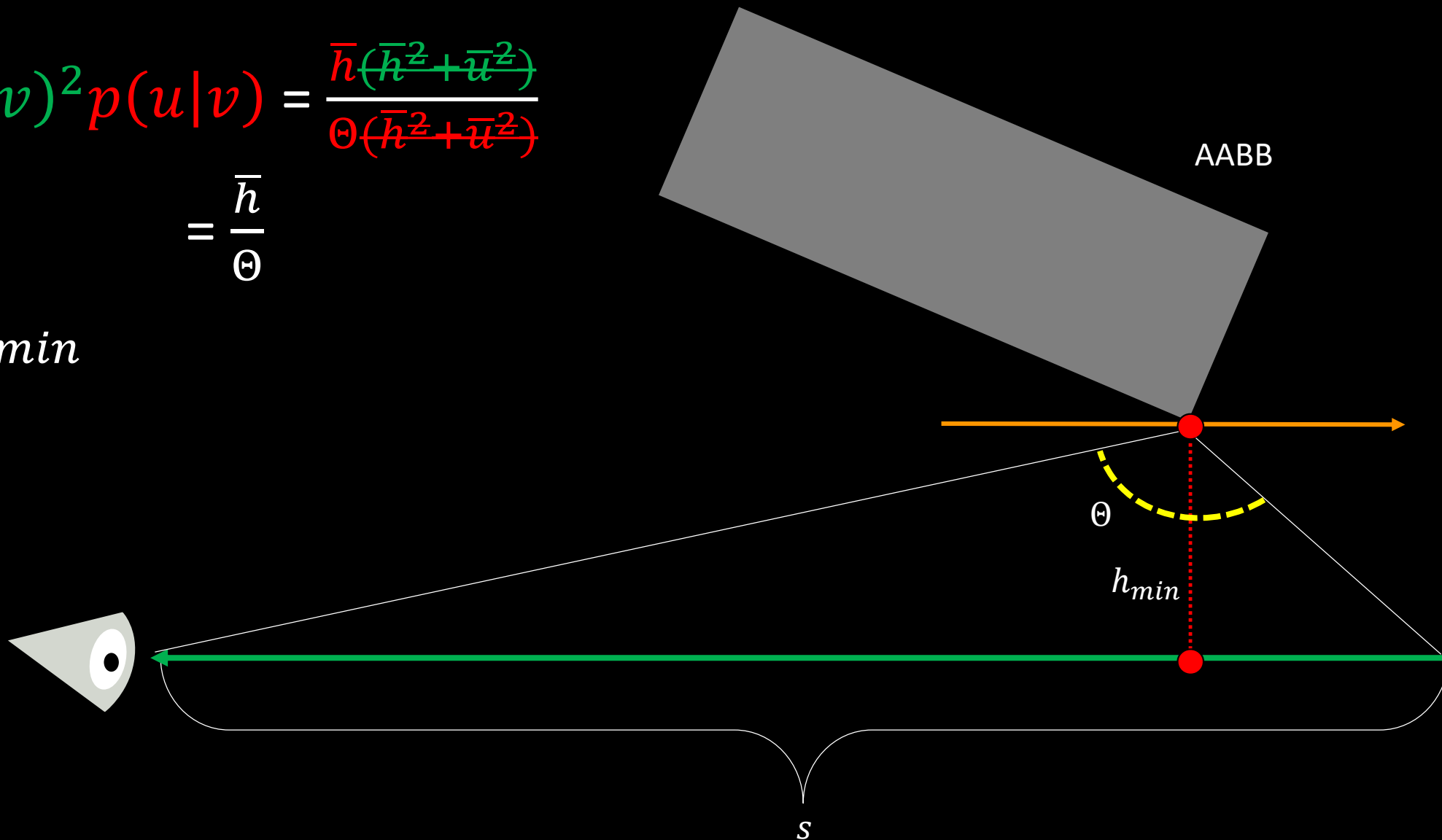


Our solution: Upper bound

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$$= \frac{\bar{h}}{\Theta}$$

$$\bar{h} > h_{min}$$

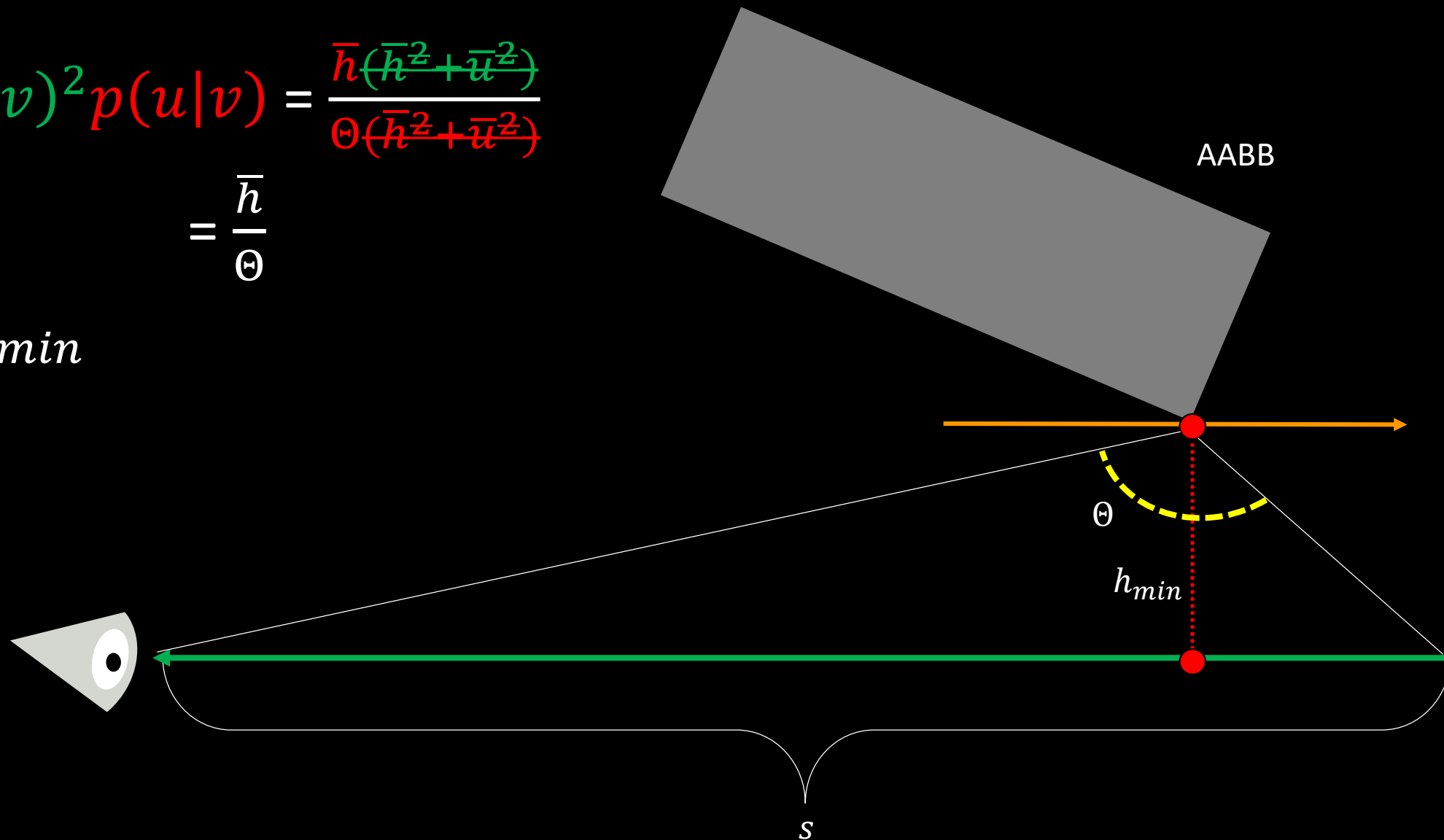


Our solution: Upper bound

$$w(u, v)^2 p(u|v) = \frac{\bar{h}(\bar{h}^2 + \bar{u}^2)}{\Theta(\bar{h}^2 + \bar{u}^2)}$$

$$= \frac{\bar{h}}{\Theta}$$

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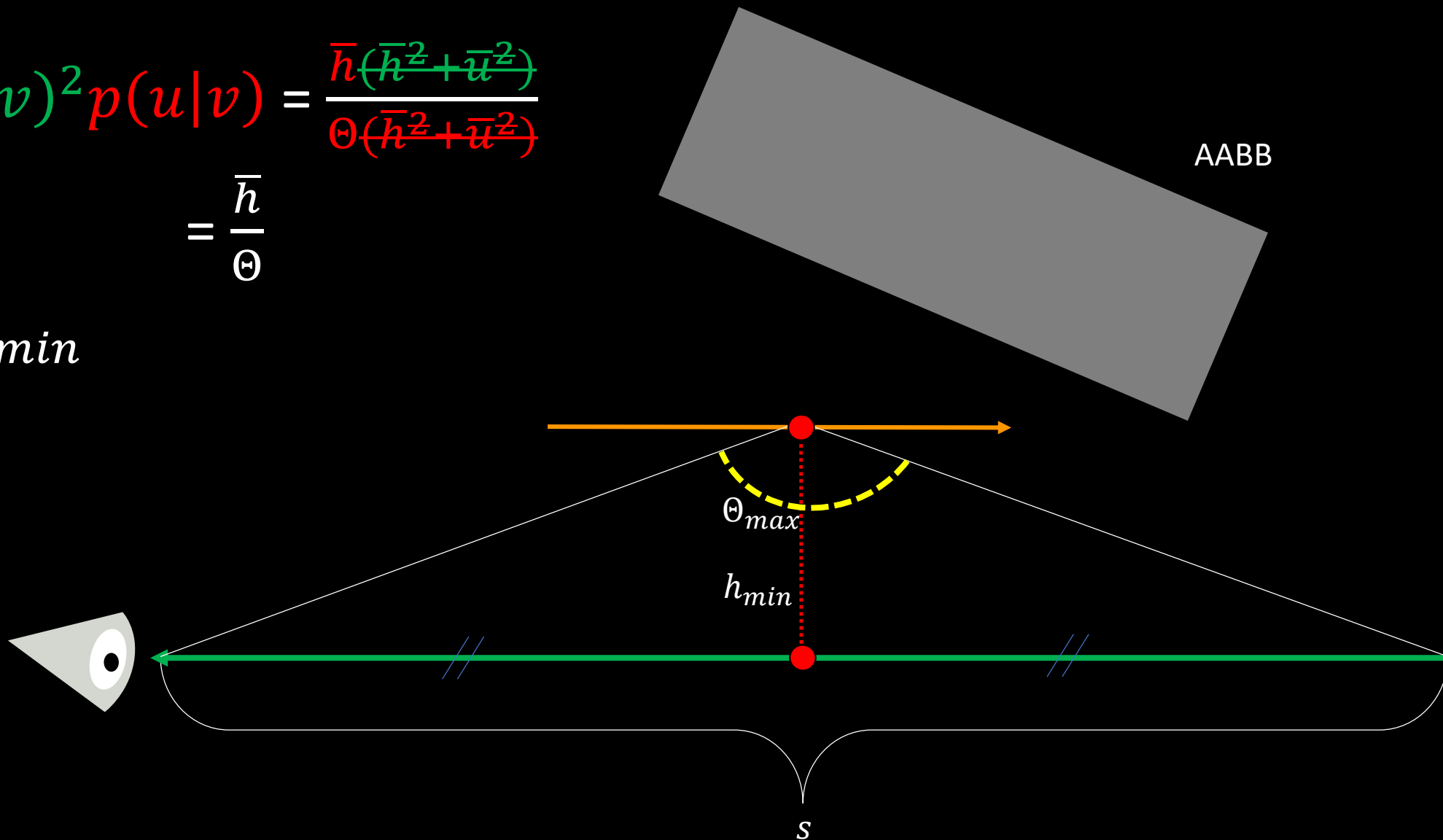


Our solution: Upper bound

$$w(u, v)^2 p(u|v) = \frac{\bar{h}(\bar{h}^2 + \bar{u}^2)}{\Theta(\bar{h}^2 + \bar{u}^2)}$$

$$= \frac{\bar{h}}{\Theta}$$

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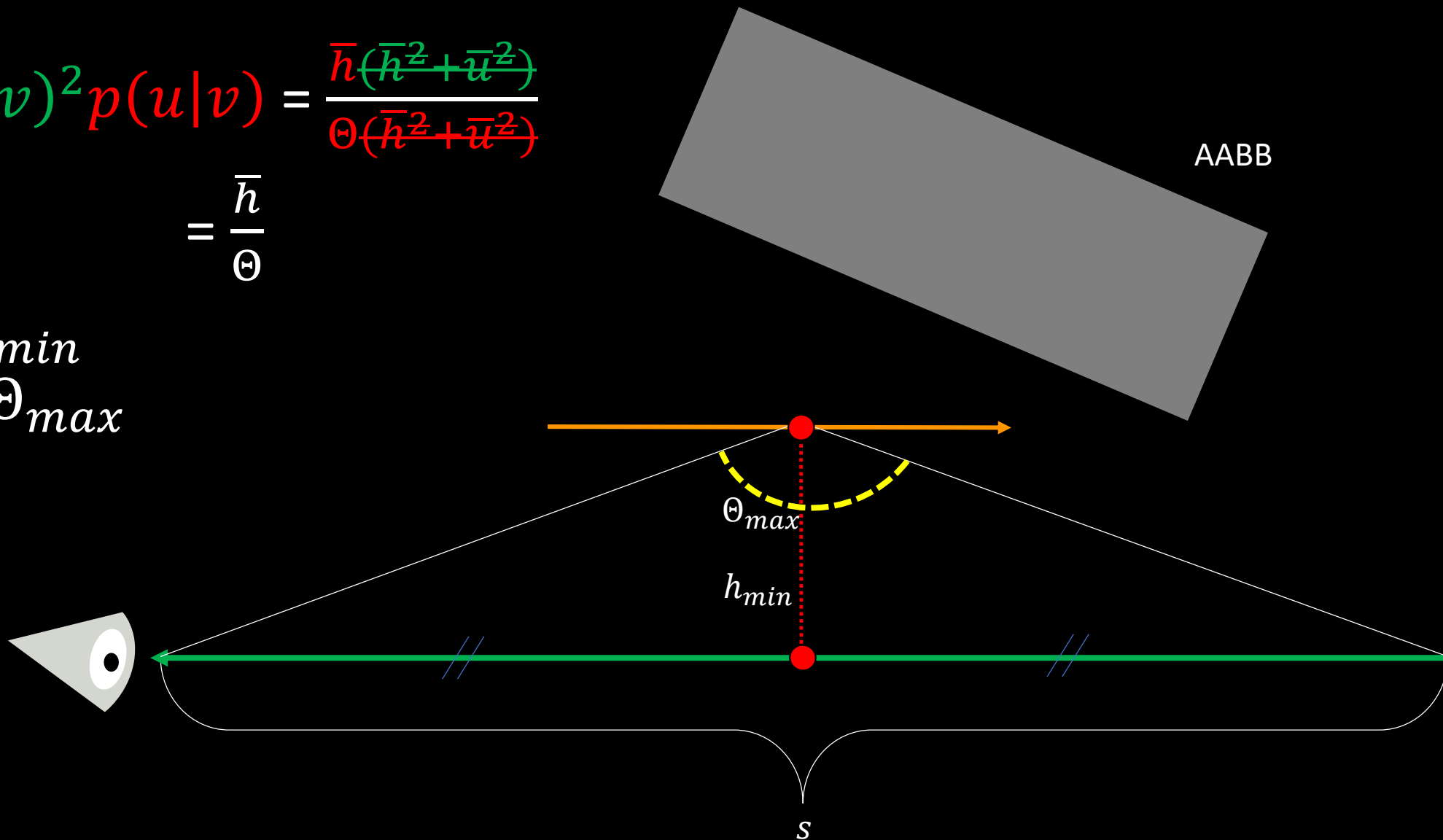
Our solution: Upper bound

$$w(u, v)^2 p(u|v) = \frac{\bar{h}(\bar{h}^2 + \bar{u}^2)}{\Theta(\bar{h}^2 + \bar{u}^2)}$$

$$= \frac{\bar{h}}{\Theta}$$

$$\bar{h} > h_{min}$$

$$\Theta < \Theta_{max}$$



$$B = \frac{\Phi f(u, v) T_r(h_{\min}) \Theta_{\max} L_{\max}}{h_{\min}}$$

Our solution: Light tree

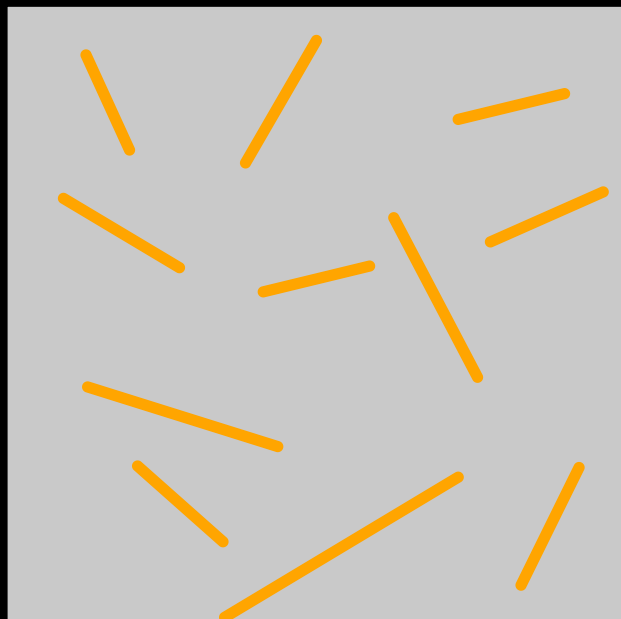
Agglomerative approach [Walter et al. 2008]:

- Not multithreaded
- Does not scale with high node overlapping $O(N^2)$

What we need:

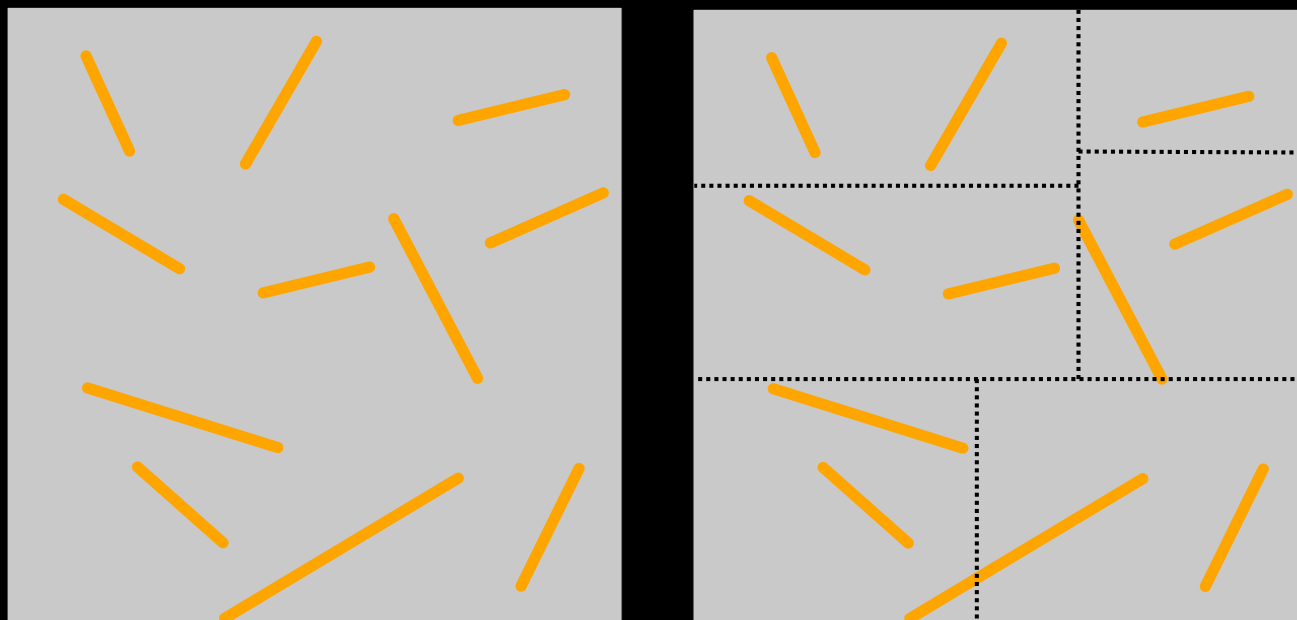
- Fast/Parallelizable
- Agglomerative principal

Our solution: Light tree



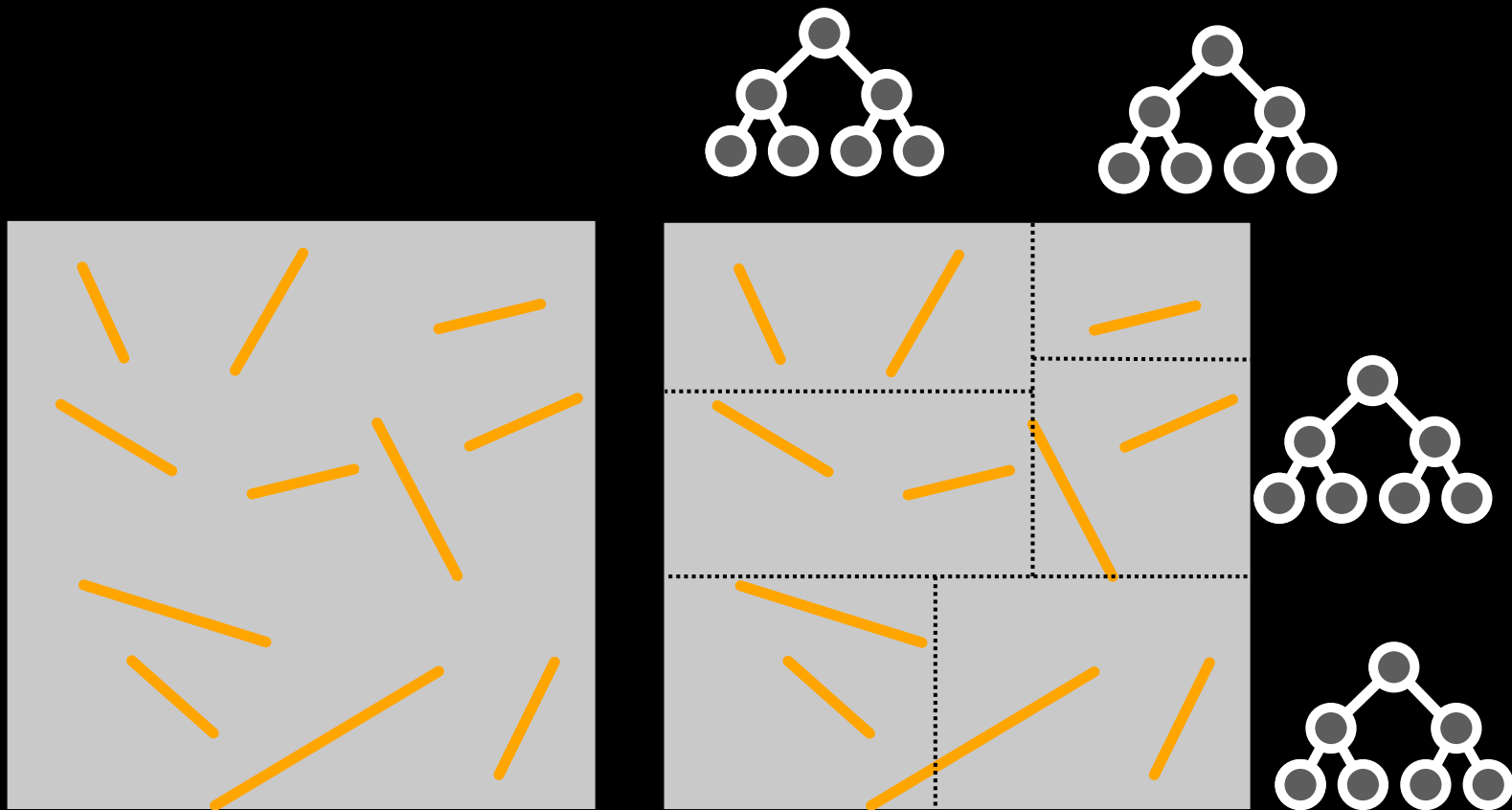
Our solution: Light tree

Step 1: Partition the space with sorting



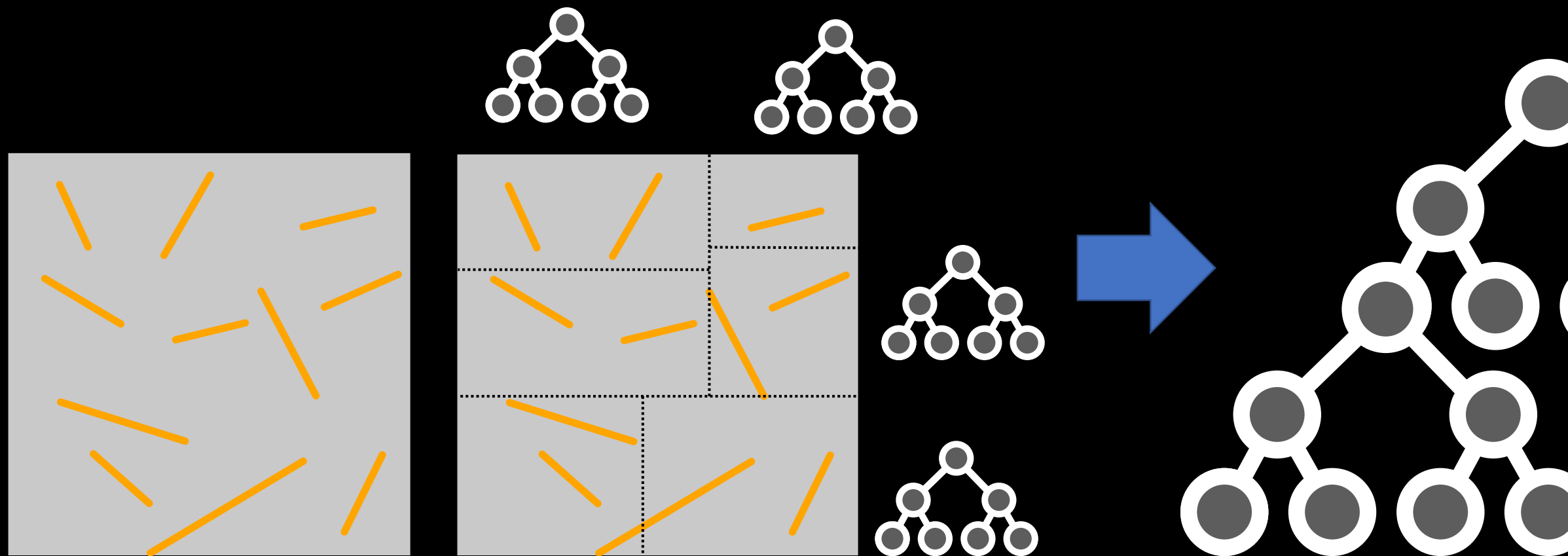
Our solution: Light tree

Step 2: Build local light tree that minimize the metric







Our solution: Light tree

Step 3: Build final tree with agglomerative process



- Equal time comparison
 - VPL with LC
 - VRL
- Two metrics
 - RMSE: sensitive to fireflies
 - SMAPE: robust to fireflies
- Isotropic medium, only medium-medium interactions

Results

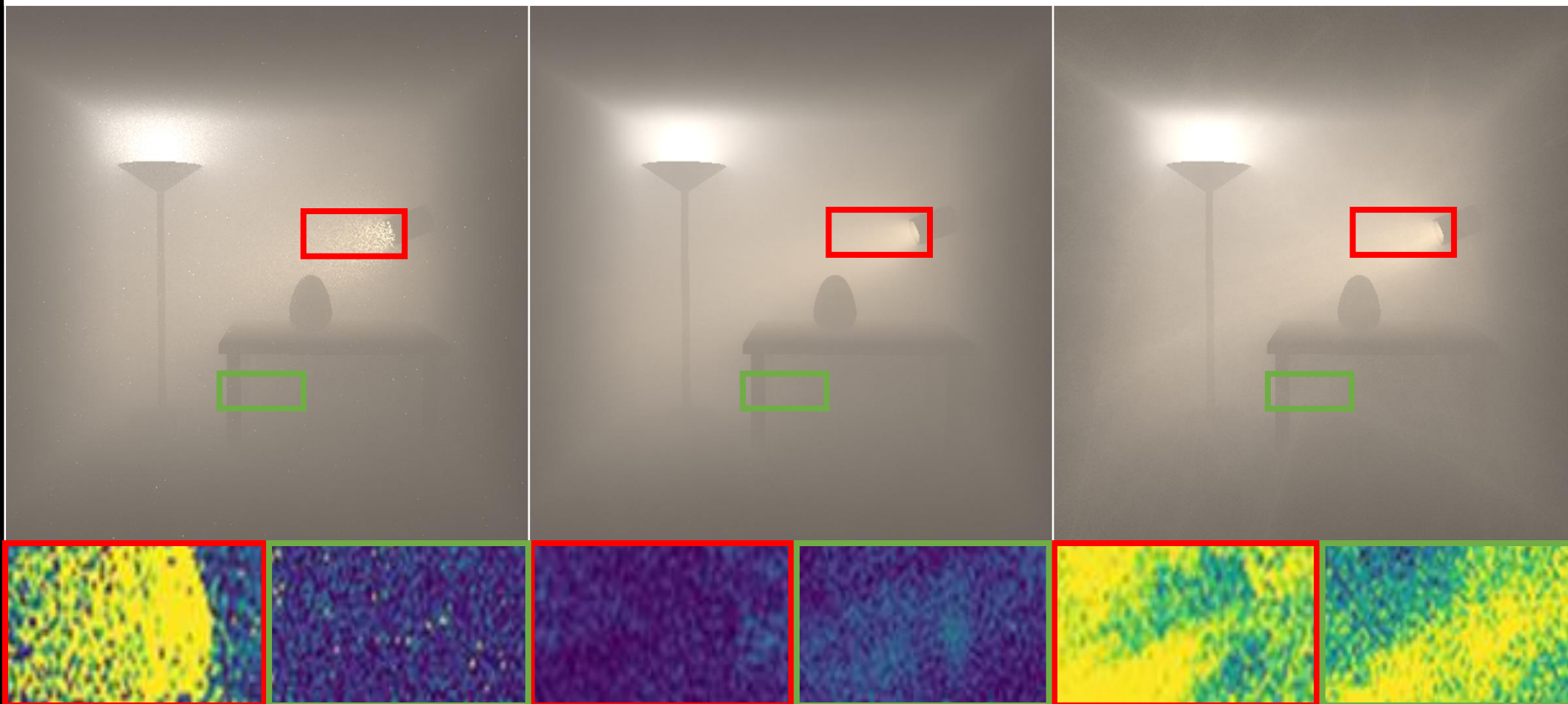
Reference	VPL LC (1M) 344 secs RMSE: 9.01 SMAPE: 3.25	VRL LC (100k) 370 secs RMSE: 2.70 SMAPE: 4.31	VRL (10k) 323 secs RMSE: 5.46 SMAPE: 9.93
			

Results

VPL LC (1M) - 147 secs
RMSE: 0.33
SMAPE: 2.44

VRL LC (100k) - 121 secs
RMSE: 0.01
SMAPE 1.88

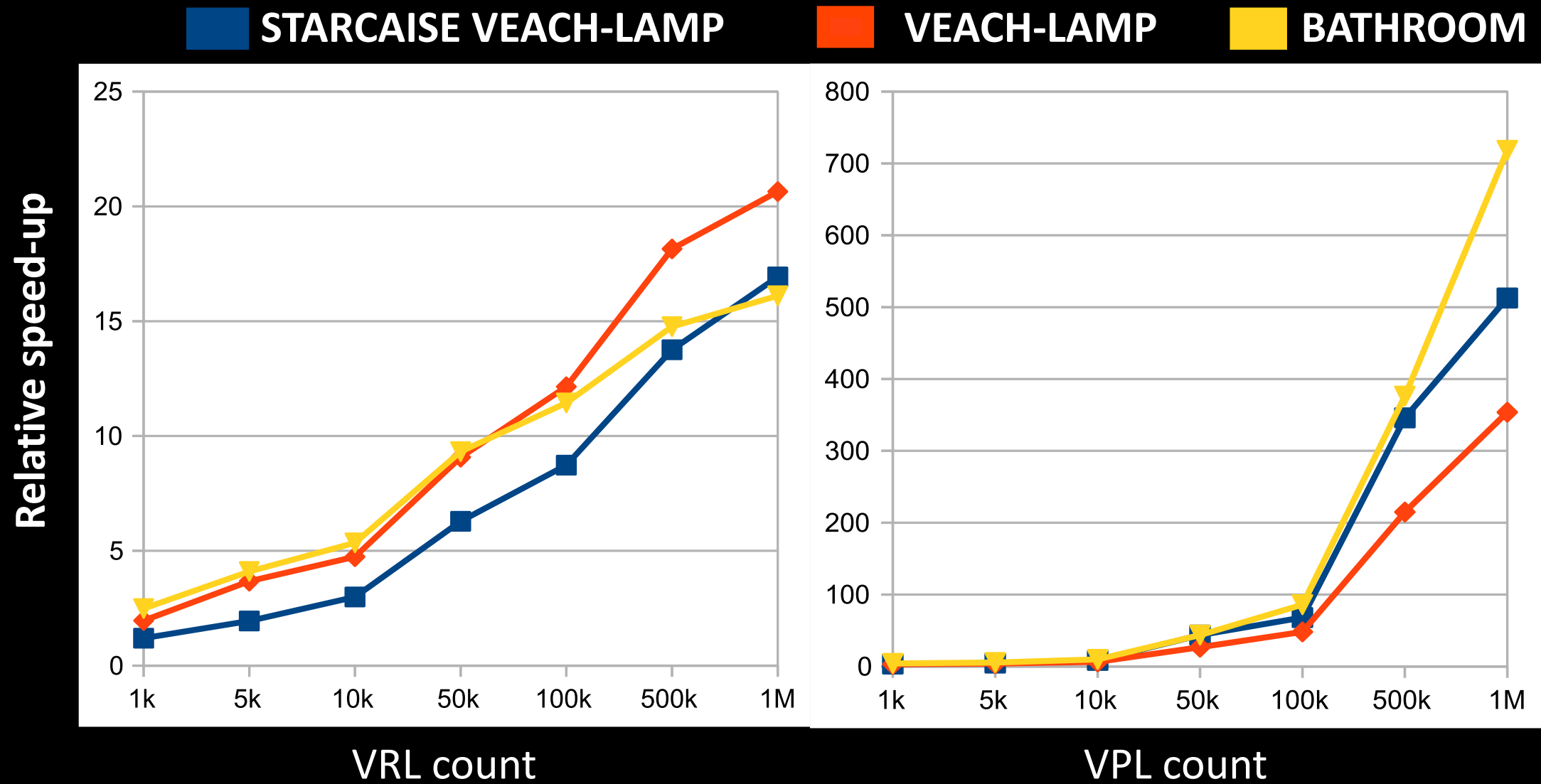
VRL (10k) - 147 secs
RMSE: 0.05
SMAPE 9.11



> 0.05

SMAPE

0.0



Contributions:

- New bound for VRL cluster
- Efficient tree construction
- X10 Speedup

Questions ?