

# CS489/698

## Lecture 4: Jan 16, 2017

Statistical Learning

[RN]: Sec 20.1, 20.2, [M]: Sec. 2.2, 3.2

# Statistical Learning

- View: we have uncertain knowledge of the world
- Idea: **learning simply reduces this uncertainty**

# Terminology

- **Probability distribution:**
  - A specification of a probability for each event in our sample space
  - Probabilities must sum to 1
- Assume the world is described by two (or more) random variables
  - **Joint probability distribution**
    - Specification of probabilities for all combinations of events

# Joint distribution

- Given two random variables  $A$  and  $B$ :
- Joint distribution:

$$\Pr(A = a \wedge B = b) \text{ for all } a, b$$

- **Marginalisation (sumout rule):**

$$\Pr(A = a) = \sum_b \Pr(A = a \wedge B = b)$$

$$\Pr(B = b) = \sum_a \Pr(A = a \wedge B = b)$$

# Example: Joint Distribution

	sunny		~sunny	
	cold	~cold	cold	~cold
headache	0.108	0.012	0.072	0.008
~headache	0.016	0.064	0.144	0.576

$$P(\text{headache} \wedge \text{sunny} \wedge \text{cold}) =$$

$$P(\sim \text{headache} \wedge \text{sunny} \wedge \sim \text{cold}) =$$

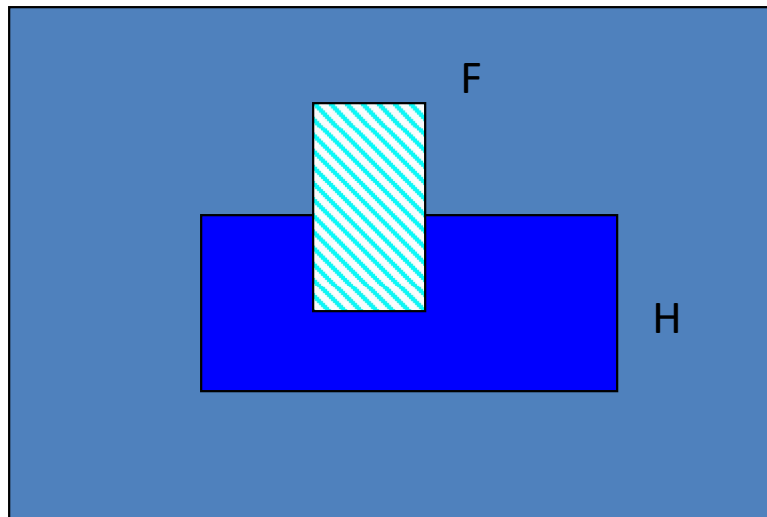
$$P(\text{headache} \vee \text{sunny}) =$$

$$P(\text{headache}) =$$

**marginalization**

# Conditional Probability

- $\Pr(A|B)$ : fraction of worlds in which  $B$  is true that also have  $A$  true



H="Have headache"  
F="Have Flu"

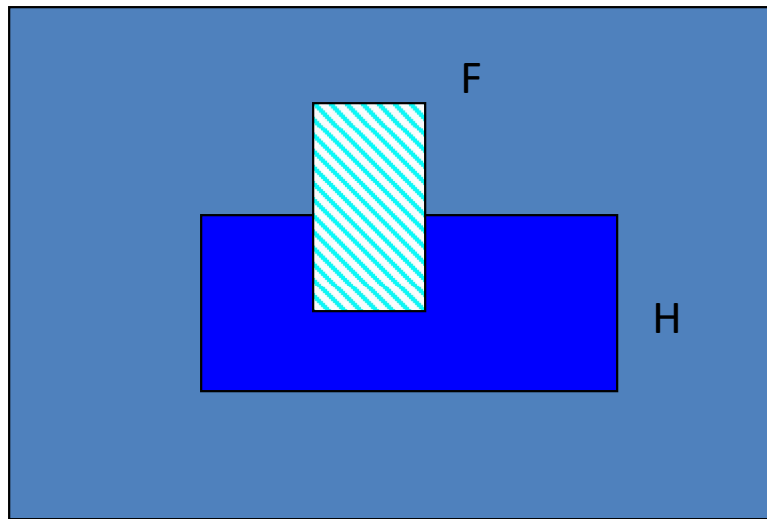
$$\Pr(H) = 1/10$$

$$\Pr(F) = 1/40$$

$$\Pr(H|F) = 1/2$$

Headaches are rare and flu is rarer, but if you have the flu, then there is a 50-50 chance you will have a headache

# Conditional Probability



H="Have headache"  
F="Have Flu"

$$\Pr(H) = 1/10$$

$$\Pr(F) = 1/40$$

$$\Pr(H|F) = 1/2$$

$\Pr(H|F)$  = Fraction of flu inflicted worlds in which you have a headache

$$= (\# \text{ worlds with flu and headache}) / (\# \text{ worlds with flu})$$

$$= (\text{Area of "H and F" region}) / (\text{Area of "F" region})$$

$$= \Pr(H \wedge F) / \Pr(F)$$

# Conditional Probability

- Definition:

$$\Pr(A|B) = \Pr(A \wedge B) / \Pr(B)$$

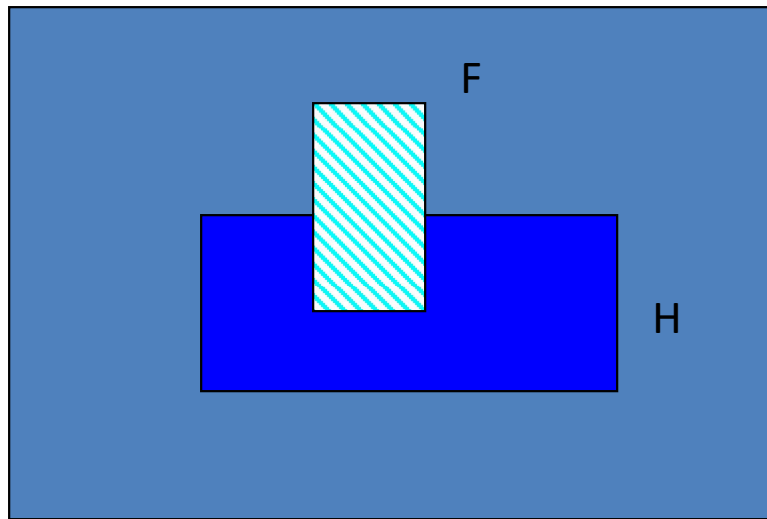
- Chain rule:

$$\Pr(A \wedge B) = \Pr(A|B) \Pr(B)$$

**Memorize these!**



# Inference



One day you wake up with a headache. You think "Drat! 50% of flues are associated with headaches so I must have a 50-50 chance of coming down with the flu"

H="Have headache"  
F="Have Flu"

$$\Pr(H) = 1/10$$

$$\Pr(F) = 1/40$$

$$\Pr(H|F) = 1/2$$

Is your reasoning correct?

$$\Pr(F \wedge H) =$$

$$\Pr(F|H) =$$

# Example: Joint Distribution

	sunny		~sunny	
	cold	~cold	cold	~cold
headache	0.108	0.012	0.072	0.008
~headache	0.016	0.064	0.144	0.576

$$\Pr(\text{headache} \wedge \text{cold} \mid \text{sunny}) =$$

$$\Pr(\text{headache} \wedge \text{cold} \mid \sim\text{sunny}) =$$

# Bayes Rule

- Note

$$\Pr(A|B)\Pr(B) = \Pr(A \wedge B) = \Pr(B \wedge A) = \Pr(B|A)\Pr(A)$$

- Bayes Rule

$$\Pr(B|A) = [(\Pr(A|B)\Pr(B))]/\Pr(A)$$

**Memorize this!**

# Using Bayes Rule for inference

- Often we want to form a hypothesis about the world based on what we have observed
- Bayes rule is vitally important when viewed in terms of stating the belief given to hypothesis  $H$ , given evidence  $e$

$$P(H|e) = \frac{P(e|H)P(H)}{P(e)}$$

*Likelihood* →  $P(e|H)$

*Prior probability* →  $P(H)$

*Posterior probability* →  $P(H|e)$

*Normalizing constant* →  $P(e)$

# Bayesian Learning

- **Prior:**  $\Pr(H)$
- **Likelihood:**  $\Pr(e|H)$
- **Evidence:**  $\mathbf{e} = \langle e_1, e_2, \dots, e_N \rangle$
- **Bayesian Learning** amounts to computing the posterior using Bayes' Theorem:  
$$\Pr(H|\mathbf{e}) = k \Pr(\mathbf{e}|H)\Pr(H)$$

# Bayesian Prediction

- Suppose we want to make a prediction about an unknown quantity  $X$
- $$\begin{aligned}\Pr(X|\mathbf{e}) &= \sum_i \Pr(X|\mathbf{e}, h_i)P(h_i|\mathbf{e}) \\ &= \sum_i \Pr(X|h_i)P(h_i|\mathbf{e})\end{aligned}$$
- Predictions are weighted averages of the predictions of the individual hypotheses
- Hypotheses serve as “intermediaries” between raw data and prediction

# Candy Example

- Favorite candy sold in two flavors:
  - Lime (hugh)
  - Cherry (yum)
- Same wrapper for both flavors
- Sold in bags with different ratios:
  - 100% cherry
  - 75% cherry + 25% lime
  - 50% cherry + 50% lime
  - 25% cherry + 75% lime
  - 100% lime

# Candy Example

- You bought a bag of candy but don't know its flavor ratio
- After eating  $k$  candies:
  - What's the flavor ratio of the bag?
  - What will be the flavor of the next candy?



# Statistical Learning

- **Hypothesis H:** probabilistic theory of the world
  - $h_1$ : 100% cherry
  - $h_2$ : 75% cherry + 25% lime
  - $h_3$ : 50% cherry + 50% lime
  - $h_4$ : 25% cherry + 75% lime
  - $h_5$ : 100% lime
- **Examples E:** evidence about the world
  - $e_1$ : 1<sup>st</sup> candy is cherry
  - $e_2$ : 2<sup>nd</sup> candy is lime
  - $e_3$ : 3<sup>rd</sup> candy is lime
  - ...

# Candy Example

- Assume prior  $\Pr(H) = \langle 0.1, 0.2, 0.4, 0.2, 0.1 \rangle$
- Assume candies are **i.i.d. (identically and independently distributed)**

$$\Pr(\mathbf{e}|h) = \prod_n P(e_n|h)$$

- Suppose first 10 candies all taste lime:

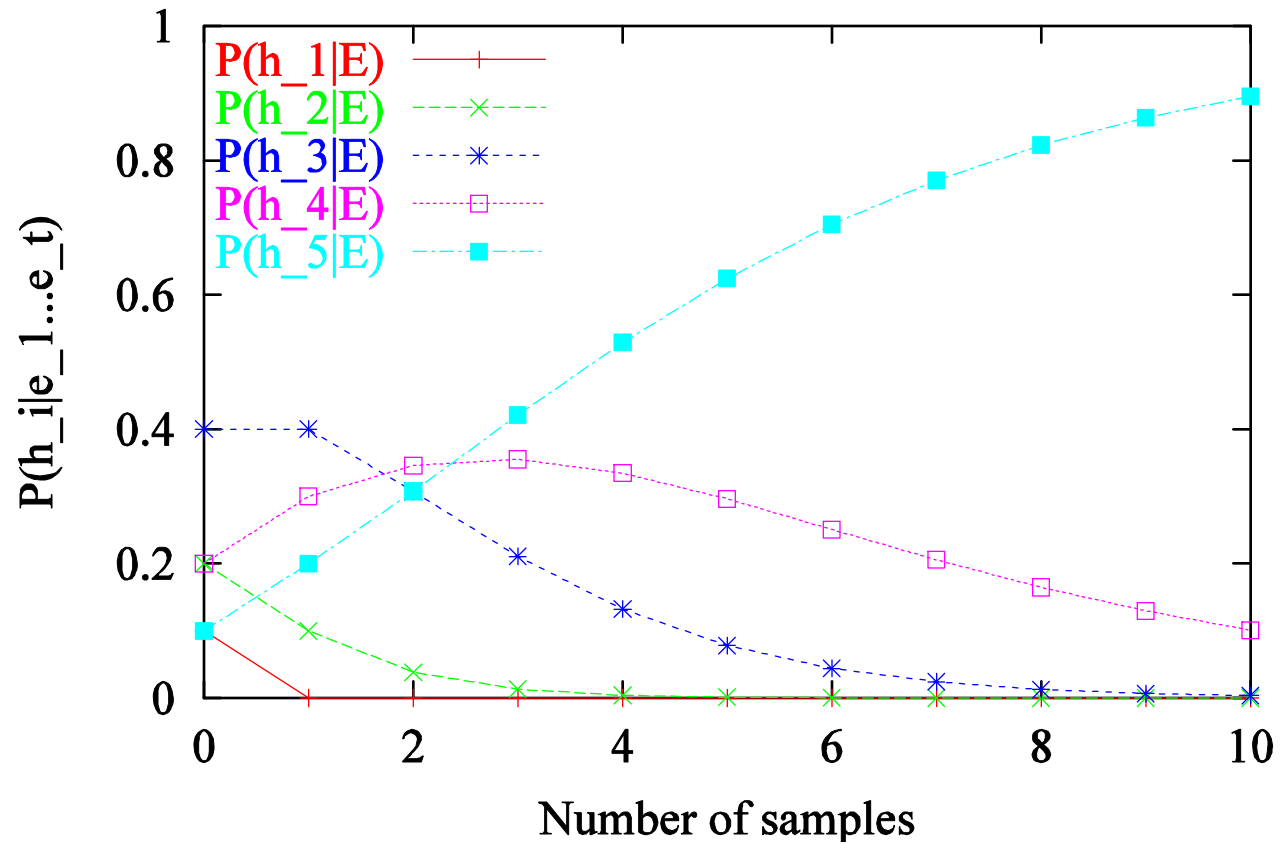
$$\Pr(\mathbf{e}|h_5) =$$

$$\Pr(\mathbf{e}|h_3) =$$

$$\Pr(\mathbf{e}|h_1) =$$

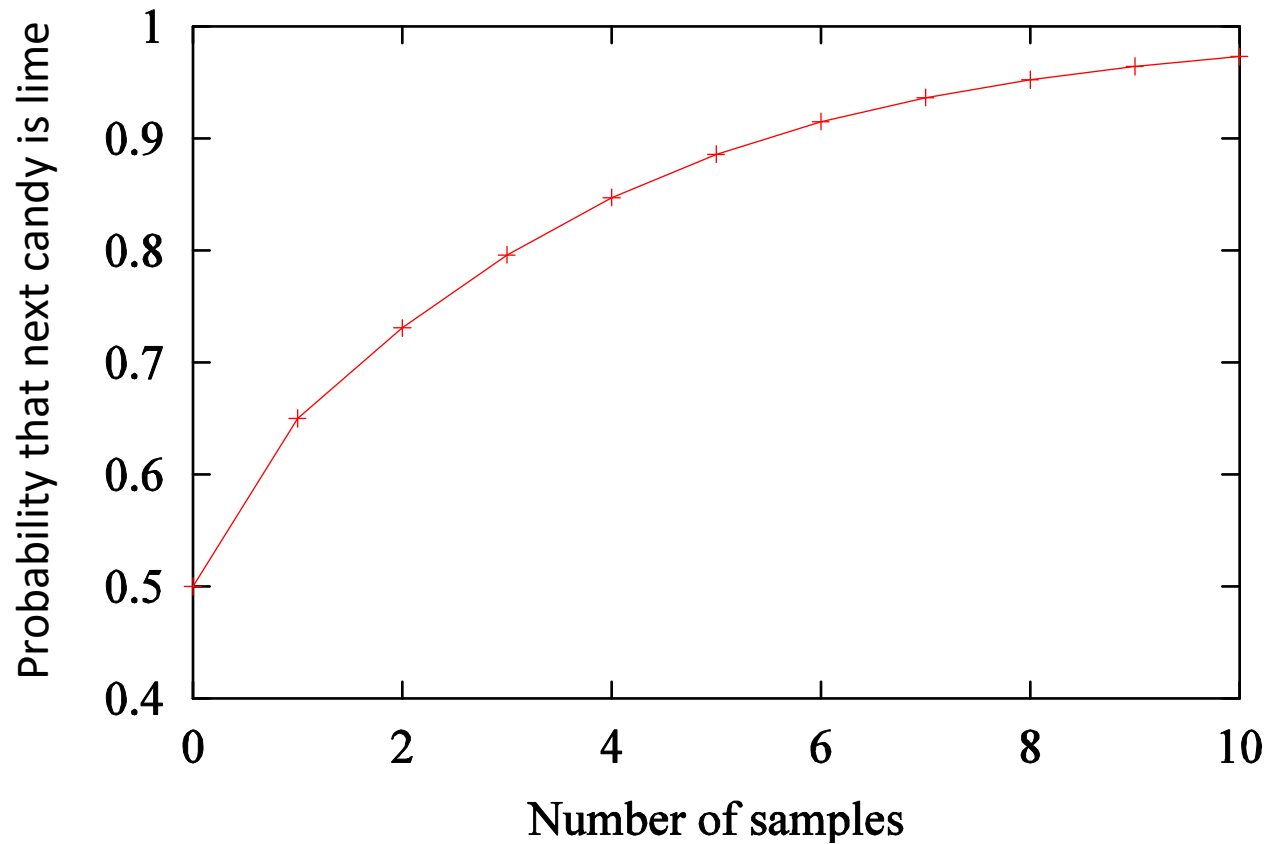
# Posterior

Posteriors given data generated from  $h_5$



# Prediction

Bayes predictions with data generated from  $h_5$



# Bayesian Learning

- Bayesian learning properties:
  - **Optimal** (i.e. given prior, no other prediction is correct more often than the Bayesian one)
  - **No overfitting** (all hypotheses considered and weighted)
- There is a price to pay:
  - When hypothesis space is large Bayesian learning may be intractable
  - i.e. sum (or integral) over hypothesis often intractable
- Solution: approximate Bayesian learning

# Maximum a posteriori (MAP)

- Idea: make prediction based on **most probable hypothesis**  $h_{MAP}$

$$h_{MAP} = \operatorname{argmax}_{h_i} \Pr(h_i | \mathbf{e})$$

$$\Pr(X | \mathbf{e}) \approx \Pr(X | h_{MAP})$$

- In contrast, Bayesian learning makes prediction based on **all** hypotheses weighted by their probability

# MAP properties

- MAP prediction **less accurate** than Bayesian prediction since it relies only on **one** hypothesis  $h_{MAP}$
- But MAP and Bayesian predictions converge as data increases
- **Controlled overfitting** (prior can be used to penalize complex hypotheses)
- **Finding  $h_{MAP}$  may be intractable:**
  - $h_{MAP} = \operatorname{argmax}_h \Pr(h|e)$
  - Optimization may be difficult

# Maximum Likelihood (ML)

- Idea: simplify MAP by assuming uniform prior (i.e.,  $\Pr(h_i) = \Pr(h_j) \forall i, j$ )

$$h_{MAP} = \operatorname{argmax}_h \Pr(h) \Pr(\mathbf{e}|h)$$

$$h_{ML} = \operatorname{argmax}_h \Pr(\mathbf{e}|h)$$

- Make prediction based on  $h_{ML}$  only:

$$\Pr(X|\mathbf{e}) \approx \Pr(X|h_{ML})$$



# ML properties

- ML prediction **less accurate** than Bayesian and MAP predictions since it ignores prior info and relies only on **one** hypothesis  $h_{ML}$
- But ML, MAP and Bayesian predictions converge as data increases
- Subject to **overfitting** (no prior to penalize complex hypothesis that could exploit statistically insignificant data patterns)
- Finding  $h_{ML}$  is often easier than  $h_{MAP}$   
$$h_{ML} = \operatorname{argmax}_h \sum_n \log \Pr(e_n|h)$$