# Photon Mapping



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Global Illumination



Direct Illumination

#### Before photon mapping

- Radiosity
  - \* Mostly diffuse
  - \* Mesh based lighting representation
- Monte Carlo path tracing
  - \* Noisy
  - \* Slow convergence

$$L(x, \vec{\omega}) = L_e(x, \vec{\omega}) + \int_S f_r(x, \vec{\omega}, x' \to x) L(x' \to x) V(x, x') G(x, x') dA'$$

$$G(x,x') = \frac{(\vec{\omega}' \cdot \vec{n})(\vec{\omega}' \cdot \vec{n}')}{||x'-x||^2}$$



Specular-Diffuse-Specular light transport is difficult

### Basic Observation

- The lights are important
- The camera / eye is important

# Photon Mapping

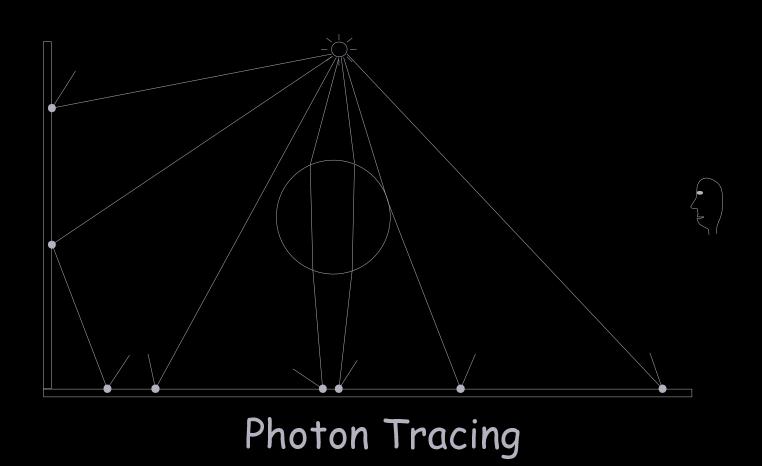
# Photon Mapping

A two-pass method

Pass 1: Build the photon map (photon tracing)

Pass 2: Render the image using the photon map

# Pass 1: Building the Photon Map



# Photon Tracing

- Photon emission
- Photon scattering
- Photon storing

# What is a photon?

- Flux (power) not radiance!
- Collection of physical photons
  - \* A fraction of the light source power
  - \* Several wavelengths combined into one entity

#### Photon emission

Given  $\Phi$  Watt lightbulb.

Emit N photons.

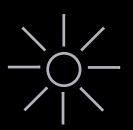
Each photon has the power  $\frac{\Phi}{N}$  Watt.



 Photon power depends on the number of emitted photons.

# Diffuse point light

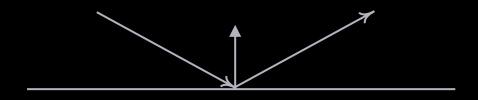
Generate random direction Emit photon in that direction



```
// Find random direction
do {
    x = 2.0*random()-1.0;
    y = 2.0*random()-1.0;
    z = 2.0*random()-1.0;
} while ( (x*x + y*y + z*z) > 1.0 );
```

## Photon scattering

Same as path tracing (with small exceptions).



$$\vec{d}_r = \vec{d}_i - 2\vec{n}(\vec{n} \cdot \vec{d}_i)$$

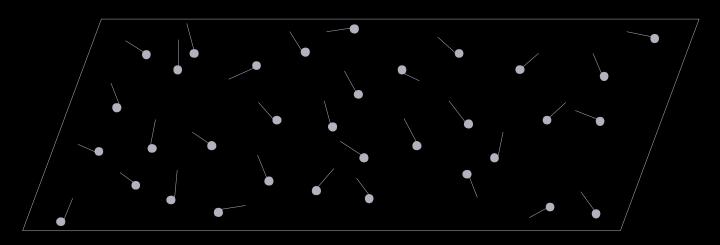
## Photon scattering

#### Important optimizations:

- Use Russian roulette to avoid bias
- Create only one photon per scattering event

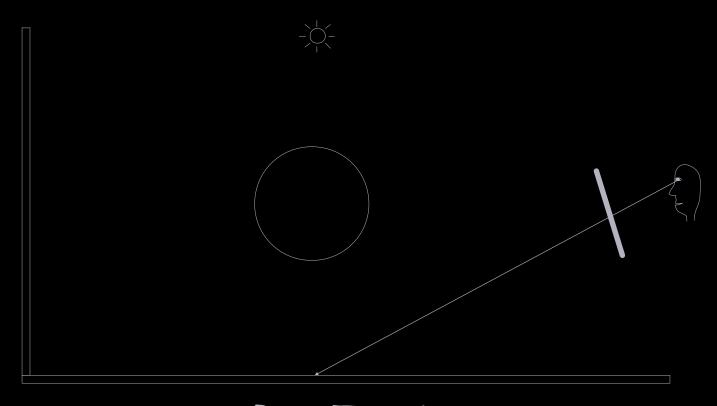
# Photon storing

When a photon hits a non-specular surface information about it is stored in a global data structure called the photon map. The information includes the photon power, incoming direction and the hit location.



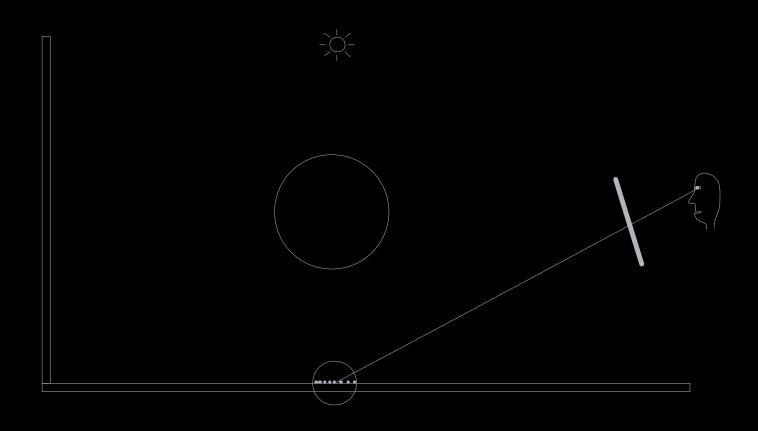
Photon map

# Pass 2: Rendering

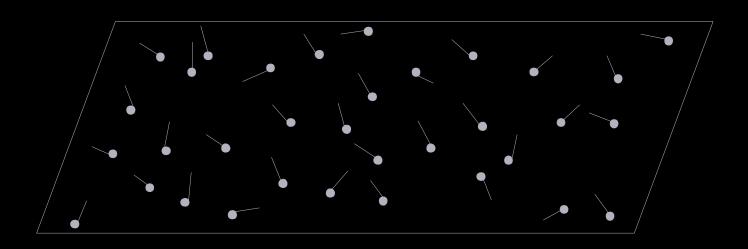


Ray Tracing

# Rendering with the photon map



# Rendering with the photon map



We need radiance, but the photons carry flux

$$L(x, \vec{\omega}) = \int_{\Omega} f_r(x, \vec{\omega}', \vec{\omega}) L'(x, \vec{\omega}') \cos \theta' d\omega$$

$$L(x,\vec{\omega}) = \int_{\Omega} f_r(x,\vec{\omega}',\vec{\omega}) L'(x,\vec{\omega}') \cos\theta' d\omega$$
$$= \int_{\Omega} f_r(x,\vec{\omega}',\vec{\omega}) \frac{d\Phi^2(x,\vec{\omega}')}{d\omega \cos\theta' dA} \cos\theta' d\omega$$

$$L(x,\vec{\omega}) = \int_{\Omega} f_r(x,\vec{\omega}',\vec{\omega}) L'(x,\vec{\omega}') \cos \theta' d\omega$$

$$= \int_{\Omega} f_r(x,\vec{\omega}',\vec{\omega}) \frac{d\Phi^2(x,\vec{\omega}')}{d\omega \cos \theta' dA} \cos \theta' d\omega$$

$$= \int_{\Omega} f_r(x,\vec{\omega}',\vec{\omega}) \frac{d\Phi^2(x,\vec{\omega}')}{dA}$$

$$L(x, \vec{\omega}) = \int_{\Omega} f_r(x, \vec{\omega}', \vec{\omega}) L'(x, \vec{\omega}') \cos \theta' d\omega$$

$$= \int_{\Omega} f_r(x, \vec{\omega}', \vec{\omega}) \frac{d\Phi^2(x, \vec{\omega}')}{d\omega \cos \theta' dA} \cos \theta' d\omega$$

$$= \int_{\Omega} f_r(x, \vec{\omega}', \vec{\omega}) \frac{d\Phi^2(x, \vec{\omega}')}{dA}$$

$$\approx \sum_{p=1}^n f_r(x, \vec{\omega}'_p, \vec{\omega}) \frac{\Delta \Phi_p(x, \vec{\omega}'_p)}{\Delta A}$$

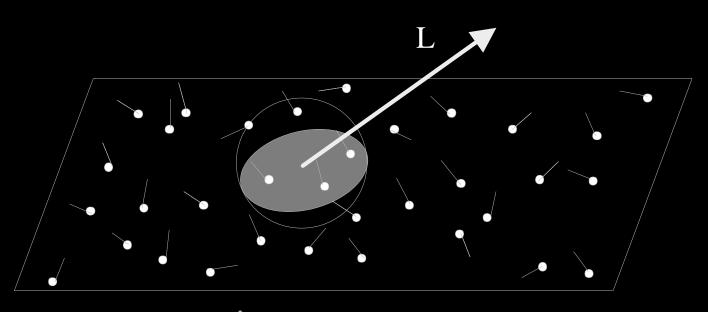
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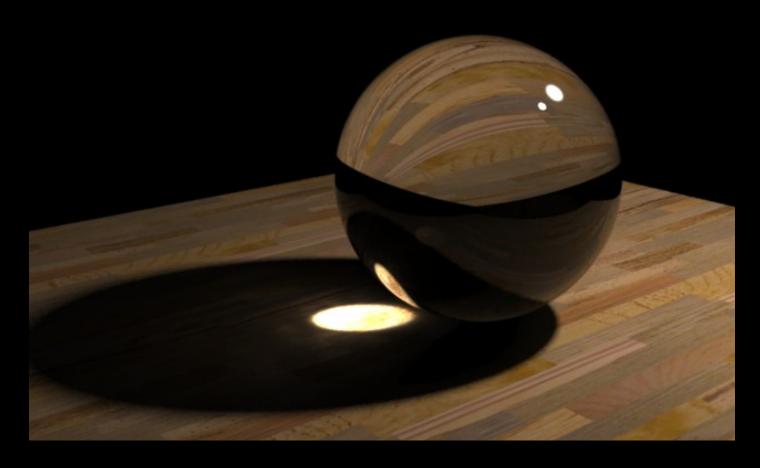
Photon density estimate



knn estimate

$$L(x, \vec{\omega}) \approx \sum_{p=1}^{n} f_r(x, \vec{\omega}_p', \vec{\omega}) \frac{\Delta \Phi_p(x, \vec{\omega}_p')}{\pi r^2}$$

# Caustic from a Glass Sphere



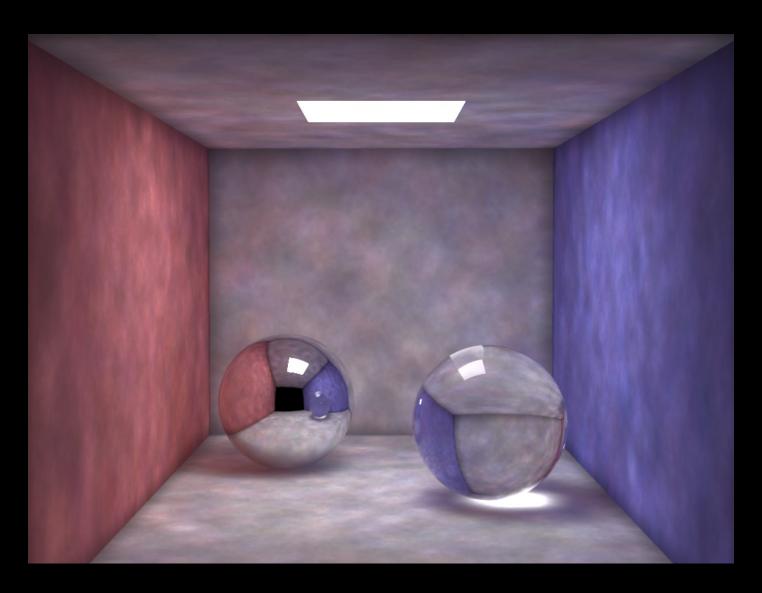
Photon Mapping: 10000 photons / 50 photons in radiance estimate

# Caustic from a Glass Sphere



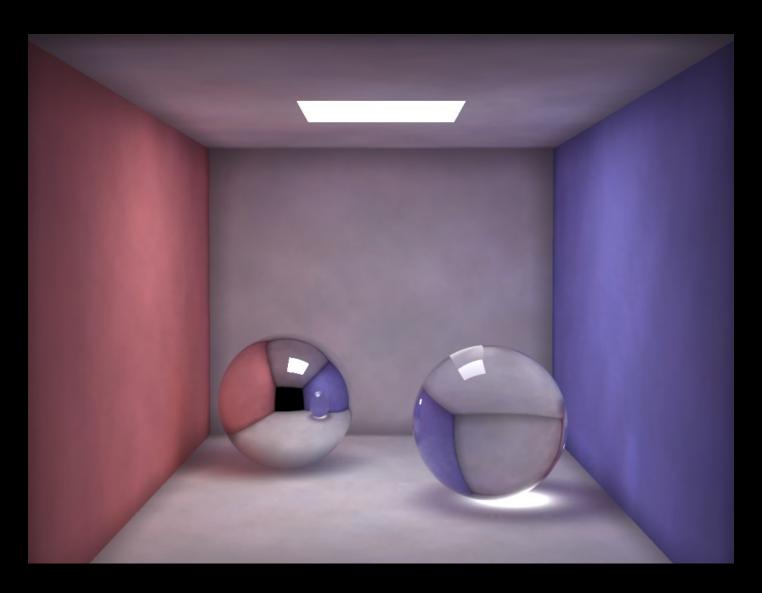
Path Tracing: 1000 paths/pixel

# Global Illumination



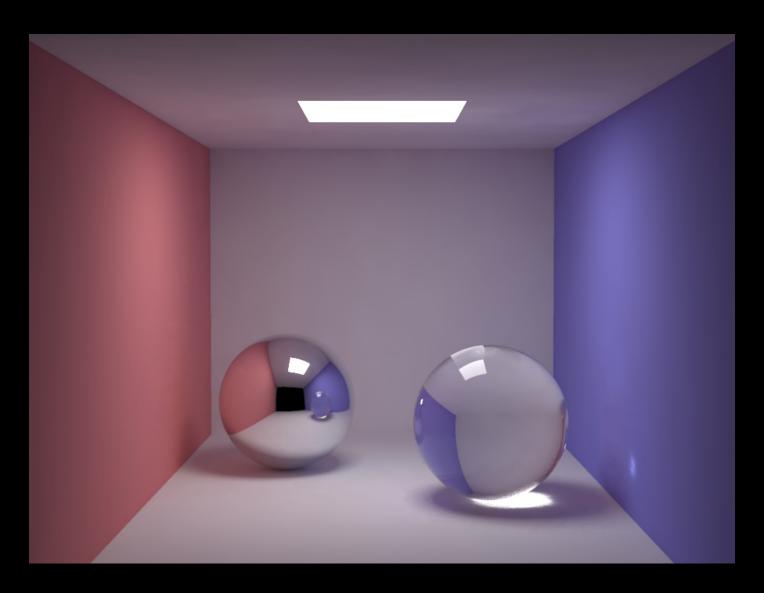
100000 photons / 50 photons in radiance estimate

# Global Illumination



500000 photons / 500 photons in radiance estimate

# Adding final gathering



200000 global photons, 50000 caustic photons

# Global Photons



200000 global photons

### Final observations

- Photon mapping is consistent
- Density estimate is the source of bias (blur)