

# Lecture 1: Amortized Analysis & Union Find

Rafael Oliveira

University of Waterloo  
Cheriton School of Computer Science

rafael.oliveira.teaching@gmail.com

September 14, 2020

# Overview

- Introduction
  - Why amortized analysis?
  - Types of amortized analyses
  - Union-Find
- Implementing Union-Find
  - Setup
  - First approach
  - Tree Representation & Path Compression
  - Analysis
- Acknowledgements

# Why Amortized Analysis?

In your first data structures course, you learned how to devise data structures that had good *worst-case* or *average-case* behaviour *per query*.

# Why Amortized Analysis?

In your first data structures course, you learned how to devise data structures that had good *worst-case* or *average-case* behaviour *per query*.

## Worst or average-case complexity of data structures

Data Structure	search	insertion	deletion
Doubly-Linked List	$O(n)$	$O(1)$	$O(n)$
Ordered Array	$O(\log n)$	$O(n)$	$O(n)$
Hash Tables <sup>a</sup>	$O(1)$	$O(1)$	$O(1)$
Balanced Binary Search Trees <sup>b</sup>	$O(\log n)$	$O(\log n)$	$O(\log n)$

<sup>a</sup>Average-case, although worst-case search time is  $\Theta(n)$

<sup>b</sup>Also average-case. Worst-case complexity is  $O(\text{height})$  of the tree, which can be  $\Theta(n)$ .

# Why Amortized Analysis?

In **amortized analysis**, one averages the *total time* required to perform a sequence of data-structure operations over *all operations performed*.

Upshot of amortized analysis: worst-case cost *per query* may be high for one particular query, so long as overall average cost per query is small in the end!

## Remark

Amortized analysis is a *worst-case* analysis. That is, it measures the average performance of each operation in the worst case.

# Types of amortized analyses

Three common types of amortized analyses:

# Types of amortized analyses

Three common types of amortized analyses:

- 1 **Aggregate Analysis:** determine upper bound  $T(n)$  on total cost of sequence of  $n$  operations. So amortized complexity is  $T(n)/n$ .

# Types of amortized analyses

Three common types of amortized analyses:

- 1 **Aggregate Analysis:** determine upper bound  $T(n)$  on total cost of sequence of  $n$  operations. So amortized complexity is  $T(n)/n$ .
- 2 **Accounting Method:** assign certain *charge* to each operation (independent of the actual cost of the operation). If operation is cheaper than the charge, then build up credit to use later.



# Types of amortized analyses

Three common types of amortized analyses:

- 1 **Aggregate Analysis:** determine upper bound  $T(n)$  on total cost of sequence of  $n$  operations. So amortized complexity is  $T(n)/n$ .
- 2 **Accounting Method:** assign certain *charge* to each operation (independent of the actual cost of the operation). If operation is cheaper than the charge, then build up credit to use later.
- 3 **Potential Method:** one comes up with *potential energy* of a data structure, which maps each state of entire data-structure to a real number (its “potential”). Differs from accounting method because we assign credit to the data structure as a whole, instead of assigning credit to each operation.

## Why Union Find?

Certain problems/applications require one to maintain/group distinct elements into a collection of disjoint sets. For instance: maintaining connected components of a graph which keeps changing over time.

## Why Union Find?

Certain problems/applications require one to maintain/group distinct elements into a collection of disjoint sets. For instance: maintaining connected components of a graph which keeps changing over time.

Uses: graph algorithms, social network graphs, etc.

These applications require data structure to perform two operations:

# Why Union Find?

Certain problems/applications require one to maintain/group distinct elements into a collection of disjoint sets. For instance: maintaining connected components of a graph which keeps changing over time.

Uses: graph algorithms, social network graphs, etc.

These applications require data structure to perform two operations:

- 1 Find the unique set containing a particular element
  - 1 Input: element  $v$  from universe of elements
  - 2 Output: set containing  $v$

# Why Union Find?

Certain problems/applications require one to maintain/group distinct elements into a collection of disjoint sets. For instance: maintaining connected components of a graph which keeps changing over time.

Uses: graph algorithms, social network graphs, etc.

These applications require data structure to perform two operations:

- 1 Find the unique set containing a particular element
  - 1 Input: element  $v$  from universe of elements
  - 2 Output: set containing  $v$
- 2 Take union of two disjoint sets
  - 1 Input: two sets  $A, B$  from you current collection of sets
  - 2 Output: updated collection of sets, i.e. with  $A \cup B$  and without  $A, B$

## Application: Kruskal's minimum spanning tree algorithm

**Input:** graph  $G(V, E)$  and edge weights  $w : E \rightarrow \mathbb{N}$

**Output:** spanning tree  $T$  of minimum weight among all spanning trees.

## Application: Kruskal's minimum spanning tree algorithm

**Input:** graph  $G(V, E)$  and edge weights  $w : E \rightarrow \mathbb{N}$

**Output:** spanning tree  $T$  of minimum weight among all spanning trees.

- 1 Sort edges  $e_1, \dots, e_{|E|}$  by weight such that  $w(e_i) \leq w(e_{i+1})$

## Application: Kruskal's minimum spanning tree algorithm

**Input:** graph  $G(V, E)$  and edge weights  $w : E \rightarrow \mathbb{N}$

**Output:** spanning tree  $T$  of minimum weight among all spanning trees.

- 1 Sort edges  $e_1, \dots, e_{|E|}$  by weight such that  $w(e_i) \leq w(e_{i+1})$
- 2 Set  $T \leftarrow \emptyset$  (each vertex is a component by itself)



## Application: Kruskal's minimum spanning tree algorithm

**Input:** graph  $G(V, E)$  and edge weights  $w : E \rightarrow \mathbb{N}$

**Output:** spanning tree  $T$  of minimum weight among all spanning trees.

- 1 Sort edges  $e_1, \dots, e_{|E|}$  by weight such that  $w(e_i) \leq w(e_{i+1})$
- 2 Set  $T \leftarrow \emptyset$  (each vertex is a component by itself)
- 3 for  $i = 1, \dots, |E|$ :

## Application: Kruskal's minimum spanning tree algorithm

**Input:** graph  $G(V, E)$  and edge weights  $w : E \rightarrow \mathbb{N}$

**Output:** spanning tree  $T$  of minimum weight among all spanning trees.

- 1 Sort edges  $e_1, \dots, e_{|E|}$  by weight such that  $w(e_i) \leq w(e_{i+1})$
- 2 Set  $T \leftarrow \emptyset$  (each vertex is a component by itself)
- 3 for  $i = 1, \dots, |E|$ :
  - 1 if endpoints of  $e_i$  in different connected components of  $T$  (use two find operations on endpoints of  $e_i$  to check this step)
    - $T \leftarrow T \cup \{e_i\}$
    - combine the connected components of endpoints of  $e_i$  (union operation)

## Application: Kruskal's minimum spanning tree algorithm

**Input:** graph  $G(V, E)$  and edge weights  $w : E \rightarrow \mathbb{N}$

**Output:** spanning tree  $T$  of minimum weight among all spanning trees.

- 1 Sort edges  $e_1, \dots, e_{|E|}$  by weight such that  $w(e_i) \leq w(e_{i+1})$
- 2 Set  $T \leftarrow \emptyset$  (each vertex is a component by itself)
- 3 for  $i = 1, \dots, |E|$ :
  - 1 if endpoints of  $e_i$  in different connected components of  $T$  (use two find operations on endpoints of  $e_i$  to check this step)
    - $T \leftarrow T \cup \{e_i\}$
    - combine the connected components of endpoints of  $e_i$  (union operation)
- 4 return  $T$

## Application: Kruskal's minimum spanning tree algorithm

**Input:** graph  $G(V, E)$  and edge weights  $w : E \rightarrow \mathbb{N}$

**Output:** spanning tree  $T$  of minimum weight among all spanning trees.

- 1 Sort edges  $e_1, \dots, e_{|E|}$  by weight such that  $w(e_i) \leq w(e_{i+1})$
- 2 Set  $T \leftarrow \emptyset$  (each vertex is a component by itself)
- 3 for  $i = 1, \dots, |E|$ :
  - 1 if endpoints of  $e_i$  in different connected components of  $T$  (use two find operations on endpoints of  $e_i$  to check this step)
    - $T \leftarrow T \cup \{e_i\}$
    - combine the connected components of endpoints of  $e_i$  (union operation)
- 4 return  $T$

### Remark

In this application, we care about the *total cost* of all operations (unions and finds). Thus, amortized analysis is better than worst-case per query.

# Example

## Example (continued)

- Introduction
  - Why amortized analysis?
  - Types of amortized analyses
  - Union-Find
- Implementing Union-Find
  - Setup
  - First approach
  - Tree Representation & Path Compression
  - Analysis
- Acknowledgements

# Setup

Notation:

---

<sup>1</sup>Number of unions is  $\leq n - 1$ . We will assume that  $m \geq n$



# Setup

Notation:

- $n \leftarrow$  number of elements (we denote the elements by  $1, 2, \dots, n$ )

---

<sup>1</sup>Number of unions is  $\leq n - 1$ . We will assume that  $m \geq n$

# Setup

Notation:

- $n \leftarrow$  number of elements (we denote the elements by  $1, 2, \dots, n$ )
- $m \leftarrow$  number of operations. That is

$$m = (\text{number of finds}) + (\text{number of unions})^1$$

---

<sup>1</sup>Number of unions is  $\leq n - 1$ . We will assume that  $m \geq n$

# Setup

Notation:

- $n \leftarrow$  number of elements (we denote the elements by  $1, 2, \dots, n$ )
- $m \leftarrow$  number of operations. That is

$$m = (\text{number of finds}) + (\text{number of unions})^1$$

- $FIND(k) \leftarrow$  find the set containing element  $k$

---

<sup>1</sup>Number of unions is  $\leq n - 1$ . We will assume that  $m \geq n$

# Setup

Notation:

- $n \leftarrow$  number of elements (we denote the elements by  $1, 2, \dots, n$ )
- $m \leftarrow$  number of operations. That is

$$m = (\text{number of finds}) + (\text{number of unions})^1$$

- $FIND(k) \leftarrow$  find the set containing element  $k$
- $UNION(A, B) \leftarrow$  updates data structure by deleting sets  $A, B$  and constructing  $A \cup B$

---

<sup>1</sup>Number of unions is  $\leq n - 1$ . We will assume that  $m \geq n$

## Naive approach

Keep an array  $S$  of size  $n$  where

$S[i]$  contains the name of set containing element  $i$ .

## Naive approach

Keep an array  $S$  of size  $n$  where

$S[i]$  contains the name of set containing element  $i$ .

In this case, we have

- $FIND(k)$  takes time  $O(1)$  (per operation)
- $UNION(A, B)$  takes time  $O(|A| + |B|)$ . Thus,  $\Theta(n)$  worst case (per operation)

## Naive approach

Keep an array  $S$  of size  $n$  where

$S[i]$  contains the name of set containing element  $i$ .

In this case, we have

- $FIND(k)$  takes time  $O(1)$  (per operation)
- $UNION(A, B)$  takes time  $O(|A| + |B|)$ . Thus,  $\Theta(n)$  worst case (per operation)

No amortized analysis yet.

## Naive approach

Keep an array  $S$  of size  $n$  where

$S[i]$  contains the name of set containing element  $i$ .

In this case, we have

- $FIND(k)$  takes time  $O(1)$  (per operation)
- $UNION(A, B)$  takes time  $O(|A| + |B|)$ . Thus,  $\Theta(n)$  worst case (per operation)

No amortized analysis yet.

What if when taking the union of  $A$  and  $B$ , we only change name of the set of least size?



## Naive Approach

What if when taking *UNION*, we only change name of the set of least size?

## Naive Approach

What if when taking *UNION*, we only change name of the set of least size?

We will use *aggregate analysis* for this case: that is, determine upper bound on total cost of all operations.

## Naive Approach

What if when taking *UNION*, we only change name of the set of least size?

We will use *aggregate analysis* for this case: that is, determine upper bound on total cost of all operations.

Cost of all unions =  $O(n \log n)$ , as for each element  $i \in \{1, \dots, n\}$ , we have that the *UNION* operation will change  $S[i]$  at most  $\log n$  times.

### Proof.

Every time we change  $S[i]$ , the size of the set containing element  $i$  doubles. □

## Naive Approach

What if when taking *UNION*, we only change name of the set of least size?

We will use *aggregate analysis* for this case: that is, determine upper bound on total cost of all operations.

Cost of all unions =  $O(n \log n)$ , as for each element  $i \in \{1, \dots, n\}$ , we have that the *UNION* operation will change  $S[i]$  at most  $\log n$  times.

### Proof.

Every time we change  $S[i]$ , the size of the set containing element  $i$  doubles. □

Thus, cost of  $m$  operations is  $O(m + n \log n)$  and we get that amortized cost is  $O\left(1 + \frac{n \log n}{m}\right)$ . If  $m = \Omega(n \log n)$  this is best possible.

## Naive Approach

What if when taking *UNION*, we only change name of the set of least size?

We will use *aggregate analysis* for this case: that is, determine upper bound on total cost of all operations.

Cost of all unions =  $O(n \log n)$ , as for each element  $i \in \{1, \dots, n\}$ , we have that the *UNION* operation will change  $S[i]$  at most  $\log n$  times.

### Proof.

Every time we change  $S[i]$ , the size of the set containing element  $i$  doubles. □

Thus, cost of  $m$  operations is  $O(m + n \log n)$  and we get that amortized cost is  $O\left(1 + \frac{n \log n}{m}\right)$ . If  $m = \Omega(n \log n)$  this is best possible.

Are we done? What if  $m = o(n \log n)$ , can we do better?

# Tree Representation

Represent each set as a tree of parent pointers. Each set will have its root as its representative element.

# Tree Representation

Represent each set as a tree of parent pointers. Each set will have its root as its representative element.

- $FIND(k) \leftarrow$  walk up the tree from  $k$  and output name of the root

# Tree Representation

Represent each set as a tree of parent pointers. Each set will have its root as its representative element.

- $FIND(k) \leftarrow$  walk up the tree from  $k$  and output name of the root
- $UNION(A, B) \leftarrow$  link both trees by making “smaller” tree’s root point to “larger” tree’s root.



# Tree Representation

Represent each set as a tree of parent pointers. Each set will have its root as its representative element.

- $FIND(k) \leftarrow$  walk up the tree from  $k$  and output name of the root
- $UNION(A, B) \leftarrow$  link both trees by making “smaller” tree’s root point to “larger” tree’s root.

## Question

*How to define “smaller” (i.e., the “size” of a tree)?*

# Tree Representation

Represent each set as a tree of parent pointers. Each set will have its root as its representative element.

- $FIND(k) \leftarrow$  walk up the tree from  $k$  and output name of the root
- $UNION(A, B) \leftarrow$  link both trees by making “smaller” tree’s root point to “larger” tree’s root.

## Question

*How to define “smaller” (i.e., the “size” of a tree)?*

- What if we define the size of a tree to be number of elements?
- What if we define the size of a tree to be it’s height (longest path from leaf to root)?

## Bad instances

- What if we define the size of a tree to be number of elements?

## Bad instances

- What if we define the size of a tree to be its height (longest path from leaf to root)?

# Path Compression

To fix problems above, need path compression (i.e. make all trees “flat”).

## Definition (Path compression)

After each  $FIND(k)$ , for every node  $j$  on path  $k \rightarrow \dots \rightarrow \text{root}$ , set

$$PARENT(j) \leftarrow \text{root}.$$

# Path Compression

To fix problems above, need path compression (i.e. make all trees “flat”).

## Definition (Path compression)

After each  $FIND(k)$ , for every node  $j$  on path  $k \rightarrow \dots \rightarrow \text{root}$ , set

$$PARENT(j) \leftarrow \text{root}.$$

This doubles the work of  $FIND$ , but that is fine, since it has same  $O(\cdot)$  complexity. (no effect on asymptotics)

# Path Compression

To fix problems above, need path compression (i.e. make all trees “flat”).

## Definition (Path compression)

After each  $FIND(k)$ , for every node  $j$  on path  $k \rightarrow \dots \rightarrow \text{root}$ , set

$$PARENT(j) \leftarrow \text{root}.$$

This doubles the work of  $FIND$ , but that is fine, since it has same  $O(\cdot)$  complexity. (no effect on asymptotics)

This messes up the height of the tree, as path compression may change it.

# Rank of a tree

## Definition (Rank of tree)

For each tree with root  $r$ , define  $\text{rank}(r)$  as follows:

- if the tree is a single element ( $r$  in this case)  $\text{rank}(r) = 0$
- when performing union of two trees with roots  $r_1, r_2$ , if  $\text{rank}(r_1) \geq \text{rank}(r_2)$ , then
  - make  $r_1$  the new root
  - set  $\text{rank}(r_1) \leftarrow \max(\text{rank}(r_1), \text{rank}(r_2) + 1)$ .



# Rank of a tree

## Definition (Rank of tree)

For each tree with root  $r$ , define  $\text{rank}(r)$  as follows:

- if the tree is a single element ( $r$  in this case)  $\text{rank}(r) = 0$
- when performing union of two trees with roots  $r_1, r_2$ , if  $\text{rank}(r_1) \geq \text{rank}(r_2)$ , then
  - make  $r_1$  the new root
  - set  $\text{rank}(r_1) \leftarrow \max(r_1, r_2 + 1)$ .

**Intuition:** rank of a tree is the height if *no path compressions* had been done.

# Final Algorithm

**Input:** set of elements  $\{1, 2, \dots, n\}$

**Output:** at each step, a union-find data structure comprised of disjoint union of sets whose union is  $\{1, 2, \dots, n\}$

- 1 Start with each set being  $\{k\}$ , where  $k \in \{1, \dots, n\}$ . Set  $\text{rank}(k) = 0$ .
- 2  $UNION(S_1, S_2)$ : where  $r_1, r_2$  are the roots of  $S_1, S_2$   
**if**  $\text{rank}(r_1) \geq \text{rank}(r_2)$ :
  - 1 make  $\text{root}(S_1 \cup S_2) = r_1$ , by creating pointer  $r_2 \rightarrow r_1$ .
  - 2  $\text{rank}(r_1) = \max(\text{rank}(r_1), \text{rank}(r_2) + 1)$**else:**
  - 1 make  $\text{root}(S_1 \cup S_2) = r_2$ , by creating pointer  $r_1 \rightarrow r_2$ .
  - 2  $\text{rank}(r_2) = \max(\text{rank}(r_2), \text{rank}(r_1) + 1)$
- 3  $FIND(k)$ : walk up the tree from  $k$  to the root of its tree. Return name of root, and perform path compression.

# Analysis

## Theorem ([Tarjan 1975])

*The amortized cost per operation of union-find is  $\Theta(\alpha(m, n))$ , where  $\alpha(m, n)$  is the inverse Ackermann function. That is, the (worst-case) cost of  $m$  operations is  $\Theta(m \cdot \alpha(m, n))$ .*

# Analysis

## Theorem ([Tarjan 1975])

*The amortized cost per operation of union-find is  $\Theta(\alpha(m, n))$ , where  $\alpha(m, n)$  is the inverse Ackermann function. That is, the (worst-case) cost of  $m$  operations is  $\Theta(m \cdot \alpha(m, n))$ .*

## Remark

Note the  $\Theta$  in the statement. This means that the bound above is tight. Many tight examples exist.

# Analysis

## Theorem ([Tarjan 1975])

*The amortized cost per operation of union-find is  $\Theta(\alpha(m, n))$ , where  $\alpha(m, n)$  is the inverse Ackermann function. That is, the (worst-case) cost of  $m$  operations is  $\Theta(m \cdot \alpha(m, n))$ .*

## Remark

Note the  $\Theta$  in the statement. This means that the bound above is tight. Many tight examples exist.

## Remark

Inverse Ackermann function is mega-hyper-super slow growing. For more about the Ackermann function and its inverse, see [https://en.wikipedia.org/wiki/Ackermann\\_function](https://en.wikipedia.org/wiki/Ackermann_function).

## Analysis

In this class, we will see a weaker amortized bound of  $O(\log^*(n))$  per operation. For another analysis, see [Seidel, Sharir 2005]. We will use the *accounting method*.

## Analysis

In this class, we will see a weaker amortized bound of  $O(\log^*(n))$  per operation. For another analysis, see [Seidel, Sharir 2005]. We will use the *accounting method*.

### Definition

$$\log^*(n) := \min\{i \mid \log^{(i)}(n) \leq 1\},$$

where  $\log^{(i)}$  means that we apply the log function  $i$  times.

n	1	2	3, 4 = $2^2$	5, ..., 16 = $2^{2^2}$	17, ..., 65536 = $2^{16}$
$\log^*(n)$	0	1	2	3	4

## Analysis

In this class, we will see a weaker amortized bound of  $O(\log^*(n))$  per operation. For another analysis, see [Seidel, Sharir 2005]. We will use the *accounting method*.

### Definition

$$\log^*(n) := \min\{i \mid \log^{(i)}(n) \leq 1\},$$

where  $\log^{(i)}$  means that we apply the log function  $i$  times.

n	1	2	3, 4 = 2 <sup>2</sup>	5, ..., 16 = 2 <sup>2<sup>2</sup></sup>	17, ..., 65536 = 2 <sup>16</sup>
log <sup>*</sup> (n)	0	1	2	3	4

In the accounting method, we need to choose a charge to each operation  $\hat{c}_i$  such that

$$\sum_{i=1}^{\ell} \hat{c}_i \geq \sum_{i=1}^{\ell} c_i$$

for all  $\ell \leq m$ , where  $c_i$  is the actual cost of the  $i^{\text{th}}$  operation.



## Final Algorithm - recap

**Input:** set of elements  $\{1, 2, \dots, n\}$

**Output:** at each step, a union-find data structure comprised of disjoint union of sets whose union is  $\{1, 2, \dots, n\}$

- 1 Start with each set being  $\{k\}$ , where  $k \in \{1, \dots, n\}$ . Set  $\text{rank}(k) = 0$ .
- 2  $UNION(S_1, S_2)$ : where  $r_1, r_2$  are the roots of  $S_1, S_2$   
**if**  $\text{rank}(r_1) \geq \text{rank}(r_2)$ :
  - 1 make  $\text{root}(S_1 \cup S_2) = r_1$ , by creating pointer  $r_2 \rightarrow r_1$ .
  - 2  $\text{rank}(r_1) = \max(\text{rank}(r_1), \text{rank}(r_2) + 1)$**else:**
  - 1 make  $\text{root}(S_1 \cup S_2) = r_2$ , by creating pointer  $r_1 \rightarrow r_2$ .
  - 2  $\text{rank}(r_2) = \max(\text{rank}(r_2), \text{rank}(r_1) + 1)$
- 3  $FIND(k)$ : walk up the tree from  $k$  to the root of its tree. Return name of root, and perform path compression.

# Analysis

The complex operation is *FIND*, since we will perform *path compression*.

# Analysis

The complex operation is *FIND*, since we will perform *path compression*.

## Claim

When an element  $k$  is assigned  $\text{rank}(k) = r$  then  $k$  has  $\geq 2^r$  descendants.

## Analysis

The complex operation is *FIND*, since we will perform *path compression*.

### Claim

When an element  $k$  is assigned  $\text{rank}(k) = r$  then  $k$  has  $\geq 2^r$  descendants.

### Claim

$\text{rank}(k) < \text{rank}(\text{parent}(k))$

## Analysis

The complex operation is *FIND*, since we will perform *path compression*.

### Claim

When an element  $k$  is assigned  $\text{rank}(k) = r$  then  $k$  has  $\geq 2^r$  descendants.

### Claim

$\text{rank}(k) < \text{rank}(\text{parent}(k))$

### Claim

Number of vertices of rank  $r$  is  $\leq n/2^r$ .

# Grouping Elements Based on Rank

**Idea:** divide vertices into groups based on rank.

Element of rank  $r$  goes into group  $\log^*(r)$ . In particular, for element  $k$ , we have:

$$\mathit{group}(k) := \log^*(\mathit{rank}(k))$$

# Grouping Elements Based on Rank

**Idea:** divide vertices into groups based on rank.

Element of rank  $r$  goes into group  $\log^*(r)$ . In particular, for element  $k$ , we have:

$$\text{group}(k) := \log^*(\text{rank}(k))$$

## Remark

Number of groups:  $\log^*(n)$ .

## Analysis

Actual cost of  $FIND(k)$ : distance from  $k$  to root.

**Idea:** charge some of this cost to  $FIND$  and some to nodes along path.



# Analysis

Actual cost of  $FIND(k)$ : distance from  $k$  to root.

**Idea:** charge some of this cost to  $FIND$  and some to nodes along path.

Charging scheme:

- 1  $FIND(k)$ 
  - For each element  $u$  in the path  $k \rightarrow$  root:
    - if  $u$  has parent and grandparent in path and  $group(u) = group(parent(u))$ , then charge 1 to  $u$
    - else charge 1 to  $FIND(k)$ .
- 2  $UNION(A, B)$ : just charge 1 to this operation

# Analysis

Actual cost of  $FIND(k)$ : distance from  $k$  to root.

**Idea:** charge some of this cost to  $FIND$  and some to nodes along path.

Charging scheme:

- 1  $FIND(k)$ 
  - For each element  $u$  in the path  $k \rightarrow$  root:
    - if  $u$  has parent and grandparent in path and  $group(u) = group(parent(u))$ , then charge 1 to  $u$
    - else charge 1 to  $FIND(k)$ .
- 2  $UNION(A, B)$ : just charge 1 to this operation

## Remark

Note that charging scheme for  $FIND(k)$  and nodes covers the actual cost of  $FIND(k)$ , since we are charging either the node on the path or the operation  $FIND(k)$ .

Since charging for  $UNION$  also covers the cost of the union operation, we have a valid charging scheme.

## Charging Scheme Formally

So, how do we define the charges to  $FIND(k)$ ?

$$\hat{c}_i(FIND(k)) = \tilde{c}_i(FIND(k)) + \sum_{u \in \text{path } k \rightarrow u} (\text{charge to } u)$$

## Analysis

Now we need to analyse the total amortized cost of this charging scheme.

# Analysis

Now we need to analyse the total amortized cost of this charging scheme.

- Total charge to each  $FIND(k)$  is  $\leq \log^*(n) + 1$ 
  - Group changes  $\leq \log^*(n) - 1$  times
  - +2 for root of tree and child of root of tree
- Total charge to each element of  $\{1, \dots, n\}$ :
  - if  $k$  is charged in a path compression, then  $k$  is not root and path compression will give it a parent of higher rank than old parent.
  - if  $k$  has a parent in a higher group, then  $k$  will no longer be charged.
  - thus, if  $group(k) = g$  then  $k$  can be charged at most

$$(\text{number of ranks in group } g) - 1 \leq 2 \uparrow g$$

## Analysis

Now we need to analyse the total amortized cost of this charging scheme.

- Total charge to each  $FIND(k)$  is  $\leq \log^*(n) + 1$ 
  - Group changes  $\leq \log^*(n) - 1$  times
  - +2 for root of tree and child of root of tree
- Total charge to each element of  $\{1, \dots, n\}$ :
  - if  $k$  is charged in a path compression, then  $k$  is not root and path compression will give it a parent of higher rank than old parent.
  - if  $k$  has a parent in a higher group, then  $k$  will no longer be charged.
  - thus, if  $group(k) = g$  then  $k$  can be charged at most

$$(\text{number of ranks in group } g) - 1 \leq 2 \uparrow g$$

Let  $N(g)$  be number of elements in group  $g$ . Then

$$N(g) \leq \sum_{r=2 \uparrow (g-1)+1}^{2 \uparrow g} \frac{n}{2^r} \leq \frac{n}{2^{2 \uparrow (g-1)+1}} \cdot \sum_0^{\infty} 1/2^i = \frac{n}{2 \uparrow g}$$

## Analysis

- ① Thus, total charge to all elements in group  $g$ :

$$(\text{total charge per element in group } g) \cdot N(g) \leq (2 \uparrow g) \cdot \frac{n}{2 \uparrow g} = n$$

# Analysis

- ① Thus, total charge to all elements in group  $g$ :

$$(\text{total charge per element in group } g) \cdot N(g) \leq (2 \uparrow g) \cdot \frac{n}{2 \uparrow g} = n$$

- ② Total charge to all elements of  $\{1, \dots, n\}$ :

$$(\text{charge to all elements in group } g) \cdot (\text{number of groups}) \leq n \cdot \log^*(n)$$



# Analysis

- ① Thus, total charge to all elements in group  $g$ :

$$(\text{total charge per element in group } g) \cdot N(g) \leq (2 \uparrow g) \cdot \frac{n}{2 \uparrow g} = n$$

- ② Total charge to all elements of  $\{1, \dots, n\}$ :

$$(\text{charge to all elements in group } g) \cdot (\text{number of groups}) \leq n \cdot \log^*(n)$$

- ③ Total charge to all *FIND* operations:

$$(\text{number of } FIND \text{ operations}) \cdot (\text{charge per } FIND) \leq m \cdot (\log^*(n) + 1)$$

# Analysis

- 1 Thus, total charge to all elements in group  $g$ :

$$(\text{total charge per element in group } g) \cdot N(g) \leq (2 \uparrow g) \cdot \frac{n}{2 \uparrow g} = n$$

- 2 Total charge to all elements of  $\{1, \dots, n\}$ :

$$(\text{charge to all elements in group } g) \cdot (\text{number of groups}) \leq n \cdot \log^*(n)$$

- 3 Total charge to all *FIND* operations:

$$(\text{number of } FIND \text{ operations}) \cdot (\text{charge per } FIND) \leq m \cdot (\log^*(n) + 1)$$



- 4 Total charge overall: sum of 2 + 3.

$$O((m + n) \log^* n) = O(m \log^* n), \text{ as we assumed } n \leq m$$

# Acknowledgement

Lecture based largely on Anna Lubiw's notes. See her notes at <https://www.student.cs.uwaterloo.ca/~cs466/Lectures/Lecture5.pdf>

# References I

-  Tarjan, Robert (1975)  
Efficiency of a good but not linear set union algorithm.  
*J. Assoc. Comput. Mach.* 22, 215 – 225
-  Seidel, Raimund and Sharir, Micha. (2005)  
Top-down analysis of path compression.  
*SIAM J. Computing* 34(3), 515 – 525.