

A Progressive Error Estimation Framework for Photon Density Estimation

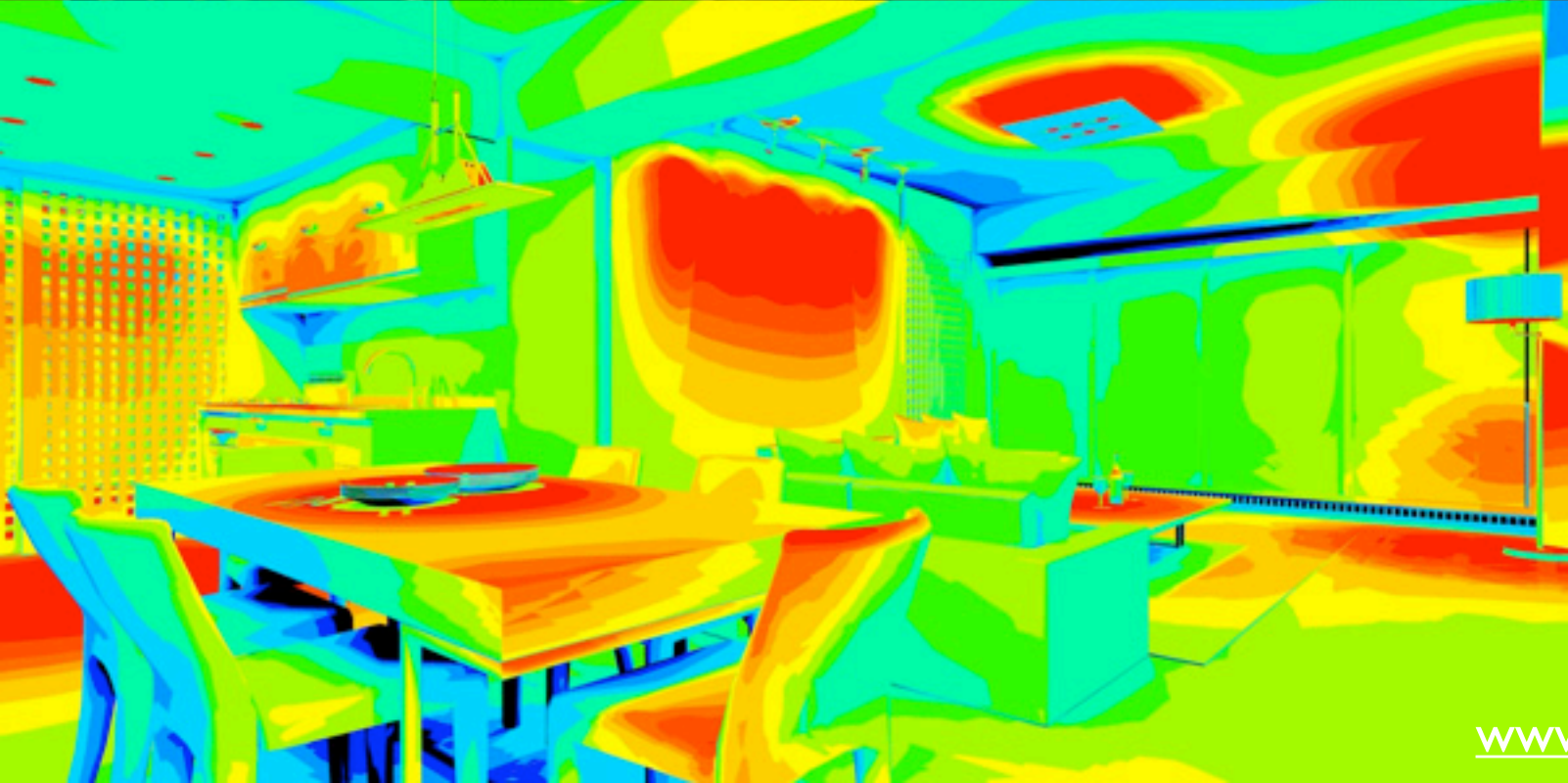
Toshiya Hachisuka* Wojciech Jarosz^{†*} Henrik Wann Jensen*

*University of California, San Diego

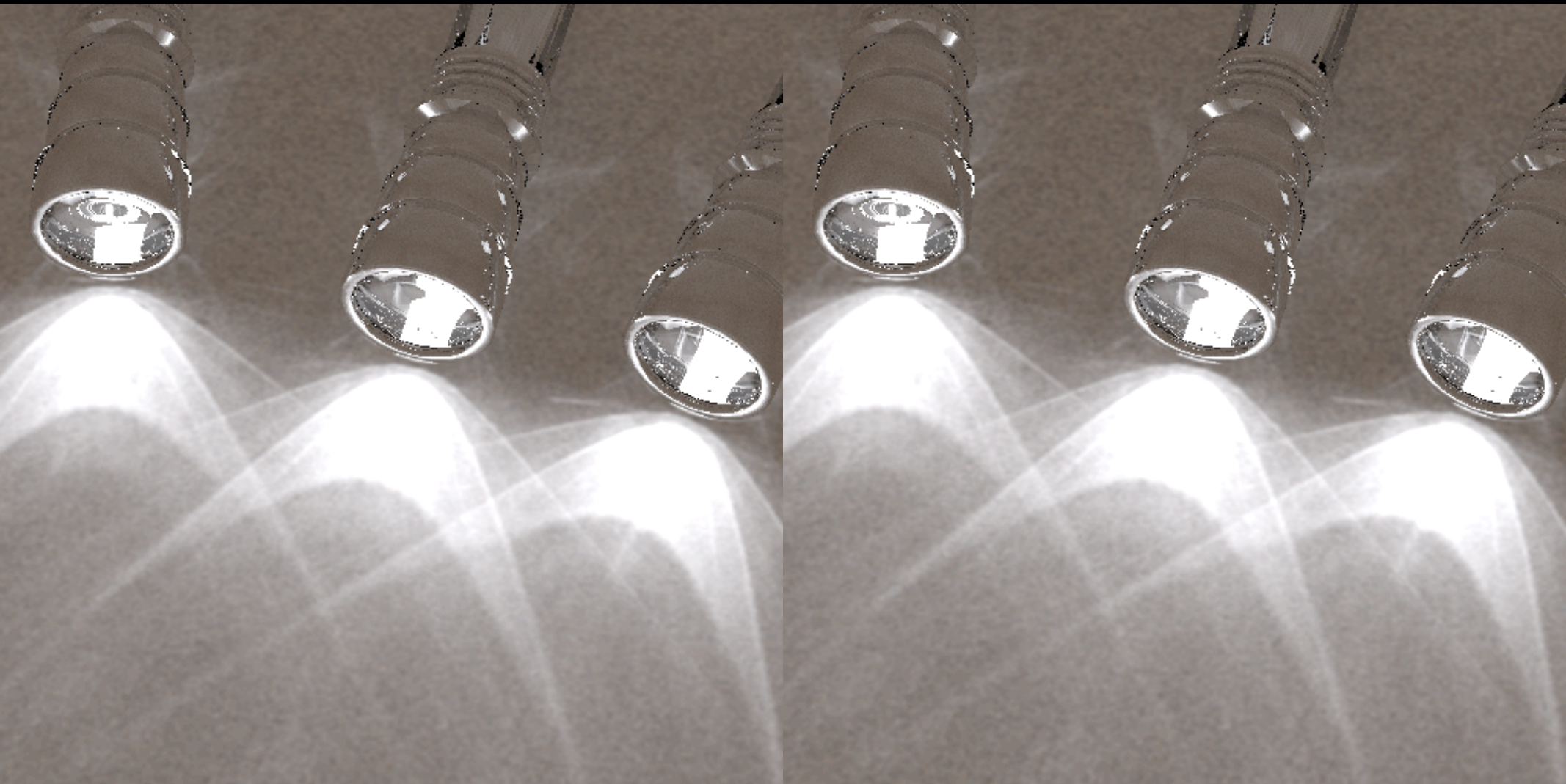
[†]Disney Research Zürich



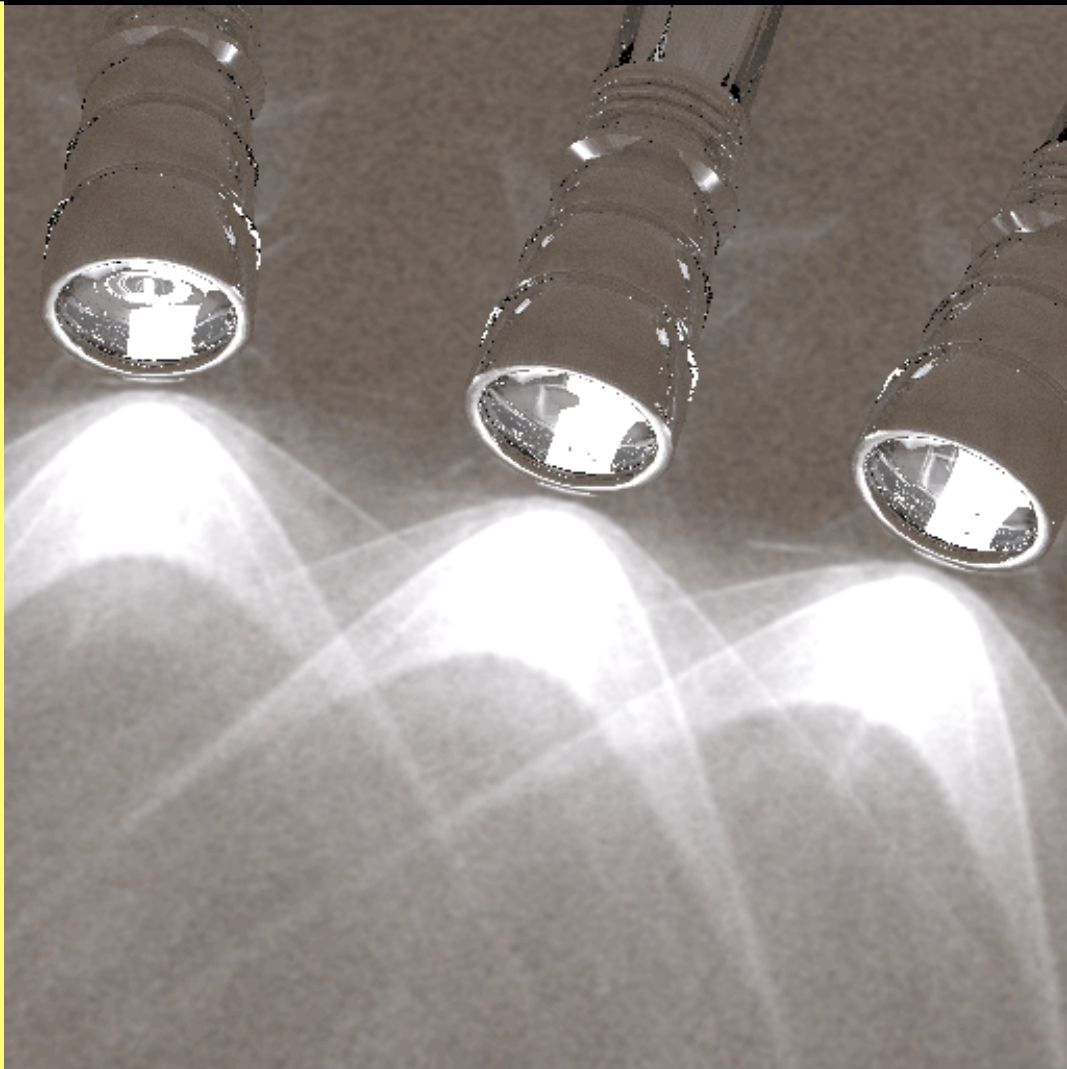
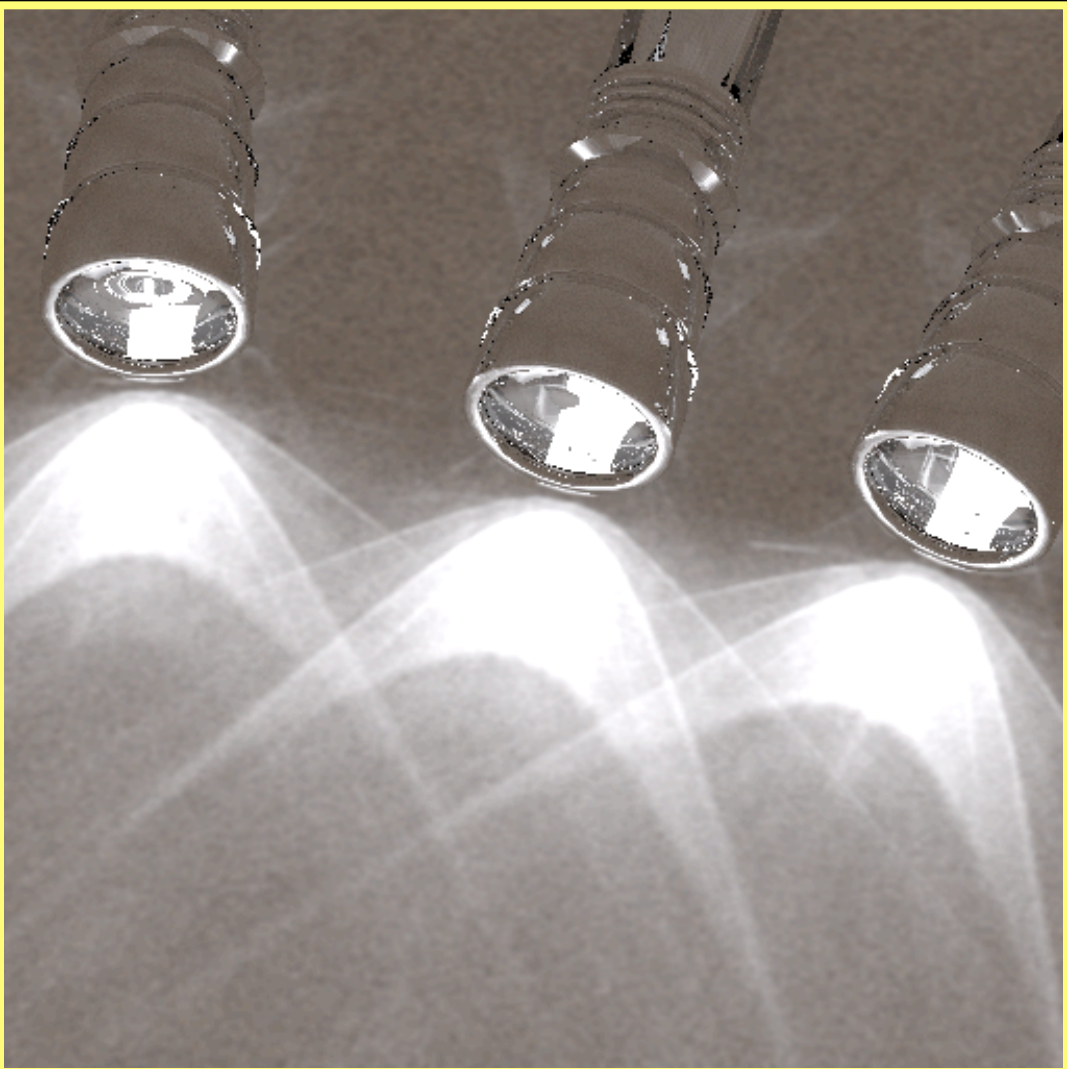




Quiz



Quiz



Importance of Error Estimation

- 'Guesswork' does not work!

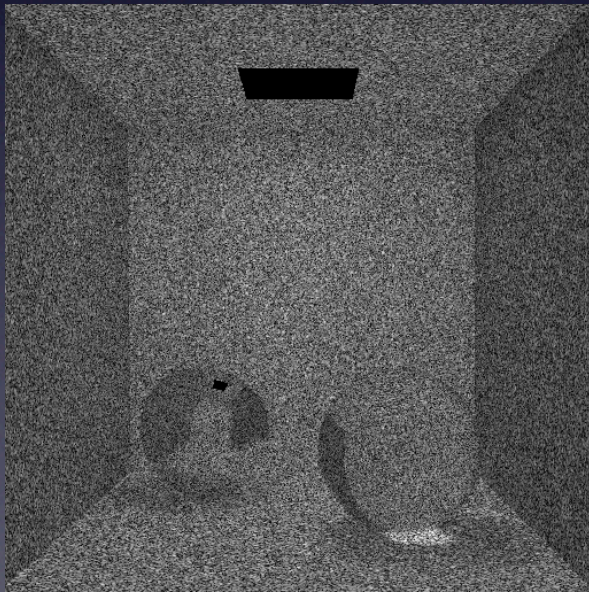
Importance of Error Estimation

- ‘Guesswork’ does not work!
- Key element for many applications
 - Predictive rendering (e.g., lighting engineering)
 - Error-driven computation
 - Theoretical error analysis

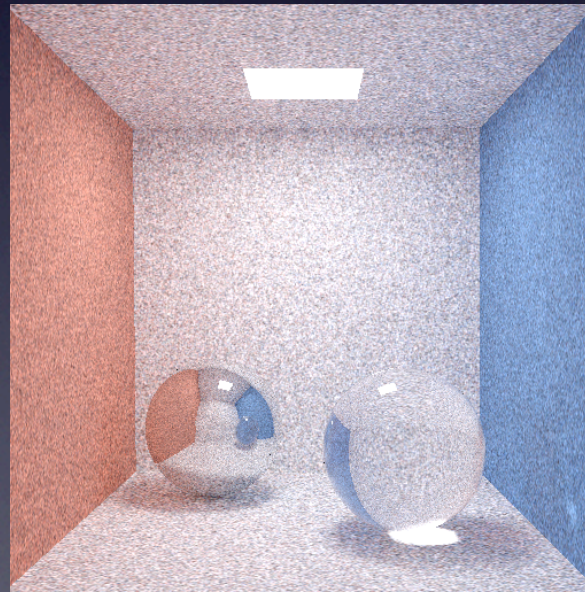
Definition of Error

- Difference between computed and exact

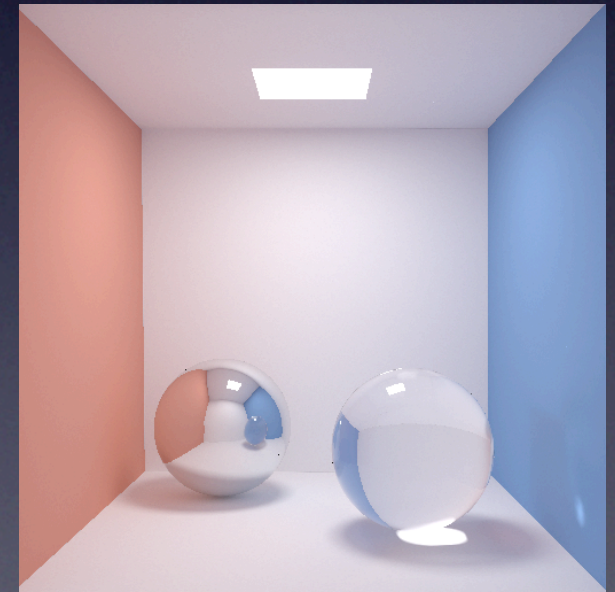
$$E_i = L_i - L$$



=



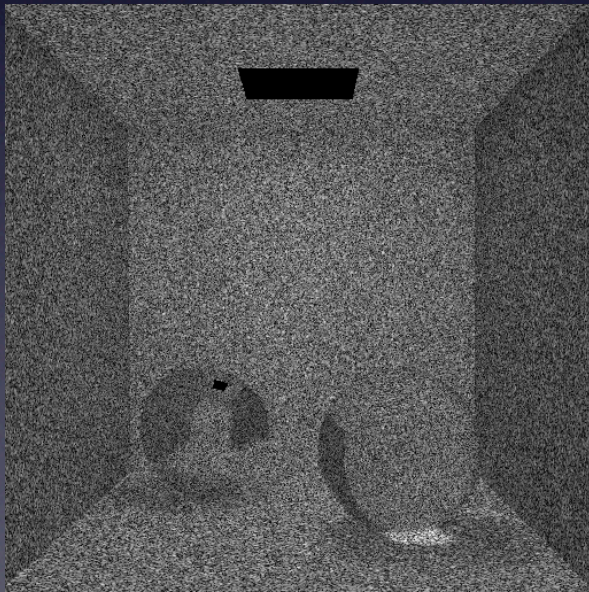
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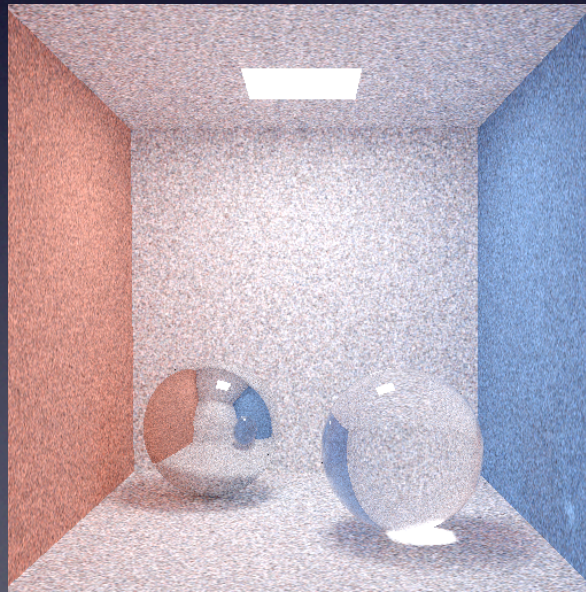
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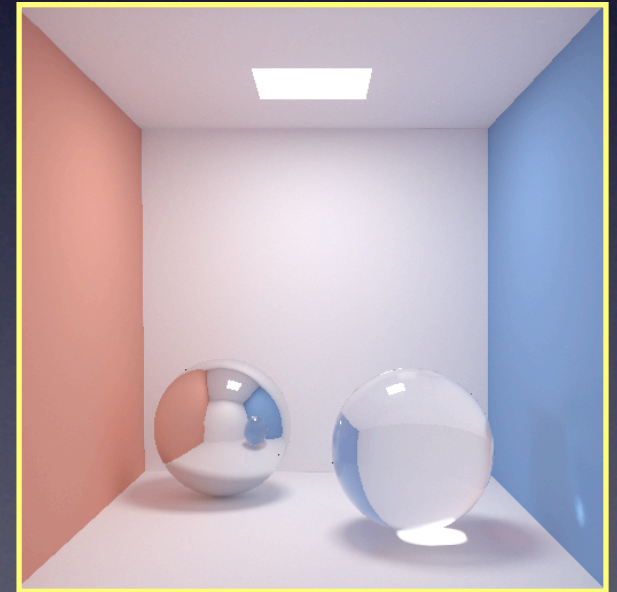
$$E_i = L_i - \boxed{L} \text{ Unknown}$$



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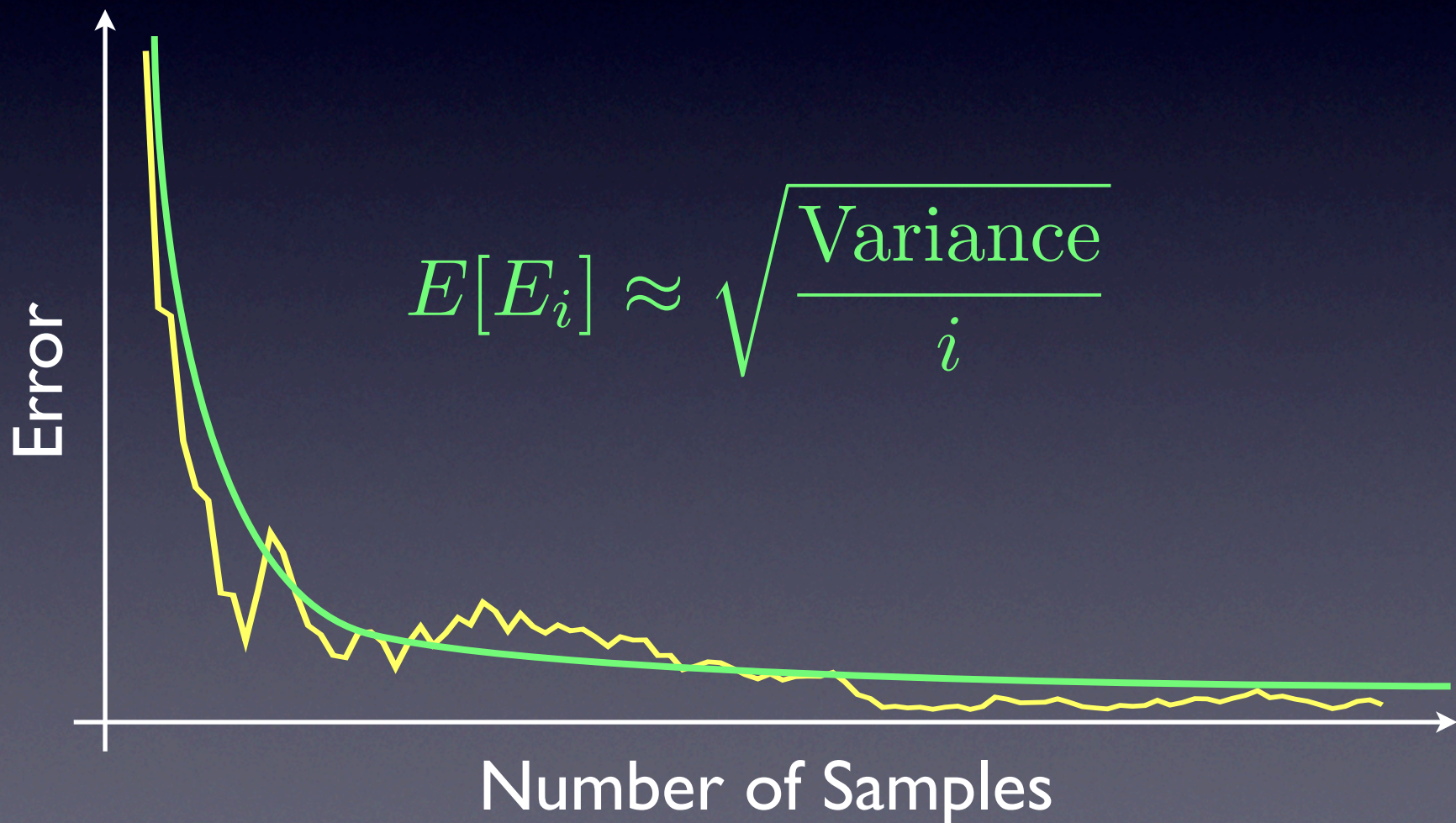


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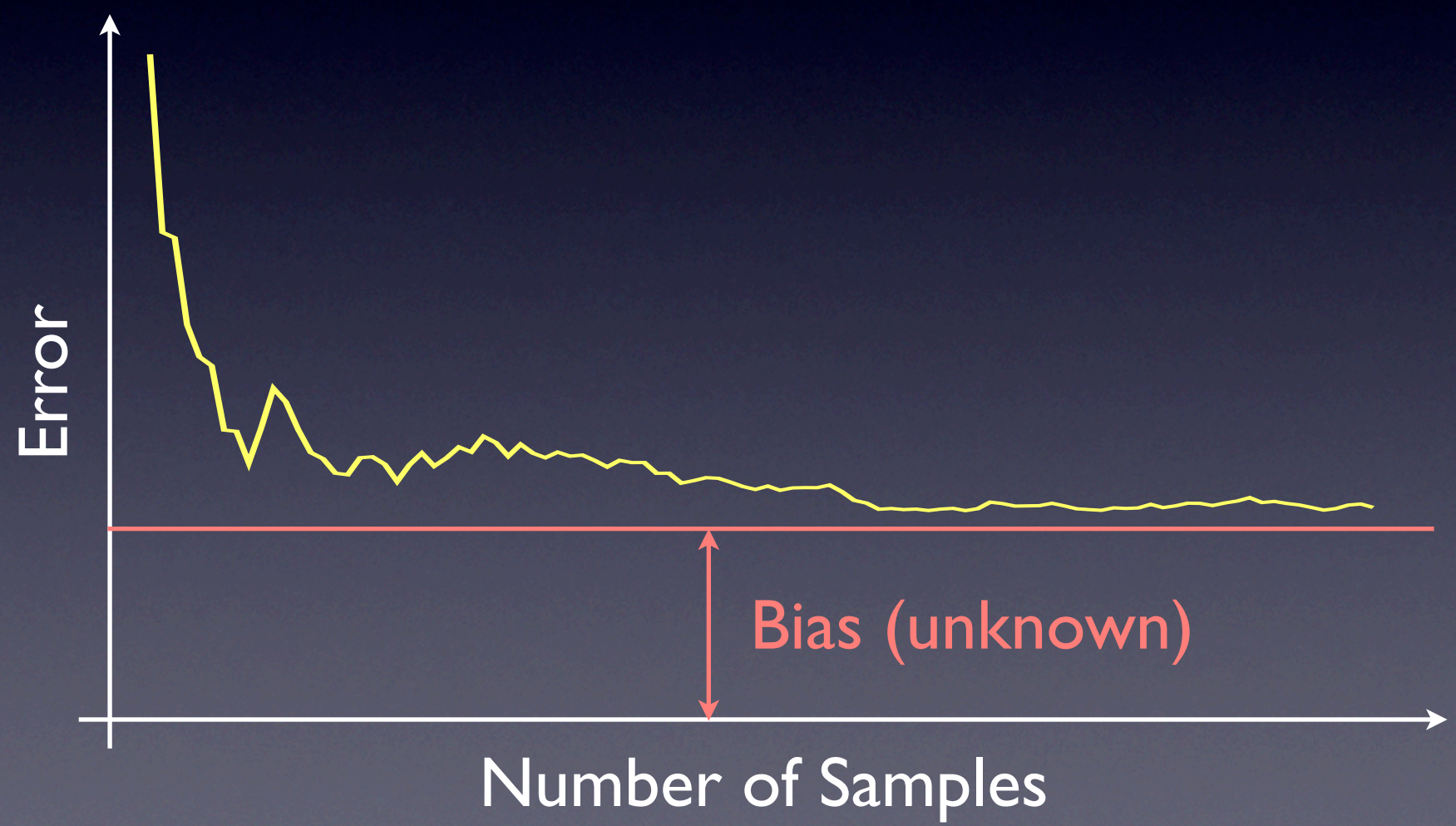
Error in Unbiased Methods

- Path Tracing [Kajiya 86]



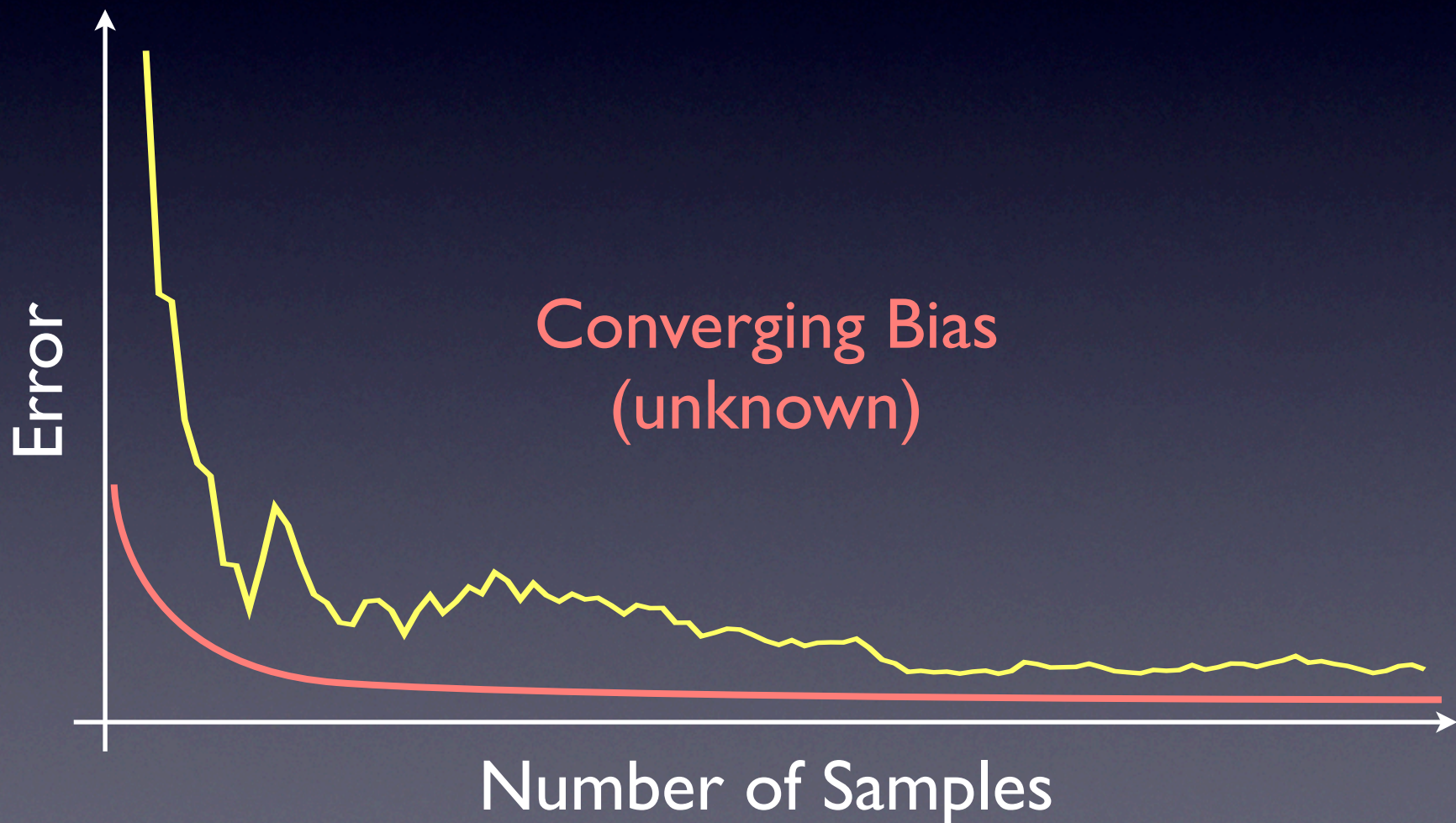
Error in Biased Methods

- Photon Density Estimation [Jensen 96][Walter 98]



Error in Biased Methods

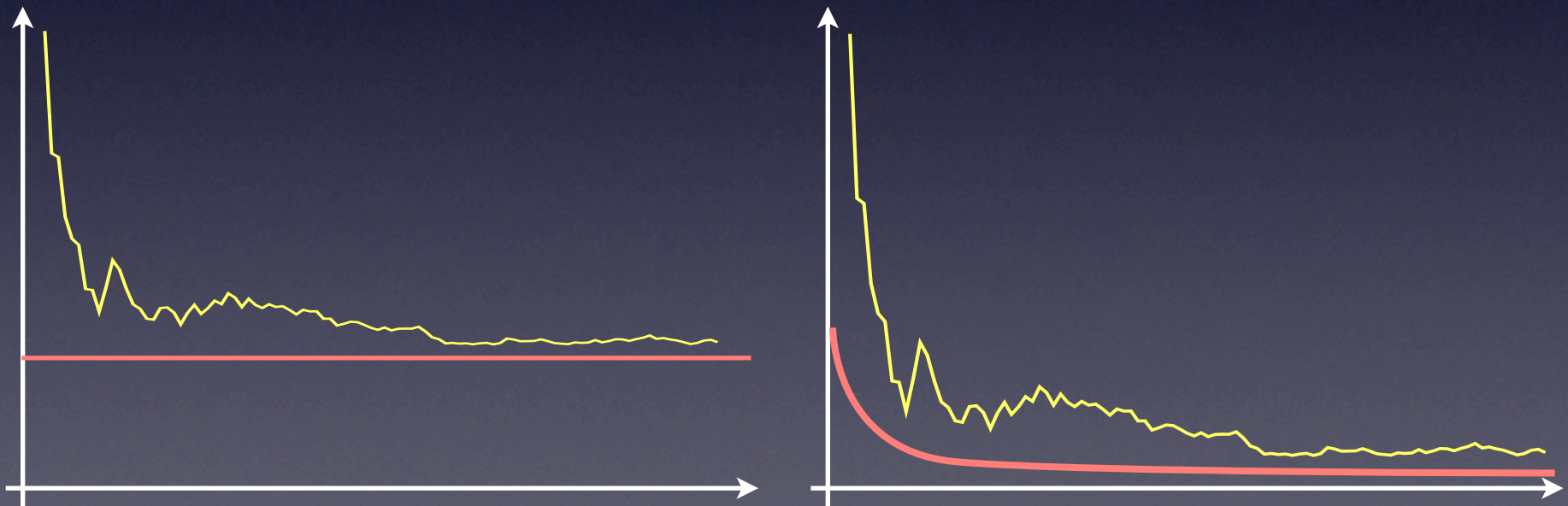
- Progressive Photon Mapping [Hachisuka et al. 08]



Error in Biased Methods

- Error estimation in biased methods is challenging

$$E_i = ?$$



Related Work

Related Work

- Variance-based estimation for unbiased methods
[Lee et al. 85][Purgathofer 87][Tamstorf et al. 97]

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[Myszkowski 97][Schregle 03]

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- Heuristic error estimation
[Walter 98]

Contribution

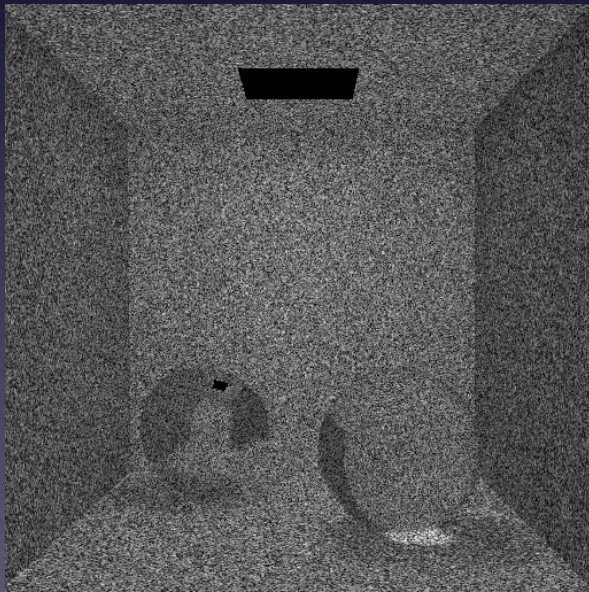
Error estimator for photon density estimation

Method

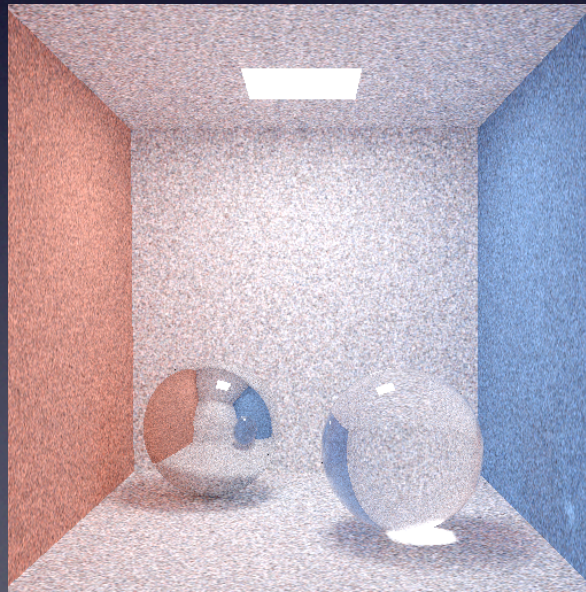
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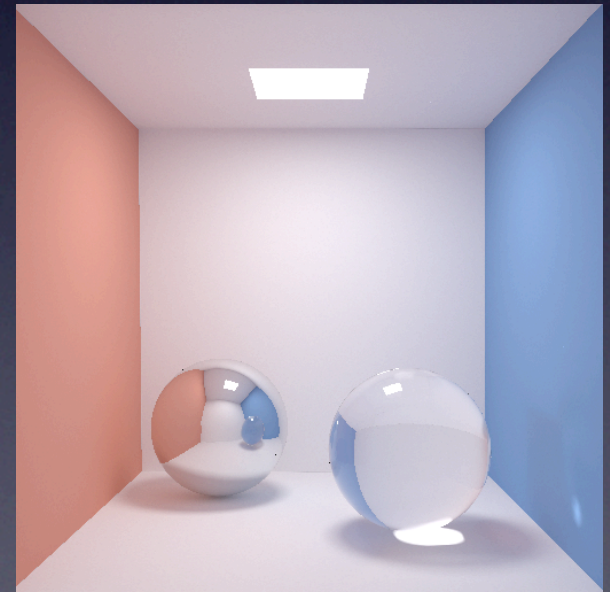
$$E_i = L_i - L$$



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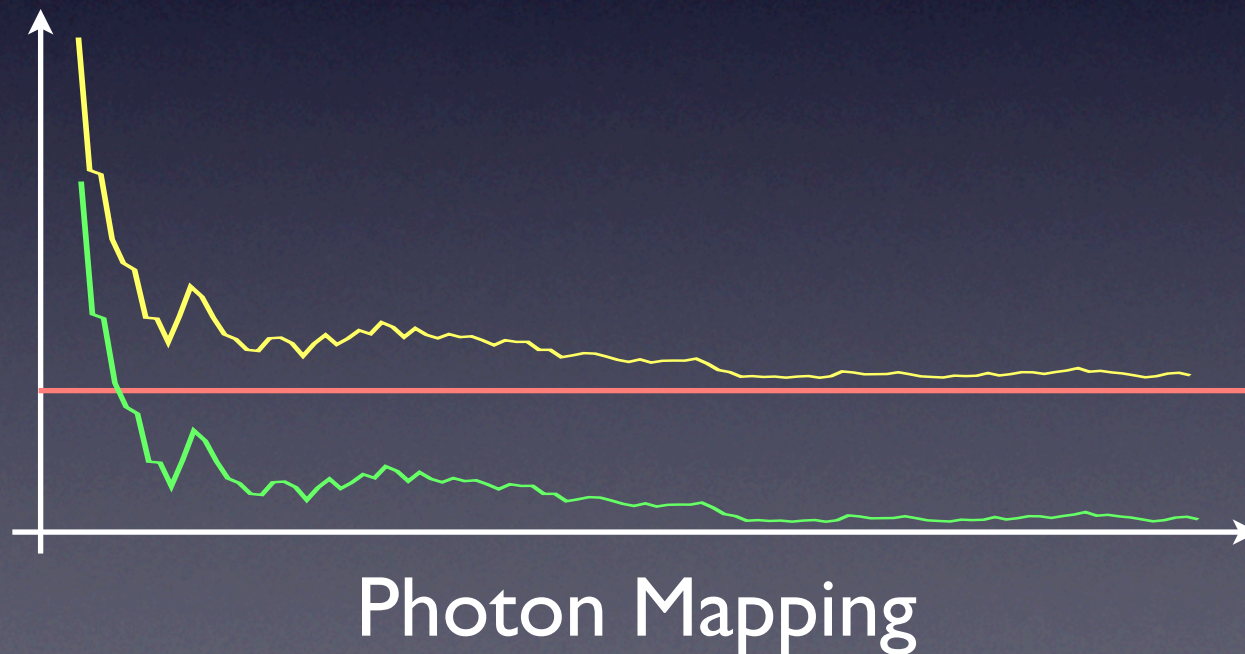
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Error in Biased Methods

- **Bias-Noise** decomposition

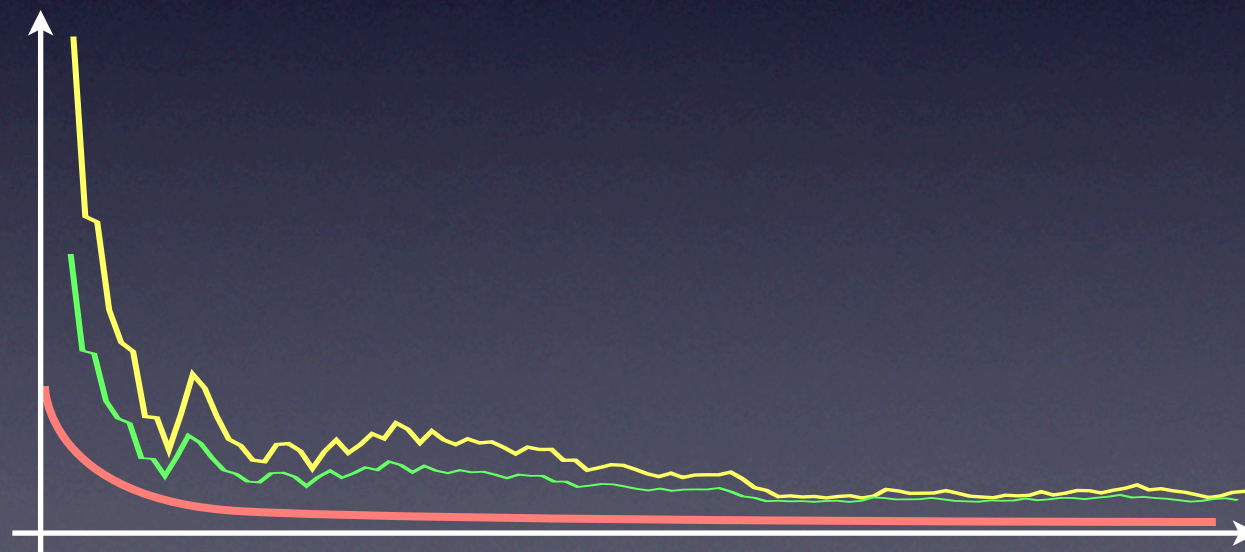
$$E_i = L_i - L = B_i + N_i$$



Error in Biased Methods

- **Bias-Noise** decomposition

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Progressive Photon Mapping

Error Estimation in Monte Carlo Methods

- Can we estimate E_i ?

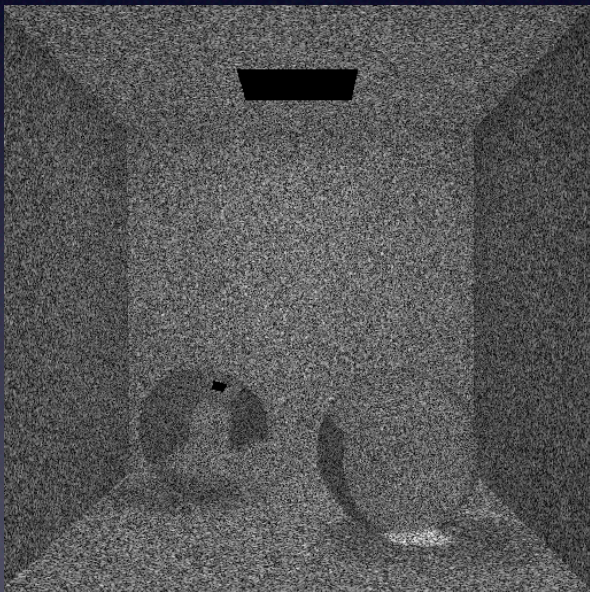
Error Estimation in Monte Carlo Methods

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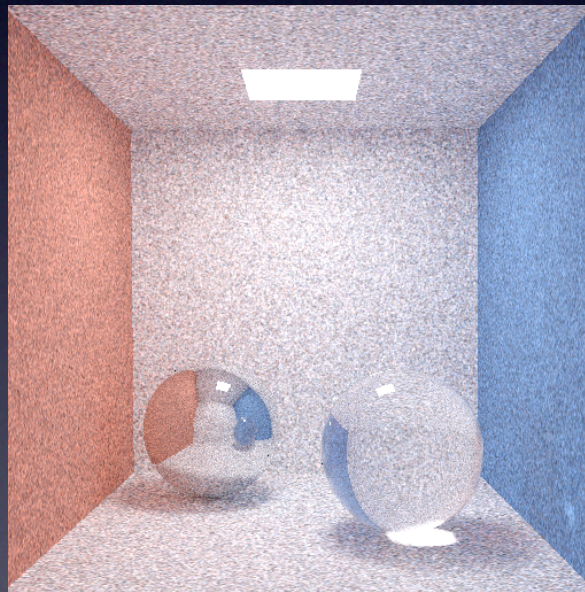
Probably Not

Error Estimation in Monte Carlo Methods

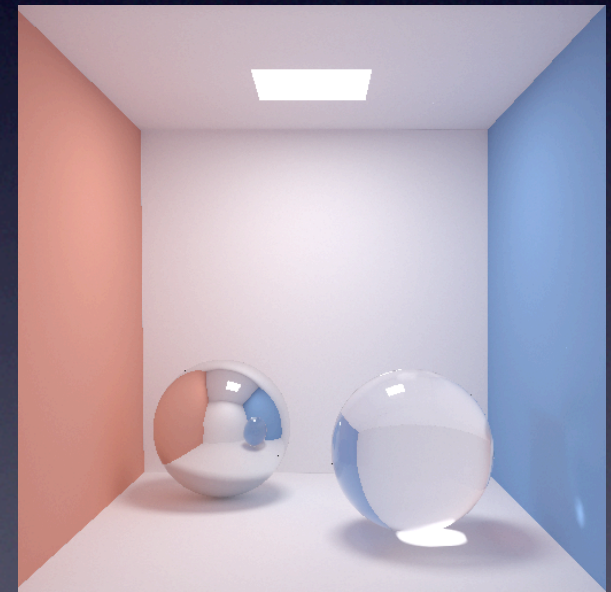
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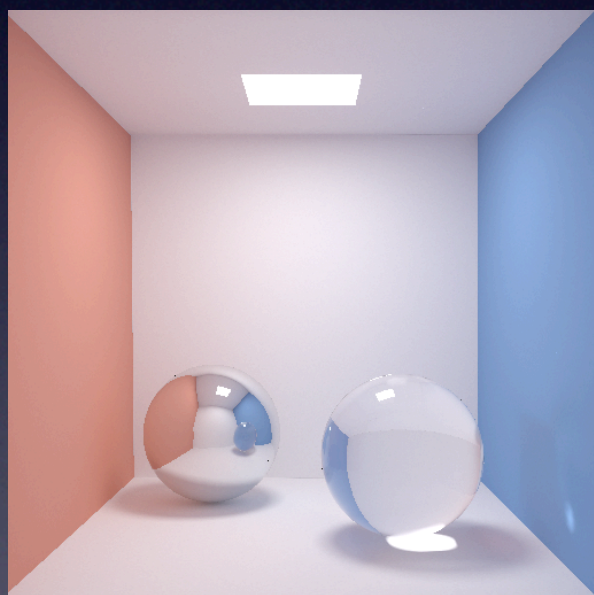


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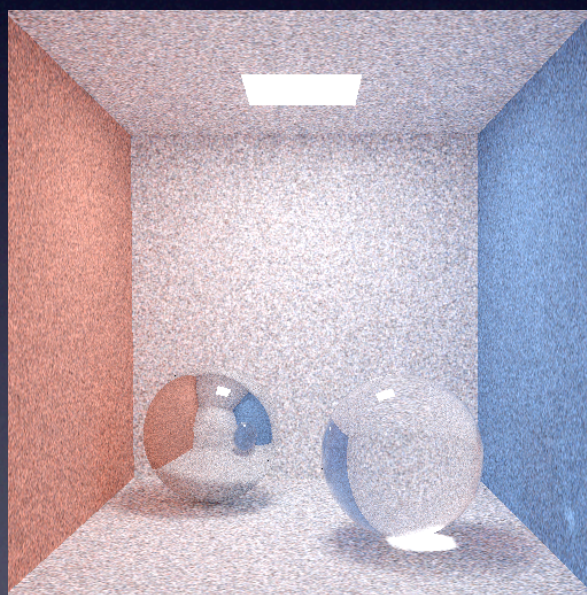


Error Estimation in Monte Carlo Methods

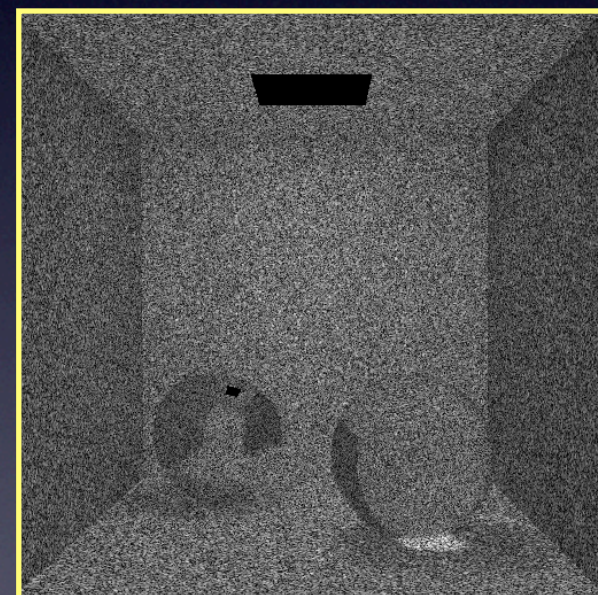
$$L = L_i - \boxed{E_i}$$



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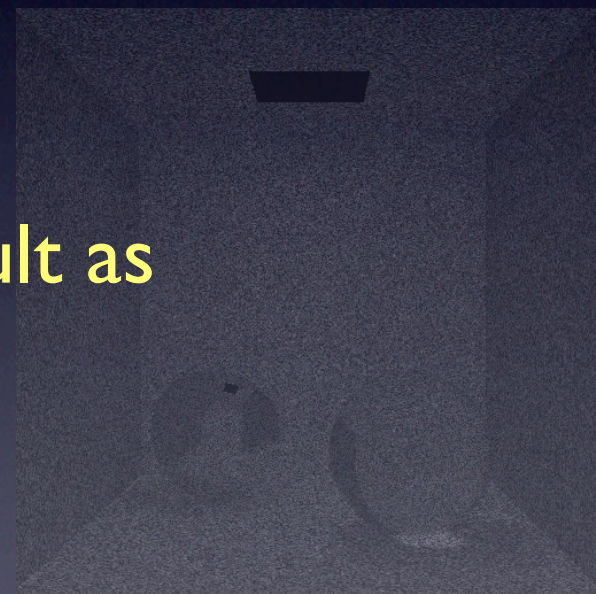
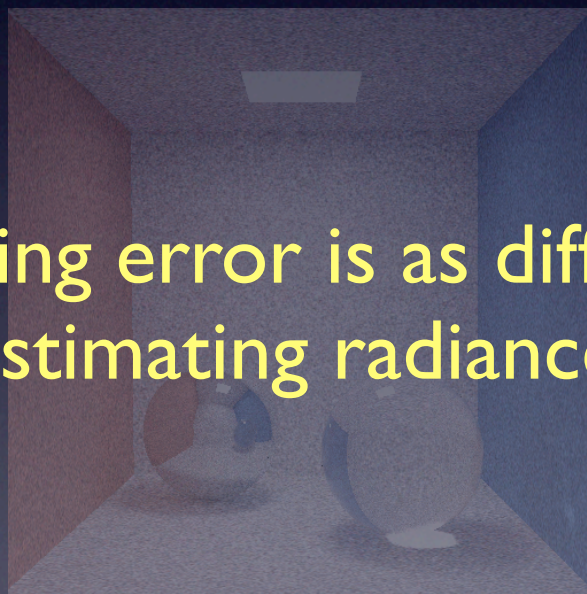
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Error Estimation in Monte Carlo Methods

$$L = L_i - E_i$$

Estimating error is as difficult as estimating radiance



Error Estimation in Monte Carlo Methods

- Can we estimate bounds of E_i ?

$$E_{\min,i} \leq E_i \leq E_{\max,i}$$

Error Estimation in Monte Carlo Methods

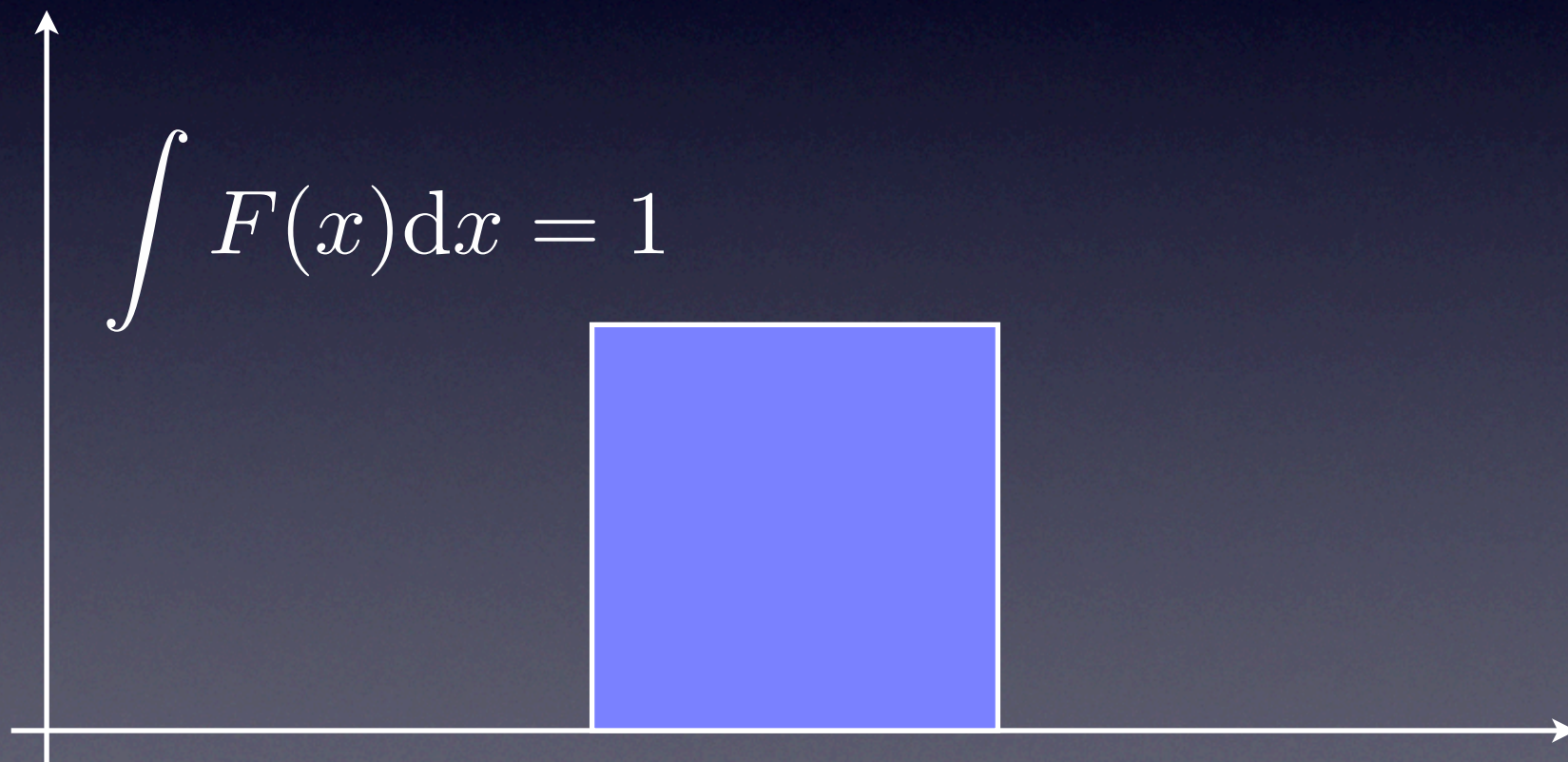
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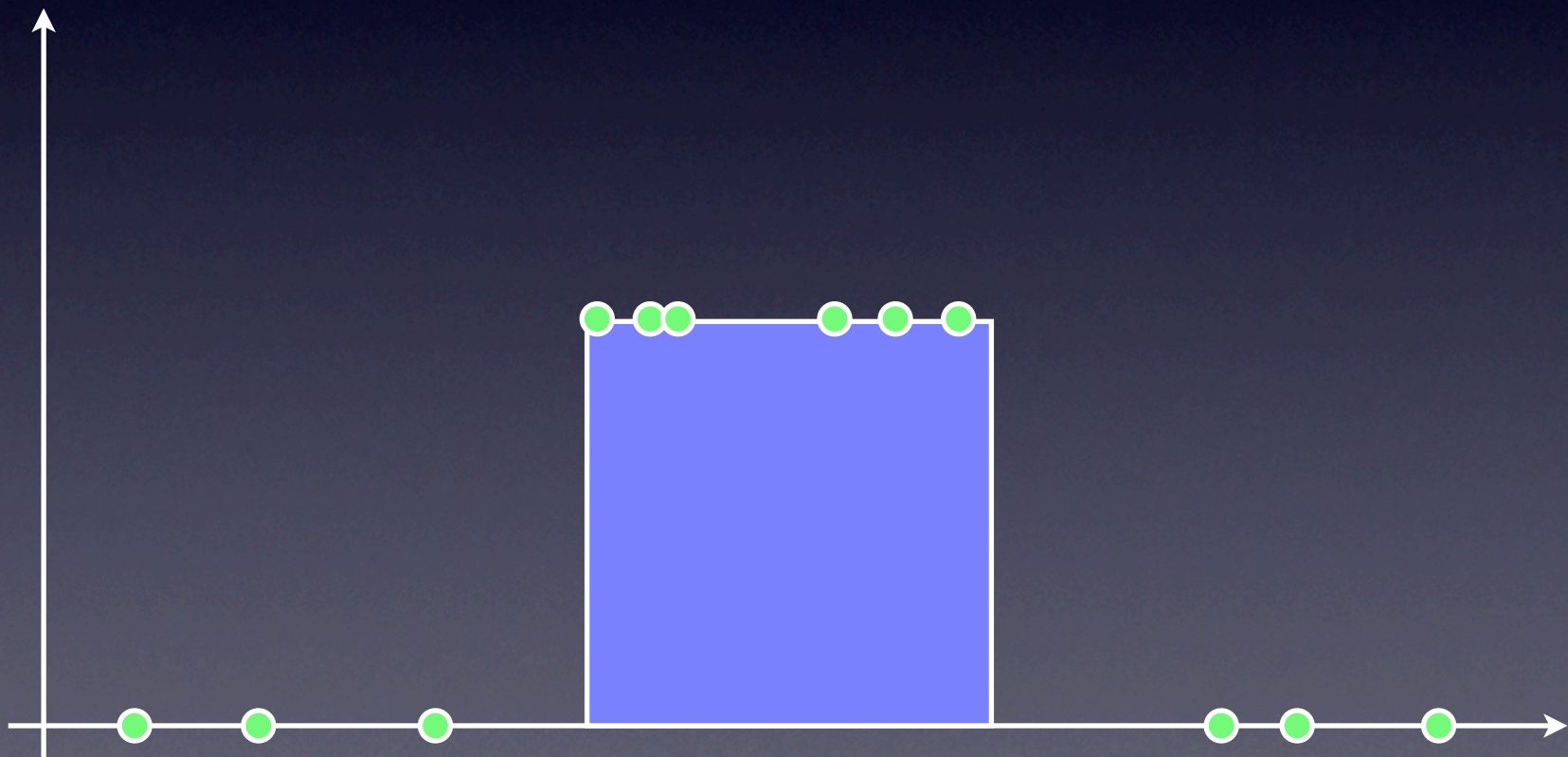
Error Estimation in Monte Carlo Methods

- Integration of a rectangular function



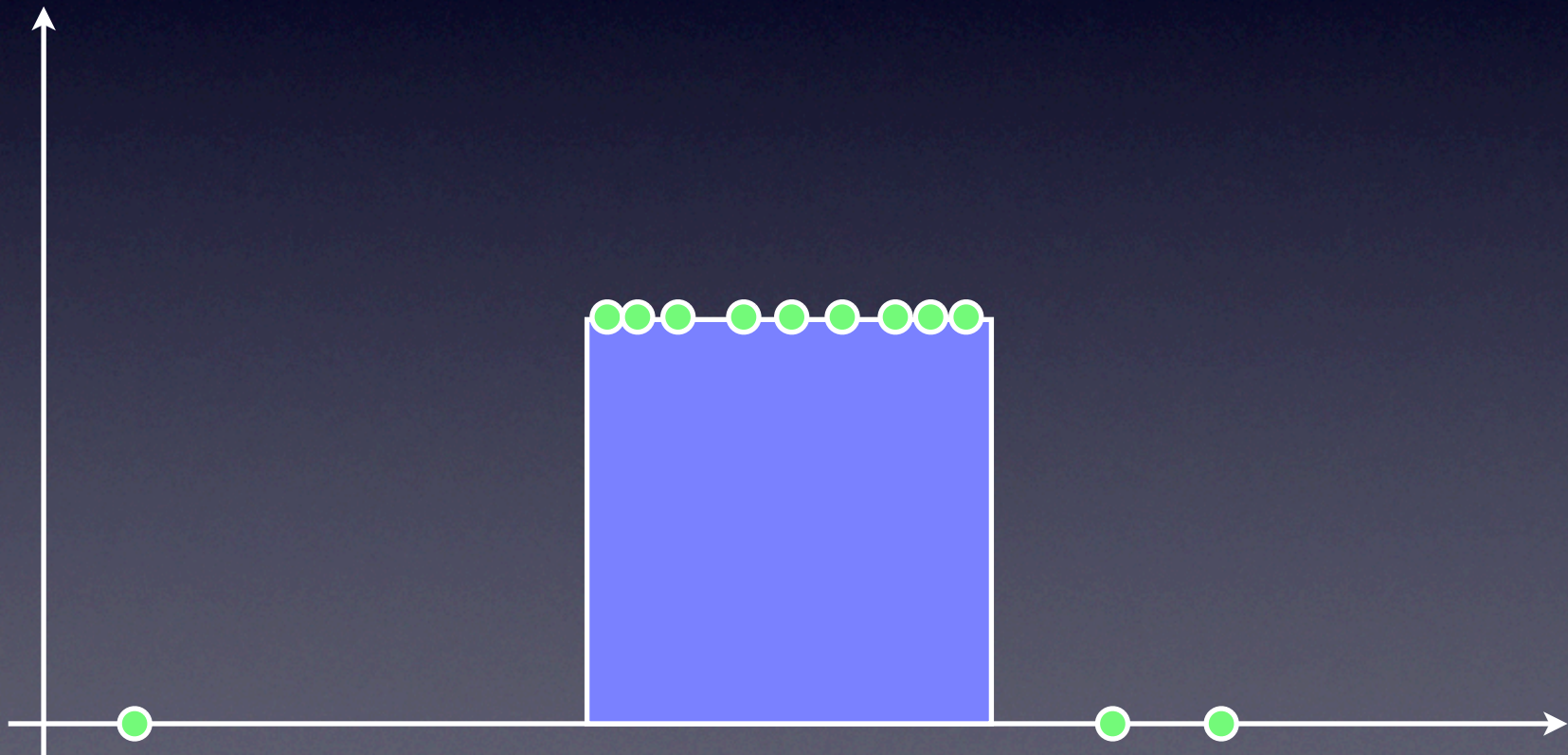
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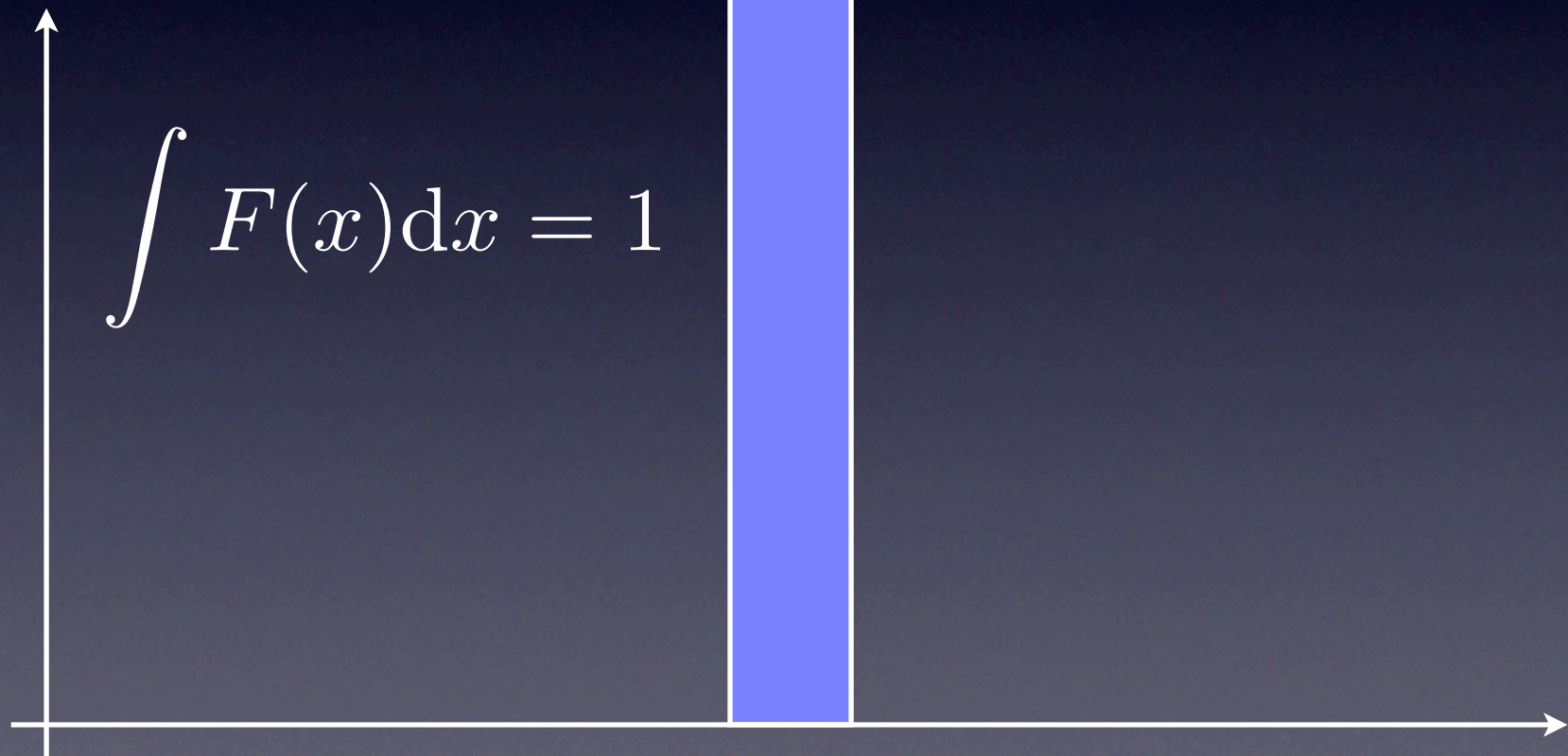
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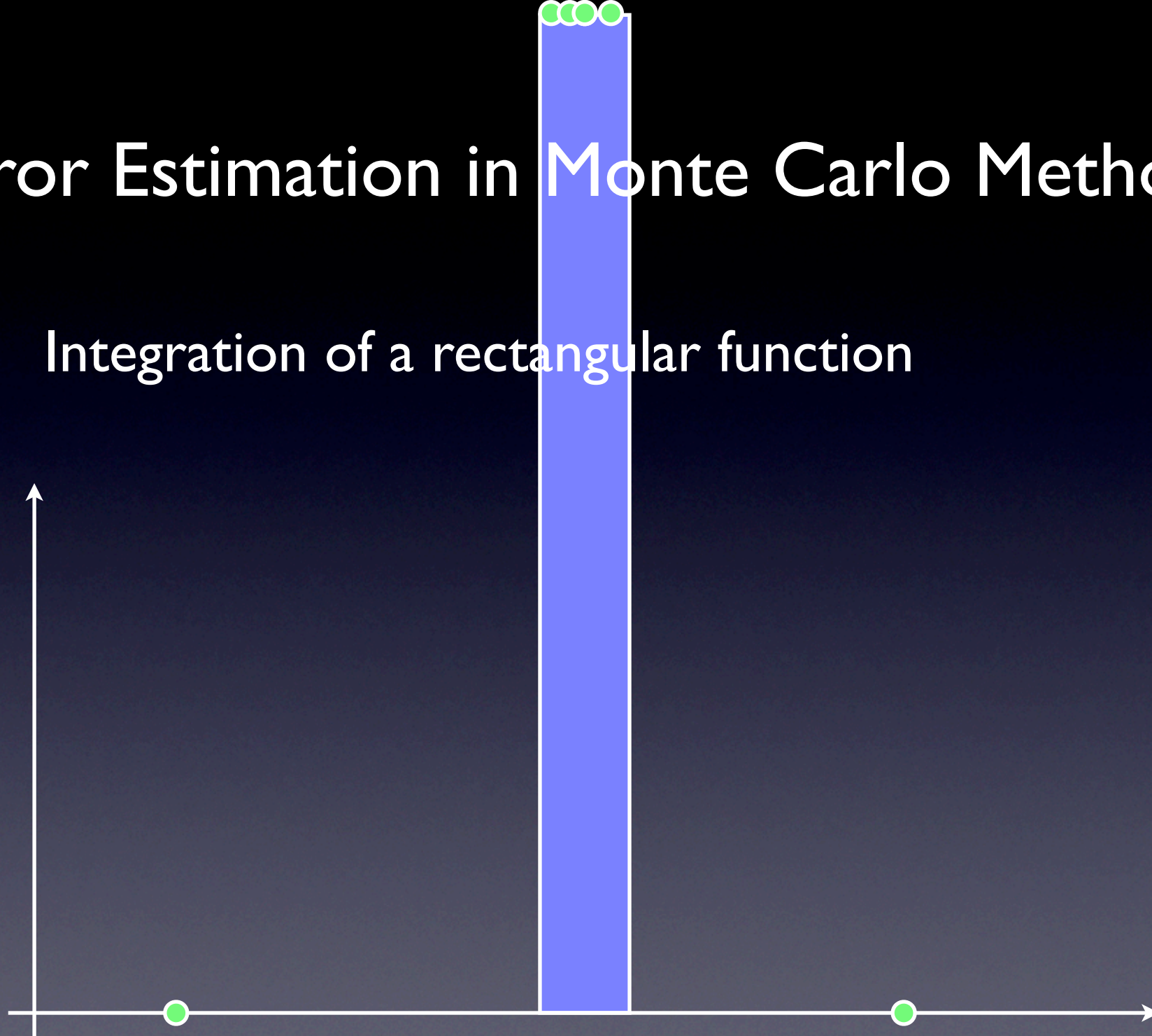
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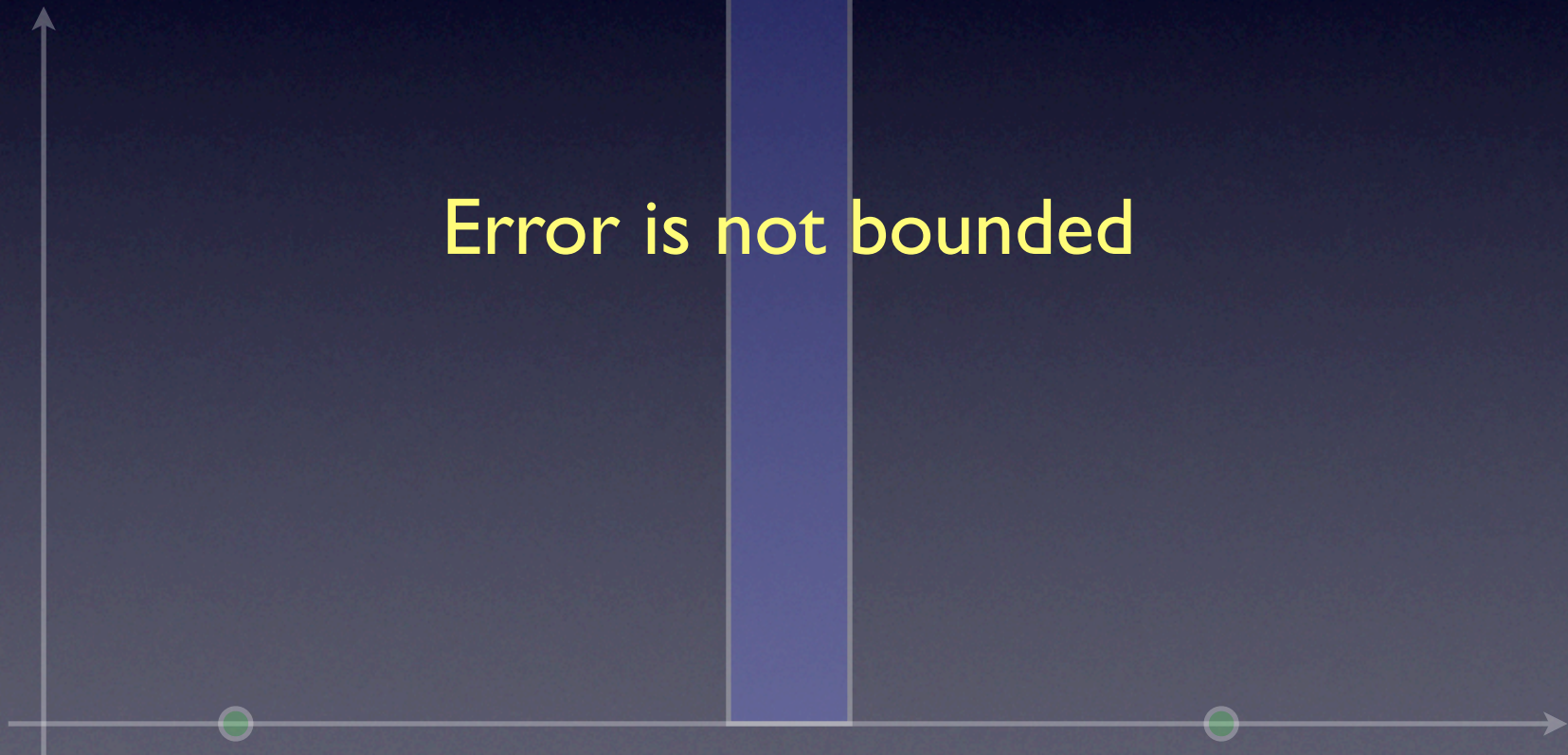
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Error Estimation in Monte Carlo Methods

- Integration of a rectangular function



Error Estimation in Monte Carlo Methods

$$\text{Probability}(E_{\min,i} \leq E_i \leq E_{\max,i}) = 90\%$$

Drop a few cases where

$$E_{\min,i} \leq E_i \leq E_{\max,i}$$

is false

Stochastic Error Bounds

- Bounds that are true with some probability
- Well-known concept in computational statistics

$$P\left(E_{\min,i} \leq E_i \leq E_{\max,i}\right) = 1 - \beta$$

Stochastic error bound User-defined Confidence

Stochastic Error Bound Derivation

$$L_i - L = E_i = B_i + N_i$$

Stochastic Error Bound Derivation

- Subtract bias

$$L_i - L - B_i = E_i - B_i = N_i$$

Stochastic Error Bound Derivation

- Noise follows the t-distribution

$$L_i - L - B_i = E_i - B_i = N_i$$

$$P(-N_b \leq N_i \leq N_b) = 1 - \beta$$

$$N_b = C_{i, 1 - \frac{\beta}{2}} \sqrt{\frac{\text{Variance}}{i}}$$

Stochastic Error Bound Derivation

- Add back bias

$$L_i - L = E_i = B_i + N_i$$

$$P(-N_b + B_i \leq E_i \leq N_b + B_i) = 1 - \beta$$

$$N_b = C_{i, 1 - \frac{\beta}{2}} \sqrt{\frac{\text{Variance}}{i}}$$

Stochastic Error Bound Derivation

- Take the absolute value

$$L_i - L = E_i = B_i + N_i$$

$$P(|E_i| \leq |N_b| + |B_i|) \leq 1 - \beta$$

$$N_b = C_{i, 1 - \frac{\beta}{2}} \sqrt{\frac{\text{Variance}}{i}}$$

Stochastic Error Bound Derivation

$$L_i - L = E_i = B_i + N_i$$

Stochastic error bound

User-defined
Probability

$$P(|E_i| \leq E_{b,i}) \leq 1 - \beta$$

$$E_{b,i} = C_{i,1-\frac{\beta}{2}} \sqrt{\frac{\text{Variance}}{i}} + |B_i|$$

Stochastic Error Bound Derivation

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Error due to Noise

Stochastic Error Bound Derivation

$$L_i - L = E_i = B_i + N_i$$

$$P(|E_i| \leq E_{b,i}) \leq 1 - \beta$$

$$E_{b,i} = C_{i,1-\frac{\beta}{2}} \sqrt{\frac{\text{Variance}}{i}} + \boxed{|B_i|}$$

Error due to Bias

Challenges

$$E_{b,i} = C_{i,1-\frac{\beta}{2}} \sqrt{\frac{\text{Variance}}{i}} + |B_i|$$

- B_i (bias) is unknown

Challenges

$$E_{b,i} = C_{i,1-\frac{\beta}{2}} \sqrt{\frac{\text{Variance}}{i}} + |B_i|$$

- B_i (bias) is unknown
- Variance estimation assumes i.i.d.
 - independent and identically distributed
 - not true in progressive photon mapping

Bias Estimation

- B_i (bias) is unknown
- Well-known approximation [Silverman 86]

$$B_i \approx k_2 R_i^2 \Delta L$$

k_2 constant

R_i search radius

ΔL Laplacian of radiance

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k_2 constant

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Unknown

Radiance Derivative Estimation

- Kernel-based estimation of Laplacian

$$L_i(x) = \frac{\sum \overset{\text{Kernel}}{\boxed{K(x_p - x)}} f_r(x, \omega, \omega_p) \Phi(x_p, x)}{\pi R_i^2}$$

Radiance Derivative Estimation

- Kernel-based estimation of Laplacian

Laplacian of the kernel

$$\Delta L_i(x) = \frac{\sum \Delta K(x_p - x) f_r(x, \omega, \omega_p) \Phi(x_p, x)}{\pi R_i^2}$$

Radiance Derivative Estimation

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Extended to progressive photon mapping

Radiance Derivative Estimation

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Extended to progressive photon mapping

- Applicable to any order

Radiance Derivative Estimation

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Laplacian of the kernel

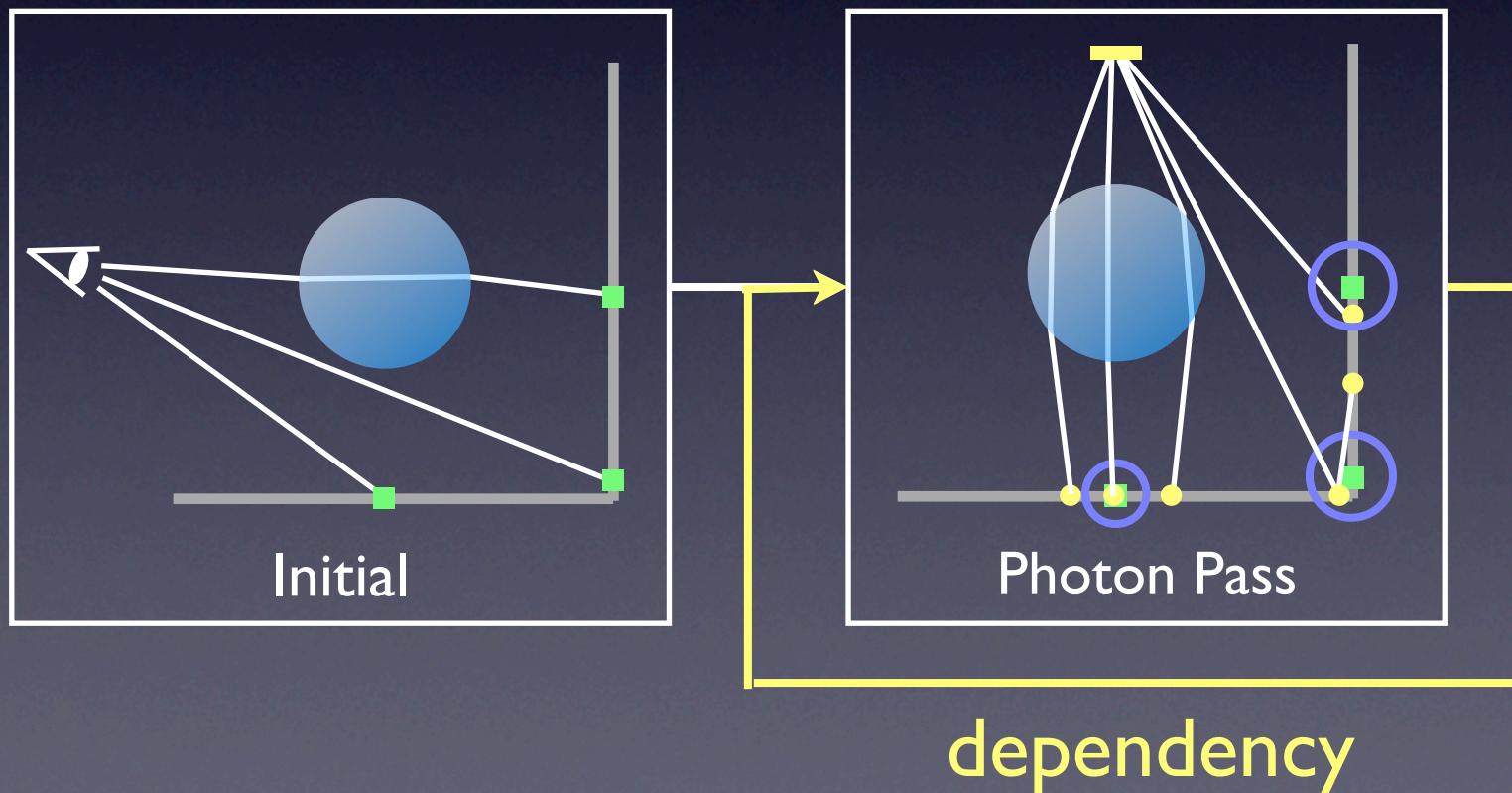
$$\Delta L_i(x) = \frac{\sum \Delta K(x_p - x) f_r(x, \omega, \omega_p) \Phi(x_p, x)}{\pi R_i^2}$$

Extended to progressive photon mapping

- Applicable to any order
- Convergent

Variance Estimation

- Variance estimation assumes i.i.d.
- not true in progressive photon mapping



Variance Estimation

- Two key observations
 - Photon tracing itself is independent
 - Dependency is only in radius reduction

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Bias-corrected radiance

$$L'_i = L_i - B_i$$

$$\text{Variance} \approx \frac{\sum L_i'^2 - \frac{(\sum L_i')^2}{i}}{i - 1}$$

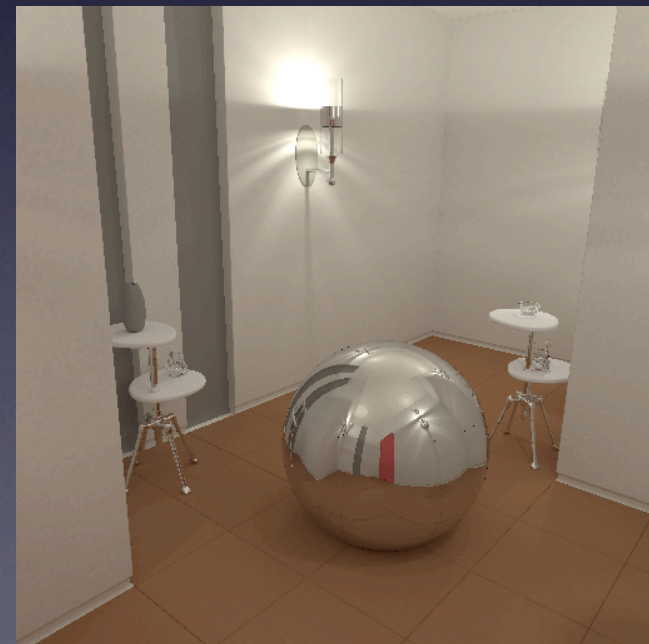
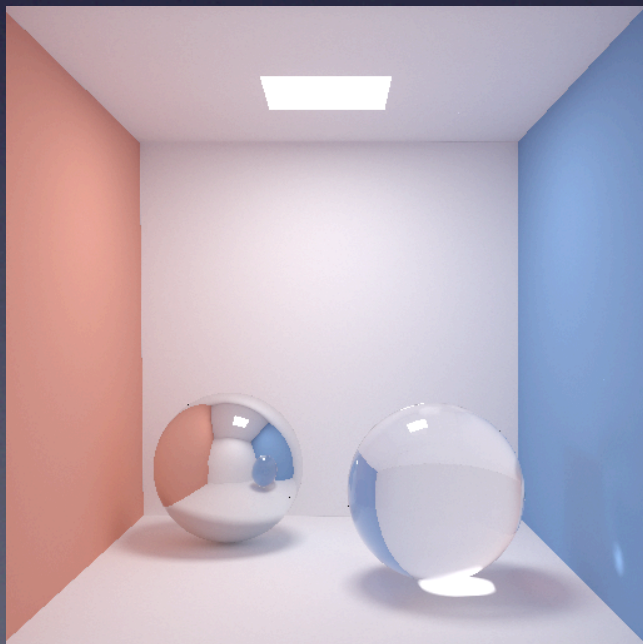
Key Points

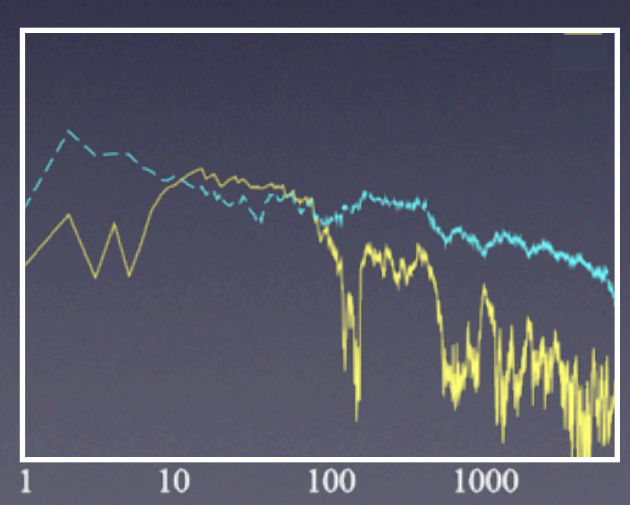
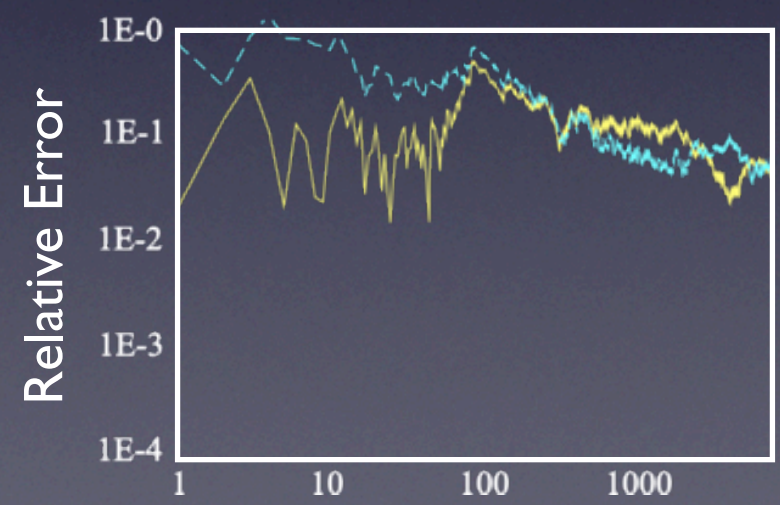
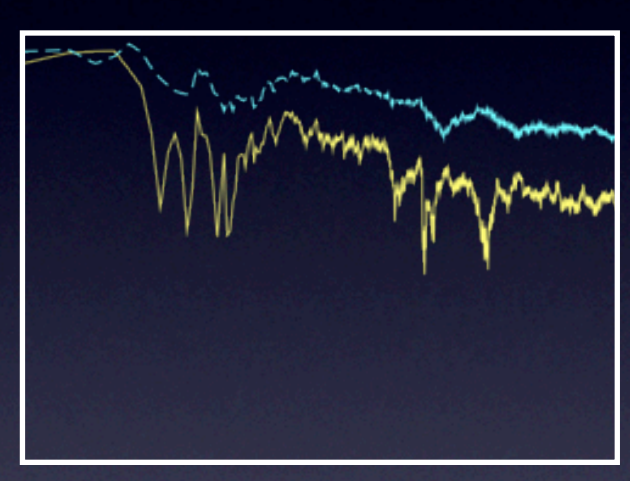
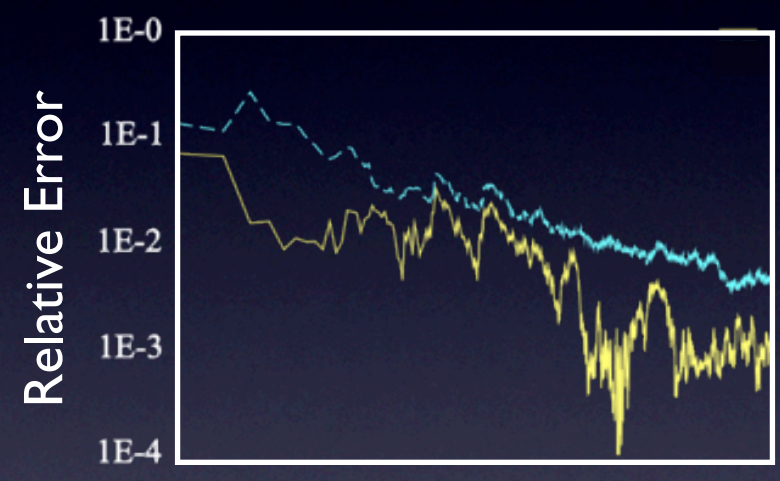
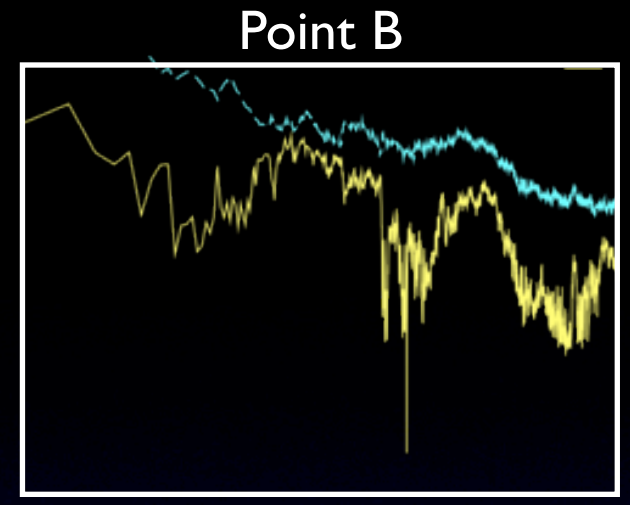
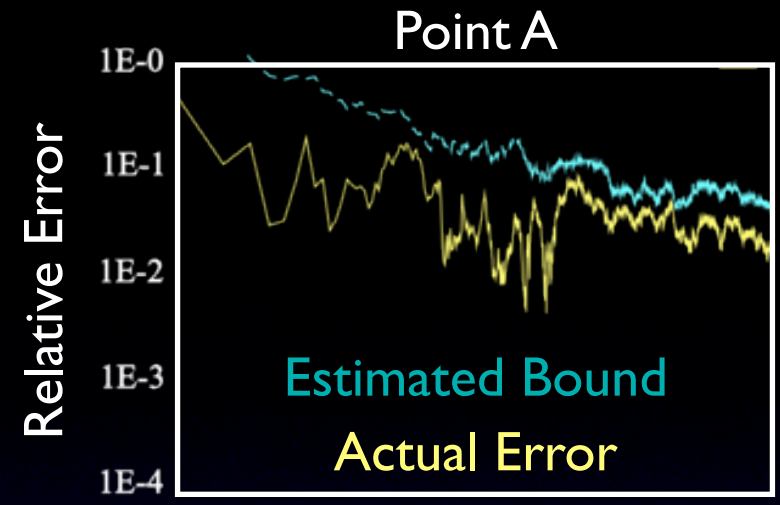
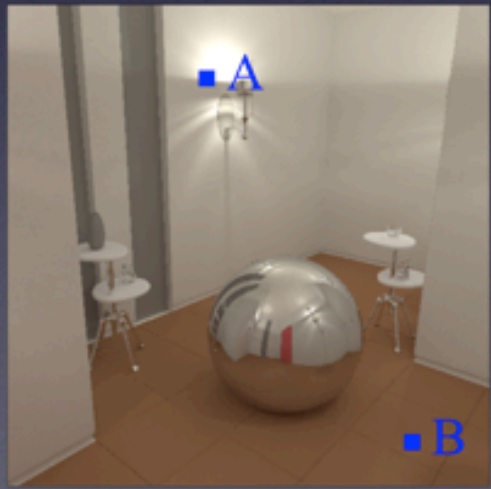
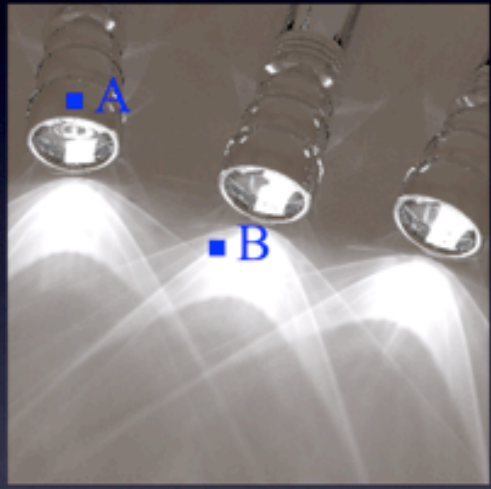
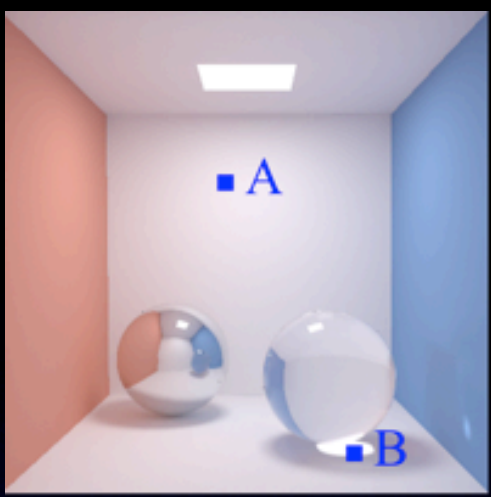
- Approximate stochastic error bounds
- Convergent derivative estimator
- Bias/Noise estimators valid for PPM

Results

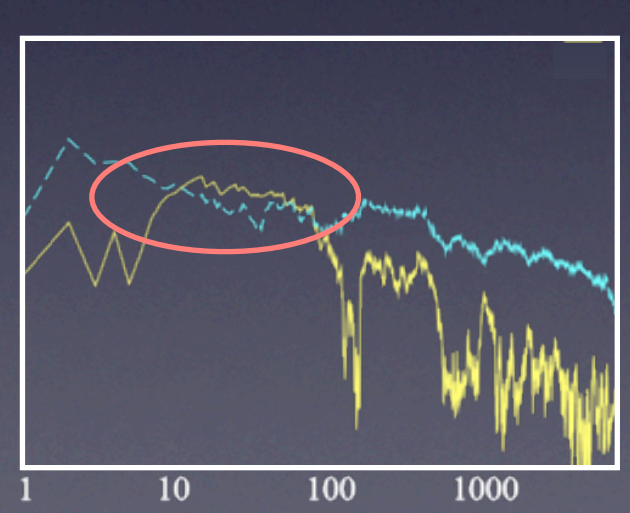
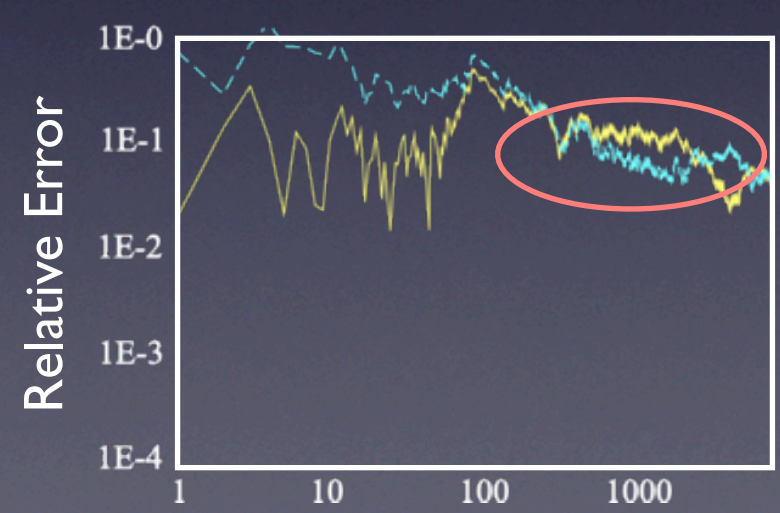
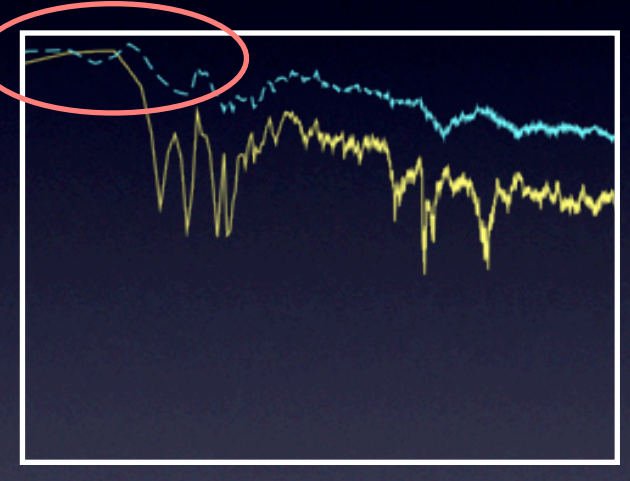
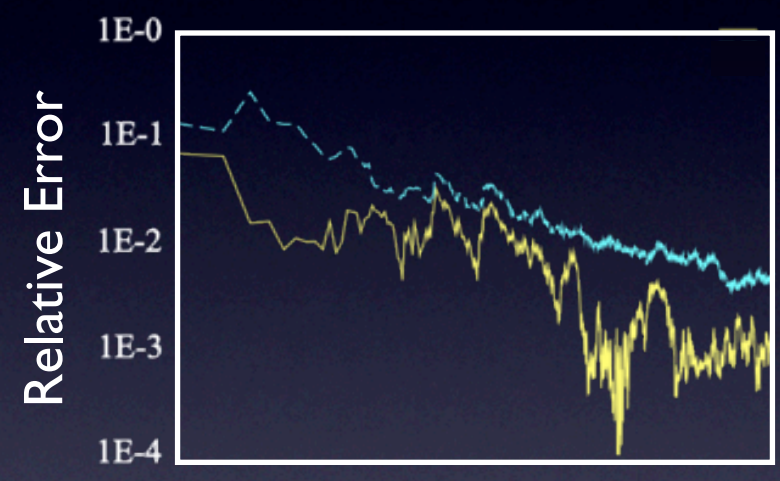
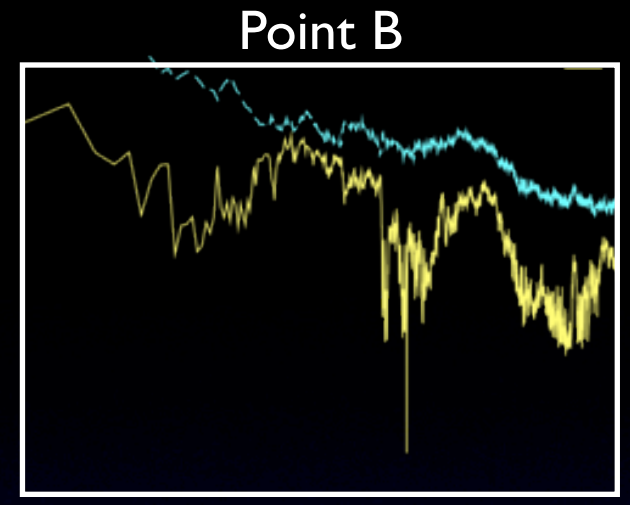
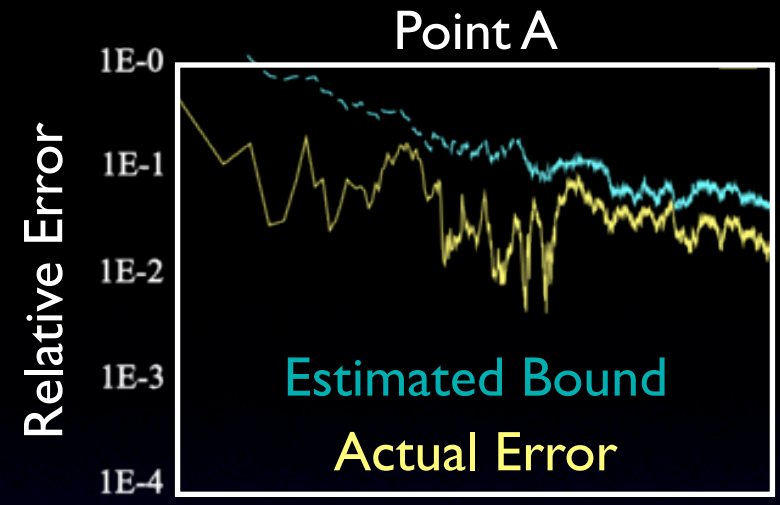
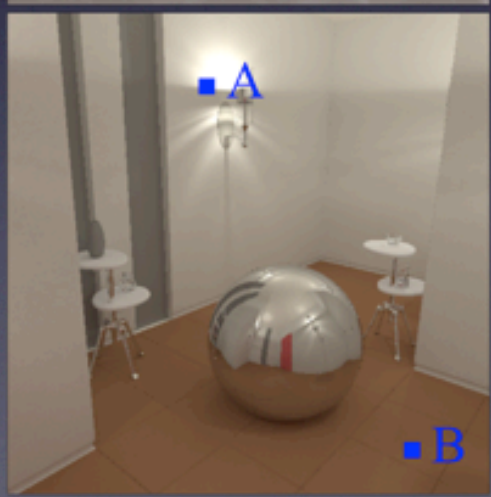
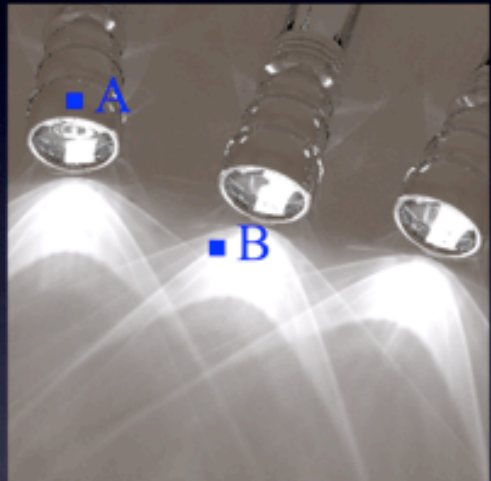
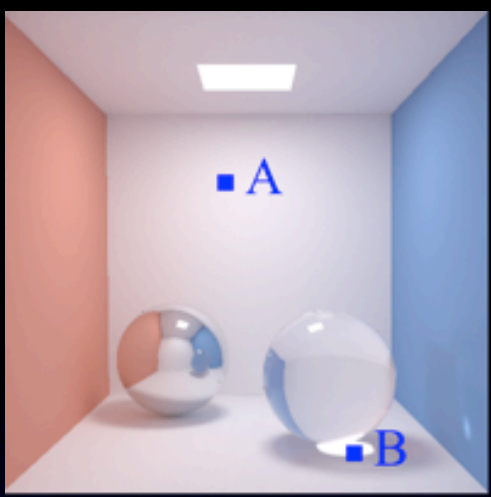
Experiments Setup

- Progressive Photon Mapping [Hachisuka et al. 08]
- 15k photons per pass
- Three test scenes with full global illumination





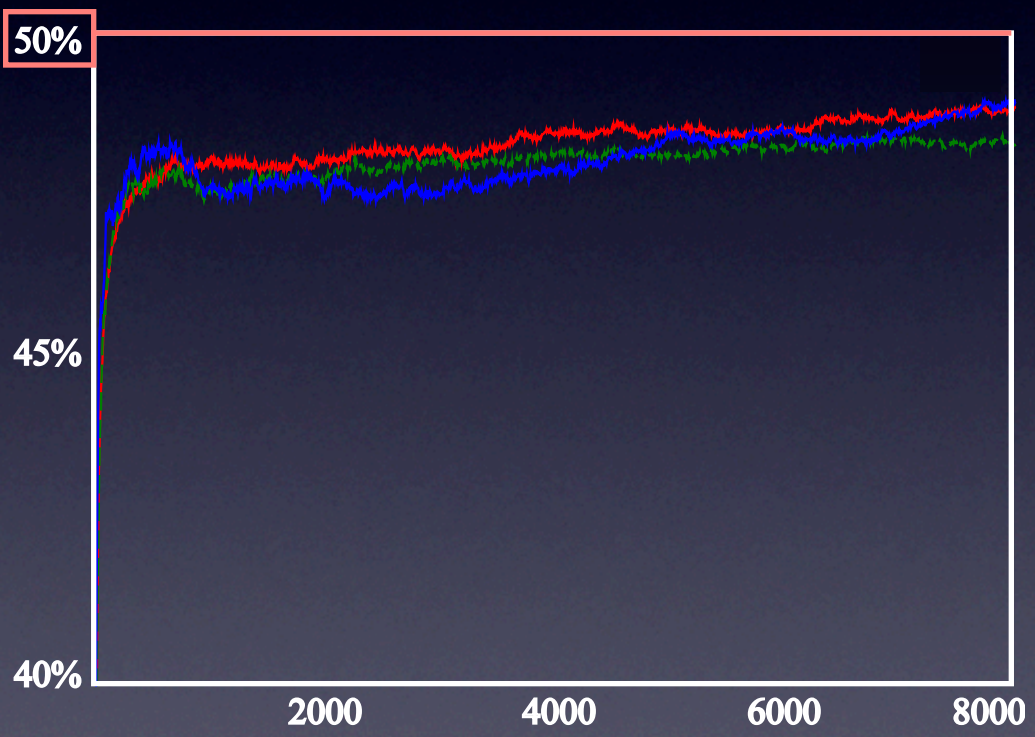
Number of Passes



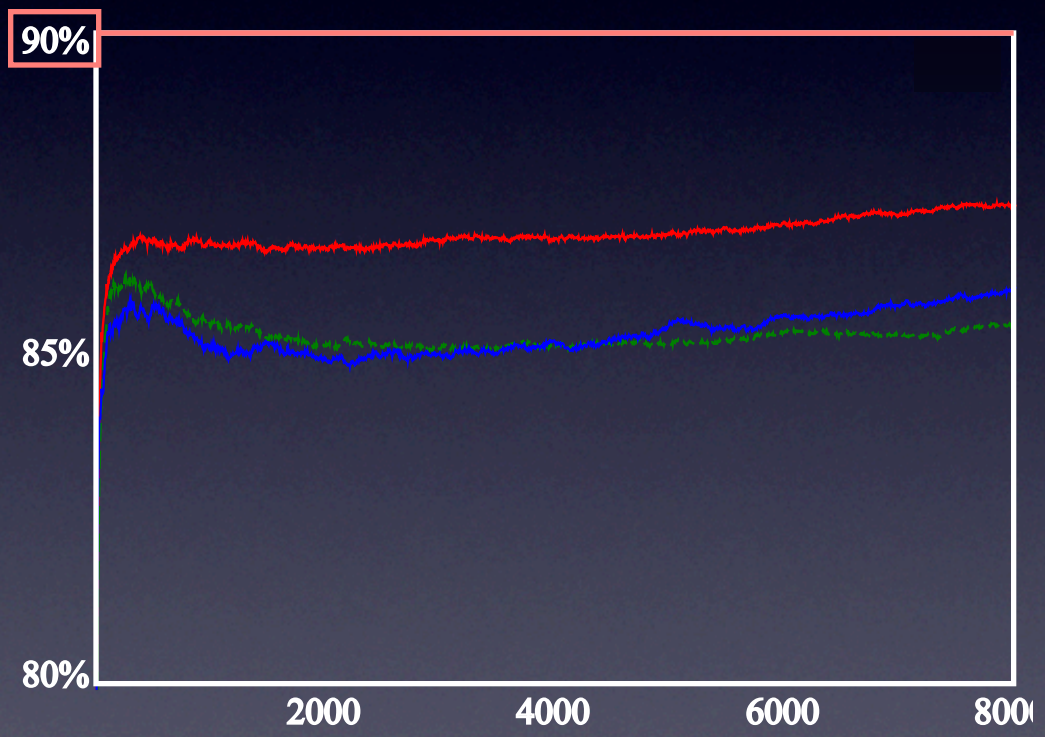
Number of Passes

Calculated Probability of Bounds

$$P(|E_i| \leq E_{b,i}) \leq 1 - \beta$$



$1 - \beta = 50\%$

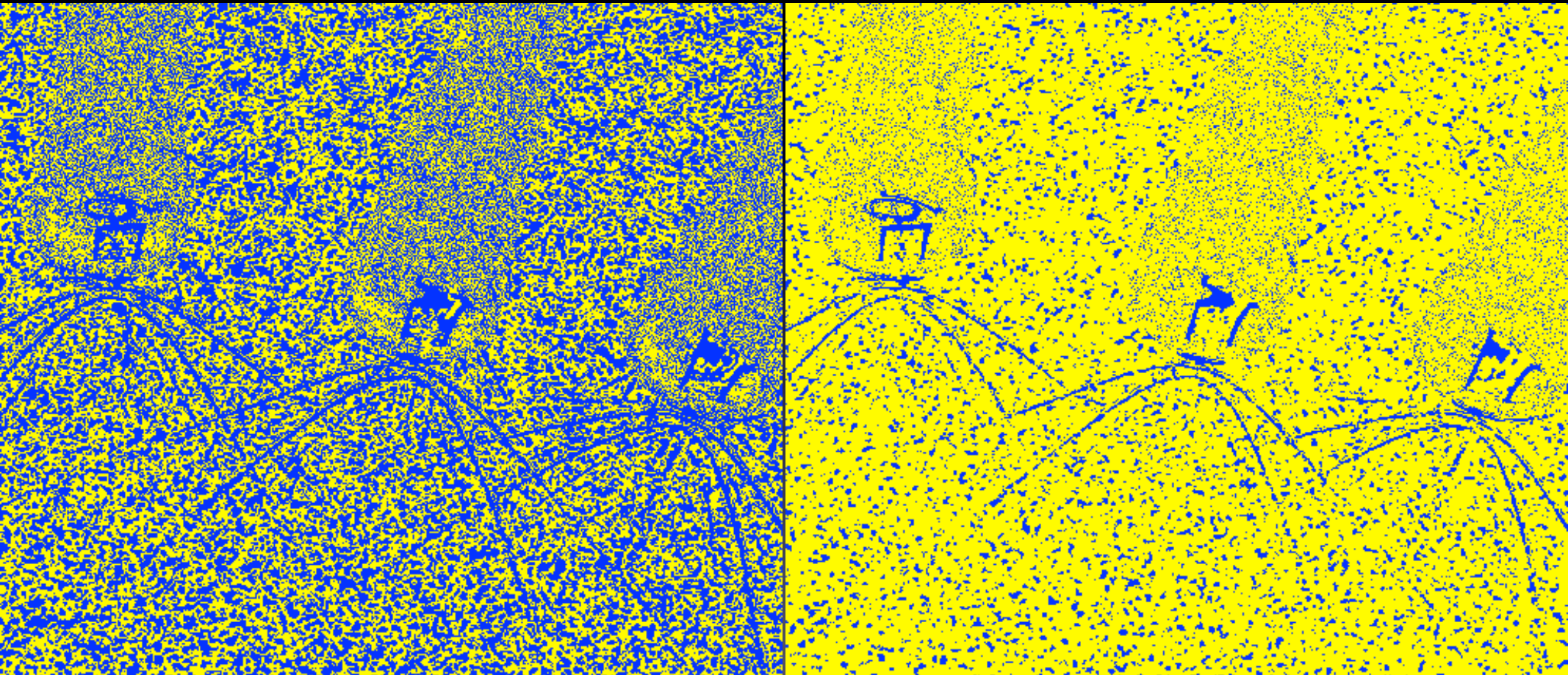


$1 - \beta = 90\%$

within 5% deviation

Bounded Pixel Visualization

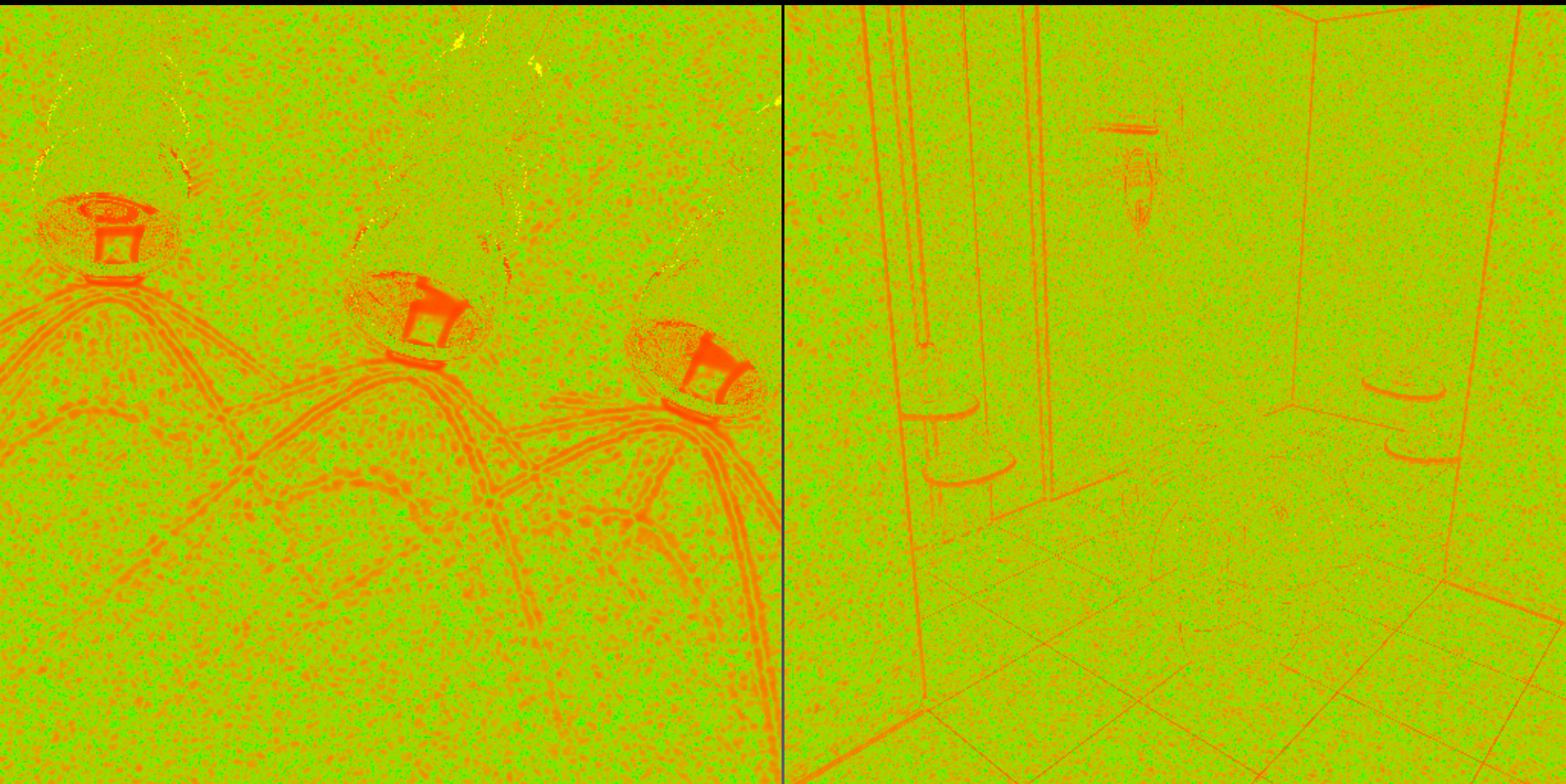
Bounded/Not bounded



$1 - \beta = 50\%$

$1 - \beta = 90\%$

Noise-Bias Ratio



Automatic Rendering Termination

Stochastic Bound Per Pixel (50%)

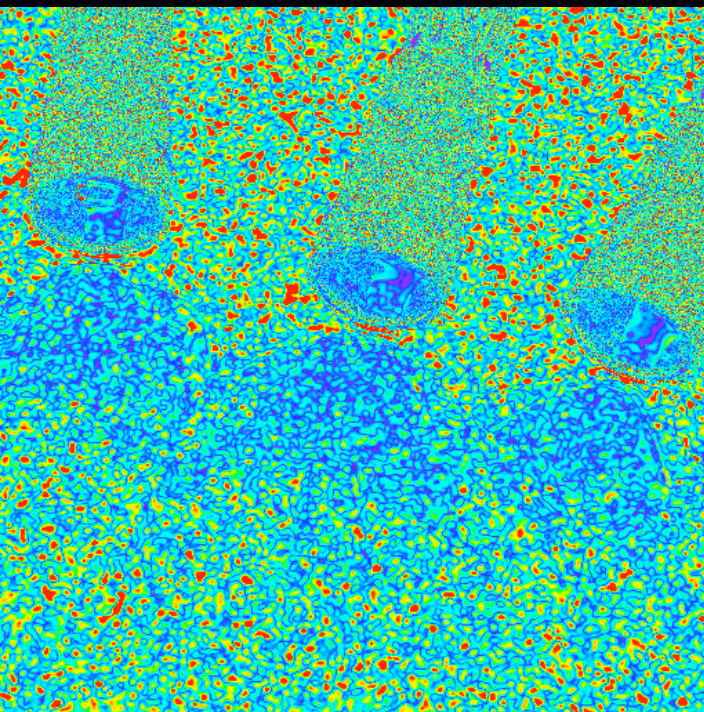
$$P(|E_i| \leq E_{b,i}) \leq 50\%$$

Stop rendering if

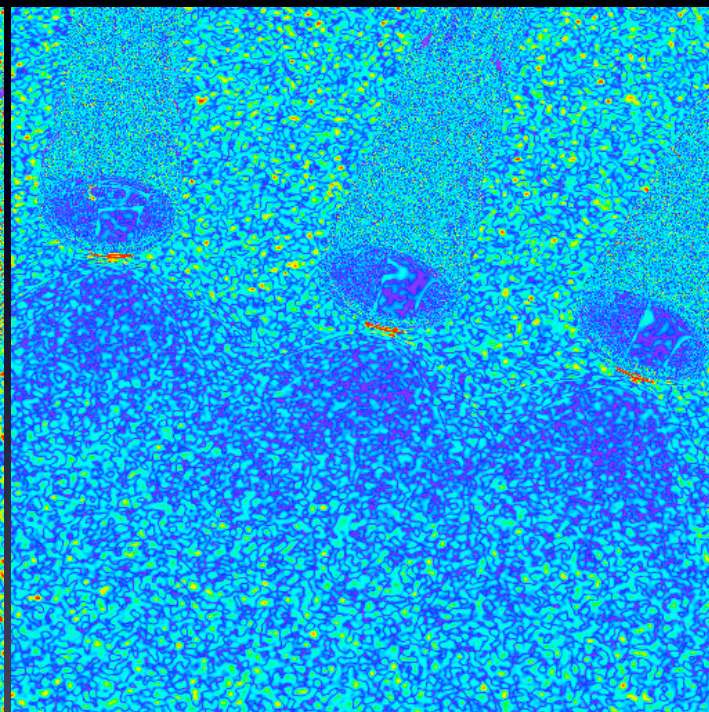
$$\text{Average}[E_{b,i}] < \boxed{E_{\text{thr}}}$$

User-specified
allowable error

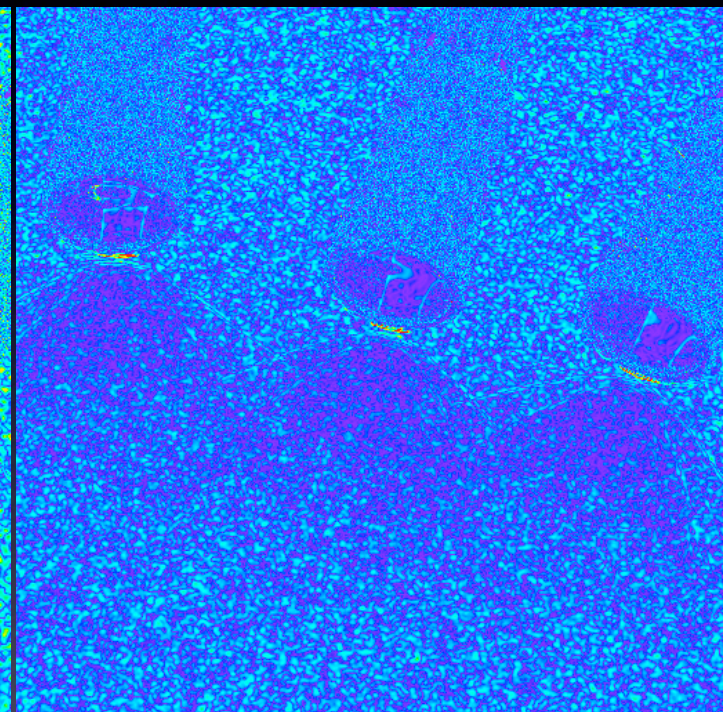
Automatic Rendering Termination



specified: 0.25
actual: 0.1916



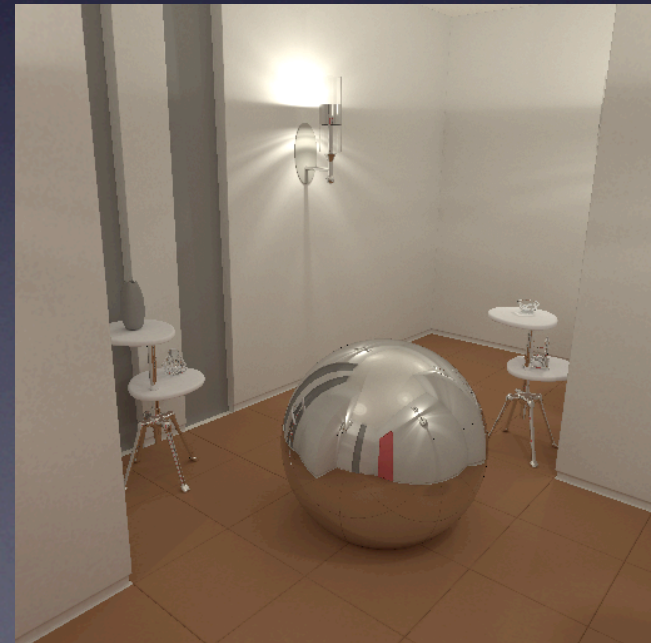
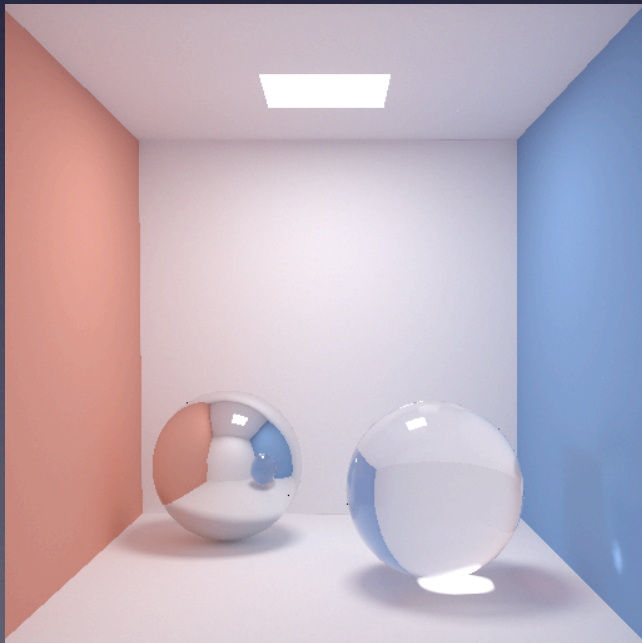
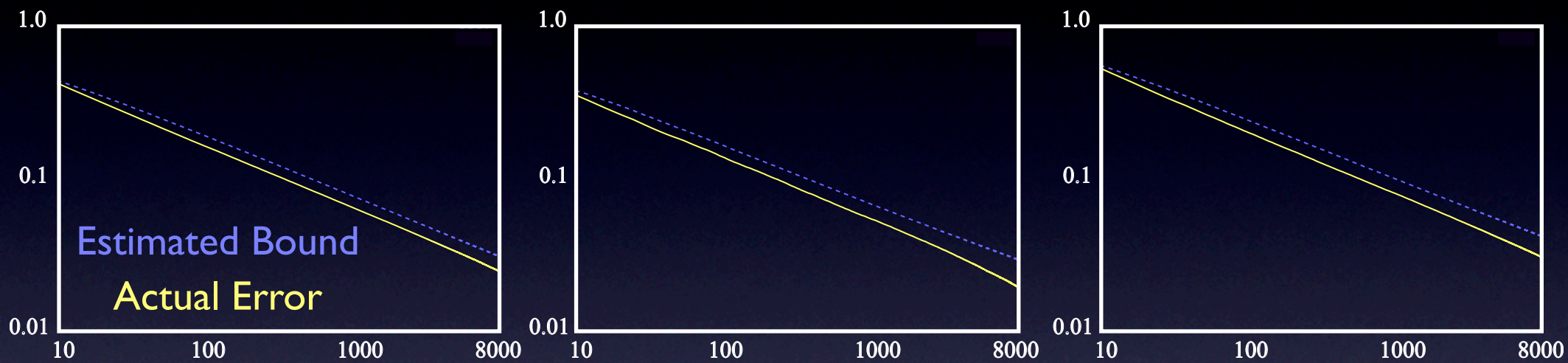
specified: 0.125
actual: 0.09294



specified: 0.0625
actual: 0.04482

1.3 times overestimation on average

Automatic Rendering Termination



Future Work

- Various applications of error estimates

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 - ... and many more
- Extension to stochastic PPM [Hachisuka et al. 09]
- More accurate bias estimation

Conclusion

- Error estimation for photon density estimation
 - General and non-heuristic (gives an error-bar)
 - Estimator applies to progressive photon mapping

Conclusion

- Error estimation for photon density estimation
 - General and non-heuristic (gives an error-bar)
 - Estimator applies to progressive photon mapping
- Take-home message:
 - First step toward answering:
“How many photons are enough?”

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Thank You

