

Conditional Random Fields

November 17, 2008
 CS 486/686
 University of Waterloo

Outline

- Conditional Random Fields
- Reading: Hanna M. Wallach, *Conditional Random Fields: An Introduction*, Technical Report MS-CIS-04-21, Department of Computer and Information Science, University of Pennsylvania, 2004.

Conditional Random Fields

- CRF: special Markov network that represents a **conditional distribution**
- $\Pr(\mathbf{X}|\mathbf{E}) = 1/k(\mathbf{E}) e^{\sum_j \lambda_j \phi_j(\mathbf{X}, \mathbf{E})}$
 - NB: $k(\mathbf{E})$ is a normalization function (it is not a constant since it depends on \mathbf{E} - see Slide 5)
- **Useful in classification:** $\Pr(\text{class}|\text{input})$
- **Advantage:** no need to model distribution over inputs

Conditional Random Fields

- Joint distribution:
 - $\Pr(\mathbf{X}, \mathbf{E}) = 1/k e^{\sum_j \lambda_j \phi_j(\mathbf{X}, \mathbf{E})}$
- Conditional distribution
 - $\Pr(\mathbf{X}|\mathbf{E}) = e^{\sum_j \lambda_j \phi_j(\mathbf{X}, \mathbf{E})} / \sum_{\mathbf{X}} e^{\sum_j \lambda_j \phi_j(\mathbf{X}, \mathbf{E})}$
- **Partition features in two sets:**
 - $\phi_{j1}(\mathbf{X}, \mathbf{E})$: depend on at least one var in \mathbf{X}
 - $\phi_{j2}(\mathbf{E})$: depend only on evidence \mathbf{E}

Conditional Random Fields

- Simplified conditional distribution:
 - $\Pr(\mathbf{X}|\mathbf{E}) = \frac{e^{\sum_{j1} \lambda_{j1} \phi_{j1}(\mathbf{X}, \mathbf{E}) + \sum_{j2} \lambda_{j2} \phi_{j2}(\mathbf{E})}}{\sum_{\mathbf{X}} e^{\sum_{j1} \lambda_{j1} \phi_{j1}(\mathbf{X}, \mathbf{E}) + \sum_{j2} \lambda_{j2} \phi_{j2}(\mathbf{E})}}$
 - $= \frac{e^{\sum_{j1} \lambda_{j1} \phi_{j1}(\mathbf{X}, \mathbf{E})} e^{\sum_{j2} \lambda_{j2} \phi_{j2}(\mathbf{E})}}{\sum_{\mathbf{X}} e^{\sum_{j1} \lambda_{j1} \phi_{j1}(\mathbf{X}, \mathbf{E})} e^{\sum_{j2} \lambda_{j2} \phi_{j2}(\mathbf{E})}}$
 - $= 1/k(\mathbf{E}) e^{\sum_{j1} \lambda_{j1} \phi_{j1}(\mathbf{X}, \mathbf{E})}$
- **Evidence features can be ignored!**

Parameter Learning

- Parameter learning is simplified since we don't need to model a distribution over the evidence
- Objective: maximum conditional likelihood
 - $\lambda^* = \operatorname{argmax}_{\lambda} P(\mathbf{X}=\mathbf{x}|\lambda, \mathbf{E}=\mathbf{e})$
 - Convex optimization, but no closed form
 - Use iterative technique (e.g., gradient descent)

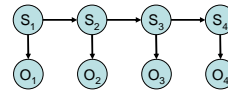
Sequence Labeling

- Common task in
 - Entity recognition
 - Part of speech tagging
 - Robot localisation
 - Image segmentation
- $L^* = \operatorname{argmax}_L \Pr(L|O)?$
= $\operatorname{argmax}_{L_1, \dots, L_n} \Pr(L_1, \dots, L_n | O_1, \dots, O_n)?$

CS4386/686 Lecture Slides (c) 2009 P. Poupart

7

Hidden Markov Model



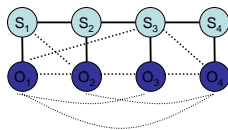
- Assumption: observations are independent given the hidden state

CS4386/686 Lecture Slides (c) 2009 P. Poupart

8

Conditional Random Fields

- Since the distribution over observations is not modeled, there is no independence assumption among observations



- Can also model long-range dependencies without significant computational cost

CS4386/686 Lecture Slides (c) 2009 P. Poupart

9

Entity Recognition

- Task: label each word with a predefined set of categories (e.g., person, organization, location, expression of time, etc.)
 - Ex: Jim bought 300 shares of Acme Corp. in 2006
person nil nil nil nil org org nil time
- Possible features:
 - Is the word numeric or alphabetic?
 - Does the word contain capital letters?
 - Is the word followed by "Corp."?
 - Is the word preceded by "in"?
 - Is the preceding label an organization?

CS4386/686 Lecture Slides (c) 2009 P. Poupart

10

Next Class

- First-order logic

CS4386/686 Lecture Slides (c) 2009 P. Poupart

11