Lecture 16: Semidefinite Programming Relaxation and MAX-CUT

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Overview

• Max-Cut SDP Relaxation & Rounding

Conclusion

Acknowledgements

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 - If solution to SDP is *integral* and *one-dimensional*, then it is a solution to QP and we are done
 - If solution has higher dimension, then we have to devise rounding procedure that transforms

high dimensional solutions \rightarrow integral & 1D solutions

rounded SDP solution value $\geq c \cdot OPT(QP)$

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Max-Cut

Maximum Cut (Max-Cut):

$$G(V, E)$$
 graph.

Cut $S \subseteq V$ and size of cut is

$$|E(S,\overline{S})| = |\{(u,v) \in E \mid u \in S, v \notin S\}|.$$

Goal: find cut of maximum size.

Example - Weighted Variant

Maximum Cut (Max-Cut):

$$G(V, E, w)$$
 weighted graph. $\sum_{e \in E} w_e = 1$

Cut $S \subseteq V$ and weight of cut is the sum of weights of edges crossing cut. Goal: find cut of maximum weight.

Max-Cut

$$G(V, E, w)$$
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Quadratic Program:

maximize
$$\sum_{\{u,v\}\in E} rac{1}{2} \cdot w_{u,v} \cdot (1-x_ux_v)$$
 subject to $x_v^2=1$ for $v\in V$

SDP Relaxation [Delorme, Poljak 1993]

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 weighted graph, $|\mathit{V}| = \mathit{n}$ and $\sum_{e \in \mathit{E}} \mathit{w}_e = 1$

Semidefinite Program:

$$\begin{aligned} & \text{maximize} \quad \sum_{\{u,v\} \in E} \frac{1}{2} \cdot w_{u,v} \cdot \left(1 - y_u^T y_v\right) \\ & \text{subject to} \quad \|y_v\|_2^2 = 1 \quad \text{for } v \in V \\ & y_v \in \mathbb{R}^d \quad \text{for } v \in V \end{aligned}$$

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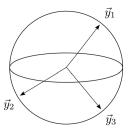


Figure 10.1: Vectors $\vec{y_v}$ embedded onto a unit sphere in \mathbb{R}^d .

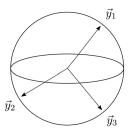


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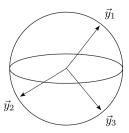


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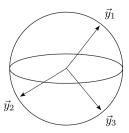


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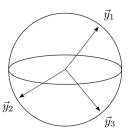


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- If all y_v 's are in a one-dimensional space, then we get original quadratic program

Let's consider $G = K_3$ with equal weights on edges.

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- **Practice problem:** try this with C_5 .

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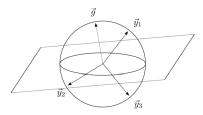


Figure 10.2: Vectors being separated by a hyperplane with normal \vec{g} .

Facts we need

• We can pick a random hyperplane through origin in polynomial time. sample vector $g=(g_1,\ldots,g_n)$ by drawing $g_i\in\mathcal{N}(0,1)$

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- We can pick a random hyperplane through origin in polynomial time. sample vector $g=(g_1,\ldots,g_n)$ by drawing $g_i\in\mathcal{N}(0,1)$
- If g' is the projection of g onto a two dimensional plane, then $g'/||g'||_2$ is *uniformly distributed* over the unit circle in this plane.

Analysis of Rounding

• Probability that edge $\{u, v\}$ crosses the cut is same as probability that z_u, z_v fall in different sides of hyperplane

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• Probability of splitting z_u, z_v :

$$\Pr[\{u, v\} \text{ crosses cut}] = \frac{\theta}{\pi} = \frac{\cos^{-1}(z_u^T z_v)}{\pi} = \frac{\cos^{-1}(\gamma_{uv})}{\pi}$$

• Expected value of cut:

$$\mathbb{E}[\mathsf{value} \; \mathsf{of} \; \mathsf{cut}] = \sum_{\{u,v\} \in E} w_{u,v} \cdot \frac{\mathsf{cos}^{-1}(\gamma_{uv})}{\pi}$$

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Recall that

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• If we find α such that

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• For $x \in [-1, 1]$, we have

$$\frac{\cos^{-1}(x)}{\pi} \ge 0.878 \cdot \frac{1-x}{2}$$

proof by elementary calculus.

Conclusion of rounding algorithm

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3 With constant probability, our solution will be $\geq 0.878OPT(Max-Cut)$

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All of these are amazing final project topics!

Conclusion

- Mathematical programming very general, and pervasive in (combinatorial) algorithmic life
- Mathematical Programming hard in general
- Sometimes can get SDP rounding!
- Solve SDP and round the solution
 - Deterministic rounding when solutions are nice
 - Randomized rounding when things a bit more complicated

Acknowledgement

- Lecture based largely on:
 - Lecture 14 of Anupam Gupta and Ryan O'Donnell's Optimization class https://www.cs.cmu.edu/~anupamg/adv-approx/
 - Chapter 6 of book [Williamson, Shmoys 2010]
- See their notes at

https://www.cs.cmu.edu/~anupamg/adv-approx/lecture14.pdf

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