Lecture 8

Feb 2, 2010 CS 886

Outline

- Multi-agent systems
- Game theory
- Russell and Norvig: Sect 17.6

Multi-agent systems

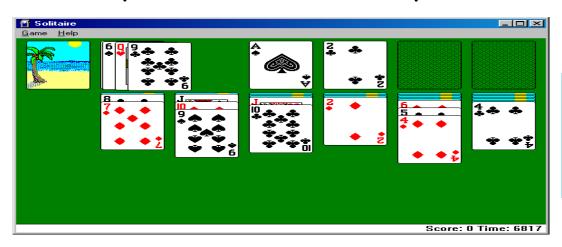
- So far...
 - Single agent optimizing some objectives in a possibly uncertain environment
 - But, what if there are several agents?
- · Multi-agent systems
 - Two (or more) agents can influence the world
 - How should an agent act given that it shares "control" with other agents?

Multi-agent Systems

- Search techniques for deterministic games with alternating play
 - Minimax algorithm
 - Alpha-beta pruning
- Today:
 - Extend decision theory to multi-agent systems
 - View other agents as sources of uncertainty
 - Framework: Game theory

What is game theory?

- Game theory is a formal way to analyze interactions among a group of rational agents who behave strategically
 - Group: Must have more than 1 decision maker
 - · Otherwise you have a decision problem, not a game



Solitaire is not a game!

What is game theory?

- Game theory is a formal way to analyze interactions among a group of rational agents who behave strategically
 - Interaction: What one agent does directly affects at least one other agent in the group
 - Rational: An agent chooses its best action
 - Strategic: Agents take into account how other agents influence the game

Games

· Examples:

- Chess, soccer, poker, etc.
- Elections
- Auctions, Trades
- Taxation system
- Negotiation
- Packet routing protocols,
- Driving laws

Two aspects

Agent design

- Given a game, what is a rational strategy?
- Ex: playing chess, driving, voting, filling up an income tax report, etc.

Mechanism design

- Given that agents behave rationally, what should the rules of the game be?
- Ex: designing driving laws, an election, a taxation system, an auction, etc.

Strategic Games (aka normal form)

- Formally: <I,{S_i},{U_i}>
- Set of agents I={1,2,...,n}
- Each agent i can choose a strategy $s_i \in S_i$
- Outcome of the game is defined by a strategy profile $(s_1,...,s_n) \in S$
- Agents have preferences over the outcomes
 - utility functions: $U_i(s_1,...,s_n) \in \Re$

Example: Election

- Agents: electors
- Strategies: possible votes for different candidates
- Outcome: set of all votes determines a winner (elected candidate)
- · Utility fn: preferences for each candidate

Simple Games

- Assumptions:
 - Single decision
 - Deterministic game
 - Fully observable game
 - Simultaneous play
- · Possible to relax those assumptions...

Example: Even or Odd

Agent 2

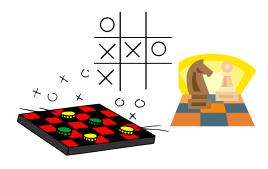
One	Two
OHE	IVVO

Zero-sum game.

$$\Sigma_{i=1}^{n} u_i(o)=0$$

$$I=\{1,2\}$$

 $S_i=\{One,Two\}$
An outcome is (One, Two)
 $U_1((One,Two))=-3$ and $U_2((One,Two))=3$



Examples of strategic games

Baseball or Soccer

B S

B 2,1 0,0 s 0,0 1,2

Chicken

T -1,-1 10,0 C 0,10 5,5









Coordination Game

Anti-Coordination Game

Example: Prisoner's Dilemma







Confess

Don't Confess

Confess

Don't Confess

-5,-5	0,-10
-10,0	-1,-1

Playing a game

- We now know how to describe a game
- Next step Playing the game!
- · Recall, agents are rational
 - Let p_i be agent i's beliefs about what its opponent will do
 - Agent i is rational if it chooses to play strategy s_i^* where

$$s_i^* = argmax_{s_i} \sum_{s_{-i}} u_i(s_i, s_{-i}) p_i(s_{-i})$$

Notation: $s_{-i} = (s_1, ..., s_{i-1}, s_{i+1}, ..., s_n)$

Dominated Strategies

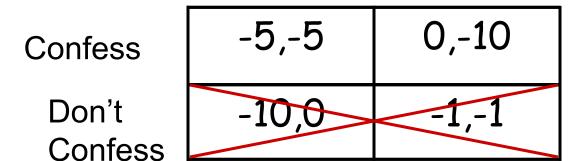
 Definition: A strategy s_i is strictly dominated if

$$\exists s_i', \forall s_{-i}, u_i(s_i,s_{-i}) < u_i(s_i',s_{-i})$$

- A rational agent will never play a strictly dominated strategy!
 - This allows us to solve some games!

Example: Prisoner's Dilemma

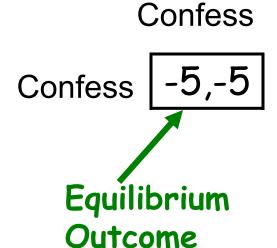
Confess Don't Confess



Confess Don't Confess

Confess





Strict Dominance does not capture the whole picture

	Α	В	С
A	0,4	4,0	5,3
В	4,0	0,4	5,3
C	3,5	3,5	6,6

What strict dominance eliminations can we do?

None...

So what should the players of this game do?

Nash Equilibrium

- Sometimes an agent's best-response depends on the strategies other agents are playing
- A strategy profile, s*, is a Nash
 equilibrium if no agent has incentive to
 deviate from its strategy given that
 others do not deviate:

$$\forall i \ u_i(s_i^*, s_{-i}^*) \ge u_i(s_i', s_{-i}^*) \ \forall s_i'$$

Nash Equilibrium

 Equivalently, s* is a N.E. iff $\forall i \ s_i^* = argmax_{s_i} u_i(s_i,s_{-i}^*)$

_	Α	В	С
A	0,4	4,0	5,3
В	4,0	0,4	5,3
C	3,5	3,5	6,6

(C,C) is a N.E. because

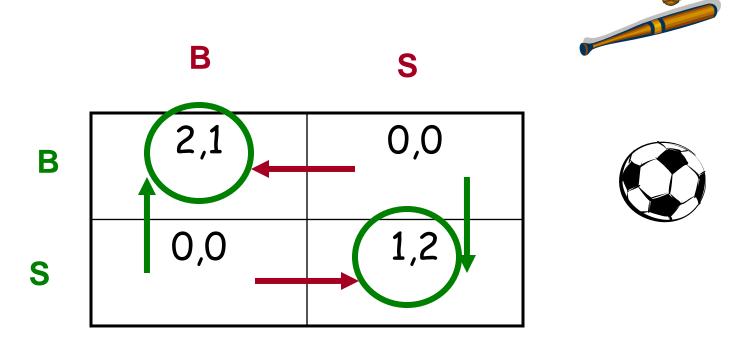
$$u_1(C,C) = \max \begin{bmatrix} u_1(A,C) \\ u_1(B,C) \\ u_1(C,C) \end{bmatrix}$$

$$AND$$

$$u_2(C,C) = \max \begin{bmatrix} u_2(C,A) \\ u_2(C,B) \\ u_2(C,C) \end{bmatrix}$$

$$u_2(C,C) = \max \begin{vmatrix} u_2(C,A) \\ u_2(C,B) \\ u_2(C,C) \end{vmatrix}$$

Another example

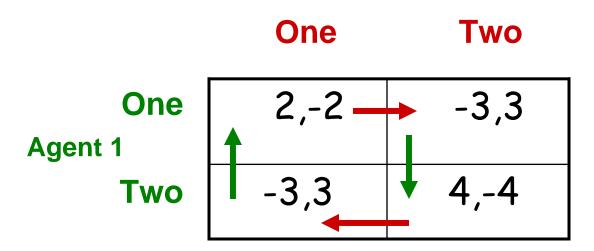


2 Nash Equilibria

Coordination Game

Yet another example





There is no <u>PURE</u> strategy Nash Equilibrium for this game

(Mixed) Nash Equilibria

- Mixed strategy σ_i:
 - $\sigma_i \in \Sigma_i$ defines a probability distribution over S_i
- Strategy profile: $\sigma = (\sigma_1, ..., \sigma_n)$
- Expected utility: $u_i(\sigma) = \sum_{s \in S} (\Pi_j \sigma(s_j)) u_i(s)$
- Nash Equilibrium: σ^* is a (mixed) Nash equilibrium if

$$u_i(\sigma_i^*, \sigma_{-i}^*) \ge u_i(\sigma_i', \sigma_{-i}^*) \ \forall \sigma_i'$$

Yet another example

How do we determine p and q?

$$U_A(p,q) = 2pq - 3p(1-q) - 3(1-p)q + 4(1-p)(1-q)$$

$$U_B(p,q) = -2pq + 3p(1-q) + 3(1-p)q - 4(1-p)(1-q)$$

$$\frac{\partial}{\partial p}U_A(p,q) = 12q - 7 \Rightarrow q = \frac{7}{12}$$

$$\frac{\partial}{\partial q}U_B(p,q) = -12p + 7 \Rightarrow p = \frac{7}{12}$$

Exercise

B S

B 2,1 0,0

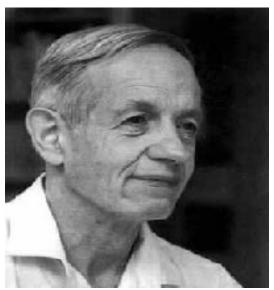
This game has 3 Nash Equilibria (2 pure strategy NE and 1 mixed strategy NE). Find them.

Mixed Nash Equilibrium

· Theorem (Nash 50):

Every game in which the strategy sets $S_1,...,S_n$ have a finite number of elements has a mixed strategy equilibrium.

John Nash Nobel Prize in Economics (1994)



Other Useful Theorems

• Thm: In an n-player pure strategy game $G=(S_1,...,S_n; u_1,...,u_n)$, if iterated elimination of strictly dominated strategies eliminates all but the strategies $(S_1^*,...,S_n^*)$ then these strategies are the unique NE of the game

 Thm: Any NE will survive iterated elimination of strictly dominated strategies.

Nash Equilibrium

Interpretations:

- Focal points, self-enforcing agreements, stable social convention, consequence of rational inference..

Criticisms

- They may not be unique
 - Ways of overcoming this: Refinements of equilibrium concept, Mediation, Learning
- They may be hard to find
- People don't always behave based on what equilibria would predict (ultimatum games and notions of fairness,...)

Bayesian Games

What should player A do?

Question: When does such a situation arise?

Bayesian Games

- Hockey lover gets 2 units for watching hockey and 1 unit for watching curling
- Curling lover gets 2
 units for watching
 curling and 1 unit for
 watching hockey
- · Pat is a hockey lover
- Pat thinks that Chris is probably a hockey lover, but is not sure

		11	O
Pat	Н	2,2	0,0
	С	0,0	1,1

With 2/3 chance

Chris

Chris

		н с	
Pat	н	2,1	0,0
	С	0,0	1,2

With 1/3 chance

Bayesian Games

- In a Bayesian game each player has a type
- All players know their own type, but have only a probability distribution over their opponents types
- · Game G
 - Set of action spaces: $A_1,...,A_n$
 - Set of type spaces: T₁,...,T_n
 - Set of beliefs: P₁,...,P_n
 - Set of payoff functions: u₁,...,u_n
 - $P_i(t_{-i}|t_i)$ is the prob distribution of the types for the other players, given player i has type t_i
 - $u_i(a_1,...,a_n;t_i)$ is the utility (payoff) to agent i if player j chooses action a_j and agent i has type $t_i \in T_i$

Knowledge Assumptions (Who knows what)

- All players know A_i's, T_i's, P_i's and u_i's
- The i'th player knows t_i but not $t_1, t_2, ..., t_{i-1}, t_{i+1}, ..., t_n$
- All players know that all players know the above
- And they know that they know that they know..... (common knowledge)
- Def: A strategy $s_i(t_i)$ in a Bayesian game is a mapping from T_i to A_i (i.e. it specifies what action should be taken for each type)

Back to our game

- $A_1 = \{H, C\} A_2 = \{H, C\}$
- $T_1=\{hl, cl\} T_2=\{hl, cl\}$
- P₁
 - $P_1(t_2=h||t_1=h|)=2/3$, $P_1(t_2=c||t_1=h|)=1/3$, $P_1(t_2=h||h_1=c|)=2/3$, $P_1(t_2=c||t_1=c|)=1/3$
- P₂
 - $P_2(t_1=h||t_2=h|)=1$, $P_2(t_1=c||t_2=h|)=0$, $P_2(t_1=h||t_2=c|)=1$, $P_2(t_1=c||t_2=c|)=0$
- U₁
 - $u_1(H,H,hl)=2$, $u_1(H,H,cl)=1$, $u_1(H,C,hl)=0$,...
- U₂
 - $u_2(H,H,hl)=2$, $u_2(H,H,cl)=1$, $u_2(H,C,cl)=0$,...

Bayesian Nash Equilibrium

• A set of strategies $(s_1^*,...,s_n^*)$ are a Pure Bayesian Nash Equilibrium if and only if for each player i, and for all possible types $t_i \in T_i$

$$s_{i}^{*}(t_{i}) = argmax_{a_{i} \in A_{i}} \Sigma_{t_{-i}} u_{i}(a_{i}, s_{-i}^{*}(t_{-i}))$$

No player, for any of their type, wants to change their strategy