

Lecture 13: Multivariate Polynomial Division Algorithm & Monomial Ideals

Rafael Oliveira

University of Waterloo
Cheriton School of Computer Science

rafael.oliveira.teaching@gmail.com

March 1, 2021

Overview

- Two Familiar Division Algorithms
- Generalization: Multivariate Multipolynomial Division
- Issues with the division algorithm
- Monomial Ideals & Dickson's Lemma
- Conclusion
- Acknowledgements

Division with remainder over $\mathbb{F}[x]$

- **Input:** two elements $a, b \in \mathbb{F}[x]$, with b non-zero
- **Output:** $q, r \in \mathbb{F}[x]$ such that $\deg(r) < \deg(b)$ and $a = q \cdot b + r$

Division with remainder over $\mathbb{F}[x]$

- **Input:** two elements $a, b \in \mathbb{F}[x]$, with b non-zero
- **Output:** $q, r \in \mathbb{F}[x]$ such that $\deg(r) < \deg(b)$ and $a = q \cdot b + r$
- Start with $r = a, q = 0$

Division with remainder over $\mathbb{F}[x]$

- **Input:** two elements $a, b \in \mathbb{F}[x]$, with b non-zero
- **Output:** $q, r \in \mathbb{F}[x]$ such that $\deg(r) < \deg(b)$ and $a = q \cdot b + r$
- Start with $r = a, q = 0$
- While $\deg(r) \geq \deg(b)$:

maintain $a = qb + r$

$$q \leftarrow q + x^{\deg(r) - \deg(b)}$$

$$r \leftarrow r - x^{\deg(r) - \deg(b)} \cdot \frac{LC(r)}{LC(b)} \cdot b$$

$$+ \frac{LC(r)}{LC(b)} \cdot x^{\deg(r) - \deg(b)}$$

reducing degree of remainder

$$LT(r) = LC(r) \cdot x^{\deg(r)}$$

$$\frac{LC(r)}{LC(b)} x^{\deg(r) - \deg(b)} \cdot LC(b) \cdot x^{\deg(b)} = LC(r) \cdot x^{\deg(r)}$$

Division with remainder over $\mathbb{F}[x]$

- **Input:** two elements $a, b \in \mathbb{F}[x]$, with b non-zero
- **Output:** $q, r \in \mathbb{F}[x]$ such that $\deg(r) < \deg(b)$ and $a = q \cdot b + r$
- Start with $r = a, q = 0$
- While $\deg(r) \geq \deg(b)$:
 - $q \leftarrow q + x^{\deg(r) - \deg(b)}$
 - $r \leftarrow r - x^{\deg(r) - \deg(b)} \cdot \frac{LC(r)}{LC(b)} \cdot b$
- Analysis: we will perform at most $\deg(a) - \deg(b) + 1$ subtractions to r . Total time $(\deg(a) - \deg(b) + 1)(\deg(b) + 1)$.

Example

• $a(x) = x^3 + 2x^2 + x + 1$, $b(x) = 2x + 1$

$$r = \frac{7}{8}$$

$$q = \frac{x^2}{2} + \frac{3}{4}x + \frac{1}{8}$$

$$\begin{array}{r} b = 2x + 1 \quad \left| \begin{array}{l} x^3 + 2x^2 + x + 1 \\ \underline{x^3 + \frac{x^2}{2}} \\ \frac{3}{2}x^2 + x + 1 \\ \underline{\frac{3}{2}x^2 + \frac{3x}{4}} \\ \frac{x}{4} + 1 \\ \underline{\frac{x}{4} + \frac{1}{8}} \\ \frac{7}{8} \quad \color{red}{/} \end{array} \right. \end{array}$$

Solving Linear System - Gaussian Elimination

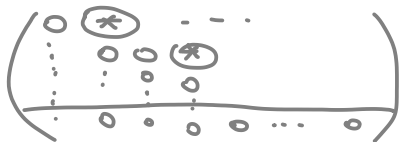
- **Input:** matrix $A \in \mathbb{F}^{n \times d}$, vector $b \in \mathbb{F}^n$
- **Output:** Is there a solution $y \in \mathbb{F}^d$ to $Ay = b$?

Solving Linear System - Gaussian Elimination

- **Input:** matrix $A \in \mathbb{F}^{n \times d}$, vector $b \in \mathbb{F}^n$
- **Output:** Is there a solution $y \in \mathbb{F}^d$ to $Ay = b$?
- Algorithm
 - 1 Put $C = (A \ b)$ in reduced row-echelon form

we will focus on this

$\mathbb{F}^{n \times (d+1)}$



Solving Linear System - Gaussian Elimination

- **Input:** matrix $A \in \mathbb{F}^{n \times d}$, vector $b \in \mathbb{F}^n$
- **Output:** Is there a solution $y \in \mathbb{F}^d$ to $Ay = b$?
- Algorithm
 - 1 Put $C = (A \ b)$ in reduced row-echelon form *we will focus on this*
 - 2 From bottom-up along rows of A , if the equation has a solution then set it properly

Solving Linear System - Gaussian Elimination

- **Input:** matrix $A \in \mathbb{F}^{n \times d}$, vector $b \in \mathbb{F}^n$
- **Output:** Is there a solution $y \in \mathbb{F}^d$ to $Ay = b$?
- Algorithm
 - 1 Put $C = (A \ b)$ in reduced row-echelon form *we will focus on this*
 - 2 From bottom-up along rows of A , if the equation has a solution then set it properly
 - 3 So long as there are no inconsistencies, we found a solution

Example

• $A = \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 2 & 3 & -1 \end{pmatrix}$ and $b = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$

$\begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} \rightarrow \exists y \in \mathbb{F}^3 \text{ s.t. } Ay = b$

$C = \left(\begin{array}{ccc|c} 1 & 0 & 1 & 3 \\ \rightarrow 1 & 1 & 0 & 1 \\ \rightarrow 2 & 3 & -1 & 0 \end{array} \right) \rightarrow \begin{pmatrix} 1 & 0 & 1 & 3 \\ 0 & 1 & -1 & -2 \\ 0 & 3 & -3 & -6 \end{pmatrix}$

$\rightarrow \begin{pmatrix} 1 & 0 & 1 & 3 \\ 0 & 1 & -1 & -2 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{array}{l} \leftarrow \text{non-redundant} \\ \leftarrow \text{redundant} \end{array}$

$\boxed{y_3 = t} \quad y_2 - t = -2 \Rightarrow \boxed{y_2 = t - 2}$

$y_1 + t = 3 \Rightarrow y_1 = 3 - t \quad \begin{pmatrix} 3-t \\ t-2 \\ t \end{pmatrix} \quad t \in \mathbb{F}$

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 2 & 3 & -1 \end{pmatrix} \quad b = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$$

$$\rightarrow f_1 \quad y_1 + y_3 - 3 = 0$$

$$\left. \begin{array}{l} \\ \\ \end{array} \right\} f_2 \quad y_1 + y_2 - 1 = 0$$

$$\rightarrow \left. \begin{array}{l} \\ \\ \end{array} \right\} f_3 \quad y_1 + 3y_2 - y_3 = 0$$

$$y_1 > y_2 > y_3$$

$$\underline{f_1}, \quad \underline{f_2 - f_1}, \quad \underbrace{f_3 - f_1 - 3(f_2 - f_1)}_0$$

- Two Familiar Division Algorithms
- **Generalization: Multivariate Multipolynomial Division**
- Issues with the division algorithm
- Monomial Ideals & Dickson's Lemma
- Conclusion
- Acknowledgements

Why Multivariate Multipolynomial Division?

- From last lecture, many algorithmic problems we really would like to solve:
 - ① ideal membership problem
 - ② solving polynomial equations
 - ③ implicitization problem
 - ④ finding irreducible components of algebraic set
 - ⑤ among others...

Why Multivariate Multipolynomial Division?

- From last lecture, many algorithmic problems we really would like to solve:
 - ① ideal membership problem
 - ② solving polynomial equations
 - ③ implicitization problem
 - ④ finding irreducible components of algebraic set
 - ⑤ among others...
- It turns out that a generalization of both algorithms above is fundamental to solve all the problems above!

Why Multivariate Multipolynomial Division?

- From last lecture, many algorithmic problems we really would like to solve:
 - ① ideal membership problem
 - ② solving polynomial equations
 - ③ implicitization problem
 - ④ finding irreducible components of algebraic set
 - ⑤ among others...
- It turns out that a generalization of both algorithms above is fundamental to solve all the problems above!
- Implicit in the seminal works of Hilbert and Gordan from 1890s!

Why Multivariate Multipolynomial Division?

- From last lecture, many algorithmic problems we really would like to solve:
 - ① ideal membership problem
 - ② solving polynomial equations
 - ③ implicitization problem
 - ④ finding irreducible components of algebraic set
 - ⑤ among others...
- It turns out that a generalization of both algorithms above is fundamental to solve all the problems above!
- Implicit in the seminal works of Hilbert and Gordan from 1890s!
- Complexity analyzed by Buchberger in 1960s!

Monomial Ordering

- In division algorithm over $\mathbb{F}[x]$, implicitly assumed $x \leq x^2 \leq x^3 \leq \dots$ and that constants were "smaller than" any power of x

Monomial Ordering

- In division algorithm over $\mathbb{F}[x]$, implicitly assumed $x \leq x^2 \leq x^3 \leq \dots$ and that constants were "smaller than" any power of x
- In our linear system solving algorithm, we implicitly assumed that $y_1 \geq y_2 \geq \dots \geq y_d$

Monomial Ordering

- In division algorithm over $\mathbb{F}[x]$, implicitly assumed $x \leq x^2 \leq x^3 \leq \dots$ and that constants were "smaller than" any power of x
- In our linear system solving algorithm, we implicitly assumed that $y_1 \geq y_2 \geq \dots \geq y_d$
- Can we assume a similar ordering for monomials in $\mathbb{F}[x_1, \dots, x_n]$?
YES!

Monomial Ordering

- In division algorithm over $\mathbb{F}[x]$, implicitly assumed $x \leq x^2 \leq x^3 \leq \dots$ and that constants were "smaller than" any power of x
- In our linear system solving algorithm, we implicitly assumed that $y_1 \geq y_2 \geq \dots \geq y_d$
- Can we assume a similar ordering for monomials in $\mathbb{F}[x_1, \dots, x_n]$?
YES!
- Even to write a polynomial in a "humanly consistent way" we assume a monomial order (i.e., the ones we write first)
- Example: given two monomials $\mathbf{x}^{\mathbf{a}}, \mathbf{x}^{\mathbf{b}} \in \mathbb{F}[x_1, \dots, x_n]$, we say

$\mathbf{x}^{\mathbf{a}} \succeq \mathbf{x}^{\mathbf{b}}$ if $\mathbf{a} \succeq \mathbf{b}$ in lexicographic order over \mathbb{N}^n

$\mathbf{a} \succeq \mathbf{b}$ if first index i s.t.

$a_i \neq b_i$ we have $a_i > b_i$

aadverb > aoriginal $(2, \underline{4}, 3) > (2, \underline{0}, 100)$

Monomial Ordering

- In division algorithm over $\mathbb{F}[x]$, implicitly assumed $x \leq x^2 \leq x^3 \leq \dots$ and that constants were "smaller than" any power of x
- In our linear system solving algorithm, we implicitly assumed that $y_1 \geq y_2 \geq \dots \geq y_d$
- Can we assume a similar ordering for monomials in $\mathbb{F}[x_1, \dots, x_n]$?
YES!
- Even to write a polynomial in a "humanly consistent way" we assume a monomial order (i.e., the ones we write first)
- Example: given two monomials $\mathbf{x}^{\mathbf{a}}, \mathbf{x}^{\mathbf{b}} \in \mathbb{F}[x_1, \dots, x_n]$, we say

$\mathbf{x}^{\mathbf{a}} \succeq \mathbf{x}^{\mathbf{b}}$ if $\mathbf{a} \succeq \mathbf{b}$ in lexicographic order over \mathbb{N}^n

- In general a good monomial order has:

- 1 *Total order*: any two elements can be compared
- 2 *Transitive*: $\mathbf{x}^{\mathbf{a}} \succeq \mathbf{x}^{\mathbf{b}}$ and $\mathbf{x}^{\mathbf{b}} \succeq \mathbf{x}^{\mathbf{c}}$ then $\mathbf{x}^{\mathbf{a}} \succeq \mathbf{x}^{\mathbf{c}}$
- 3 *Well-behaved under multiplication*: $\mathbf{x}^{\mathbf{a}} \succeq \mathbf{x}^{\mathbf{b}} \Rightarrow \mathbf{x}^{\mathbf{a}+\mathbf{c}} \succeq \mathbf{x}^{\mathbf{b}+\mathbf{c}}$
- 4 *Well-ordering*: every non-empty subset has a *smallest element*

(ensure that algorithms will terminate)

$$\underline{LT(f) \cdot LT(g) = LT(f \cdot g)}$$



Leading Terms, Monomials, Coefficients

- Now we are ready to define special terms of polynomials

$$f(\mathbf{x}) = \sum_{\alpha} f_{\alpha} \cdot \mathbf{x}^{\alpha}$$

Leading Terms, Monomials, Coefficients

- Now we are ready to define special terms of polynomials

$$f(\mathbf{x}) = \sum_{\alpha} f_{\alpha} \cdot \mathbf{x}^{\alpha}$$

- The *support* of f

$$\text{supp}(f) := \{\alpha \in \mathbb{N}^n \mid f_{\alpha} \neq 0\}$$

Leading Terms, Monomials, Coefficients

$$f(x, y) = x^2y + xy^{100} + xy^{99} + y^{200}$$

- Now we are ready to define special terms of polynomials

≙ lex

$$\text{mdeg}(f) = (2, 1)$$

$$f(\mathbf{x}) = \sum_{\alpha} f_{\alpha} \cdot \mathbf{x}^{\alpha}$$

≙ graded lex
 $\text{mdeg}(f) = y^{200}$

- The *support* of f

$$\text{supp}(f) := \{\alpha \in \mathbb{N}^n \mid f_{\alpha} \neq 0\}$$

- The *multidegree* of f is the maximum monomial in the support of f according to \succeq . Termed $\text{mdeg}(f)$.
- The *leading monomial* of f is $LM(f) := \mathbf{x}^{\text{mdeg}(f)}$
- The *leading coefficient* of f is $LC(f) := f_{\text{mdeg}(f)}$
- The *leading term* of f is $LC(f) \cdot LM(f)$.

A Division Algorithm - a first attempt $\overline{\mathbf{x}} = (x_1, \dots, x_n)$

- **Input:** polynomials $G, F_1, \dots, F_s \in \mathbb{F}[\mathbf{x}]$ and a monomial order \succeq
- **Output:** Q_1, \dots, Q_s , R $\in \mathbb{F}[\mathbf{x}]$ such that

$$G = F_1 \cdot Q_1 + \dots + F_s \cdot Q_s + R$$

where $\text{mdeg}(R) < \text{mdeg}(F_i)$ for $i \in [s]$

A Division Algorithm - a first attempt

- **Input:** polynomials $G, F_1, \dots, F_s \in \mathbb{F}[\mathbf{x}]$ and a monomial order \succ
- **Output:** $Q_1, \dots, Q_s, R \in \mathbb{F}[\mathbf{x}]$ such that

$$G = F_1 \cdot Q_1 + \dots + F_s \cdot Q_s + R$$

where $\text{mdeg}(R) < \text{mdeg}(F_i)$ for $i \in [s]$

- **Idea:** same as in one-variable case - cancel the leading term of G by using F_i

A Division Algorithm - a first attempt

- **Input:** polynomials $G, F_1, \dots, F_s \in \mathbb{F}[\mathbf{x}]$ and a monomial order \succeq
- **Output:** $Q_1, \dots, Q_s, R \in \mathbb{F}[\mathbf{x}]$ such that

$$G = F_1 \cdot Q_1 + \dots + F_s \cdot Q_s + R$$

where $\text{mdeg}(R) < \text{mdeg}(F_i)$ for $i \in [s]$

- **Idea:** same as in one-variable case - cancel the leading term of G by using F_i
- Example 1: $G = xy^2 + 1$, $F_1 = xy + 1$ and $F_2 = y + 1$

$$Q_2: -1$$

$$Q_1: y$$

$$F_2 = \underline{y+1}$$

$$F_1 = \underline{xy+1}$$

$$r = 2$$

$$\begin{array}{r} xy^2 + 1 \\ \underline{xy^2 + y} \\ -y + 1 \\ \underline{-y - 1} \\ 2/0 \end{array}$$

A Division Algorithm - a first attempt

- **Input:** polynomials $G, F_1, \dots, F_s \in \mathbb{F}[\mathbf{x}]$ and a monomial order \succ
- **Output:** $Q_1, \dots, Q_s, R \in \mathbb{F}[\mathbf{x}]$ such that

$$G = F_1 \cdot Q_1 + \dots + F_s \cdot Q_s + R$$

where $\text{mdeg}(R) < \text{mdeg}(F_i)$ for $i \in [s]$

- *Idea:* same as in one-variable case - cancel the leading term of G by using F_i
- Example 1: $G = xy^2 + 1$, $F_1 = xy + 1$ and $F_2 = y + 1$
- Thus we have

$$xy^2 + 1 = y \cdot (xy + 1) + (-1) \cdot (y + 1) + 2$$

A Division Algorithm - a first attempt

- **Input:** polynomials $G, F_1, \dots, F_s \in \mathbb{F}[\mathbf{x}]$ and a monomial order \succeq
- **Output:** $Q_1, \dots, Q_s, R \in \mathbb{F}[\mathbf{x}]$ such that

$$G = F_1 \cdot Q_1 + \dots + F_s \cdot Q_s + R$$

where ~~$\text{mdeg}(R) < \text{mdeg}(F_i)$~~ for $i \in [s]$

$\text{mdeg}(F_i) \nmid \alpha \in \text{supp}(R)$

- **Idea:** same as in one-variable case - cancel the leading term of G by using F_i
- Example 1: $G = xy^2 + 1$, $F_1 = xy + 1$ and $F_2 = y + 1$
- Thus we have

$$xy^2 + 1 = y \cdot (xy + 1) + (-1) \cdot (y + 1) + 2$$

- Quotients are not unique:

$$xy^2 + 1 = \underline{xy} \cdot \underline{(y + 1)} + \underline{(-1)} \cdot \underline{(xy + 1)} + 2$$

$$x^2 y > x y^{100}$$

but $x y^{100} \neq x^2 y$

problem for the division
question that we
posed

Division Algorithm - Subtlety

- The following subtlety comes because we have more than one variable
- Example 2: $G = x^2y + xy^2 + y^2$, $F_1 = xy - 1$ and $F_2 = y^2 - 1$ with lex order

$$Q_1 : x + y$$

$$Q_2 : 1$$

$$F_1 = xy - 1$$

$$F_2 = y^2 - 1$$

$$x = x + y + 1$$

$$\begin{array}{r} x^2y + xy^2 + y^2 \\ \hline x^2y - x \\ \hline xy^2 + x + y^2 \\ xy^2 - y \\ \hline x + y^2 + y \\ \hline y^2 + y \\ y^2 - 1 \end{array} \Big/ y + 1 \quad / 0$$

Division Algorithm - Subtlety

- The following subtlety comes because we have more than one variable
- Example 2: $G = x^2y + xy^2 + y^2$, $F_1 = xy - 1$ and $F_2 = y^2 - 1$ with lex order
- Thus we have

$$x^2y + xy^2 + y^2 = \underbrace{(x + y)} \cdot \underbrace{(xy - 1)} + \underbrace{1} \cdot \underbrace{(y^2 - 1)} + \underbrace{(x + y + 1)}$$

⌘

Division Algorithm - Subtlety

- The following subtlety comes because we have more than one variable
- Example 2: $G = x^2y + xy^2 + y^2$, $F_1 = xy - 1$ and $F_2 = y^2 - 1$ with lex order
- Thus we have

$$x^2y + xy^2 + y^2 = (x + y) \cdot (xy - 1) + 1 \cdot (y^2 - 1) + (x + y + 1)$$

- So, instead of requiring that the leading term of remainder be smaller than leading term of divisors, better to require that *no monomial* of R is divisible by *any leading monomial* of the F_i 's

A Division Algorithm - second attempt

- **Input:** polynomials $G, F_1, \dots, F_s \in \mathbb{F}[\mathbf{x}]$
- **Output:** $Q_1, \dots, Q_s, R \in \mathbb{F}[\mathbf{x}]$ such that

$$G = \underline{F_1} \cdot \underline{Q_1} + \dots + \underline{F_s} \cdot \underline{Q_s} + \underline{R}$$

no monomial of R be divisible by any leading term of the F_i 's.
Furthermore if $F_i Q_i \neq 0$, we also want:

$$LM(G) \succeq LM(F_i Q_i)$$

A Division Algorithm - second attempt

- **Input:** polynomials $G, F_1, \dots, F_s \in \mathbb{F}[\mathbf{x}]$
- **Output:** $Q_1, \dots, Q_s, R \in \mathbb{F}[\mathbf{x}]$ such that

$$G = F_1 \cdot Q_1 + \dots + F_s \cdot Q_s + R$$

no monomial of R be divisible by *any leading term* of the F_i 's.
Furthermore if $F_i Q_i \neq 0$, we also want:

$$LM(G) \succeq LM(F_i Q_i)$$

- Algorithm:
 - 1 While $LM(G)$ is divisible by some $LM(F_i)$, divide appropriately (respecting the order preference of F_i 's)
 - 2 If no $LM(F_i) \mid LM(G)$, add $LT(G)$ to the remainder and go back to step 1

A Division Algorithm - second attempt

- **Input:** polynomials $G, F_1, \dots, F_s \in \mathbb{F}[\mathbf{x}]$
- **Output:** $Q_1, \dots, Q_s, R \in \mathbb{F}[\mathbf{x}]$ such that

$$G = F_1 \cdot Q_1 + \dots + F_s \cdot Q_s + R$$

no monomial of R be divisible by *any leading term* of the F_i 's.
Furthermore if $F_i Q_i \neq 0$, we also want:

$$LM(G) \succeq LM(F_i Q_i)$$

- Algorithm:
 - 1 While $LM(G)$ is divisible by some $LM(F_i)$, divide appropriately (respecting the order preference of F_i 's)
 - 2 If no $LM(F_i) \mid LM(G)$, add $LT(G)$ to the remainder and go back to step 1
- The algorithm above always terminates.

A Division Algorithm - second attempt

- **Input:** polynomials $G, F_1, \dots, F_s \in \mathbb{F}[\mathbf{x}]$
- **Output:** $Q_1, \dots, Q_s, R \in \mathbb{F}[\mathbf{x}]$ such that

$$G = F_1 \cdot Q_1 + \dots + F_s \cdot Q_s + R$$

no monomial of R be divisible by *any leading term* of the F_i 's.
Furthermore if $F_i Q_i \neq 0$, we also want:

$$LM(G) \succeq LM(F_i Q_i)$$

- Algorithm:
 - 1 While $LM(G)$ is divisible by some $LM(F_i)$, divide appropriately (respecting the order preference of F_i 's)
 - 2 If no $LM(F_i) \mid LM(G)$, add $LT(G)$ to the remainder and go back to step 1
- The algorithm above always terminates.
- Proof is by well-ordering principle of the monomial order and fact that each step of division algorithm decreases leading term of G .

~~Pseudocode~~

Proof of termination

$$G^{(0)}, G^{(1)}, G^{(2)}, \dots$$

$$LM(G^{(0)}) \succ LM(G^{(1)}) \succ LM(G^{(2)}) \succ \dots$$

monomial ordering is a well ordering.

$S = \{LM(G^{(i)})\}$ must have a smallest element!

How does this generalize the two previous algorithms?

- Note that for univariate polynomials, the division algorithm works in the same way, if we consider the leading term of G one at a time

¹This is more appropriate when checking if a linear form is in the span of a set of other linear forms

How does this generalize the two previous algorithms?

- Note that for univariate polynomials, the division algorithm works in the same way, if we consider the leading term of G one at a time
- For row-echelon form, note that it is exactly the division algorithm when the polynomials are linear¹

¹This is more appropriate when checking if a linear form is in the span of a set of other linear forms

- Two Familiar Division Algorithms
- Generalization: Multivariate Multipolynomial Division
- **Issues with the division algorithm**
- Monomial Ideals & Dickson's Lemma
- Conclusion
- Acknowledgements

Does it have the properties we want?

- What properties would we want from a division algorithm?
 - ① remainder should be *uniquely determined*
 - ② ordering shouldn't really matter (especially since we are trying to use it to solve ideal membership problem)
 - ③ univariate division algorithm solves ideal membership problem - so our division algorithm should also solve it

$$g \in? (f_1, f_2) \\ (f_2, f_1)$$

$$g = f \cdot q + r \quad g \in (f) \text{ iff } r=0$$

Does it have the properties we want?

- What properties would we want from a division algorithm?
 - ① remainder should be *uniquely determined*
 - ② ordering shouldn't really matter (especially since we are trying to use it to solve ideal membership problem)
 - ③ univariate division algorithm solves ideal membership problem - so our division algorithm should also solve it
- Example 3: $G = x^2y + xy^2 + y^2$, $F_1 = y^2 - 1$ and $F_2 = xy - 1$ with lex order same as example 2 with order reversed

$$Q_1: x + 1$$

$$Q_2: x$$

$$F_1 = y^2 - 1$$

$$F_2 = xy - 1$$

$$x = 2x + 1$$

$$\begin{array}{r} x^2y + xy^2 + y^2 \\ \hline x^2y - x \\ \hline xy^2 + x + y^2 \\ \hline xy^2 - x \\ \hline \end{array}$$

$$\begin{array}{r} 2x + y^2 \\ \hline y^2 \\ \hline y^2 - 1 \\ \hline 1 \\ \hline 0 \end{array}$$

Does it have the properties we want?

- What properties would we want from a division algorithm?
 - ① remainder should be *uniquely determined*
 - ② ordering shouldn't really matter (especially since we are trying to use it to solve ideal membership problem)
 - ③ univariate division algorithm solves ideal membership problem - so our division algorithm should also solve it
- Example 3: $G = x^2y + xy^2 + y^2$, $F_1 = y^2 - 1$ and $F_2 = xy - 1$ with lex order same as example 2 with order reversed
- Note that remainder here is $2x + 1$, which is different from remainder in example 2: $(x + y + 1)$

Does it have the properties we want?

- What properties would we want from a division algorithm?
 - ① remainder should be *uniquely determined*
 - ② ordering shouldn't really matter (especially since we are trying to use it to solve ideal membership problem)
 - ③ univariate division algorithm solves ideal membership problem - so our division algorithm should also solve it
- Example 3: $G = x^2y + xy^2 + y^2$, $F_1 = y^2 - 1$ and $F_2 = xy - 1$ with lex order same as example 2 with order reversed
- Note that remainder here is $2x + 1$, which is different from remainder in example 2: $(x + y + 1)$
- Our division algorithm only gives *sufficient* condition for ideal membership problem: if G has zero remainder when divided by (F_1, \dots, F_s) then we know $G \in (F_1, \dots, F_s)$

Does it have the properties we want?

- What properties would we want from a division algorithm?
 - ① remainder should be *uniquely determined*
 - ② ordering shouldn't really matter (especially since we are trying to use it to solve ideal membership problem)
 - ③ univariate division algorithm solves ideal membership problem - so our division algorithm should also solve it
- Example 3: $G = x^2y + xy^2 + y^2$, $F_1 = y^2 - 1$ and $F_2 = xy - 1$ with lex order same as example 2 with order reversed
- Note that remainder here is $2x + 1$, which is different from remainder in example 2: $(x + y + 1)$
- Our division algorithm only gives *sufficient* condition for ideal membership problem: if G has zero remainder when divided by (F_1, \dots, F_s) then we know $G \in (F_1, \dots, F_s)$
- Example 4: $G = xy^2 - x$, $F_1 = xy - 1$ and $F_2 = y^2 - 1$

Does it have the properties we want?

- What properties would we want from a division algorithm?
 - ① remainder should be *uniquely determined*
 - ② ordering shouldn't really matter (especially since we are trying to use it to solve ideal membership problem)
 - ③ univariate division algorithm solves ideal membership problem - so our division algorithm should also solve it
- Example 3: $G = x^2y + xy^2 + y^2$, $F_1 = y^2 - 1$ and $F_2 = xy - 1$ with lex order same as example 2 with order reversed
- Note that remainder here is $2x + 1$, which is different from remainder in example 2: $(x + y + 1)$
- Our division algorithm only gives *sufficient* condition for ideal membership problem: if G has zero remainder when divided by (F_1, \dots, F_s) then we know $G \in (F_1, \dots, F_s)$
- Example 4: $G = xy^2 - x$, $F_1 = xy - 1$ and $F_2 = y^2 - 1$
- The “fix” for this division algorithm is to find a *good basis* for the ideal generated by F_1, \dots, F_s - the so-called Gröbner basis

- Two Familiar Division Algorithms
- Generalization: Multivariate Multipolynomial Division
- Issues with the division algorithm
- **Monomial Ideals & Dickson's Lemma**
- Conclusion
- Acknowledgements

Description of Ideals

- In the definition of algebraic sets, we used any family of polynomials \mathcal{F} to define an algebraic set (or the ideal $I_{\mathcal{F}}$).

Question

Does every ideal of $\mathbb{F}[x_1, \dots, x_n]$ have a *finite* description?

²Which was in fact first proved by Gordan.

Description of Ideals

- In the definition of algebraic sets, we used any family of polynomials \mathcal{F} to define an algebraic set (or the ideal $I_{\mathcal{F}}$).

Question

Does every ideal of $\mathbb{F}[x_1, \dots, x_n]$ have a *finite* description?

- Today we will address this question for *monomial ideals*. This will be done by Dickson's lemma²

²Which was in fact first proved by Gordan.

Description of Ideals

- In the definition of algebraic sets, we used any family of polynomials \mathcal{F} to define an algebraic set (or the ideal $I_{\mathcal{F}}$).

Question

Does every ideal of $\mathbb{F}[x_1, \dots, x_n]$ have a *finite* description?

- Today we will address this question for *monomial ideals*. This will be done by Dickson's lemma²
- A monomial ideal is any ideal generated by a family \mathcal{F} of monomials (not necessarily a finite number of them)

²Which was in fact first proved by Gordan.

Description of Ideals

- In the definition of algebraic sets, we used any family of polynomials \mathcal{F} to define an algebraic set (or the ideal $I_{\mathcal{F}}$).

Question

Does every ideal of $\mathbb{F}[x_1, \dots, x_n]$ have a *finite* description?

- Today we will address this question for *monomial ideals*. This will be done by Dickson's lemma²
- A monomial ideal is any ideal generated by a family \mathcal{F} of monomials (not necessarily a finite number of them)

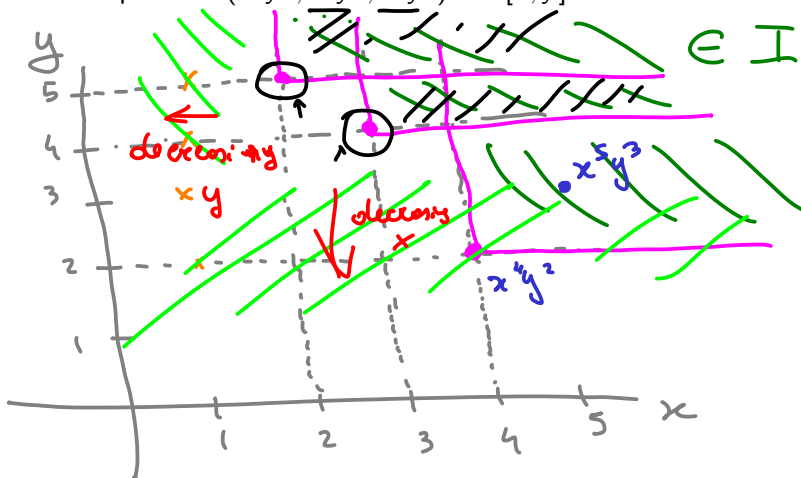
Theorem (Dickson's lemma)

Let $I = (\mathbf{x}^\alpha \mid \alpha \in \mathcal{F}) \subset \mathbb{F}[x_1, \dots, x_n]$ be a monomial ideal. Then I can be written as $I = (\mathbf{x}^{\alpha(1)}, \dots, \mathbf{x}^{\alpha(s)})$, where $\alpha(1), \dots, \alpha(s) \in \mathcal{F}$

²Which was in fact first proved by Gordan.

Dickson's Lemma - picture & example

- Example: $I = (x^4y^2, x^3y^4, x^2y^5) \subset \mathbb{F}[x, y]$



Proof of Dickson's Lemma

- Induction on number of variables:

Proof of Dickson's Lemma

- Induction on number of variables:

① $n = 1$ then we know all monomial ideals are generated by x_1^α for some $\alpha \in \mathbb{N}$. If $\beta \in \mathcal{F}$ is its *smallest* element, then we have $I = \underline{(x_1^\beta)}$

$$\mathcal{F} = \{x_1^\alpha\}_\alpha$$

$$\alpha \in \mathcal{F} \quad \text{is} \quad \alpha > \beta \Rightarrow x_1^\beta \mid x_1^\alpha$$

$$\Rightarrow x_1^\alpha \in (x_1^\beta) \Rightarrow \underline{\underline{I = (x_1^\beta)}}$$

Proof of Dickson's Lemma

- Induction on number of variables:

- 1 $n = 1$ then we know all monomial ideals are generated by x_1^α for some $\alpha \in \mathbb{N}$. If $\beta \in \mathcal{F}$ is its *smallest* element, then we have $I = (x_1^\beta)$
- 2 Suppose $n \geq 1$ and theorem proved for n . Let us now prove it for $n + 1$ variables. Rewrite variables as x_1, \dots, x_n, y .

Proof of Dickson's Lemma

- Induction on number of variables:

- ① $n = 1$ then we know all monomial ideals are generated by x_1^α for some $\alpha \in \mathbb{N}$. If $\beta \in \mathcal{F}$ is its *smallest* element, then we have $I = (x_1^\beta)$
- ② Suppose $n \geq 1$ and theorem proved for n . Let us now prove it for $n + 1$ variables. Rewrite variables as x_1, \dots, x_n, y .
- ③ Let $J \subseteq \mathbb{F}[x_1, \dots, x_n]$ be the monomial ideal generated by \mathbf{x}^α such that $\mathbf{x}^\alpha \cdot y^m \in I$ for some $m \geq 0$.

$$I = I_{\mathcal{F}}$$

$$J \subset \mathbb{F}[x_1, \dots, x_n]$$

Proof of Dickson's Lemma

- Induction on number of variables:

- ① $n = 1$ then we know all monomial ideals are generated by x_1^α for some $\alpha \in \mathbb{N}$. If $\beta \in \mathcal{F}$ is its *smallest* element, then we have $I = (x_1^\beta)$
- ② Suppose $n \geq 1$ and theorem proved for n . Let us now prove it for $n + 1$ variables. Rewrite variables as x_1, \dots, x_n, y .
- ③ Let $J \subseteq \mathbb{F}[x_1, \dots, x_n]$ be the monomial ideal generated by \mathbf{x}^α such that $\mathbf{x}^\alpha \cdot y^m \in I$ for some $m \geq 0$.
- ④ J is finitely generated, say $J = (\mathbf{x}^{\alpha(1)}, \dots, \mathbf{x}^{\alpha(s)})$

by induction hypothesis

Proof of Dickson's Lemma

- Induction on number of variables:

- ① $n = 1$ then we know all monomial ideals are generated by x_1^α for some $\alpha \in \mathbb{N}$. If $\beta \in \mathcal{F}$ is its *smallest* element, then we have $I = (x_1^\beta)$
- ② Suppose $n \geq 1$ and theorem proved for n . Let us now prove it for $n + 1$ variables. Rewrite variables as x_1, \dots, x_n, y .
- ③ Let $J \subseteq \mathbb{F}[x_1, \dots, x_n]$ be the monomial ideal generated by \mathbf{x}^α such that $\mathbf{x}^\alpha \cdot y^m \in I$ for some $m \geq 0$.
- ④ J is finitely generated, say $J = (\mathbf{x}^{\alpha(1)}, \dots, \mathbf{x}^{\alpha(s)})$
- ⑤ Let $m_i \in \mathbb{N}$ be smallest integer such that $\mathbf{x}^{\alpha(i)} \cdot y^{m_i} \in I$, and let $N := \max m_i$. And let $I_N := (\mathbf{x}^{\alpha(1)} \cdot y^{m_1}, \dots, \mathbf{x}^{\alpha(s)} \cdot y^{m_s})$

Proof of Dickson's Lemma

- Induction on number of variables:

- 1 $n = 1$ then we know all monomial ideals are generated by x_1^α for some $\alpha \in \mathbb{N}$. If $\beta \in \mathcal{F}$ is its *smallest* element, then we have $I = (x_1^\beta)$
- 2 Suppose $n \geq 1$ and theorem proved for n . Let us now prove it for $n + 1$ variables. Rewrite variables as x_1, \dots, x_n, y .
- 3 Let $J \subseteq \mathbb{F}[x_1, \dots, x_n]$ be the monomial ideal generated by \mathbf{x}^α such that $\mathbf{x}^\alpha \cdot y^m \in I$ for some $m \geq 0$.
- 4 J is finitely generated, say $J = (\mathbf{x}^{\alpha(1)}, \dots, \mathbf{x}^{\alpha(s)})$
- 5 Let $m_i \in \mathbb{N}$ be smallest integer such that $\mathbf{x}^{\alpha(i)} \cdot y^{m_i} \in I$, and let $N := \max m_i$. And let $I_N := (\mathbf{x}^{\alpha(1)} \cdot y^{m_1}, \dots, \mathbf{x}^{\alpha(s)} \cdot y^{m_s})$ ←
- 6 Any $\mathbf{x}^\beta y^m$ in I such that $m \geq N$ is in I_N .

$$x^\beta y^m \in I \Rightarrow x^\beta \in J \Rightarrow x^\beta \in (x^{\alpha(i)})$$

$$m \geq N \Rightarrow y^N \mid y^m \Rightarrow y^{m_i} x^{\alpha(i)} \mid y^N x^{\alpha(i)}$$

$$y^N x^{\alpha(i)} \mid y^m x^\beta \Rightarrow x^\beta y^m \in I_N$$

Proof of Dickson's Lemma

- Induction on number of variables:

- 1 $n = 1$ then we know all monomial ideals are generated by x_1^α for some $\alpha \in \mathbb{N}$. If $\beta \in \mathcal{F}$ is its *smallest* element, then we have $I = (x_1^\beta)$
- 2 Suppose $n \geq 1$ and theorem proved for n . Let us now prove it for $n + 1$ variables. Rewrite variables as x_1, \dots, x_n, y .
- 3 Let $J \subseteq \mathbb{F}[x_1, \dots, x_n]$ be the monomial ideal generated by \mathbf{x}^α such that $\mathbf{x}^\alpha \cdot y^m \in I$ for some $m \geq 0$.
- 4 J is finitely generated, say $J = (\mathbf{x}^{\alpha(1)}, \dots, \mathbf{x}^{\alpha(s)})$
- 5 Let $m_i \in \mathbb{N}$ be smallest integer such that $\mathbf{x}^{\alpha(i)} \cdot y^{m_i} \in I$, and let $N := \max m_i$. And let $I_N := (\mathbf{x}^{\alpha(1)} \cdot y^{m_1}, \dots, \mathbf{x}^{\alpha(s)} \cdot y^{m_s})$
- 6 Any $\mathbf{x}^\beta y^m$ in I such that $m \geq N$ is in I_N .
- 7 For $0 \leq \ell < N$, let $J_\ell \subseteq \mathbb{F}[\mathbf{x}]$ be the monomial ideal defined by $\mathbf{x}^\alpha \in J_\ell \Leftrightarrow \mathbf{x}^\alpha y^\ell \in I$. Also finitely generated. $J_\ell = (\mathbf{x}^{\alpha_\ell(1)}, \dots, \mathbf{x}^{\alpha_\ell(s_\ell)})$

deg(s)
small }

by induction hypothesis

Proof of Dickson's Lemma

- Induction on number of variables:

- ① $n = 1$ then we know all monomial ideals are generated by x_1^α for some $\alpha \in \mathbb{N}$. If $\beta \in \mathcal{F}$ is its *smallest* element, then we have $I = (x_1^\beta)$
- ② Suppose $n \geq 1$ and theorem proved for n . Let us now prove it for $n + 1$ variables. Rewrite variables as x_1, \dots, x_n, y .
- ③ Let $J \subseteq \mathbb{F}[x_1, \dots, x_n]$ be the monomial ideal generated by \mathbf{x}^α such that $\mathbf{x}^\alpha \cdot y^m \in I$ for some $m \geq 0$.
- ④ J is finitely generated, say $J = (\mathbf{x}^{\alpha(1)}, \dots, \mathbf{x}^{\alpha(s)})$
- ⑤ Let $m_i \in \mathbb{N}$ be smallest integer such that $\mathbf{x}^{\alpha(i)} \cdot y^{m_i} \in I$, and let $N := \max m_i$. And let $I_N := (\mathbf{x}^{\alpha(1)} \cdot y^{m_1}, \dots, \mathbf{x}^{\alpha(s)} \cdot y^{m_s})$
- ⑥ Any $\mathbf{x}^\beta y^m$ in I such that $m \geq N$ is in I_N .
- ⑦ For $0 \leq \ell < N$, let $J_\ell \subseteq \mathbb{F}[\mathbf{x}]$ be the monomial ideal defined by $\mathbf{x}^\alpha \in J_\ell \Leftrightarrow \mathbf{x}^\alpha y^\ell \in I$. Also finitely generated. $J_\ell = (\mathbf{x}^{\alpha_\ell(1)}, \dots, \mathbf{x}^{\alpha_\ell(s_\ell)})$
- ⑧ Let $I_\ell := (\mathbf{x}^{\alpha_\ell(1)} \cdot y^\ell, \dots, \mathbf{x}^{\alpha_\ell(s_\ell)} \cdot y^\ell)$

Proof of Dickson's Lemma

- Induction on number of variables:

- 1 $n = 1$ then we know all monomial ideals are generated by x_1^α for some $\alpha \in \mathbb{N}$. If $\beta \in \mathcal{F}$ is its *smallest* element, then we have $I = (x_1^\beta)$
- 2 Suppose $n \geq 1$ and theorem proved for n . Let us now prove it for $n + 1$ variables. Rewrite variables as x_1, \dots, x_n, y .
- 3 Let $J \subseteq \mathbb{F}[x_1, \dots, x_n]$ be the monomial ideal generated by \mathbf{x}^α such that $\mathbf{x}^\alpha \cdot y^m \in I$ for some $m \geq 0$.
- 4 J is finitely generated, say $J = (\mathbf{x}^{\alpha(1)}, \dots, \mathbf{x}^{\alpha(s)})$
- 5 Let $m_i \in \mathbb{N}$ be smallest integer such that $\mathbf{x}^{\alpha(i)} \cdot y^{m_i} \in I$, and let $N := \max m_i$. And let $I_N := (\mathbf{x}^{\alpha(1)} \cdot y^{m_1}, \dots, \mathbf{x}^{\alpha(s)} \cdot y^{m_s})$
- 6 Any $\mathbf{x}^\beta y^m$ in I such that $m \geq N$ is in I_N .
- 7 For $0 \leq \ell < N$, let $J_\ell \subseteq \mathbb{F}[\mathbf{x}]$ be the monomial ideal defined by $\mathbf{x}^\alpha \in J_\ell \Leftrightarrow \mathbf{x}^\alpha y^\ell \in I$. Also finitely generated. $J_\ell = (\mathbf{x}^{\alpha_\ell(1)}, \dots, \mathbf{x}^{\alpha_\ell(s_\ell)})$
- 8 Let $I_\ell := (\mathbf{x}^{\alpha_\ell(1)} \cdot y^\ell, \dots, \mathbf{x}^{\alpha_\ell(s_\ell)} \cdot y^\ell)$
- 9 Show that $I = I_0 + I_1 + \dots + I_N$

\supset each finitely generated

Proof of Dickson's lemma

$$I \subset \underbrace{I_0 + I_1 + \dots + I_N}$$

$$x^\beta y^m \in I \text{ if } m \geq N \text{ then } x^\beta y^m \in I_N$$

suppose $m < N$

$$\text{by definition } x^\beta \in J_m \Rightarrow \exists \alpha_m(i)$$

$$\text{s.t. } x^{\alpha_m(i)} \mid x^\beta$$

$$x^{\alpha_m(i)} \cdot y^m \mid y^m x^\beta \Rightarrow x^\beta y^m \in I_m$$

$$\cap \\ I_m$$

$$\Rightarrow I \subset I_0 + \dots + I_N \quad \square$$

Consequences of Dickson's lemma

- Dickson's lemma helps us decide if a monomial relation is a proper *monomial ordering*

Corollary (Monomial Order Criterion)

If $>$ is a relation on \mathbb{N}^n satisfying

- 1 $>$ is a total ordering on \mathbb{N}^n
- 2 $\alpha > \beta$ and $\gamma \in \mathbb{N}^n$ then $\alpha + \gamma > \beta + \gamma$

behaves well under $+$

Then $>$ is a well-ordering if, and only if, $\alpha \geq 0$ for all $\alpha \in \mathbb{N}^n$.

Consequences of Dickson's lemma

- Dickson's lemma helps us decide if a monomial relation is a proper *monomial ordering*

Corollary (Monomial Order Criterion)

If $>$ is a relation on \mathbb{N}^n satisfying

- 1 $>$ is a total ordering on \mathbb{N}^n
- 2 $\alpha > \beta$ and $\gamma \in \mathbb{N}^n$ then $\alpha + \gamma > \beta + \gamma$

Then $>$ is a well-ordering if, and only if, $\alpha \geq 0$ for all $\alpha \in \mathbb{N}^n$.

- As we will see later in the course, this is great as different monomial orderings are used for different purposes.
 - elimination ordering (variant of lex order)
 - graded rev-lex order used in most ideal membership tasks

Consequences of Dickson's lemma

- Dickson's lemma helps us decide if a monomial relation is a proper *monomial ordering*

Corollary (Monomial Order Criterion)

If $>$ is a relation on \mathbb{N}^n satisfying

- 1 $>$ is a total ordering on \mathbb{N}^n
- 2 $\alpha > \beta$ and $\gamma \in \mathbb{N}^n$ then $\alpha + \gamma > \beta + \gamma$

Then $>$ is a well-ordering if, and only if, $\alpha \geq 0$ for all $\alpha \in \mathbb{N}^n$.

- As we will see later in the course, this is great as different monomial orderings are used for different purposes.
 - elimination ordering
 - graded rev-lex order used in most ideal membership tasks
- From the set of bases for a monomial ideal, there is one which is better than others:

A *minimal basis* of a monomial ideal is one where none of the generators is divisible by another generator.

no
redundant
elements

- Two Familiar Division Algorithms
- Generalization: Multivariate Multipolynomial Division
- Issues with the division algorithm
- Monomial Ideals & Dickson's Lemma
- **Conclusion**
- Acknowledgements

Conclusion

- Today we learned about the division algorithm and Dickson's lemma
- Division algorithm generalizes univariate division algorithm and Gaussian elimination
- Division algorithm is not great - we will fix that by finding a good basis
- Dickson's lemma shows that monomial ideals are finitely generated
- Can use it to have easy criterion for checking monomial orderings
- Will use this lemma to prove Hilbert Basis Theorem

Acknowledgement

- Lecture based entirely on the book by CLO: Ideals, varieties and algorithms (see course webpage for a copy - or get online version through UW library)