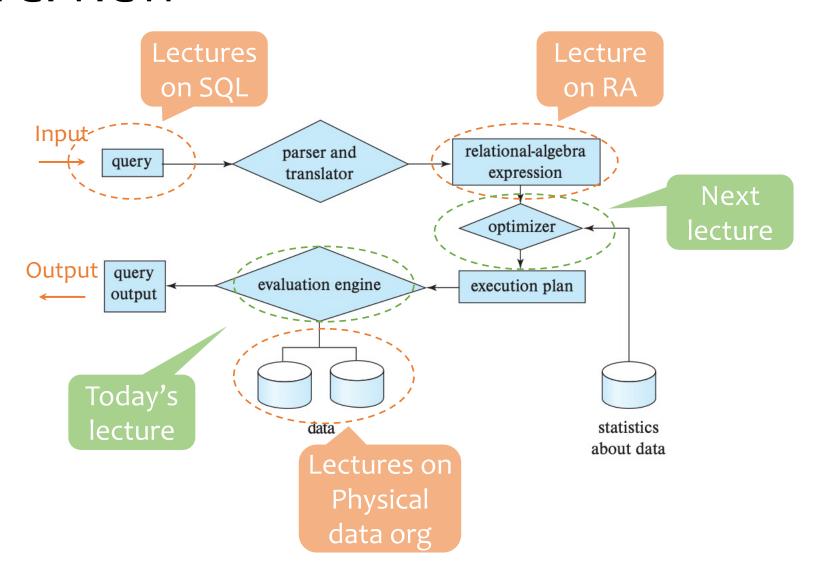
# Query Processing

CS348 Spring 2023

Instructor: Sujaya Maiyya

Sections: 002 & 004 only

#### Overview



## Overview (cont.)

- Many different ways of processing the same query
  - Scan? Sort? Hash? Use an index?
  - All have different performance characteristics and/or make different assumptions about data
- Best choice depends on the situation
  - Implement all alternatives
  - Let the query optimizer choose at run-time (next lecture)

#### Outline Number of memory blocks available: M Scan u1, u2 select \* from User where pop =0.8 u3,u4 Memory select \* from User, Member where • Index User.uid = Member.uid; Sort Member User **U1** m<sub>1</sub> Disk **u**2 m2 Hash (Optional) Number of rows for a table | *Users* | Number of disk blocks for a table $B(Users) = \frac{|Users|}{\# of \ rows \ per \ block}$

#### Notation

- Relations: R, S
- Tuples: *r*, *s*
- Number of tuples: |R|, |S|
- Number of disk blocks: B(R), B(S)
- Number of memory blocks available: M
- Cost metric
  - Number of I/O's
  - Memory requirement

## Scanning-based algorithms

#### Table scan

Scan table R and process the query

Selection over R

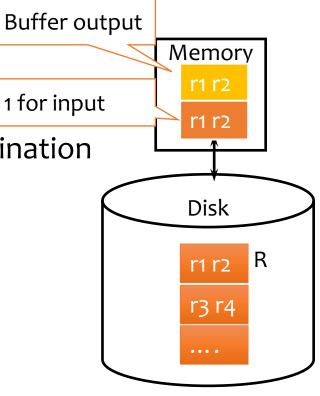
Projection of R without duplicate elimination

• I/O's: *B*(*R*)

Trick for selection:

stop early if it is a lookup by key

- Memory requirement: 2 (blocks)
  - 1 for input, 1 for buffer output
  - Increase memory does not improve I/O
- Not counting the cost of writing the result out
  - Same for any algorithm!



## Basic nested-loop join

```
R\bowtie_{p} S
```

- For each r in a block  $B_R$  of R:

  For each s in a block  $B_S$  of S:

  Output rs if p is true over r and s
  - R is called the outer table; S is called the inner table
  - I/O's:  $B(R) + |R| \cdot B(S)$

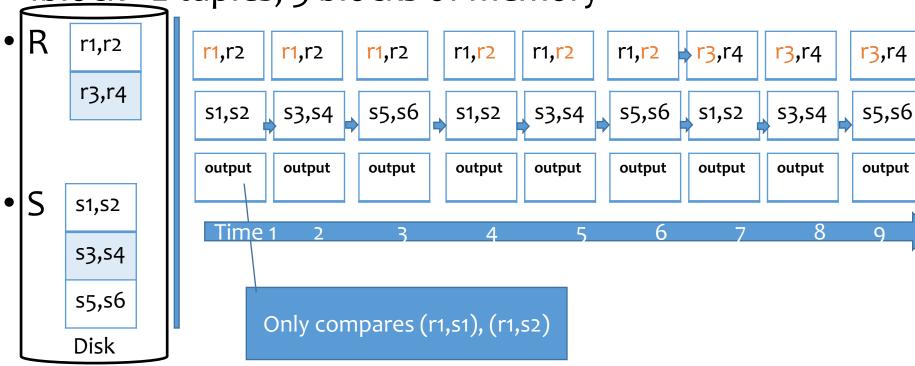
Blocks of R are moved into memory only once

Blocks of S are moved into memory |R| number of times

Memory requirement: 3

## Example for basic nested loop join

1block = 2 tuples, 3 blocks of memory



• Number of I/O: B(R) + |R| \* S(R) = 2 blocks + 4 \* 3blocks = 14

## Improvement: block nested-loop join

```
R \bowtie_p S
```

```
• For each block B_R of R:

For each block B_S of S:

For each r in B_R:

For each s in B_S:

Output rs if p is true over r and s
```

• I/O's:  $B(R) + B(R) \cdot B(S)$ 

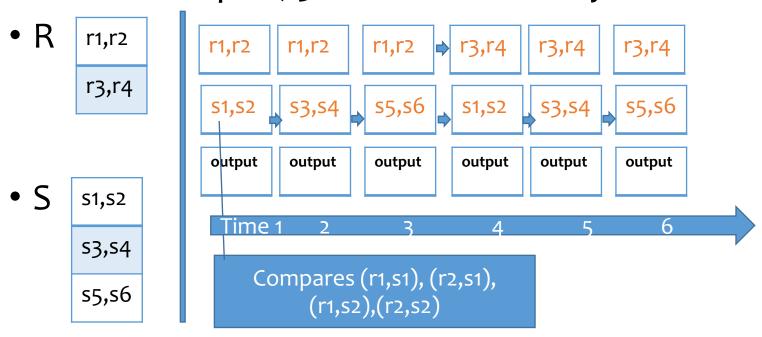
Blocks of R are moved into memory only once

Blocks of S are moved into memory B(R) number of times

Memory requirement: 3

# Example for block-based nested loop join

• 1block = 2 tuples, 3 blocks of memory



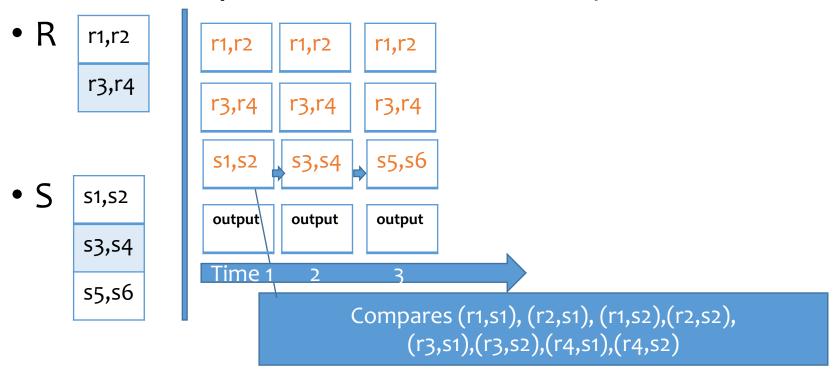
• Number of I/O: B(R) + B(R) \* B(S) = 2 blocks + 2 \* 3 blocks = 8

## More improvements

- Stop early if the key of the inner table is being matched
- Make use of available memory
  - Stuff memory with as much of *R* as possible, stream *S* by, and join every *S* tuple with all *R* tuples in memory
  - I/O's:  $B(R) + \left[\frac{B(R)}{M-2}\right] \cdot B(S)$ 
    - Or, roughly:  $B(R) \cdot B(S)/M$
  - Memory requirement: M (as much as possible)
- Which table would you pick as the outer? (exercise)

# Example for block-based nested loop join

• 1block = 2 tuples, 4 blocks of memory



• Number of I/O: B(R) + B(R)/(M-2)\* S(R) = 2 blocks + 1\* 3blocks = 5

## Case study:

- System requirements:
  - Each disk/memory block can hold up to 10 rows (from any table);
  - All tables are stored compactly on disk (10 rows per block);
  - 8 memory blocks are available for query processing: M=8
- Database:
  - User(<u>uid</u>, age, pop), Member(<u>gid</u>, <u>uid</u>, date), Group(<u>gid</u>, gname)
  - |User|=1000 rows, |Group|=100 rows, |Member|=50000 rows
  - #of blocks: B(User)=1000/10=100; B(Group)=100/10=10; B(Member)=50000/10=5k
- Q1: select \* from User where pop =0.8
  - I/O cost using table scan? B(User) = 100
- Q2: select \* from User, Member where User.uid = Member.uid;
  - I/O cost using blocked-based nested loop join

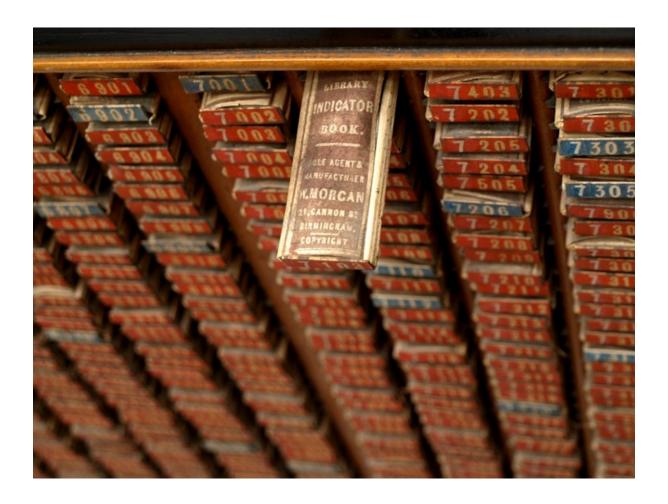
$$B(User) + \left[\frac{B(User)}{M-2}\right] \cdot B(Member) = 100 + \left[\frac{100}{8-2}\right] \cdot 5000 = 85,100$$

#### Outline

- Scan
  - Selection, duplicate-preserving projection, nested-loop join
- Index

- Sort
- Hash (Optional)

## Index-based algorithms



## Selection using index

- Equality predicate:  $\sigma_{A=v}(R)$ 
  - Use an ISAM, B+-tree, or hash index on R(A)
- Range predicate:  $\sigma_{A>v}(R)$ 
  - Use an ordered index (e.g., ISAM or B+-tree) on R(A)
  - Hash index is not applicable
- Indexes other than those on R(A) may be useful
  - Example: B<sup>+</sup>-tree index on R(A, B)
  - How about B+-tree index on R(B, A)?

#### Index versus table scan

#### Situations where index clearly wins:

- Index-only queries which do not require retrieving actual tuples
  - Example:  $\pi_A(\sigma_{A>v}(R))$
- Primary index clustered according to search key
  - One lookup leads to all result tuples in their entirety

## Index versus table scan (cont'd)

#### **BUT(!):**

- Consider  $\sigma_{A>v}(R)$  and a secondary, non-clustered index on R(A)
  - Need to follow pointers to get the actual result tuples
  - Say that 20% of R satisfies A>v
    - Could happen even for equality predicates
  - I/O's for scan-based selection: B(R)
  - I/O's for index-based selection: lookup + 20% |R|
  - Table scan wins if a block contains more than 5 tuples!
    - B(R) = |R|/5 < 20% |R| + lookup

## Index nested-loop join

#### $R \bowtie_{R.A=S.B} S$

- Idea: use a value of R.A to probe the index on S(B)
- For each block of R, and for each r in the block: Use the index on S(B) to retrieve s with s.B = r.AOutput rs
- I/O's: B(R) + |R| · (index lookup+record fetch)
  - Typically, the cost of an index lookup is 2-4 I/O's (depending on the index tree height if B+ tree)
  - Beats other join methods if |R| is not too big
  - Better pick *R* to be the smaller relation
- Memory requirement: 3 (extra memory can be used to cache index, e.g. root of B+ tree)

#### Outline

- Scan
  - Selection, duplicate-preserving projection, nested-loop join
- Index
  - Selection, index nested-loop join
- Sort
  - External merge sort, sort-merge-join
- Hash (Optional)

## Sorting-based algorithms



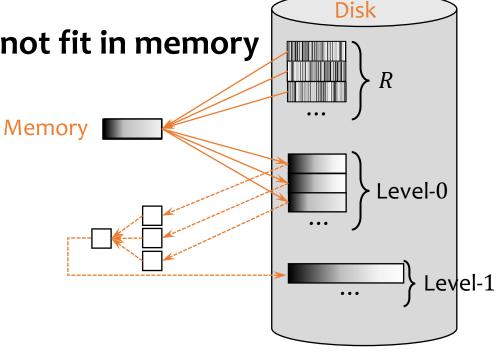
## External merge sort

Recall in-memory merge sort: Sort progressively larger runs, 2, 4, 8, ..., |R|, by merging consecutive "runs"

Problem: sort R, but R does not fit in memory

 Phase 0: read M blocks of R at a time, sort them, and write out a level-0 run

 Phase 1: merge (M − 1) level-0 runs at a time, and write out a level-1 run

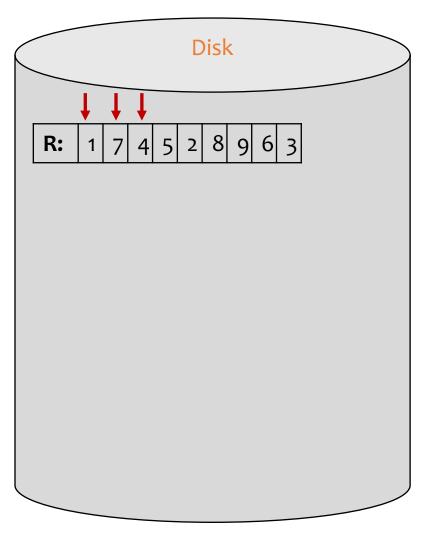


• Phase 2: merge (M-1) level-1 runs at a time, and write out a level-2 run

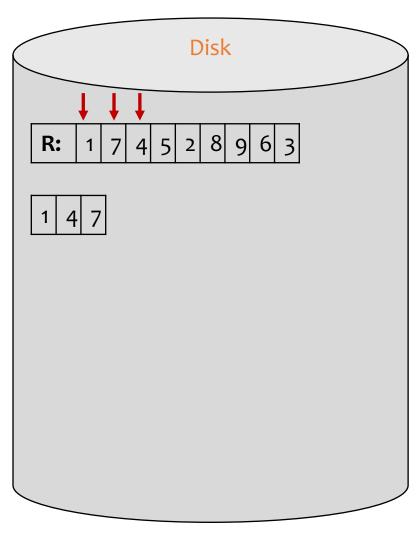
• • •

Final phase produces one sorted run

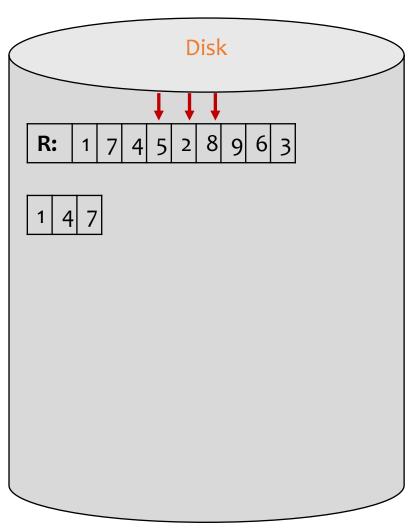
- > 3 memory blocks available; each holds one number
- ➤ Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o



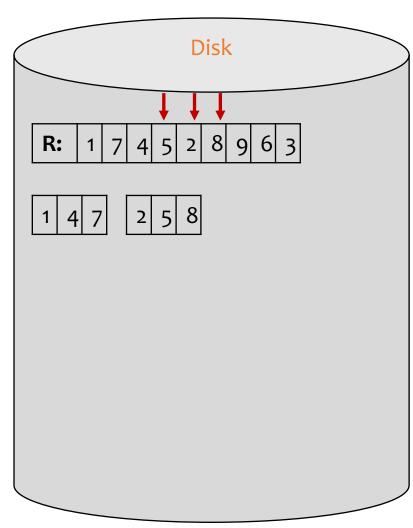
- > 3 memory blocks available; each holds one number
- ➤ Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o



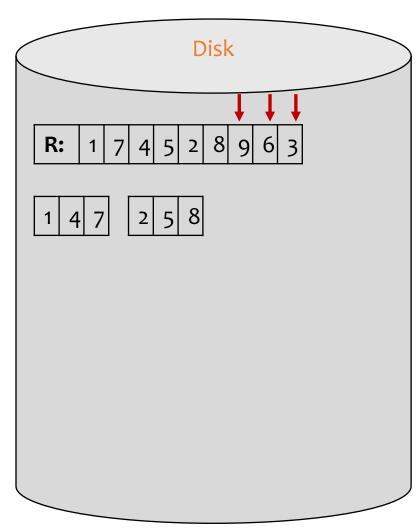
- > 3 memory blocks available; each holds one number
- ➤ Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o



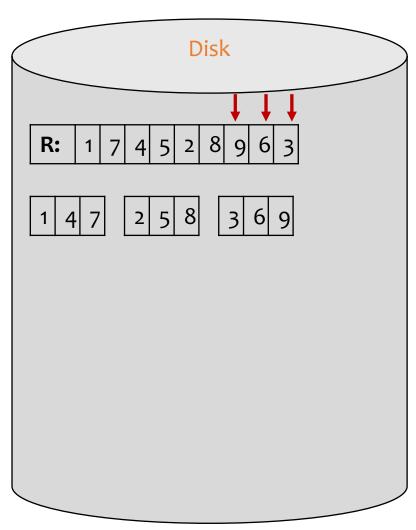
- > 3 memory blocks available; each holds one number
- ➤ Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o



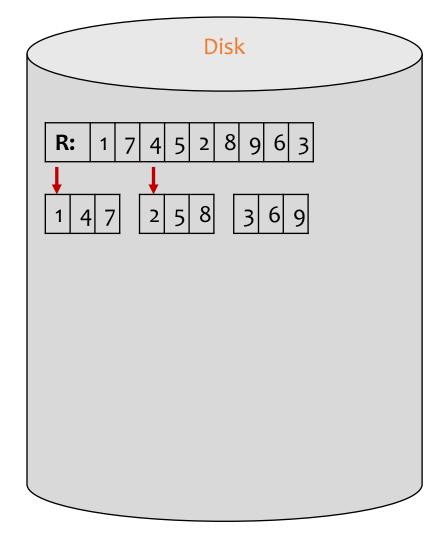
- > 3 memory blocks available; each holds one number
- ➤ Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o



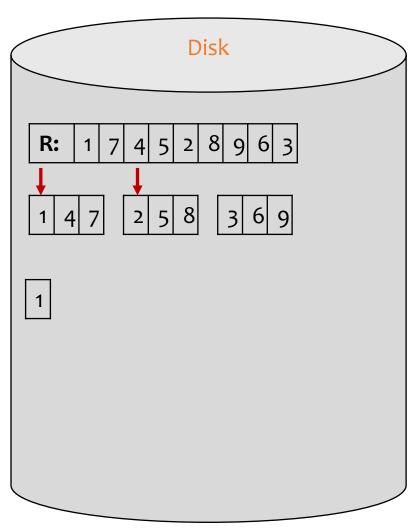
- > 3 memory blocks available; each holds one number
- ➤ Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o



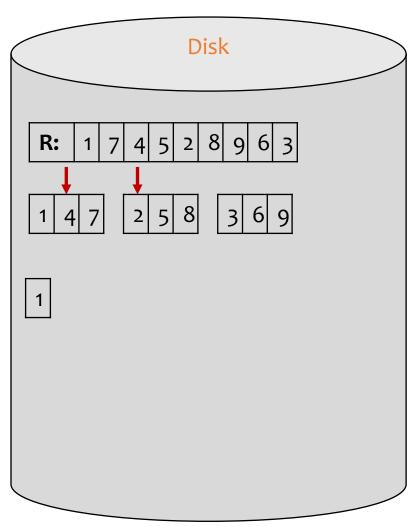
- > 3 memory blocks available; each holds one number
- > Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o
- ➤ Phase 1



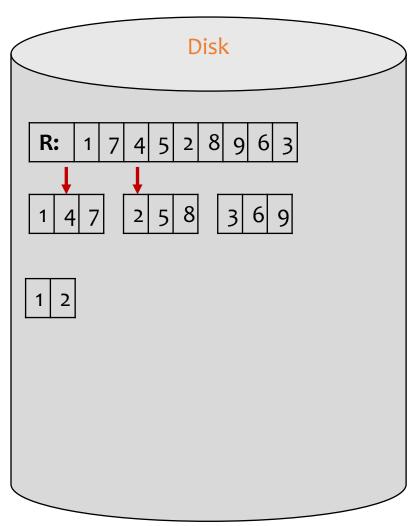
- > 3 memory blocks available; each holds one number
- > Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o
- ➤ Phase 1



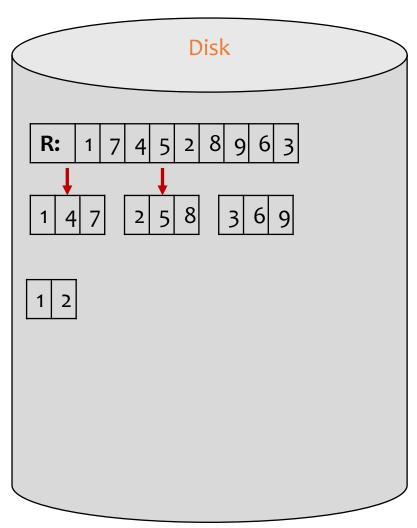
- > 3 memory blocks available; each holds one number
- > Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o
- ➤ Phase 1



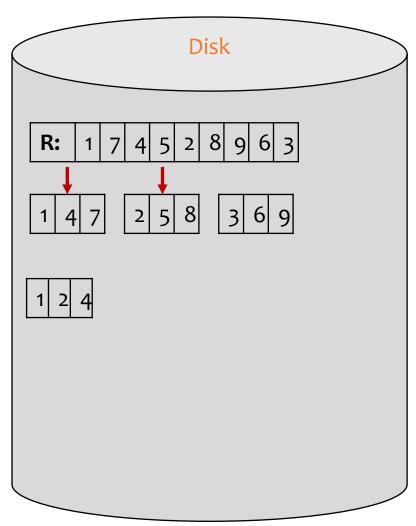
- > 3 memory blocks available; each holds one number
- > Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o
- ➤ Phase 1



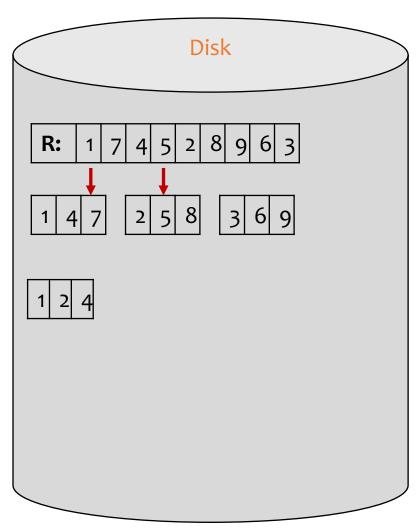
- > 3 memory blocks available; each holds one number
- > Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o
- ➤ Phase 1



- > 3 memory blocks available; each holds one number
- > Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o
- ➤ Phase 1

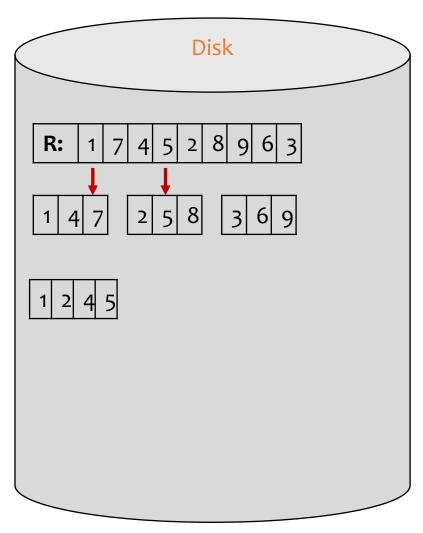


- > 3 memory blocks available; each holds one number
- > Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o
- ➤ Phase 1

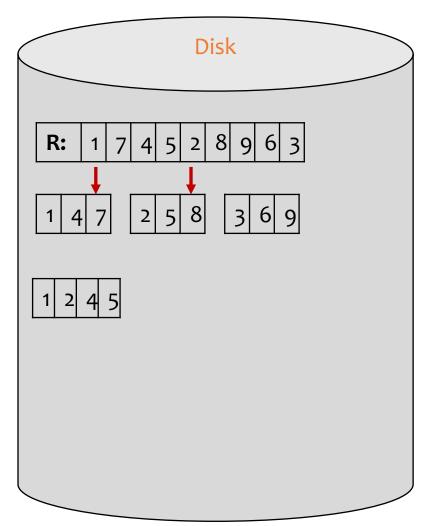


- > 3 memory blocks available; each holds one number
- > Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o

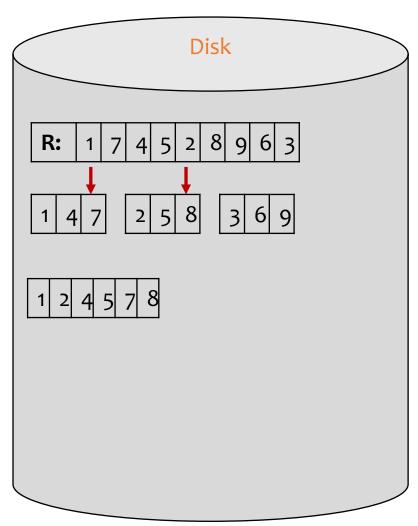
➤ Phase 1



- > 3 memory blocks available; each holds one number
- > Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o
- ➤ Phase 1



- > 3 memory blocks available; each holds one number
- > Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o
- ➤ Phase 1

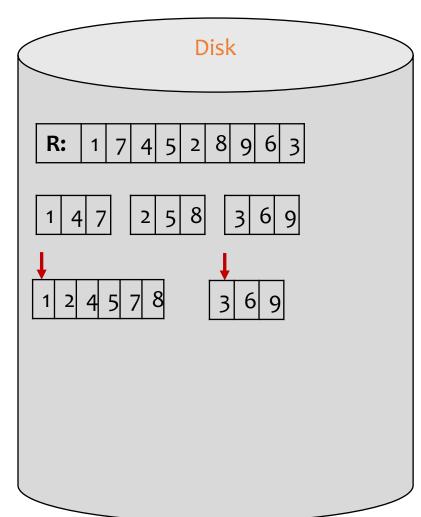


> 3 memory blocks available; each holds one number

Arrows indicate the

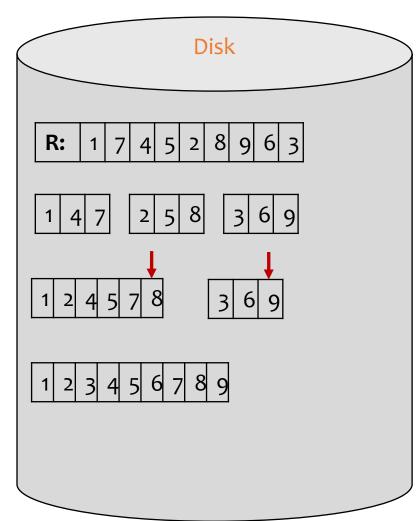
blocks in memory

- > Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o
- ➤ Phase 1
- Phase 2 (final)



- > 3 memory blocks available; each holds one number
- > Input: 1, 7, 4, 5, 2, 8, 9, 6, 3
- > Phase o

- ➤ Phase 1
- Phase 2 (final)



## Analysis

- Phase 0: read M blocks of R at a time, sort them, and write out a level-0 run
  - There are  $\left[\frac{B(R)}{M}\right]$  level-0 sorted runs

I/O cost is  $2 \cdot B(R)$ 

- Phase i: merge (M-1) level-(i-1) runs at a time, and write out a level-i run
  - (M-1) memory blocks for input, 1 to buffer output
  - The number of level-*i* runs =  $\frac{number \text{ of level-}(i-1) \text{ runs}}{M-1}$
  - $\log_{M-1} \left\lceil \frac{B(R)}{M} \right\rceil$  number of such phases
  - Final pass produces one sorted run

I/O cost is  $2 \cdot B(R)$  times # of phases

Subtract B(R) for the final pass

## Performance of external merge sort

• I/O's

• 
$$2B(R) \cdot \left(1 + \left\lceil \log_{M-1} \left\lceil \frac{B(R)}{M} \right\rceil \right\rceil \right) - B(R)$$

• Roughly, this is  $O(B(R) \times \log_M B(R))$ 

• Memory requirement: M (as much as possible)

## Case study (optional):

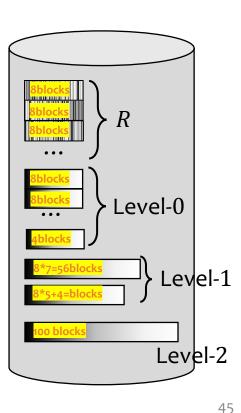
- System requirements:
  - Each disk/memory block can hold up to 10 rows (from any table);
  - All tables are stored compactly on disk (10 rows per block);
  - 8 memory blocks are available for query processing: M=8
- Database:
  - User(<u>uid</u>, age, pop), Member(<u>gid</u>, <u>uid</u>, date), Group(<u>gid</u>, gname)
  - |User|=1000 rows, |Group|=100 rows, |Member|=50000 rows
  - #of blocks: B(User)=1000/10=100; B(Group)=100/10=10; B(Member)=50000/10=5k
- Q3: select \* from User order by age asc;
  - I/O cost using external merge sort?

# Case study (optional):

- System requirements:
  - Each disk/memory block can hold up to 10 rows (from any table);
  - All tables are stored compactly on disk (10 rows per block);
  - 8 memory blocks are available for query processing: M=8
- Database:
  - User(<u>uid</u>, age, pop), Member(<u>gid</u>, uid, date), Group(<u>gid</u>, gname)
  - |User|=1000 rows, |Group|=100 rows, |Member|=50000 rows
  - #of blocks: B(User)=1000/10=100; B(Group)=100/10=10; B(Member)=50000/10=5k
- Q3: select \* from User order by age asc;
  - I/O cost using external merge sort?
    - Phase 0: read 8 blocks into memory at a time and sort it => ceil(100/8)=13 runs
    - Phase 1: merge 7 runs at a time => ceil(13/7)=2 runs
    - Phase 2: merge last 2 runs into a single run

$$\textit{Number of phases:} \left\lceil \log_{M-1} \left\lceil \frac{B(User)}{M} \right\rceil \right\rceil + 1 = \left\lceil \log_{(8-1)} \left\lceil \frac{100}{8} \right\rceil \right\rceil + 1 = 3$$

Phase 0: read B(user)=100 blocks, write B(User)=100 blocks (temporary result)
Phase 1: read B(user)=100 blocks, write B(User)=100 blocks (temporary result)
Phase 2: read B(user)=100 blocks, write B(User)=100 blocks (final result, don't count)



#### Operators That Use Sorting

- Pure Sort: e.g., ORDER BY
- Set Union, Difference, Intersection, or Join or R and S (next slide): When the join condition is an equality condition e.g., R.A = S.B,
  - All can be implemented by walking relations "in tandem" as in the merge step of merge sort.
- DISTINCT
- Group-By-and-Aggregate: Exercise: Think about how you can implement group-by-and-aggregate with sorting?

### Sort-merge join

```
R\bowtie_{R.A=S.B} S
```

- Sort R and S by their join attributes; then merge
  - r, s = the first tuples in sorted R and S
  - Repeat until one of *R* and *S* is exhausted:

```
If r.A > s.B

then s = \text{next tuple in } S

else if r.A < s.B

then r = \text{next tuple in } R

else output all matching tuples, and r, s = \text{next in } R and S
```

- I/O's: sorting +O(B(R)+B(S))
  - In most cases (e.g., join of key and foreign key)
  - Worst case is  $B(R) \cdot B(S)$ : everything joins

### Example of merge join

$$R:$$
  $S:$   $R \bowtie_{R,A=S,B} S:$ 

→  $r_1.A = 1$  →  $s_1.B = 1$   $r_1s_1$ 

→  $r_2.A = 3$  →  $s_2.B = 2$   $r_2s_3$ 
 $r_3.A = 3$  →  $s_3.B = 3$   $r_2s_4$ 

→  $r_4.A = 5$  →  $s_5.B = 8$   $r_3s_3$ 

→  $r_6.A = 7$  →  $r_7.A = 8$   $r_7s_5$ 

### Summary

- Scan
  - Selection, duplicate-preserving projection, nested-loop join
- Index
  - Selection, index nested-loop join
- Sort
  - External merge sort, sort-merge-join
- Hash (Optional)
  Optional (won't be tested)