

State of the Art in Photon Density Estimation

Photon Mapping Basics

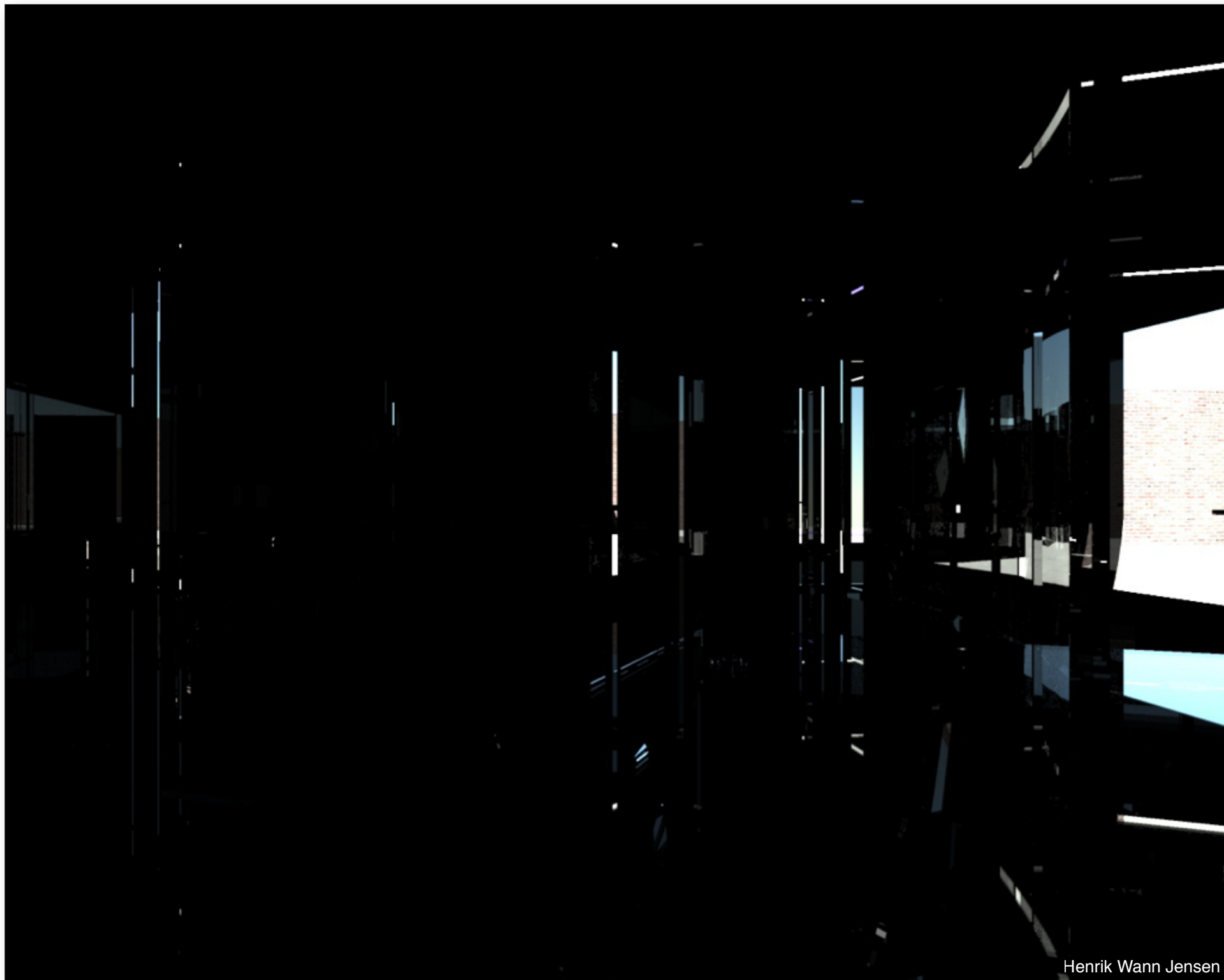
Wojciech Jarosz

Motivation - Global Illumination



Henrik Wann Jensen

Motivation - Direct Illumination



Henrik Wann Jensen

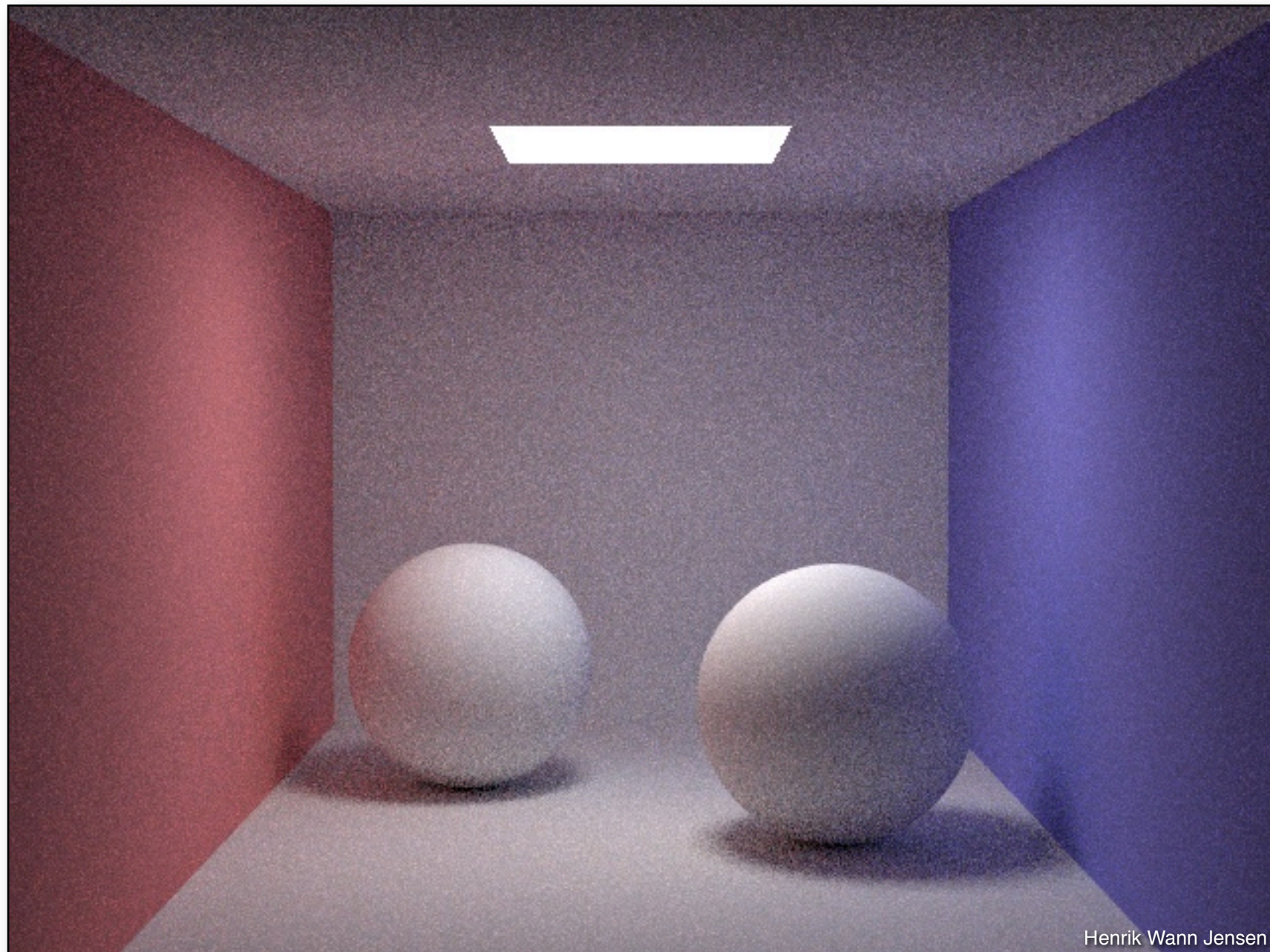
► Radiosity

- ✗ Mostly diffuse
- ✗ Mesh based lighting representation

► Monte Carlo path tracing

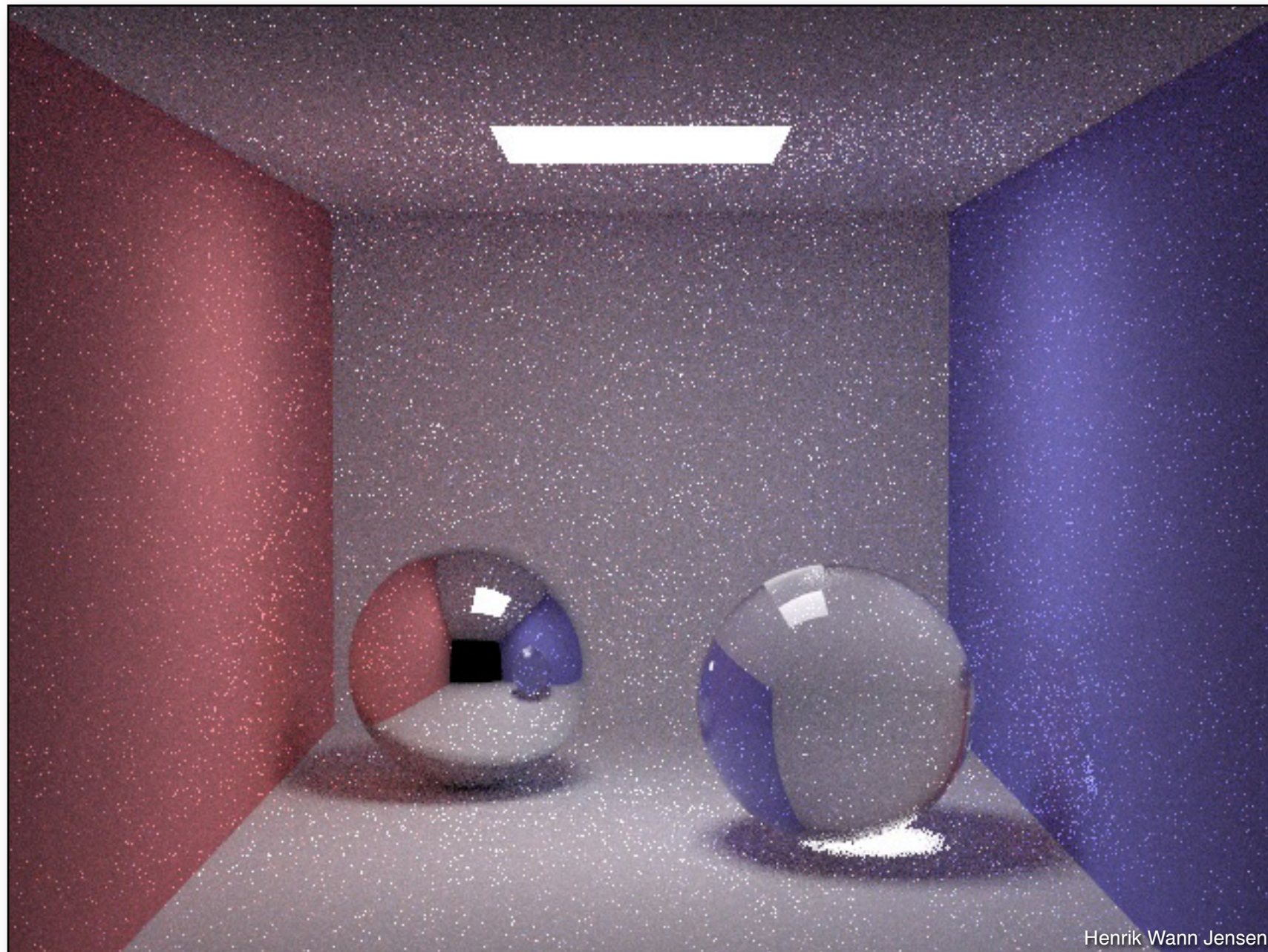
- ✓ Very general
- ✗ Noisy
- ✗ Computation time/slow convergence

Path Tracing



10 paths/pixel

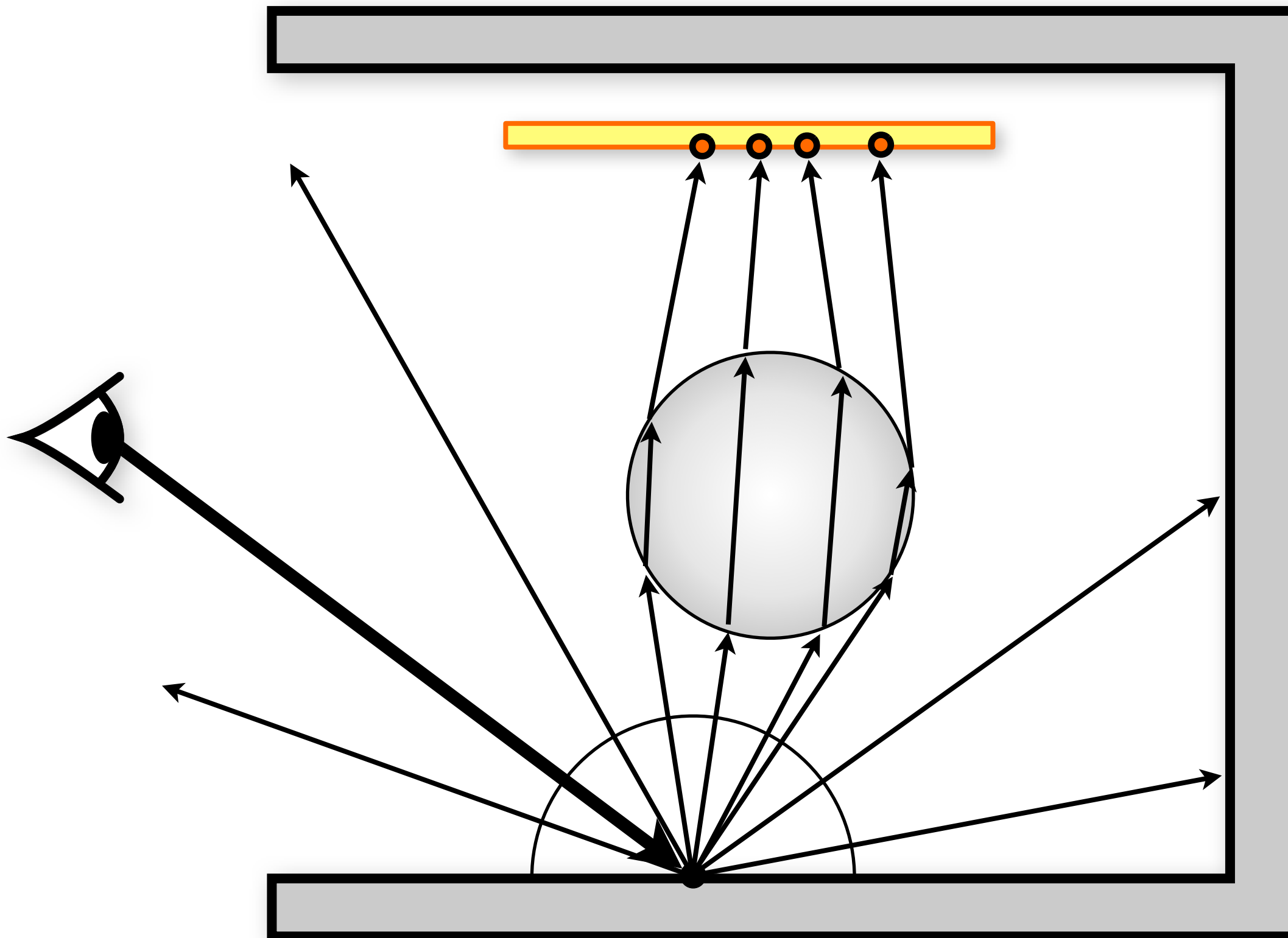
Path Tracing Caustics



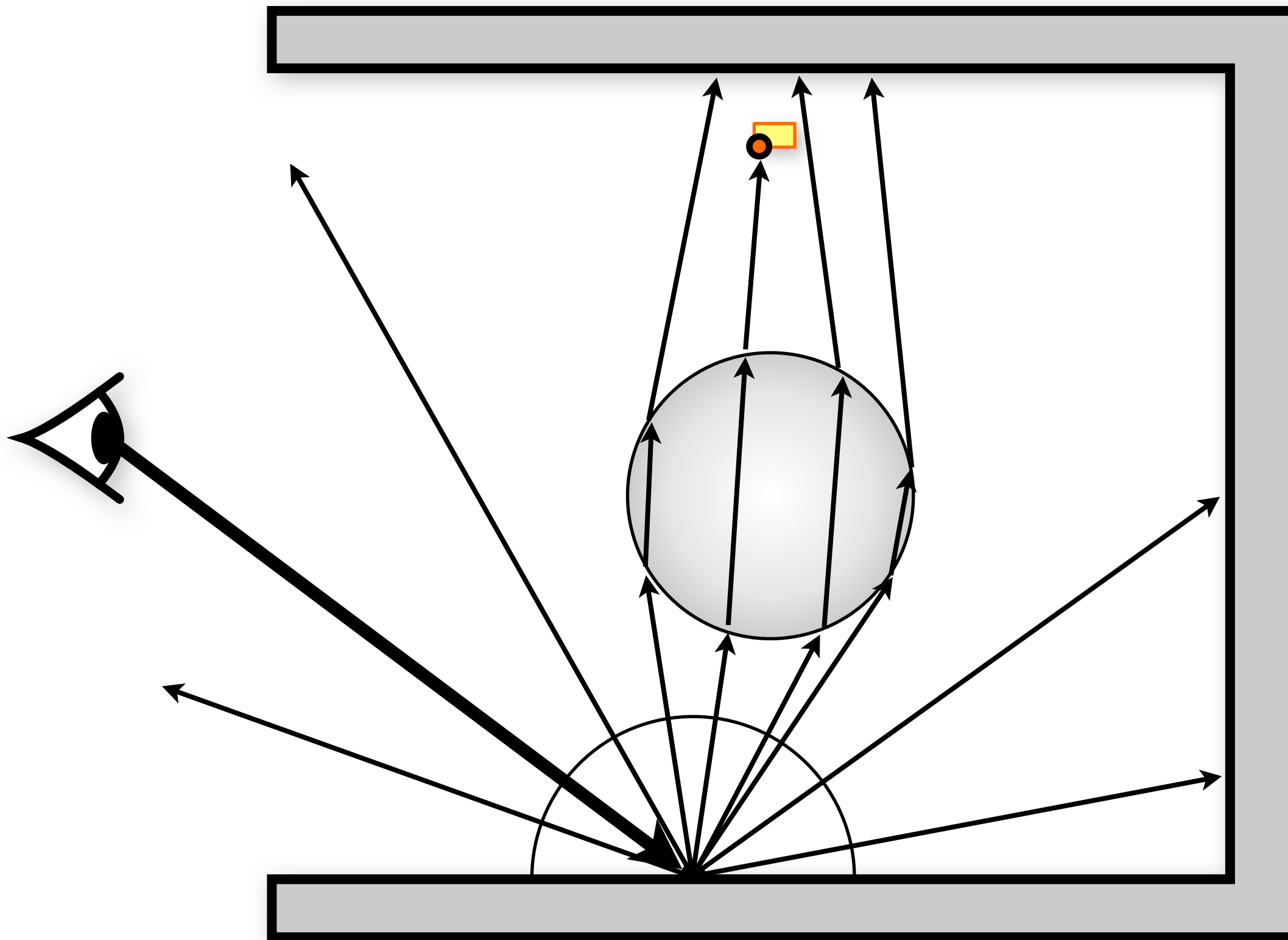
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10 paths/pixel

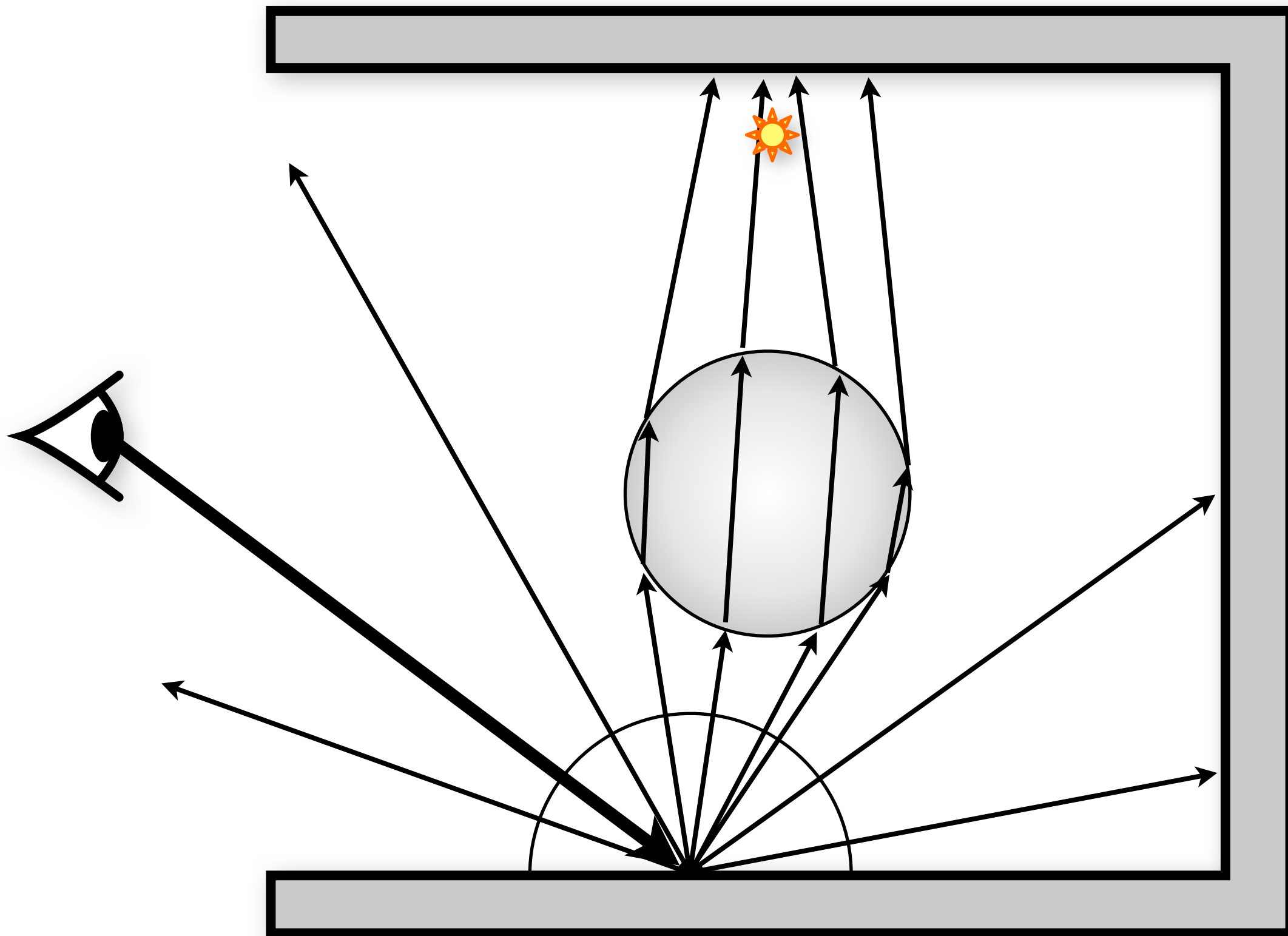
Path Tracing Caustics



Path Tracing Caustics



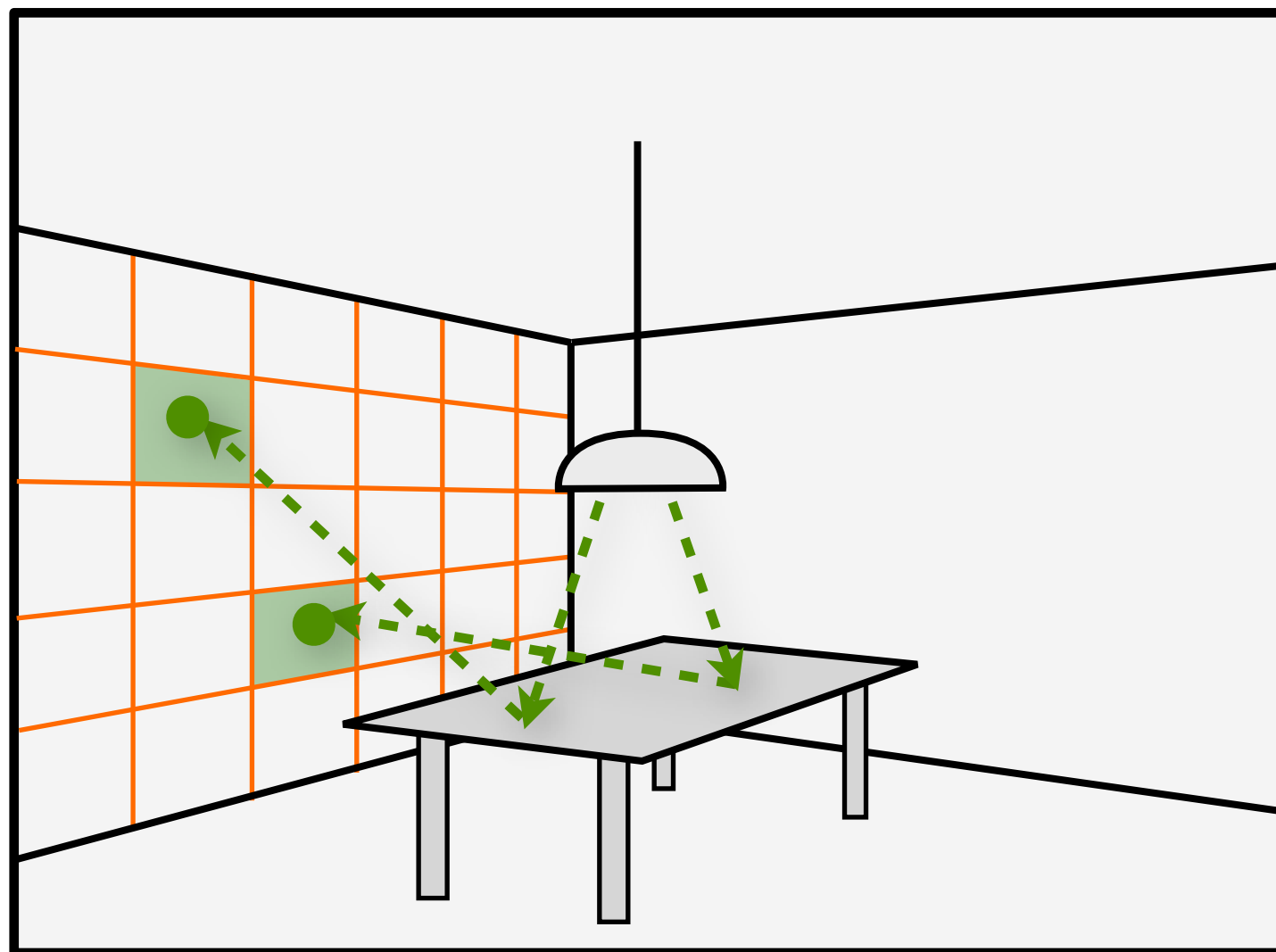
Path Tracing Caustics



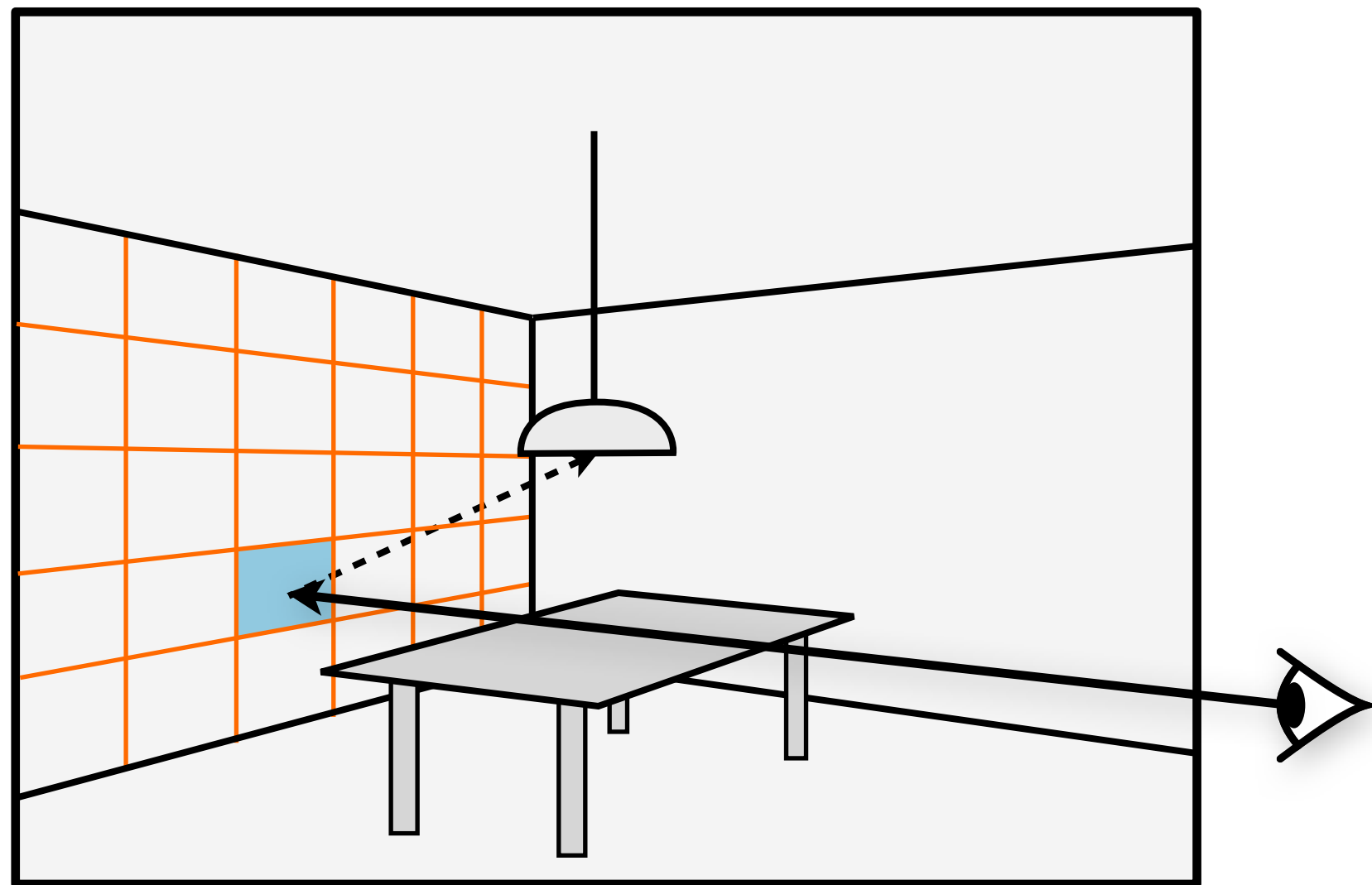
- ▶ Light tracing / “Backward ray tracing”
- ▶ James Arvo. In *Developments in Ray Tracing*, SIGGRAPH ‘86 Course Notes

► Preprocess:

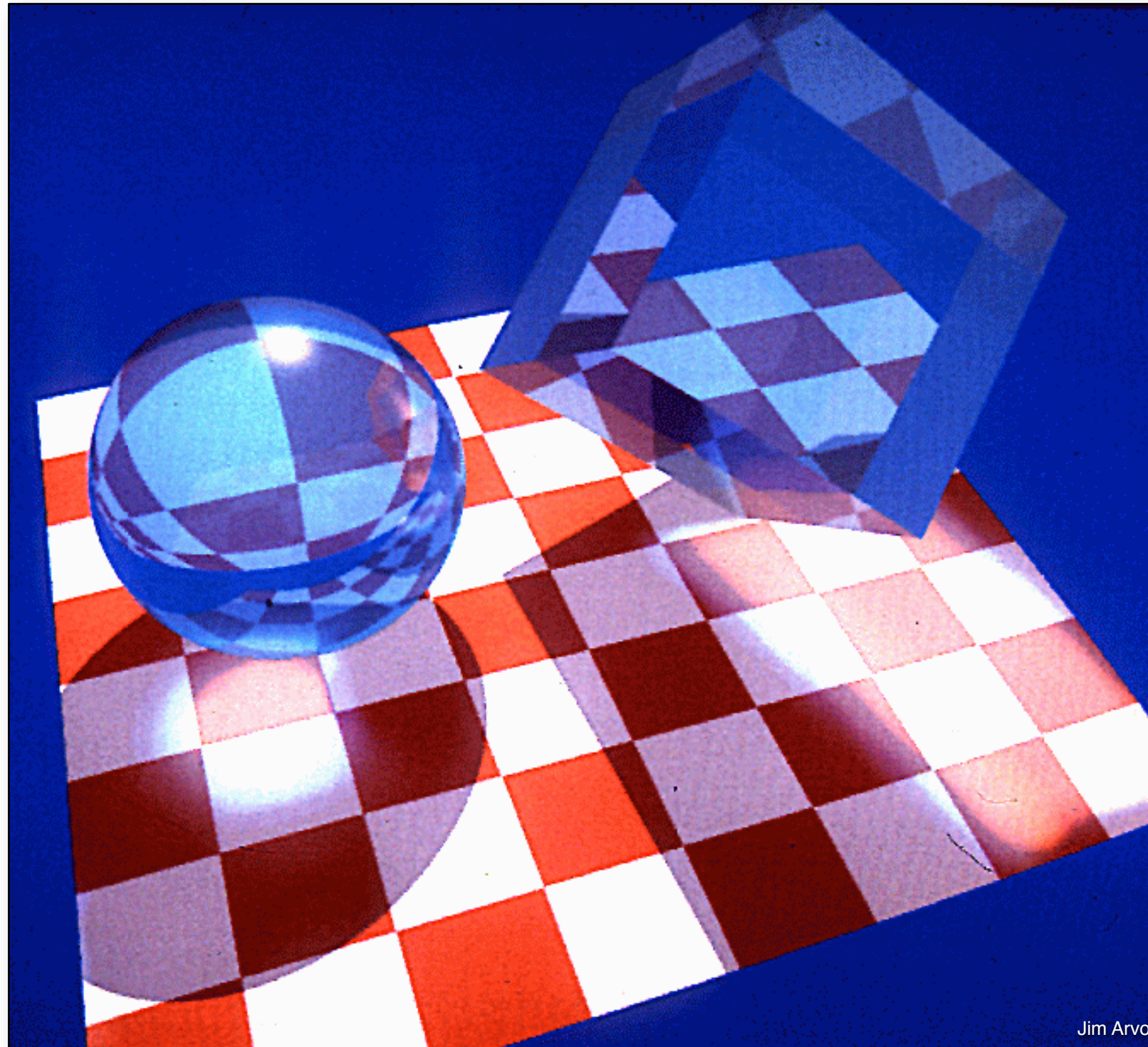
- parametrize surfaces and create “illumination maps”
- shoot light from light sources
- deposit photon energy in illumination maps



- ▶ For each shading point
 - ▶ compute direct lighting
 - ▶ lookup indirect lighting + caustics from illumination maps



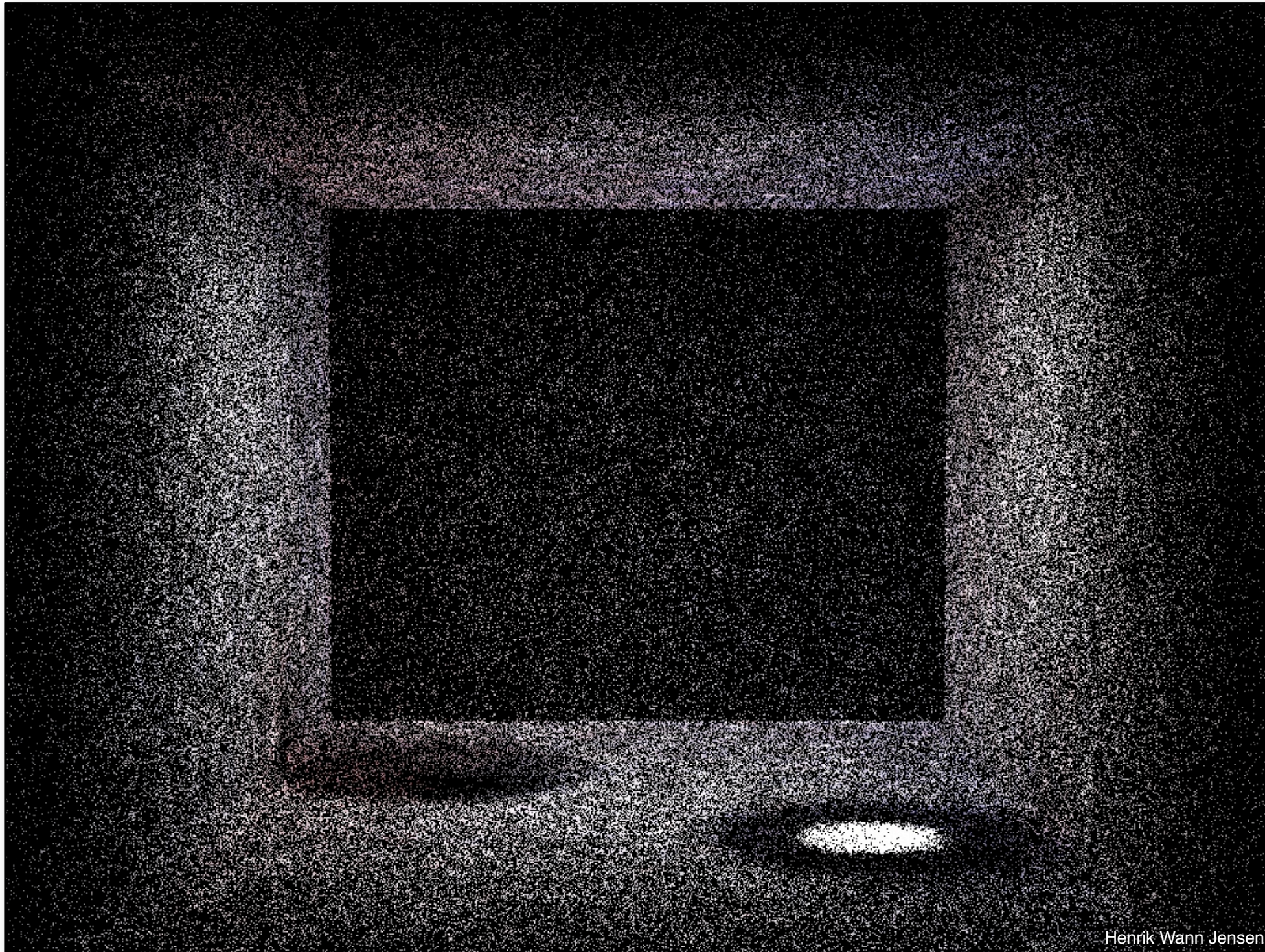
Light Tracing



- ✓ One of first techniques to simulate caustics
- ✗ Requires parametrizing surface or meshing
 - Complex/procedural geometry difficult to handle
- ✗ Illumination map resolution difficult to choose
 - high resolution/few photons: high-frequency noise
 - low resolution/many photons: blurred illumination

- ▶ A two-pass algorithm:
 - ▶ Pass 1: Trace virtual photons from the light source, scatter at surfaces, and cache
 - ▶ Pass 2: Ray trace the scene and use the photons to compute indirect illumination
- ▶ Same as light tracing, but different way of storing/caching photons

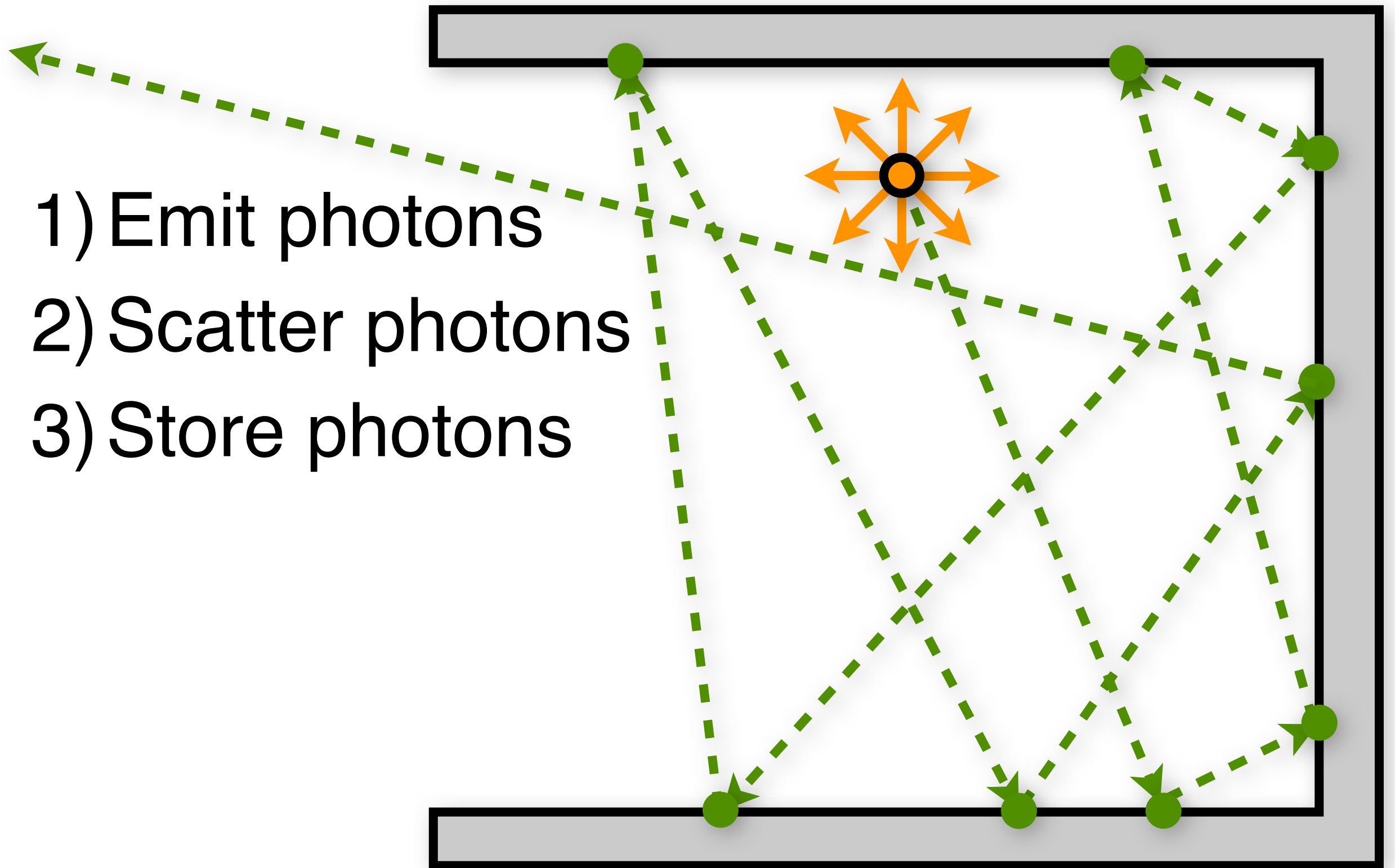
The Photon Map



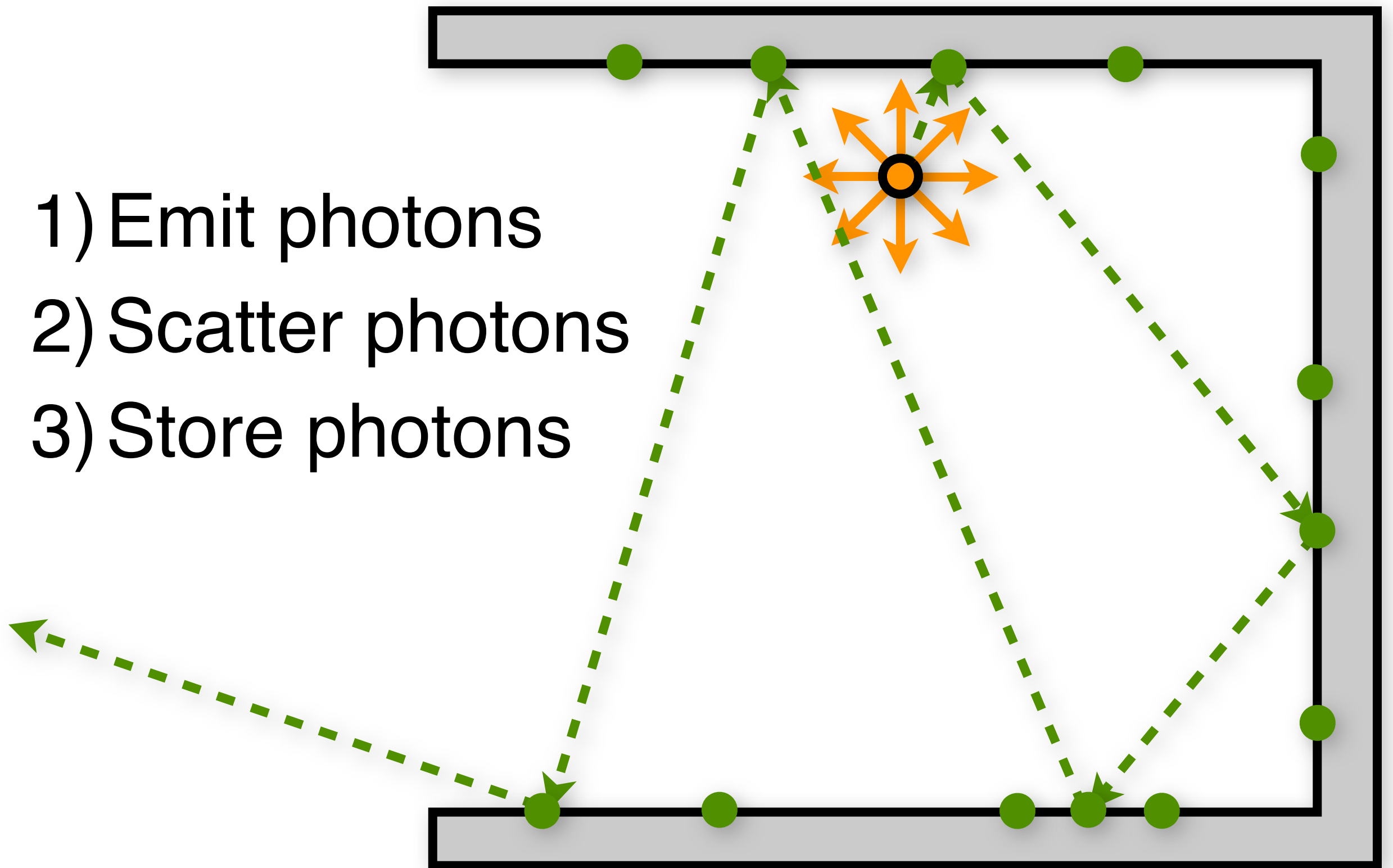
Henrik Wann Jensen



- 1) Emit photons
- 2) Scatter photons
- 3) Store photons

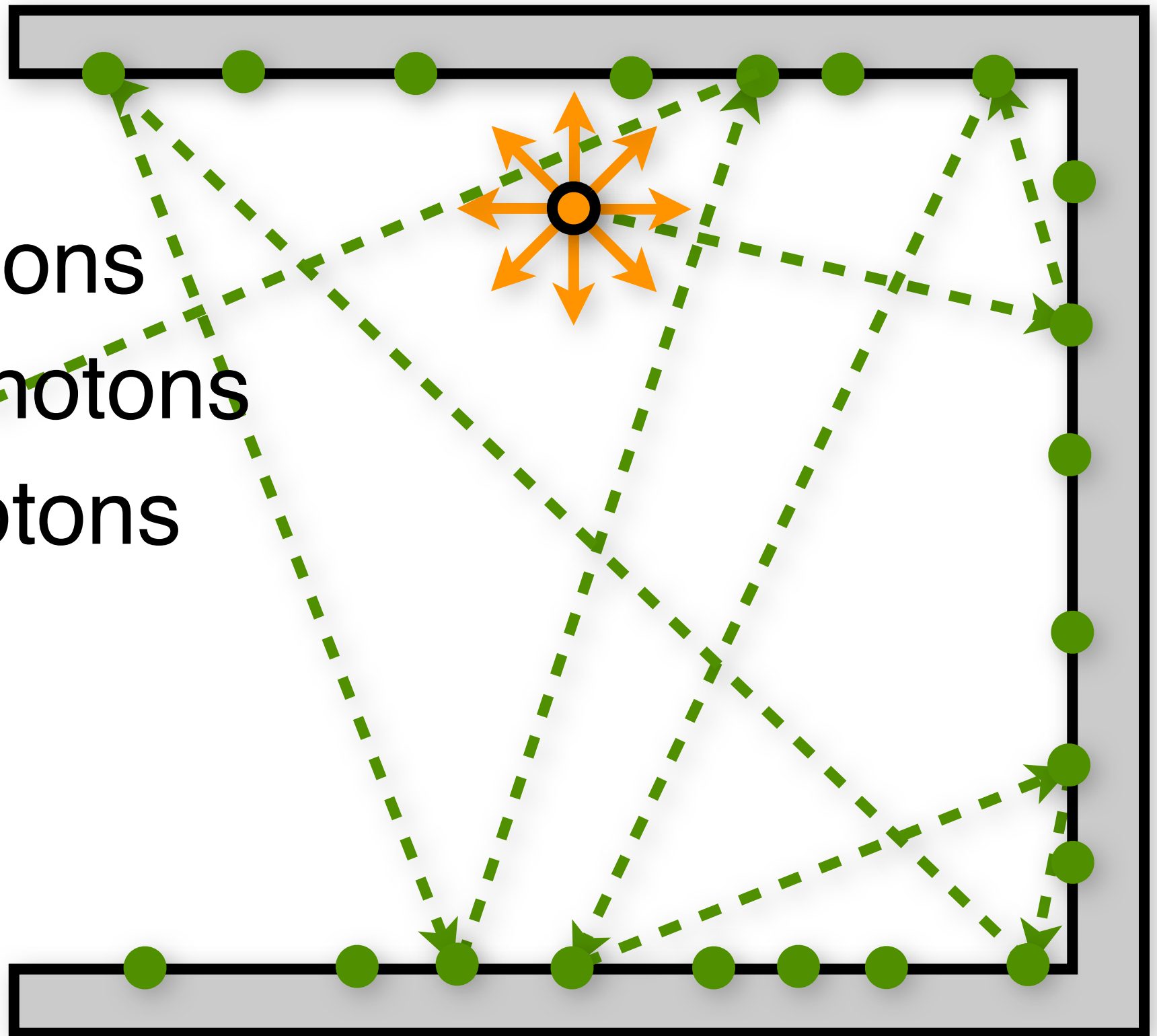


- 1) Emit photons
- 2) Scatter photons
- 3) Store photons





- 1) Emit photons
- 2) Scatter photons
- 3) Store photons



► Define initial:

- x_p : position
- ω_p : direction
- Φ_p : photon power

► Recipe:

- Sample position on surface area of light $x_p \sim \text{pdf}(x_p)$
- Sample direction $\omega_p \sim \text{pdf}(\omega_p)$
- $\Phi_p = L_e(x_p, \omega_p) / \text{pdf}(x_p) / \text{pdf}(\omega_p)$

- ▶ **Isotropic point light:**
 - ▶ Generate uniform random direction over sphere
- ▶ **Spotlight:**
 - ▶ Generate uniform random direction within spherical cap
- ▶ **Diffuse square light**
 - ▶ Generate uniform random location on square
 - ▶ Generate cosine-weighted direction over hemisphere

```
void generatePhotonMap()
```

```
  repeat:
```

```
    (l, Probl) = chooseRandomLight()
```

```
    (x,  $\omega$ ,  $\phi$ ) = emitPhotonFromLight(l)
```

```
    tracePhoton(x,  $\omega$ ,  $\phi$  / Probl)
```

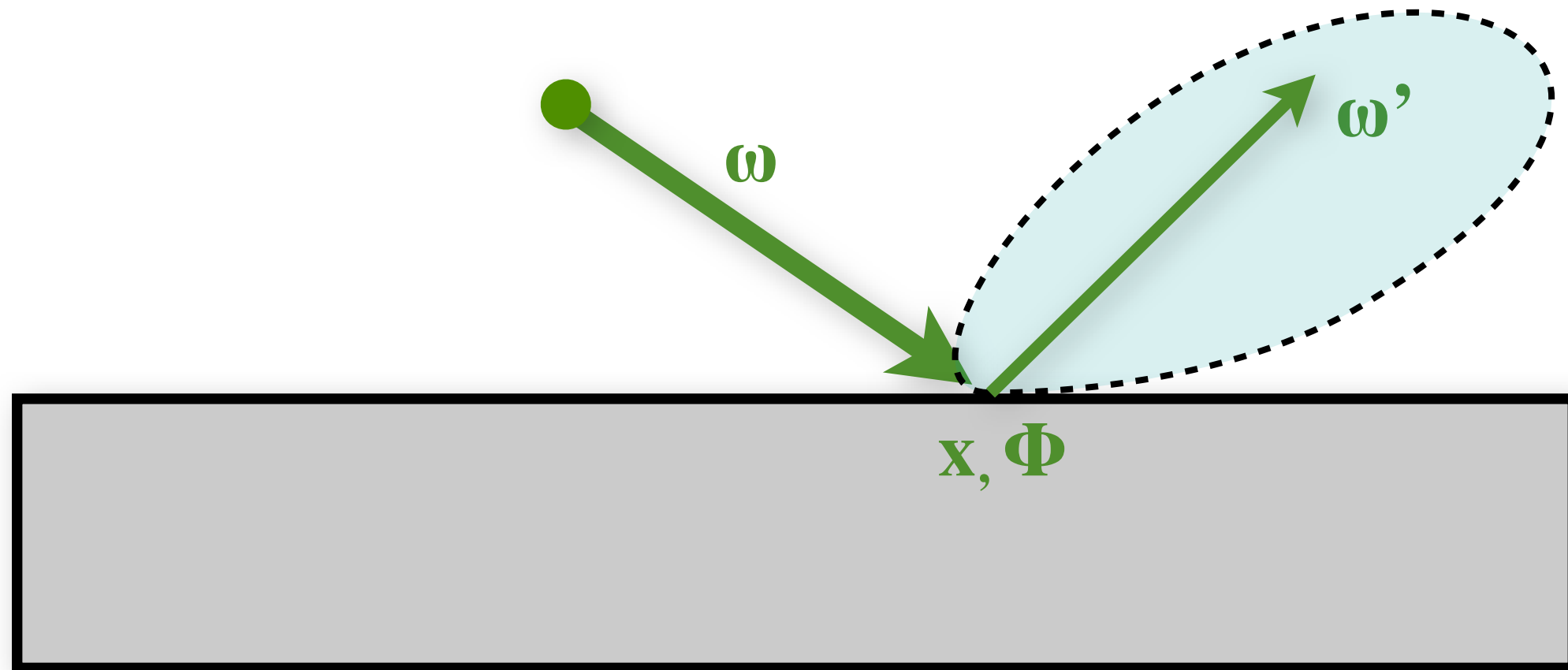
```
  until we have enough photons;
```

```
  divide all photon powers by number of emitted photons
```

Photon Tracing

```
void generatePhotonMap()
    repeat:
        (l, Probl) = chooseRandomLight()
        (x,  $\omega$ ,  $\phi$ ) = emitPhotonFromLight(l)
        tracePhoton(x,  $\omega$ ,  $\phi$  / Probl)
    until we have enough photons;
    divide all photon powers by number of emitted photons
```

```
void tracePhoton(x,  $\omega$ ,  $\phi$ )
```



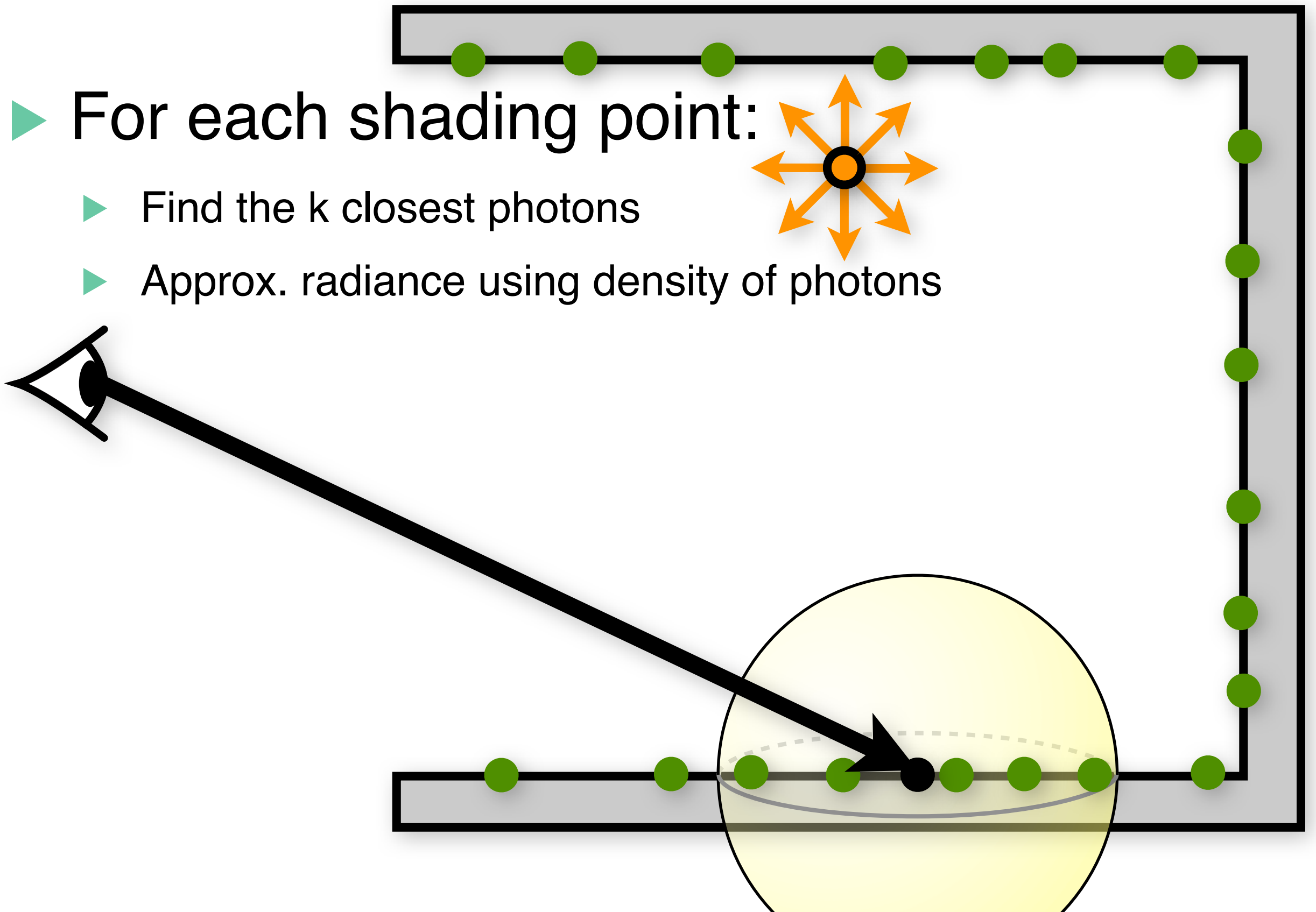
```
void tracePhoton(x, ω, Φ)
    s = nearestSurfaceHit(x, ω)
    x += s*ω           // propagate photon
    possiblyStorePhoton(x, ω, Φ)
    (ω', pdf) = sampleBxDF(x, ω)
    return tracePhoton(o, ω', Φ * BxDF(x, ω, ω') / pdf)
```

Use Russian roulette!

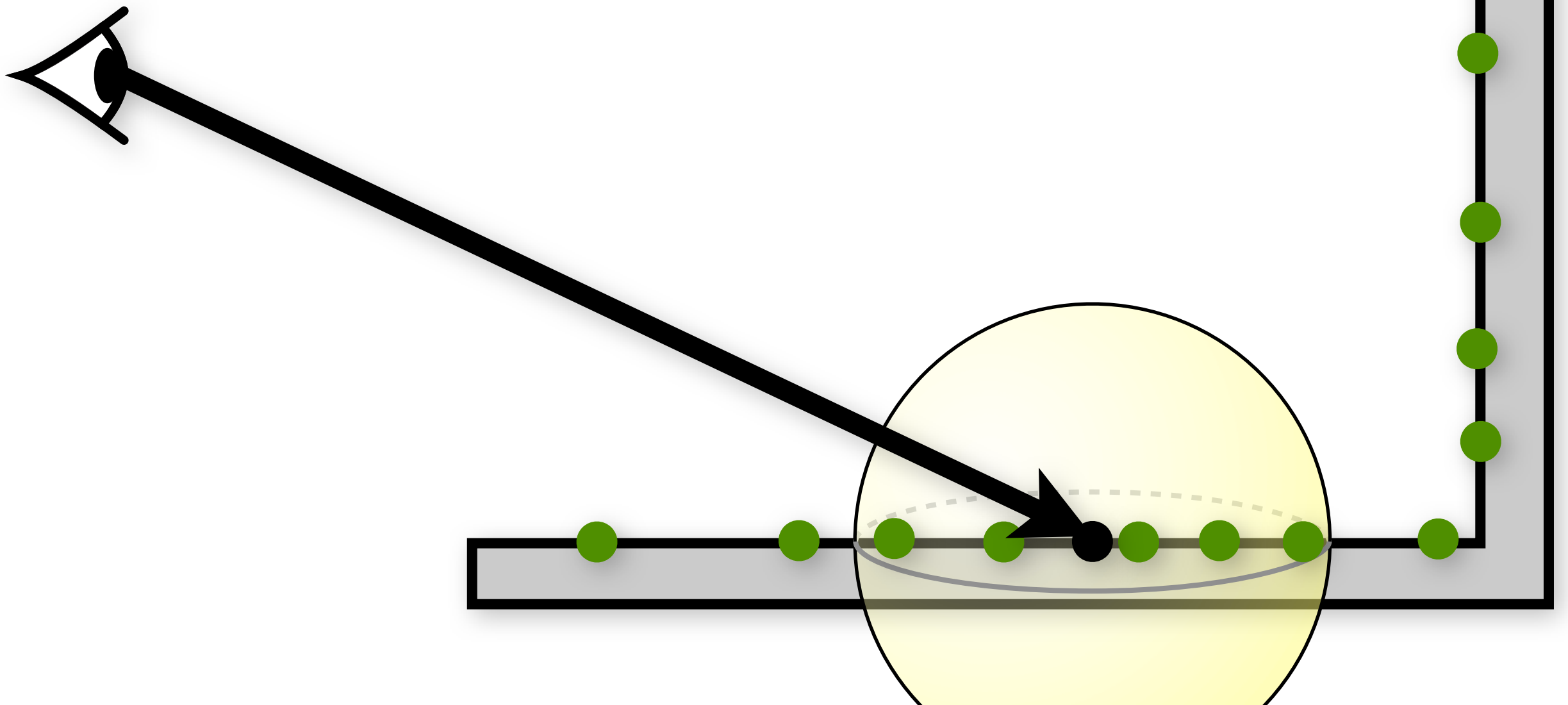
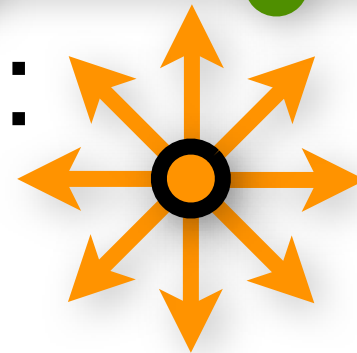
$BxDF(x, \omega, \omega') / pdf$

- ▶ A two-pass algorithm:
 - ▶ Pass 1: Trace virtual photons from the light source, scatter at surfaces, and cache
 - ▶ Pass 2: Ray trace the scene and use the photons to compute indirect illumination

- ▶ For each shading point:
 - ▶ Find the k closest photons
 - ▶ Approx. radiance using density of photons

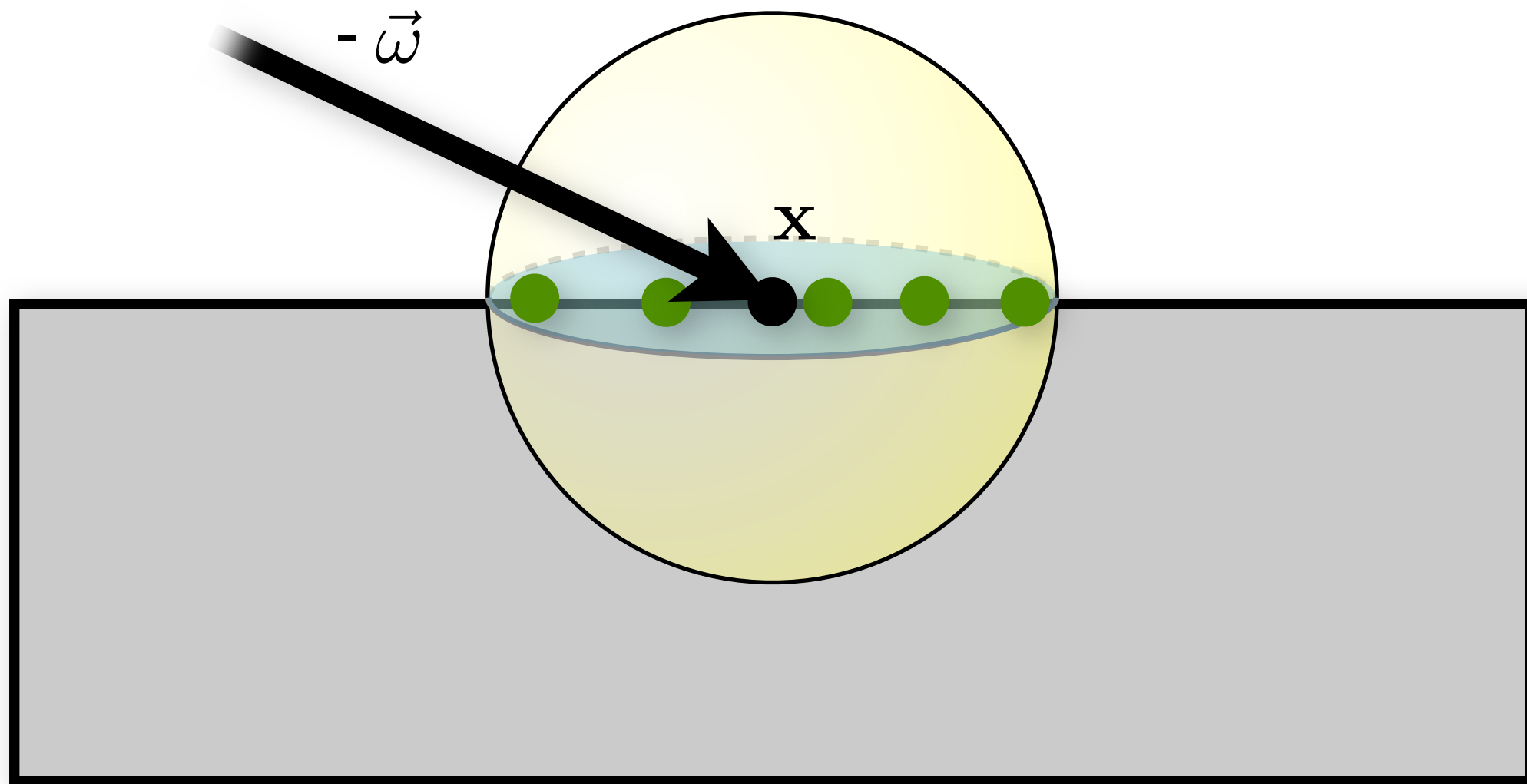


- ▶ For each shading point:
 - ▶ Find the k closest photons
 - ▶ Approx. radiance using density of photons



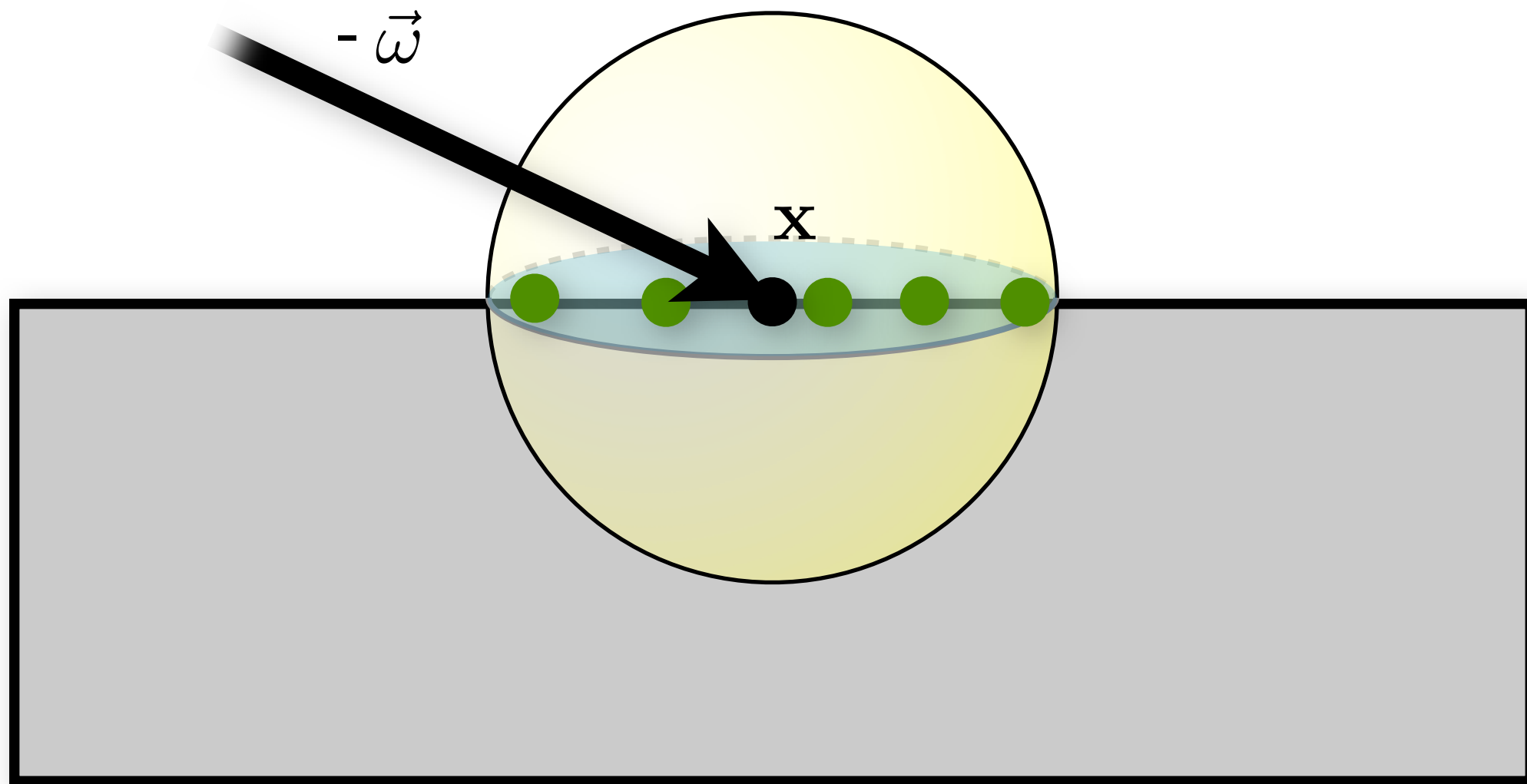
The Radiance Estimate

$$L_r(\mathbf{x}, \vec{\omega}) \approx \sum_{p=1}^{k-1} f_r(\mathbf{x}, \vec{\omega}_p, \vec{\omega}) \frac{\Phi_p}{\boxed{A_k}}$$



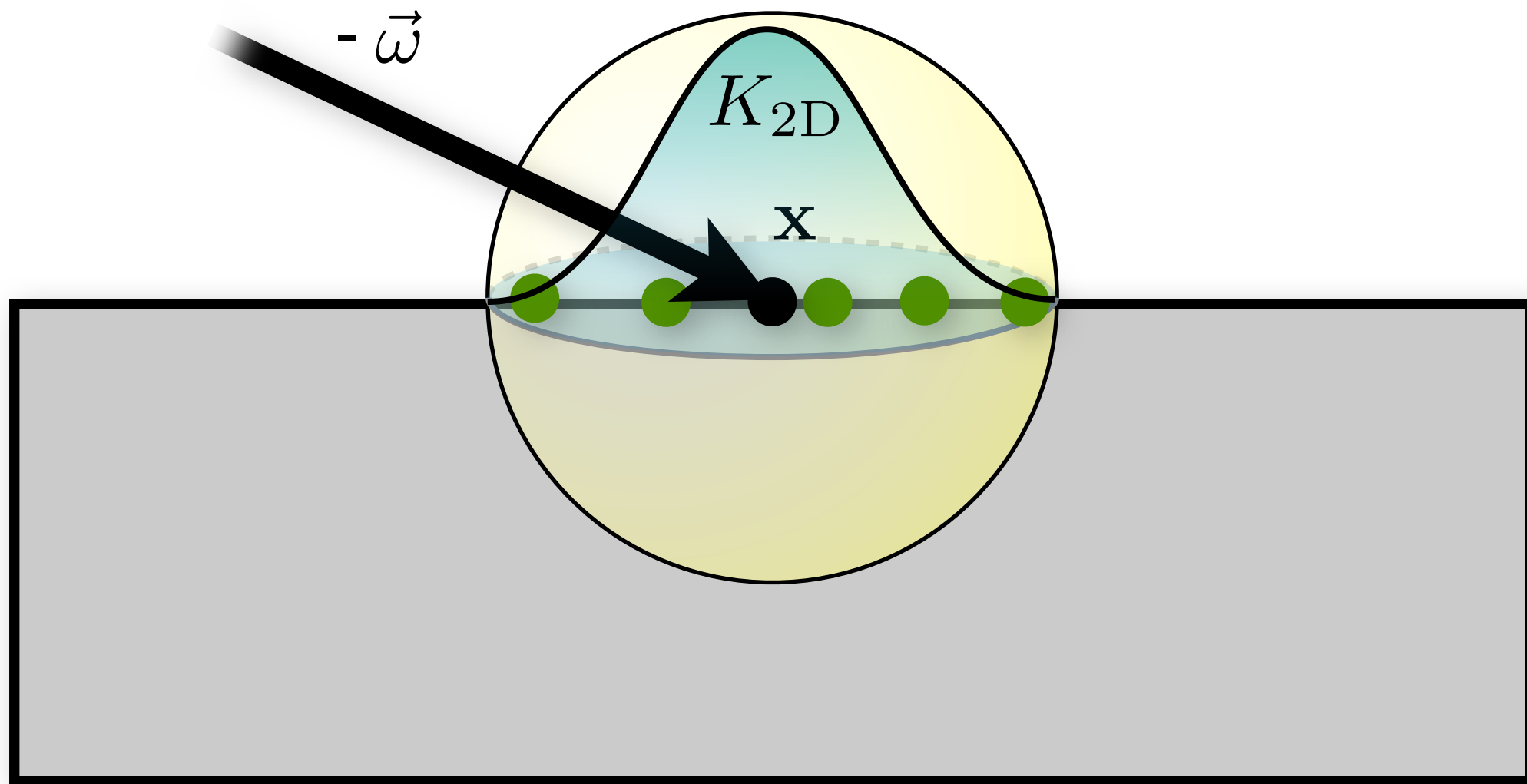
The Radiance Estimate

$$L_r(\mathbf{x}, \vec{\omega}) \approx \sum_{p=1}^{k-1} f_r(\mathbf{x}, \vec{\omega}_p, \vec{\omega}) \frac{\Phi_p}{\pi r_k^2}$$



The Radiance Estimate

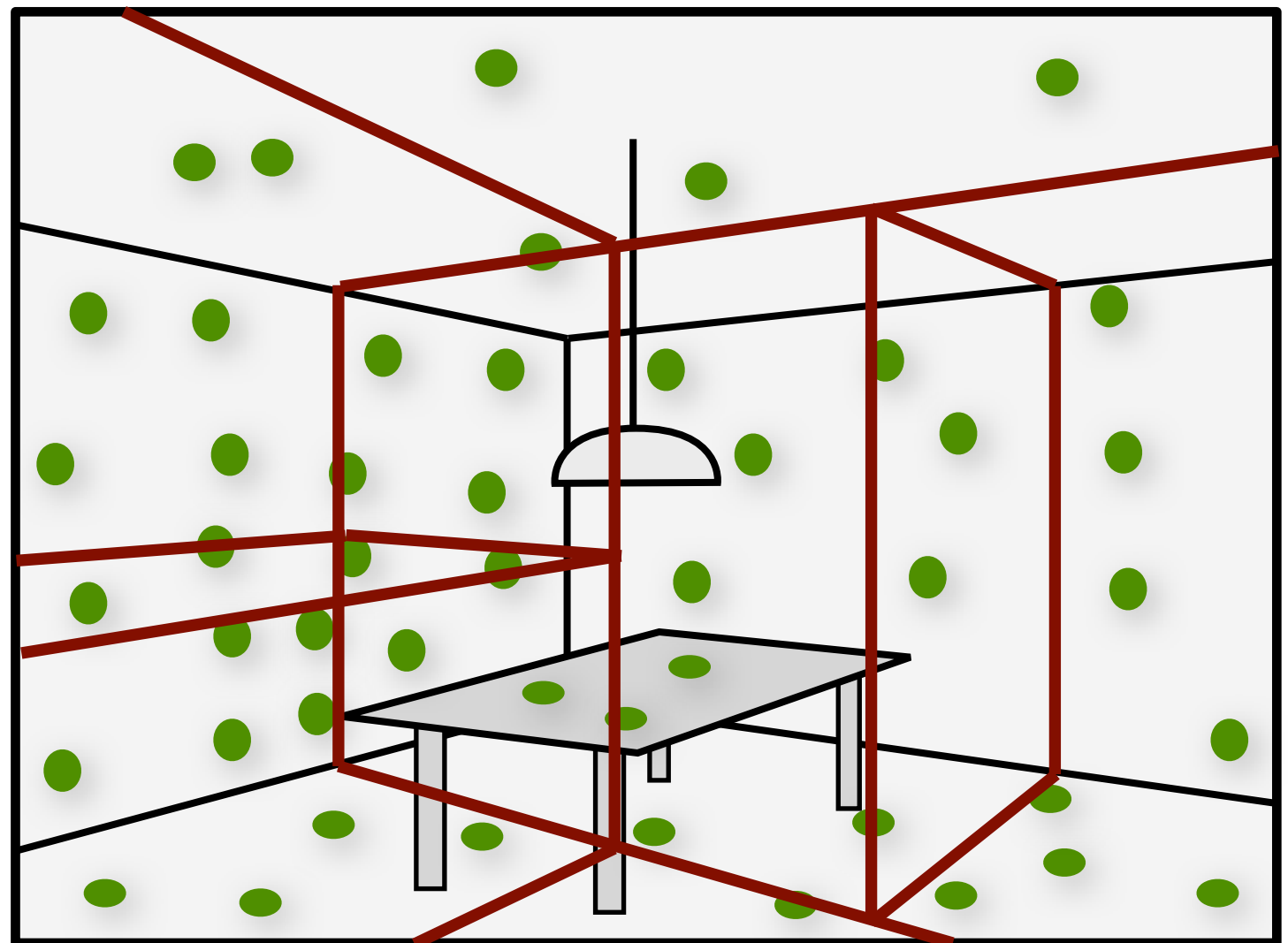
$$L_r(\mathbf{x}, \vec{\omega}) \approx \sum_{p=1}^{k-1} f_r(\mathbf{x}, \vec{\omega}_p, \vec{\omega}) \Phi_p K_{2D}(r_p, r_k)$$

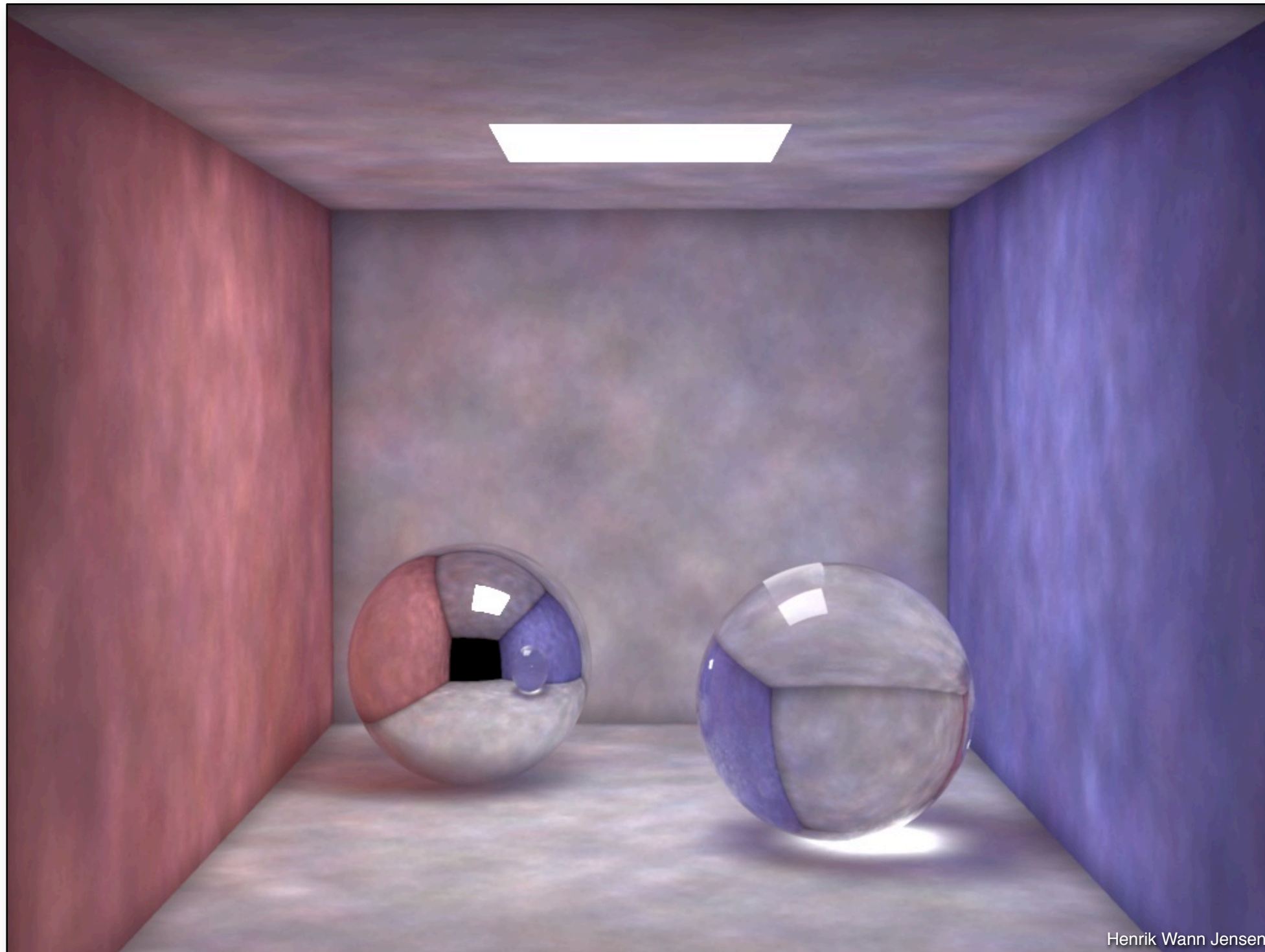


► Requirements:

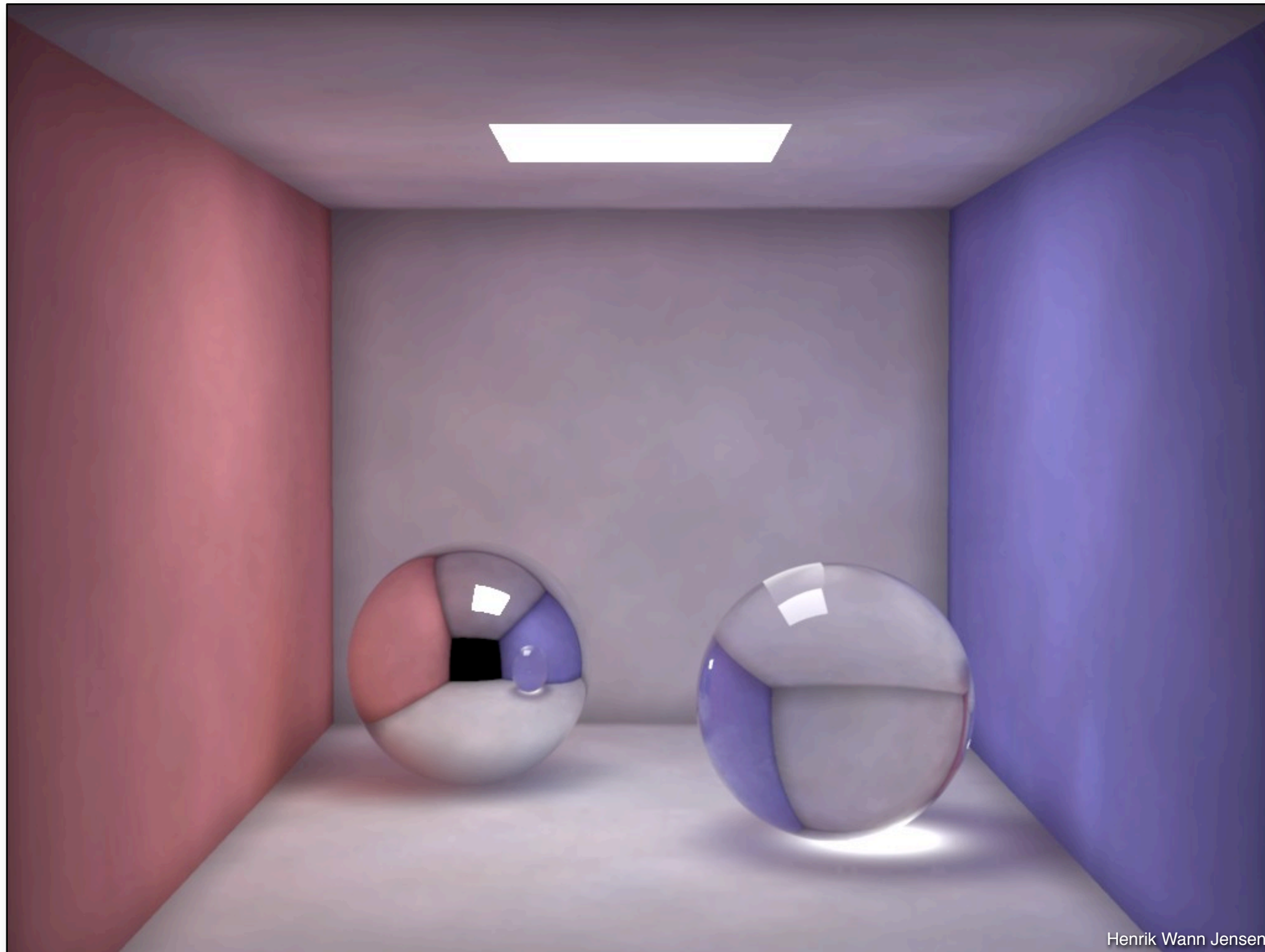
- Compact (we want many photons)
- Fast nearest neighbor search

► KD-tree



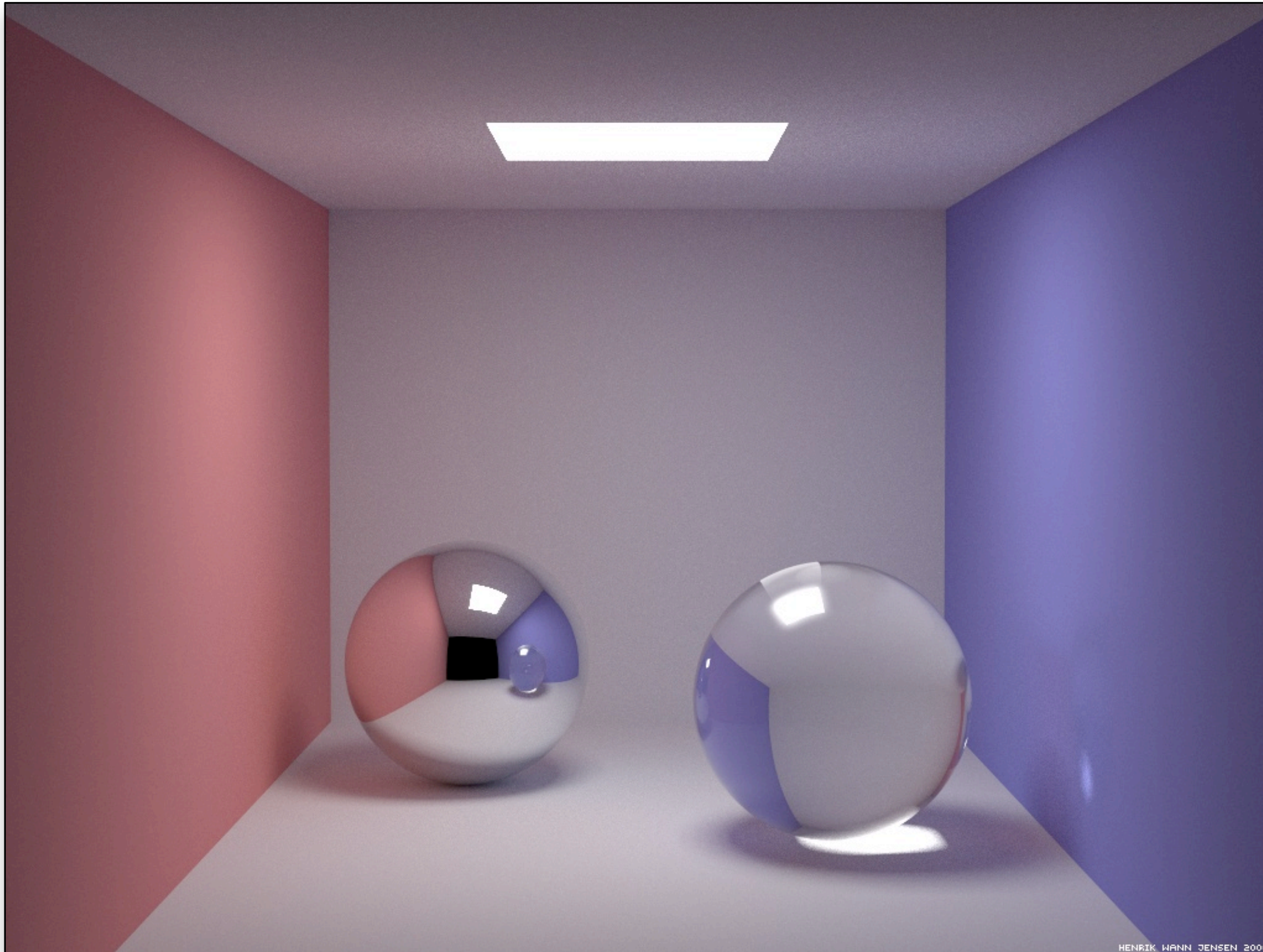


100000 photons / 50 photons in radiance estimate



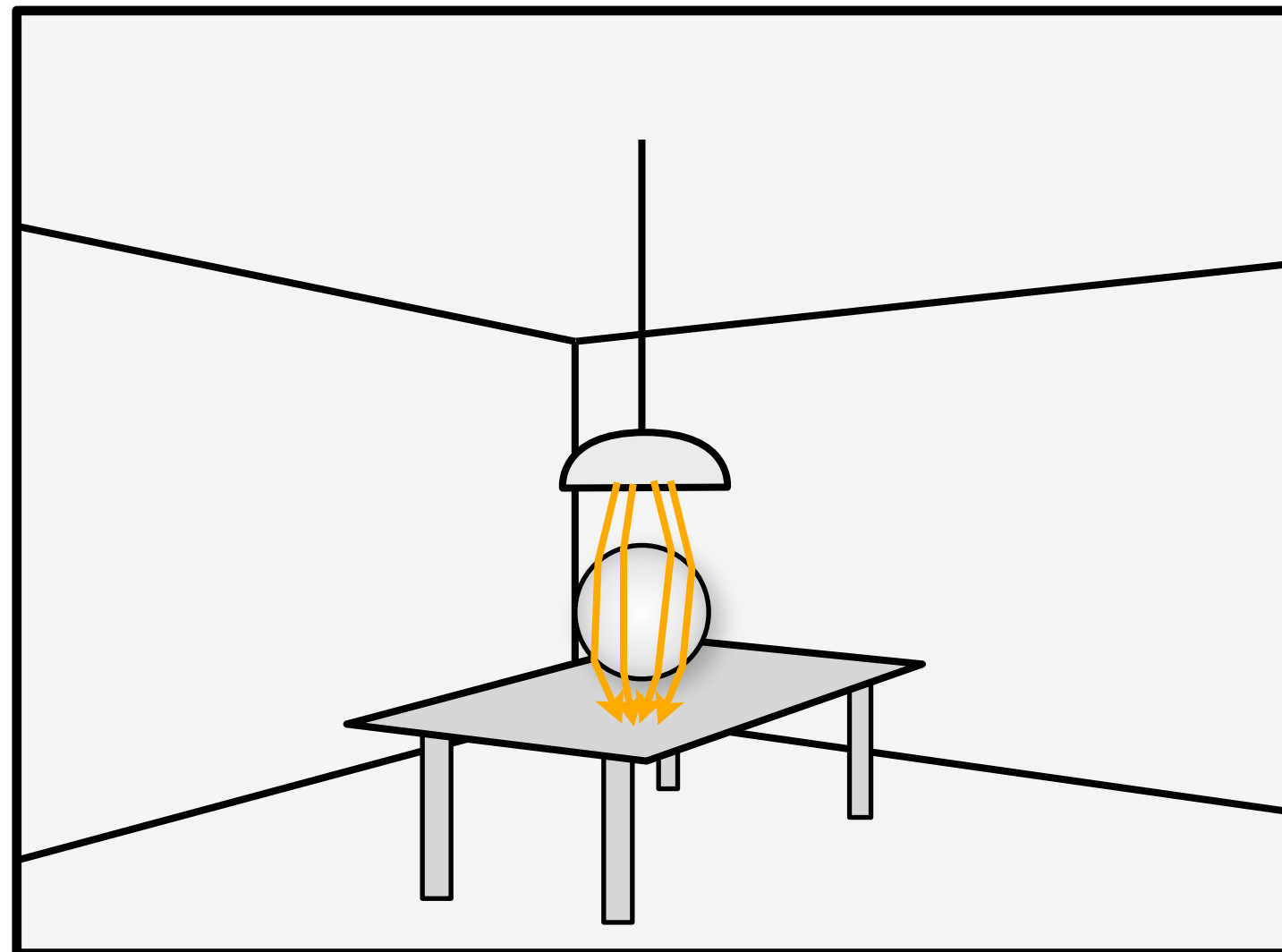
500000 photons / 500 photons in radiance estimate

Path Tracing

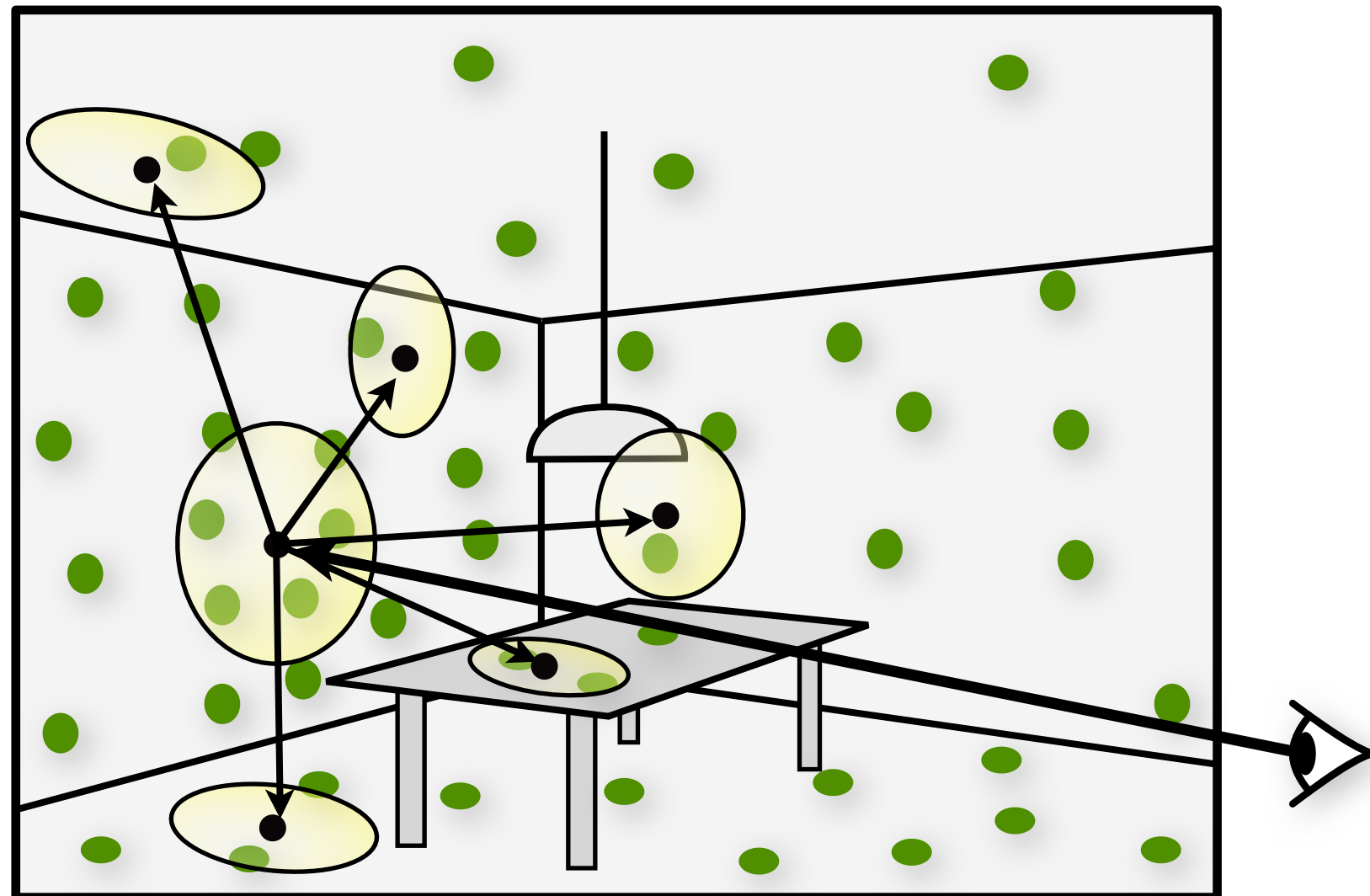


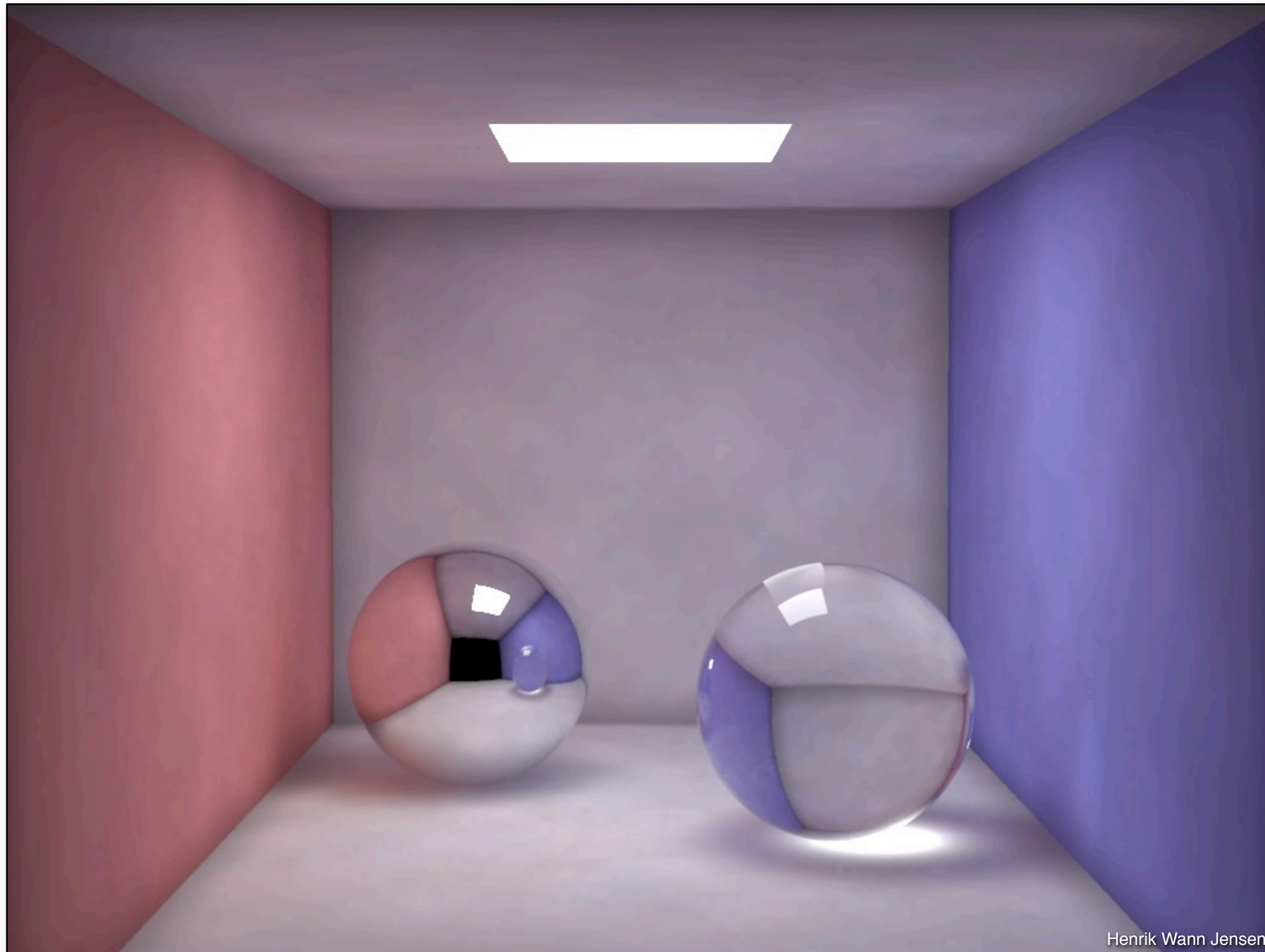
► Split illumination

- ▶ **Separate, higher quality photon map for caustics**
 - ▶ Only stores LS+D paths
 - ▶ Many photons shot directly at specular objects



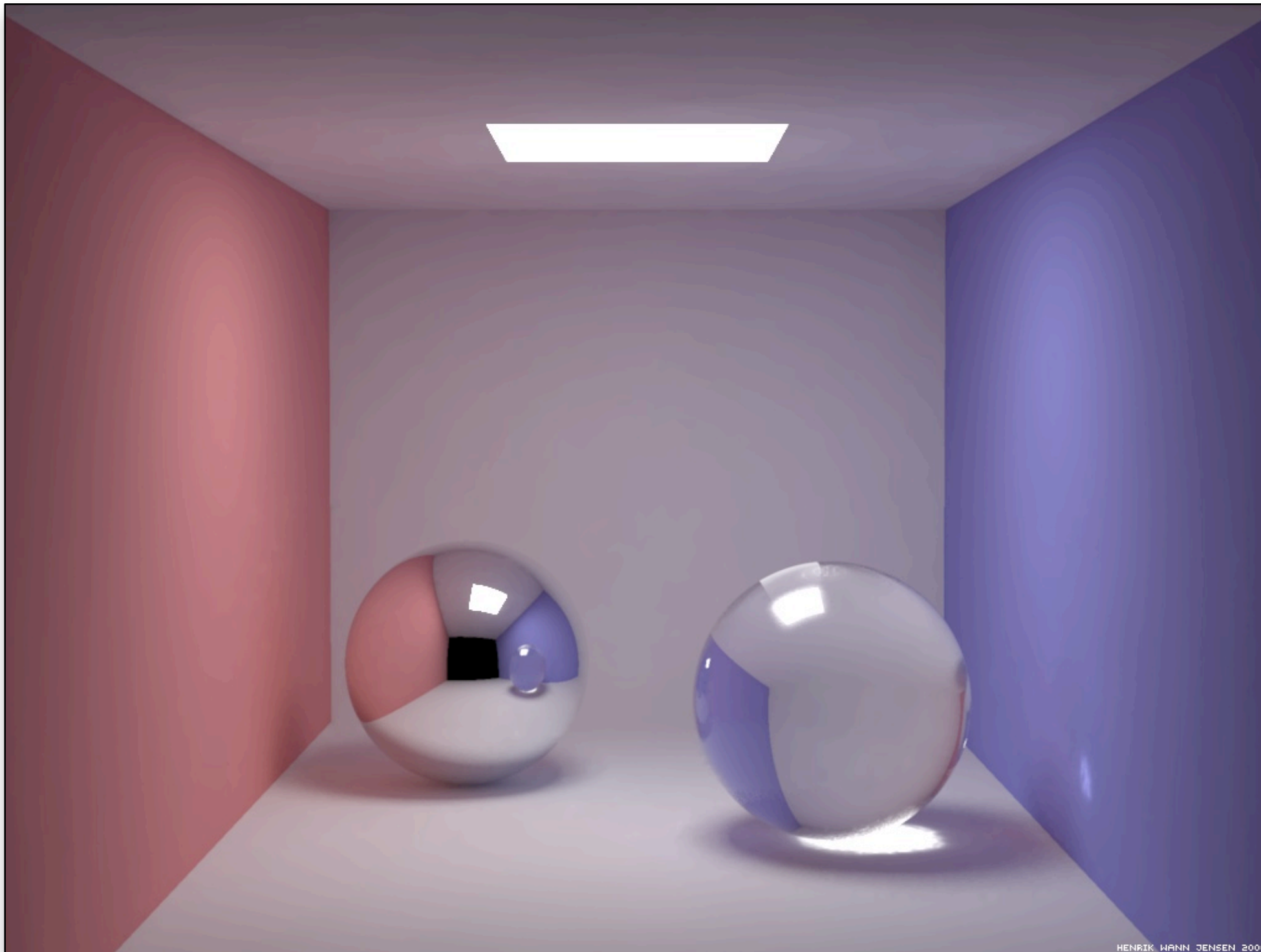
- ✗ Density estimation is blotchy
- ✓ Use final gather





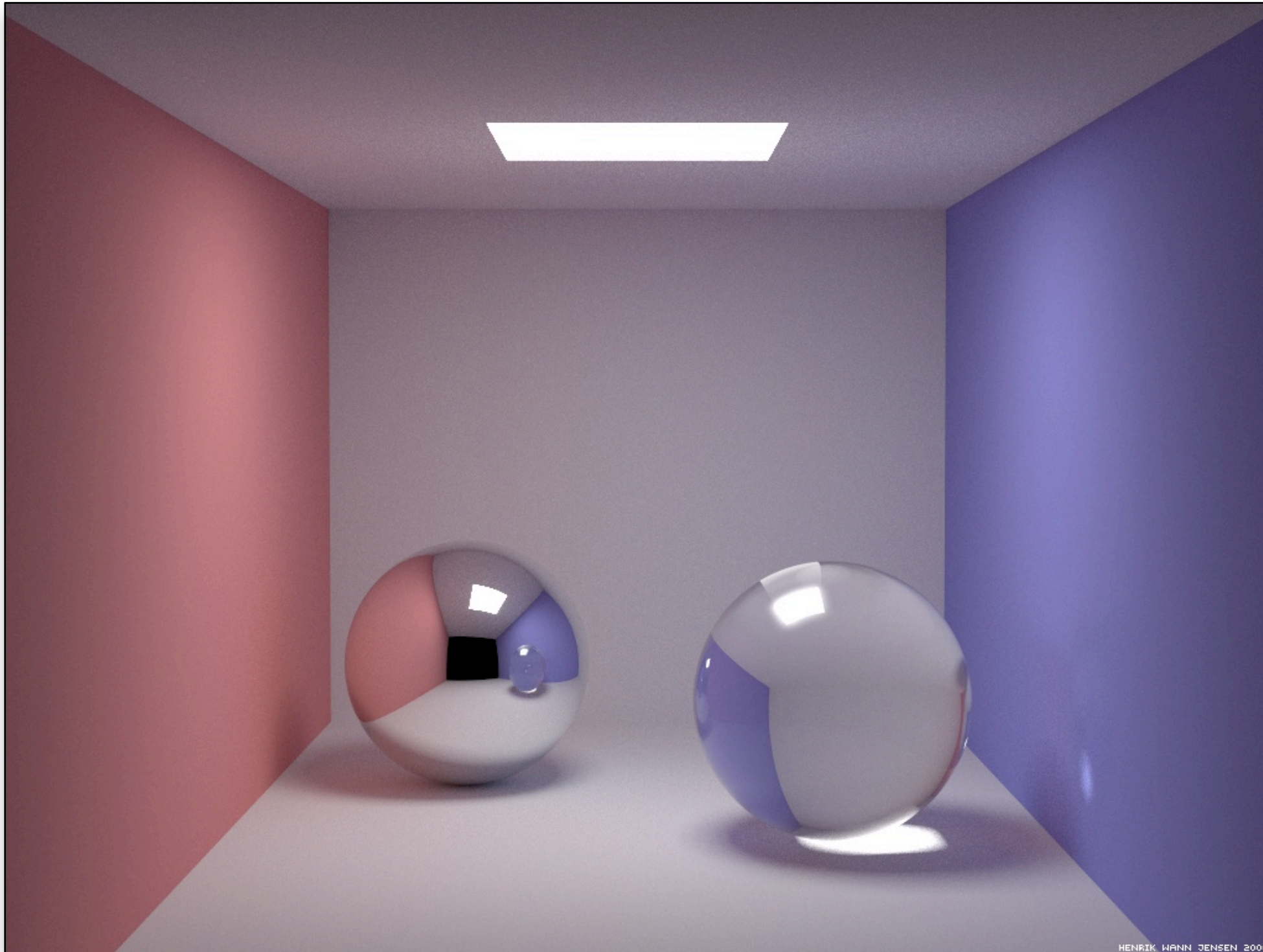
500000 photons / 500 photons in radiance estimate

Improved Photon Mapping



final gather + global photon map (200000) + caustic photon map (50000)

Path Tracing



- ▶ Improve / extend / generalize
- ▶ Progressive Photon Mapping