### Lecture 18

Nov 10, 2005 CS 886

### Outline

- Multi-agent systems
- Game theory
- · Russell and Norvig: Sect 17.6

# Multi-agent systems

- · So far...
  - Single agent optimizing some objectives in a possibly uncertain environment
  - But, what if there are several agents?
- Multi-agent systems
  - Two (or more) agents can influence the world
  - How should an agent act given that it shares "control" with other agents?

# Multi-agent Systems

- Search techniques for deterministic games with alternating play
  - Minimax algorithm
  - Alpha-beta pruning

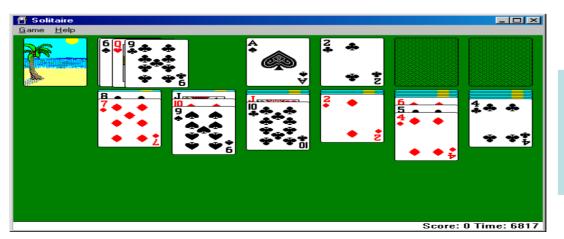
### · Today:

- Extend decision theory to multi-agent systems
- View other agents as sources of uncertainty
- Framework: Game theory

## What is game theory?

 Game theory is a formal way to analyze interactions among a group of rational agents who behave strategically

- Group: Must have more than 1 decision maker
  - · Otherwise you have a decision problem, not a game



Solitaire is not a game!

## What is game theory?

- Game theory is a formal way to analyze interactions among a group of rational agents who behave strategically
  - Interaction: What one agent does directly affects at least one other agent in the group
  - Rational: An agent chooses its best action
  - Strategic: Agents take into account how other agents influence the game

### Games

### · Examples:

- Chess, soccer, poker, etc.
- Elections
- Auctions, Trades
- Taxation system
- Negotiation
- Packet routing protocols,
- Driving laws

### Two aspects

### Agent design

- Given a game, what is a rational strategy?
- Ex: playing chess, driving, voting, filling up an income tax report, etc.
- Mechanism design
  - Given that agents behave rationally, what should the rules of the game be?
  - Ex: designing driving laws, an election, a taxation system, an auction, etc.

### Strategic Games (aka normal form)

- Formally:  $\langle I, \{S_i\}, \{U_i\} \rangle$
- Set of agents I={1,2,...,n}
- Each agent i can choose a strategy  $s_i \in S_i$
- Outcome of the game is defined by a strategy profile  $(s_1,...,s_n) \in S$
- Agents have preferences over the outcomes
  - utility functions:  $U_i(s_1,...,s_n) \in \Re$

## Example: Election

- Agents: electors
- Strategies: possible votes for different candidates
- Outcome: set of all votes determines a winner (elected candidate)
- · Utility fn: preferences for each candidate

### Simple Games

- Assumptions:
  - Single decision
  - Deterministic game
  - Fully observable game
  - Simultaneous play

 Possible to relax those assumptions... but this is beyond the scope of this lecture

## Example: Even or Odd

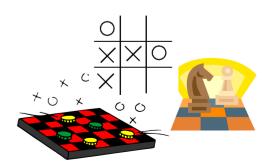
### Agent 2

One	l wo
	1 44 🔾

Zero-sum game.

$$\Sigma_{i=1}^{n} u_i(o)=0$$

$$I=\{1,2\}$$
  
 $S_i=\{One,Two\}$   
An outcome is (One, Two)  
 $U_1((One,Two))=-3$  and  $U_2((One,Two))=3$ 



# Examples of strategic games

#### **Baseball or Soccer**

B

B

2,1	0,0
0,0	1,2



### Chicken





#### **Coordination Game**

### **Anti-Coordination Game**

## Example: Prisoner's Dilemma







Confess

Don't Confess

Confess

Don't Confess

-5,-5	0,-10
-10,0	-1,-1

# Playing a game

- · We now know how to describe a game
- Next step Playing the game!
- · Recall, agents are rational
  - Let p<sub>i</sub> be agent i's beliefs about what its opponent will do
  - Agent i is rational if it chooses to play strategy  $s_i^*$  where

$$s_i^* = argmax_{s_i} \sum_{s_{-i}} u_i(s_i', s_{-i}) p_i(s_{-i})$$
  
Notation:  $s_{-i} = (s_1, ..., s_{i-1}, s_{i+1}, ..., s_n)$ 

### Dominated Strategies

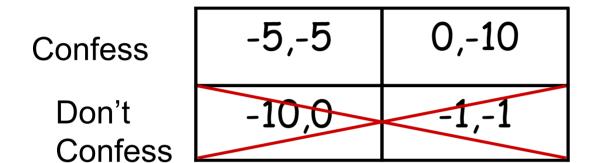
 Definition: A strategy s<sub>i</sub> is strictly dominated if

$$\exists s_i', \forall s_{-i}, u_i(s_i,s_{-i}) < u_i(s_i',s_{-i})$$

- A rational agent will never play a strictly dominated strategy!
  - This allows us to solve some games!

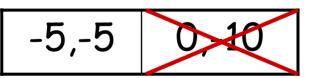
### Example: Prisoner's Dilemma

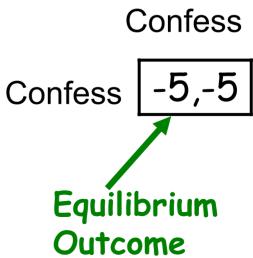




Confess Don't Confess

Confess





# Strict Dominance does not capture the whole picture

	Α	В	С
A	0,4	4,0	5,3
В	4,0	0,4	5,3
C	3,5	3,5	6,6

What strict dominance eliminations can we do?

None...

So what should the players of this game do?

## Nash Equilibrium

- Sometimes an agent's best-response depends on the strategies other agents are playing
- A strategy profile, s\*, is a Nash
   equilibrium if no agent has incentive to
   deviate from its strategy given that
   others do not deviate:

$$\forall i \ u_i(s_i^*, s_{-i}^*) \ge u_i(s_i', s_{-i}^*) \ \forall s_i'$$

## Nash Equilibrium

 Equivalently, s\* is a N.E. iff  $\forall i \ s_i^* = argmax_{s_i} u_i(s_i,s_{-i}^*)$ 

_	Α	В	С
A	0,4	4,0	5,3
В	4,0	0,4	5,3
C	3,5	3,5	6,6

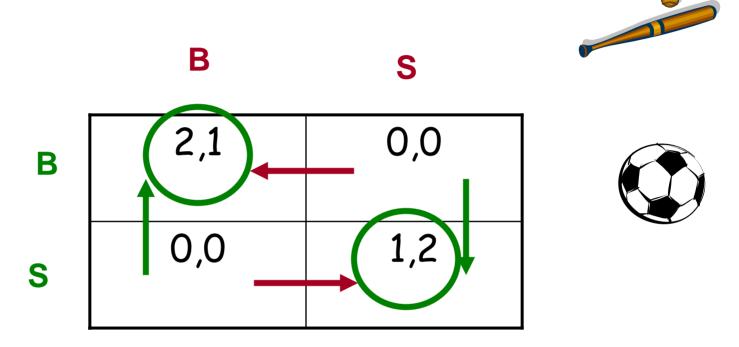
(C,C) is a N.E. because

$$u_1(C,C) = \max \begin{bmatrix} u_1(A,C) \\ u_1(B,C) \\ u_1(C,C) \end{bmatrix}$$

$$u_2(C,C) = \max \begin{bmatrix} u_2(C,A) \\ u_2(C,B) \\ u_2(C,C) \end{bmatrix}$$

$$u_2(C,C) = \max \begin{vmatrix} u_2(C,A) \\ u_2(C,B) \\ u_2(C,C) \end{vmatrix}$$

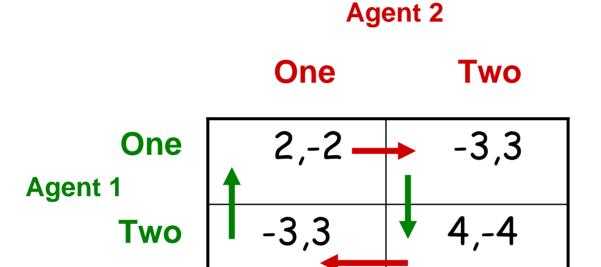
### Another example



2 Nash Equilibria

### Coordination Game

### Yet another example



There is no <u>PURE</u> strategy Nash Equilibrium for this game

## (Mixed) Nash Equilibria

- Mixed strategy  $\sigma_i$ :
  - $\sigma_i \in \Sigma_i$  defines a probability distribution over  $S_i$
- Strategy profile:  $\sigma = (\sigma_1, ..., \sigma_n)$
- Expected utility:  $u_i(\sigma) = \sum_{s \in S} (\Pi_j \sigma(s_j)) u_i(s)$
- Nash Equilibrium:  $\sigma^*$  is a (mixed) Nash equilibrium if

$$u_i(\sigma_i^*, \sigma_{-i}^*) \ge u_i(\sigma_i', \sigma_{-i}^*) \ \forall \sigma_i'$$

## Yet another example

One A Two 
$$\begin{vmatrix} 2,-2 & -3,3 \\ -3,3 & 4,-4 \end{vmatrix}$$
 p = Pr(one)

$$p = Pr(one)$$
  
 $q = Pr(one)$ 

How do we determine p and q?

$$U_A(p,q) = 2pq - 3p(1-q) - 3(1-p)q + 4(1-p)(1-q)$$

$$U_B(p,q) = -2pq + 3p(1-q) + 3(1-p)q - 4(1-p)(1-q)$$

$$\frac{\partial}{\partial p}U_A(p,q) = 12q - 7 \Rightarrow q = \frac{7}{12}$$

$$\frac{\partial}{\partial q}U_B(p,q) = -12p + 7 \Rightarrow p = \frac{7}{12}$$

### Exercise

	В	S
В	2,1	0,0
S	0,0	1,2

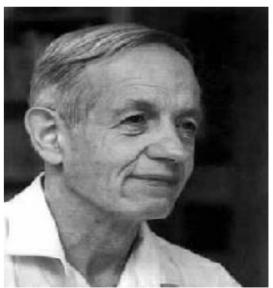
This game has 3 Nash Equilibrium (2 pure strategy NE and 1 mixed strategy NE). Find them.

### Mixed Nash Equilibrium

· Theorem (Nash 50):

Every game in which the strategy sets,  $S_1,...,S_n$  have a finite number of elements has a mixed strategy equilibrium.

John Nash Nobel Prize in Economics (1994)



### Other Useful Theorems

• Thm: In an n-player pure strategy game  $G=(S_1,...,S_n; u_1,...,u_n)$ , if iterated elimination of strictly dominated strategies eliminates all but the strategies  $(S_1^*,...,S_n^*)$  then these strategies are the unique NE of the game

 Thm: Any NE will survive iterated elimination of strictly dominated strategies.

# Nash Equilibrium

### · Interpretations:

- Focal points, self-enforcing agreements, stable social convention, consequence of rational inference..

### · Criticisms

- They may not be unique
  - Ways of overcoming this: Refinements of equilibrium concept, Mediation, Learning
- They may be hard to find
- People don't always behave based on what equilibria would predict (ultimatum games and notions of fairness,...)

### Bayesian Games

· What should player A do?

Question: When does such a situation arise?

## Bayesian Games

- Hockey lover get 2 units for watching hockey and 1 unit for watching curling
- Curling lover gets 2
   units for watching
   curling and 1 unit for
   watching hockey
- Pat is a hockey lover
- Pat thinks that Chris is probably a hockey lover, but is not sure

		Н	С
Pat	Н	2,2	0,0
	С	0,0	1,1

With 2/3 chance

Chris

		Chris	
		Н	С
Pat	Н	2,1	0,0
	С	0,0	1,2
	•		

### Bayesian Games

- · In a Bayesian game each player has a type
- All players know their own type, but have only a probability distribution over their opponents types

### · Game G

- Set of action spaces:  $A_1,...,A_n$
- Set of type spaces: T<sub>1</sub>,...,T<sub>n</sub>
- Set of beliefs: P<sub>1</sub>,...,P<sub>n</sub>
- Set of payoff functions: u<sub>1</sub>,...,u<sub>n</sub>
- $P_i(t_{-i}|t_i)$  is the prob distribution of the types for the other players, given player i has type  $t_i$
- $u_i(a_1,...,a_n;t_i)$  is the utility (payoff) to agent i if player j chooses action  $a_j$  and agent i has type  $t_i \in T_i$

# Knowledge Assumptions (Who knows what)

- All players know A<sub>i</sub>'s, T<sub>i</sub>'s, P<sub>i</sub>'s and u<sub>i</sub>'s
- The i'th player knows  $t_i$  but not  $t_1, t_2, ..., t_{i-1}, t_{i+1}, ..., t_n$
- All players know that all players know the above
- And they know that they know that they know..... (common knowledge)
- Def: A strategy  $s_i(t_i)$  in a Bayesian game is a mapping from  $T_i$  to  $A_i$  (i.e. it specifies what action should be taken for each type)

# Back to our game

- $A_1 = \{H, C\} A_2 = \{H, C\}$
- $T_1=\{hl, cl\} T_2=\{hl, cl\}$
- P<sub>1</sub>
  - $P_1(t_2=h||t_1=h|)=2/3$ ,  $P_1(t_2=c||t_1=h|)=1/3$ ,  $P_1(t_2=h||h_1=c|)=2/3$ ,  $P_1(t_2=c||t_1=c|)=1/3$
- P<sub>2</sub>
  - $P_2(t_1=h||t_2=h|)=1$ ,  $P_2(t_1=c||t_2=h|)=0$ ,  $P_2(t_1=h||t_2=c|)=1$ ,  $P_2(t_1=c||t_2=c|)=0$
- U<sub>1</sub>
  - $u_1(H,H,hl)=2$ ,  $u_1(H,H,cl)=1$ ,  $u_1(H,C,hl)=0$ ,...
- U<sub>2</sub>
  - $u_2(H,H,hl)=2$ ,  $u_2(H,H,cl)=1$ ,  $u_2(H,C,cl)=0$ ,...

# Bayesian Nash Equilibrium

• A set of strategies  $(s_1^*,...,s_n^*)$  are a Pure Bayesian Nash Equilibrium if and only if for each player i, and for all possible types  $t_i \in T_i$ 

$$s_{i}^{*}(t_{i}) = argmax_{a_{i} \in A_{i}} \Sigma_{t_{-i}} u_{i}(a_{i}, s_{-i}^{*}(t_{-i}))$$

No player, for any of their type, wants to change their strategy