Lecture 11: Linear Programming and Duality Theorems

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Overview

- Part I
 - Why Linear Programming?
 - Structural Results on Linear Programming
 - Duality Theory
- Conclusion
- Acknowledgements
- Proof of Fundamental Theorem of Linear Inequalities

```
minimize f(x)

subject to g_1(x) \leq 0

\vdots

g_m(x) \leq 0

x \in \mathbb{R}^n
```

Mathematical Programming deals with problems of the form

minimize
$$f(x)$$

subject to $g_1(x) \le 0$
 \vdots
 $g_m(x) \le 0$
 $x \in \mathbb{R}^n$

Very general family of problems.

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- Very general family of problems.
- Special case is when all functions f, g_1, \ldots, g_m are *linear* functions (called *Linear Programming* LP for short)

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- Traces of idea of LP in works of Fourier [Fourier 1823, Fourier 1824]

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- Special case is when all functions f, g_1, \ldots, g_m are *linear* functions (called *Linear Programming* LP for short)
- Traces of idea of LP in works of Fourier [Fourier 1823, Fourier 1824]
- Formally studied & importance of LP recognized in 1940's by Dantzig, Kantorovich, Koopmans and von Neumann.

A linear function $f: \mathbb{R}^n \to \mathbb{R}$ is given by

$$f(\mathbf{x}) = c_1 \cdot x_1 + \ldots + c_n \cdot x_n + b = c^T x + b$$

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Linear Programming deals with problems of the form

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We can *always* represent LPs in *standard form*:

minimize
$$c^T x$$

subject to $Ax = b$
 $x > 0$

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• Other problems, such as *data fitting, linear classification* can be modelled as linear programs.

minimize
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subject to $Ax = b$
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 - Is there a solution to the constraints at all?

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 - Do these solutions have nice description?
 - Do the solutions have *small bit complexity*?

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 - Do these solutions have nice description?
 - Do the solutions have small bit complexity?
- How do we design efficient algorithms that find optimal solutions to Linear Programs?

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Fundamental Theorem of Linear Inequalities

Theorem (Farkas (1894, 1898), Minkowski (1896))

Let $a_1, \ldots, a_m, b \in \mathbb{R}^n$, and $t := \text{rank}\{a_1, \ldots, a_m, b\}$. Then either

- b is a non-negative linear combination of linearly independent vectors from a_1, \ldots, a_m , or
- **2** there exists a hyperplane $H := \{x \mid c^T x = 0\}$ s.t.
 - $c^T b < 0$
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 - ullet H contains t-1 linearly independent vectors from a_1,\ldots,a_m

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Remark

Any hyperplane H with the above property is known as a *separating hyperplane*.

Lemma (Farkas Lemma)

- **1** There exists $x \in \mathbb{R}^n$ such that $x \ge 0$ and Ax = b
- $v^Tb \ge 0$ for each $y \in \mathbb{R}^m$ such that $v^TA \ge 0$

Lemma (Farkas Lemma)

Let $A \in \mathbb{R}^{m \times n}$ and $b \in \mathbb{R}^m$. The following are equivalent:

- **1** There exists $x \in \mathbb{R}^n$ such that $x \ge 0$ and Ax = b
- $v T b \ge 0$ for each $y \in \mathbb{R}^m$ such that $v T A \ge 0$

Equivalent formulation

Lemma (Farkas Lemma - variant 1)

Let $A \in \mathbb{R}^{m \times n}$ and $b \in \mathbb{R}^m$. Then exactly one of the following statements hold:

- **1** There exists $x \in \mathbb{R}^n$ such that $x \ge 0$ and Ax = b
- ② There exists $y \in \mathbb{R}^m$ such that $y^T b > 0$ and $y^T A \leq 0$

Equivalent formulation

Lemma (Farkas Lemma - variant 2)

- **1** There exists $x \in \mathbb{R}^n$ such that $Ax \leq b$
- 2 $y^Tb \ge 0$ for each $y \ge 0$ such that $y^TA = 0$

Equivalent formulation

Lemma (Farkas Lemma - variant 2)

- **1** There exists $x \in \mathbb{R}^n$ such that $Ax \leq b$
- 2 $y^Tb \ge 0$ for each $y \ge 0$ such that $y^TA = 0$
 - Let $M = [I \ A \ -A]$. Then $Ax \le b$ has a solution iff Mz = b has a non-negative solution $z \ge 0$

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 - Let $M = [I \ A \ -A]$. Then $Ax \le b$ has a solution iff Mz = b has a non-negative solution $z \ge 0$
 - Now apply the original version of the lemma

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- If we look at what happens when we multiply $y^T A$, note the following:

$$y^T A \le c^T \Rightarrow y^T A x \le c^T x$$

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• Thus, if $y^T A \le c^T$, then we have that $y^T b$ is a *lower bound* on the solution to our linear program!

Consider the following linear programs:

Primal LP		Dual LP	
minimize subject to		maximize subject to	$y^T b$ $y^T A \le c^T$
	x > 0		

Linear Programming Duality

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	~ <u>-</u> •			

From previous slide

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 Thus, the optimal (maximum) value of dual LP lower bounds the optimal (minimum) value of the Primal LP!

Linear Programming Duality

Consider the following linear programs:

Primal LP Dual LP minimize $c^T x$ maximize $y^T b$ subject to Ax = b subject to $y^T A \le c^T$ $x \ge 0$

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Theorem (Weak Duality)

Let x be a feasible solution of the primal LP and y be a feasible solution of the dual LP. Then

$$y^T b \leq c^T x$$
.

Primal LP

minimize $c^T x$ subject to Ax = b $x \ge 0$

Dual LP

maximize $y^T b$ subject to $y^T A \le c^T$

Primal LP		Dual LP		
minimize subject to		maximize subject to	$y^T b$ $y^T A \le c^T$	
-	$x \ge 0$,	<i>y</i> —	

 Optimal (maximum) value of dual LP lower bounds the optimal (minimum) value of the Primal LP!

Primal LP Dual LP minimize $c^T x$ maximize $y^T b$ subject to Ax = b $x \ge 0$ subject to $y^T A \le c^T$

- Optimal (maximum) value of dual LP lower bounds the optimal (minimum) value of the Primal LP!
- If $\alpha^*, \beta^* \in \mathbb{R}$ are the optimal values for primal and dual, respectively.

Primal LP Dual LP minimize c^Tx maximize y^Tb subject to Ax = b subject to $y^TA \le c^T$ x > 0

- Optimal (maximum) value of dual LP lower bounds the optimal (minimum) value of the Primal LP!
- If $\alpha^*, \beta^* \in \mathbb{R}$ are the optimal values for primal and dual, respectively.
 - We showed that when both primal and dual are feasible, we have

$$\max dual = \beta^* \le \alpha^* = \min of primal$$

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• if primal unbounded $(\alpha^* = -\infty)$ then dual infeasible $(\beta^* = -\infty)$

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- if dual *unbounded* ($\beta^* = \infty$) then primal *infeasible* ($\alpha^* = \infty$)

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- Practice problem: show that dual of the dual LP is the primal LP!

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- if dual *unbounded* $(\beta^* = \infty)$ then primal *infeasible* $(\alpha^* = \infty)$
- Practice problem: show that dual of the dual LP is the primal LP!
- When is the above inequality tight?



Strong Duality

Primal LP Dual LP minimize
$$c^T x$$
 maximize $y^T b$ subject to $Ax = b$ subject to $y^T A \le c^T$ $x > 0$

• let $\alpha^*, \beta^* \in \mathbb{R}$ be optimal values for primal and dual, respectively.

Strong Duality

Primal LP Dual LP minimize
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• let $\alpha^*, \beta^* \in \mathbb{R}$ be optimal values for primal and dual, respectively.

Theorem (Strong Duality)

If primal LP and dual LP are feasible, then

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Since we have proved weak duality, suffices to show that the following LP has a solution:

maximize 0
subject to
$$y^T A \le c^T$$

 $c^T x - y^T b \le 0$
 $Ax = b$
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If primal LP and dual LP are feasible, then

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Since we have proved weak duality, suffices to show that the following LP has a solution:

maximize 0 subject to
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 $c^T x - y^T b \le 0$ $Ax = b$ $x \ge 0$

Apply variant 2 of Farkas' lemma on the system above.

1 LP from previous page encoded by:

$$B\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} A & 0 \\ -A & 0 \\ c^T & -b^T \\ 0 & A^T \\ -I & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \le \begin{pmatrix} b \\ -b \\ 0 \\ c \\ 0 \end{pmatrix}$$

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② Variant 2 of Farkas' lemma gives that the system has solution iff for each $z = (u^T \ v^T \ \lambda \ w^T \ e^T) \ge 0$ such that zB = 0 then we have $u^T b - v^T b + w^T c \ge 0$

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- If $\lambda > 0$, then $\lambda c^T \ge (v^T u^T)A \Rightarrow \lambda c^T w \ge (v^T u^T)Aw$ and so $\lambda (u^T v^T)b + \lambda w^T c \ge \lambda (u^T v^T)b (u^T v^T)Aw$

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- If $\lambda > 0$, then $\lambda c^T \ge (v^T u^T)A \Rightarrow \lambda c^T w \ge (v^T u^T)Aw$ and so $\lambda (u^T v^T)b + \lambda w^T c \ge \lambda (u^T v^T)b (u^T v^T)Aw$
- If $\lambda = 0$, let x, y be feasible solutions (which we assumed to exist). Then $x \ge 0$, Ax = b and $y^T A \le c^T$. Thus

$$c^{T}w \ge y^{T}Aw = 0 \ge (v^{T} - u^{T})Ax = (v^{T} - u^{T})b$$



Affine form of Farkas' Lemma

A consequence of LP duality is the following lemma:

Lemma (Affine Farkas' Lemma)

Let the system

$$Ax \leq b$$

have at least one solution, and suppose that inequality

$$c^T x \leq \delta$$

holds whenever x satisfies $Ax \leq b$. Then, for some $\delta' \leq \delta$ the linear inequality

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is a non-negative linear combination of the inequalities of $Ax \leq b$.

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Practice problem: use LP duality and Farkas' lemma to prove this lemma!

Complementary Slackness

- If the optima in both primal and dual is finite, and x, y are feasible solutions, the following are equivalent:

 - $c^{T}x = y^{T}b$
 - 3 if $x_i > 0$ then the corresponding inequality $y^T A_i \le c_i$ is an equality: that is, we must have $y^T A_i = c_i$.

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 - § if $x_i > 0$ then the corresponding inequality $y^T A_i \le c_i$ is an equality: that is, we must have $y^T A_i = c_i$.
- 1 and 2 are equivalent due to strong duality
- 2 and 3 are equivalent as we can write

$$c^{T}x - y^{T}b = c^{T}x - y^{T}Ax = (c^{T} - y^{T}A)x = \sum_{i=1}^{n} (c_{i} - y^{T}A_{i})x_{i}$$

 Mathematical programming - very general, and pervasive in Algorithmic life

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- General mathematical programming very hard (how hard do you think it is?)

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- Special cases have very striking applications!

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 Linear Programming and Duality - fundamental concepts, lots of applications!

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Today: Linear Programming

- Linear Programming and Duality fundamental concepts, lots of applications!
 - Applications in Combinatorial Optimization (a lot of it happened here at UW!)
 - Applications in Game Theory (minimax theorem)
 - Applications in Learning Theory (boosting)
 - many more

Acknowledgement

- Lecture based largely on:
 - [Schrijver 1986, Chapter 7]

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- b is a non-negative linear combination of linearly independent vectors from a_1, \ldots, a_m , or
- ② there exists a hyperplane $H := \{x \mid c^T x = 0\}$ s.t.
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 - Since 1 and 2 mutually exclusive, choose linearly independent $\mathcal{L}_0 := \{a_{i_1}, \dots, a_{i_n}\}$

Theorem (Farkas (1894, 1898), Minkowski (1896))

Let $a_1, \ldots, a_m, b \in \mathbb{R}^n$, and $t := \text{rank}\{a_1, \ldots, a_m, b\}$. Then either

- b is a non-negative linear combination of linearly independent vectors from a_1, \ldots, a_m , or
- ② there exists a hyperplane $H := \{x \mid c^T x = 0\}$ s.t.
 - $c^T b < 0$
 - $c^T a_i \geq 0$
 - H contains t-1 linearly independent vectors from a_1, \ldots, a_m
 - We can assume that a_1, \ldots, a_m span \mathbb{R}^n , otherwise work on the spanning subspace after appropriate linear transformation
 - Since 1 and 2 mutually exclusive, choose linearly independent $\mathcal{L}_0 := \{a_{i_1}, \dots, a_{i_n}\}$
 - We will perform an iterative procedure:

Iterative procedure, starting with \mathcal{L}_0 :

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- **3** If $c_0^T a_i \ge 0$ for all $i \in [m]$ we are done (case 2)

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- ② If not, let h be smallest index from i_1,\ldots,i_n such that $\lambda_h<0$. Let $H_0=\{x\in\mathbb{R}^n\mid c_0^Tx=0\}$ be the hyperplane spanned by $\mathcal{L}_0\setminus\{a_h\}$. Normalize it so that $c_0^Ta_h=1$.
- **3** If $c_0^T a_i \ge 0$ for all $i \in [m]$ we are done (case 2)
- ① Otherwise, choose smallest $s \in [m]$ such that $c_0^T a_s < 0$, and let $\mathcal{L}_1 = \mathcal{L} \cup \{a_s\} \setminus \{a_h\}$. Go back to step 1.

- Write $b = \lambda_{i_1} a_{i_1} + \ldots + \lambda_{i_n} a_{i_n}$. If $\lambda_i \geq 0$ we are done
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 - To conclude the proof, need to show that this procedure always terminates. If process doesn't terminate, there are two times r < t such that $\mathcal{L}_r = \mathcal{L}_t$
- Let ℓ be the highest index for which a_{ℓ} has been removed from \mathcal{L}_k for some r < k < t.

- ① Write $b = \lambda_{i_1} a_{i_1} + \ldots + \lambda_{i_n} a_{i_n}$. If $\lambda_i \geq 0$ we are done
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- **1** If $c_0^T a_i \ge 0$ for all $i \in [m]$ we are done (case 2)
- ① Otherwise, choose smallest $s \in [m]$ such that $c_0^T a_s < 0$, and let $\mathcal{L}_1 = \mathcal{L} \cup \{a_s\} \setminus \{a_h\}$. Go back to step 1.
 - To conclude the proof, need to show that this procedure always terminates. If process doesn't terminate, there are two times r < t such that $\mathcal{L}_r = \mathcal{L}_t$
- Let ℓ be the highest index for which a_{ℓ} has been removed from \mathcal{L}_k for some $r \leq k < t$.
- $\mathcal{L}_r = \mathcal{L}_t \Rightarrow a_\ell$ has also been added from some $\mathcal{L}_{k'}$ for some r < k' < t.

- Say a_r was removed at iteration k and added back at iteration k' so $r \le k < k' < t$
- Let c be the vector defining the hyperplane at the k' iteration (when we added a_r back to the set), and let $\mathcal{L}_k = \{a_{i_1}, \ldots, a_{i_n}\}$
- Now, above implies the following contradiction:

$$0 > c^{\mathsf{T}}b = c^{\mathsf{T}}(\lambda_{i_1}a_{i_1} + \cdots + \lambda_{i_n}a_{i_n}) = \lambda_{i_1}c^{\mathsf{T}}a_{i_1} + \cdots + \lambda_{i_n}c^{\mathsf{T}}a_{i_n} \geq 0$$

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- First inequality comes because at each iteration we choose c such that $c^Tb<0$
- Second inequality holds term by term:

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