# CS485/685 Lecture 21: March 20, 2012

Nearest neighbor analysis [BDSS] Chapter 9

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1

# Nearest Neighbor Recap

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### **Analysis Challenge**

- How can we analyze nearest neighbor rules?
  - They don't have a well defined hypothesis space
    - # of hypotheses grows with the amount of data
    - Can't determine VC dimension
    - Non-parametric method
  - What is the learning bias?
    - No prior, no penalty term, no regularization...
    - Does this contradict the no-free lunch theorem?

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3

# **Learning Bias**

• Let  $\eta$  be the underlying stochastic labeling function:

$$\eta(x) = \Pr(Y = 1 | X = x)$$

Nearest neighbor works well when labeling function
 η is c-Lipschitz (smooth)

$$\exists c > 0, \forall x, x' |\eta(x) - \eta(x')| \le c ||x - x'||_2$$

 When two inputs are near each other, their labeling distributions are similar

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#### **Generalization Bound**

• Lemma: Let D be a distribution over  $\Re \times \{0,1\}$  and assume  $\eta$  is c-Lipschitz. Let S be a sample of size N and  $h_S$  be its corresponding 1-NN rule. Then

$$E_S[L_D(h_S)] \le 2L_D(h^*) + c E_{X,S}[||X - x_{\pi_1(X)}||_2]$$

where  $h^*$  is the hypothesis with minimum loss  $\pi_1(X)$  is the nearest neighbor of X in S

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5

# **Bayes Optimal Classifier**

- Suppose you know the underlying distribution D and the underlying labeling function  $\eta$
- Then the hypothesis with minimum loss (a.k.a. Bayes Optimal Classifier) is

$$h^* = argmin_h L_D(h)$$
 $h^*(x) = \begin{cases} 1 & \eta(x) > 0.5 \\ 0 & \eta(x) \le 0.5 \end{cases}$ 

• The minimum loss is:

$$L_D(h^*) = E_X[\min\{\eta(X), 1 - \eta(X)\}]$$
  
 
$$\geq E_X[\eta(X)(1 - \eta(X))]$$

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#### **Proof of Generalization Bound**

• Consider the probability of sampling different labels for x and x'.

$$\Pr_{Y \sim \eta(x), Y' \sim \eta(x')} [Y \neq Y']$$

$$= \eta(x') (1 - \eta(x)) + (1 - \eta(x')) \eta(x)$$

$$= \eta(x') - 2\eta(x)\eta(x') + \eta(x)$$

$$= 2\eta(x) (1 - \eta(x)) + \eta(x') - \eta(x)$$

$$\leq 2\eta(x) (1 - \eta(x)) + c ||x - x'||_2 \text{ (c-Lipschitz property)}$$

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7

#### **Proof of Generalization Bound**

Consider the expected error of the 1-NN rule

$$\begin{split} &E_{S}[L_{D}(h_{S})] \\ &= E_{S,(X,Y)}[Y \neq Y_{\pi_{1}(X)}] \text{ (by definition)} \\ &\leq E_{S,(X,Y)} \left[ 2\eta(X) \big( 1 - \eta(X) \big) + c \left| \left| X - x_{\pi_{1}(X)} \right| \right|_{2} \right] \text{ (prev slide)} \\ &= 2E_{X} \big[ \eta(X) \big( 1 - \eta(X) \big) \big] + cE_{S,X} \left[ \left| \left| X - x_{\pi_{1}(X)} \right| \right|_{2} \right] \\ &\leq 2L_{D}(h^{*}) + cE_{S,X} \left[ \left| \left| X - x_{\pi_{1}(X)} \right| \right|_{2} \right] \text{ (Bayes optimal rule)} \end{split}$$

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#### 1-NN Generalization Bound

• In the limit

i.e. as  $N \to \infty$  then  $\left| \left| X - x_{\pi_1(X)} \right| \right|_2 \to 0$ 

the error of the 1-NN rule is at most twice the minimum error.

• When *N* is finite, how do we bound  $||X - x_{\pi_1(X)}||_2$ ?

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9

# Nearest neighbor distance bound

• Lemma: For a sample S of N inputs in  $[0,1]^d$ , we have that

$$E_{X,S}\left[\left|\left|X - x_{\pi_1(X)}\right|\right|_2\right] \le 4\sqrt{d}N^{-\frac{1}{d+1}}$$

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#### **Cover Set**

• Consider a set of hypercubes of length  $\epsilon$  that covers the input space  $[0,1]^d$ 

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11

#### **Distance Bound**

- Consider two cases:
  - 1. There is a neighbour in **same** hypercube

$$\left| \left| X - x_{\pi_1(X)} \right| \right|_2 \le \epsilon \sqrt{d}$$

2. All neighbours in different hypercubes

$$\left|\left|X - x_{\pi_1(X)}\right|\right|_2 \le \sqrt{d}$$

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# Bound Probability of different hypercubes

• **Lemma:** Let  $C_1$ ,  $C_2$ , ...,  $C_r$  be r hypercubes and S be a sequence of N input points sampled i.i.d. from  $D_X$ . Then

$$E_S\left[\Pr\left[\bigcup_{i:C_i\cap S=\emptyset}C_i\right]\right] \leq \frac{r}{Ne}$$

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13

#### **Proof**

$$\begin{split} E_{S} \Big[ & \text{Pr} \big[ \bigcup_{i:C_{i} \cap S = \emptyset} C_{i} \big] \Big] \\ & \leq E_{S} \Big[ \sum_{i:C_{i} \cap S = \emptyset} \text{Pr}(C_{i}) \Big] \\ & = \sum_{i=1}^{r} \text{Pr}(C_{i}) \, E_{S} \big[ \delta(C_{i} \cap S = \emptyset) \big] \\ & = \sum_{i=1}^{r} \text{Pr}(C_{i}) \, \text{Pr} \big[ C_{i} \cap S = \emptyset \big] \\ & = \sum_{i=1}^{r} \text{Pr}(C_{i}) \, (1 - \text{Pr}(C_{i}))^{N} \\ & \leq \sum_{i=1}^{r} \text{Pr}(C_{i}) \, e^{-\text{Pr}(C_{i})N} \\ & \leq \frac{r}{Ne} \end{split}$$

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## **Expected Distance Bound**

$$\begin{split} E_{X,S}\left[\left|\left|X-x_{\pi_{1}(X)}\right|\right|_{2}\right] \\ &\leq E_{S}\left[\Pr\left[\bigcup_{i:C_{i}\cap S=\emptyset}C_{i}\right]\sqrt{d} + \Pr\left[\bigcup_{i:C_{i}\cap S\neq\emptyset}C_{i}\right]\epsilon\sqrt{d}\right] \\ &\leq \frac{r}{Ne} &\leq 1 \\ &\leq \sqrt{d}\left(\frac{r}{Ne}+\epsilon\right) \\ &\ldots \\ &\leq 4\sqrt{d}N^{-\frac{1}{d+1}} \end{split}$$

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15

#### 1-NN Generalization Bound

**Theorem:** Let  $h_S$  denote the result of applying the 1-NN rule to a sample S. Then

$$E_S[L_D(h_S)] \le 2L_D(h^*) + 4c\sqrt{d}N^{-\frac{1}{d+1}}$$

Proof: combine previous lemmas

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