

Lecture 5: Linear Regression by Maximum Likelihood, Maximum A Posteriori and Bayesian Learning

CS480/680 Intro to Machine Learning

2023-1-24

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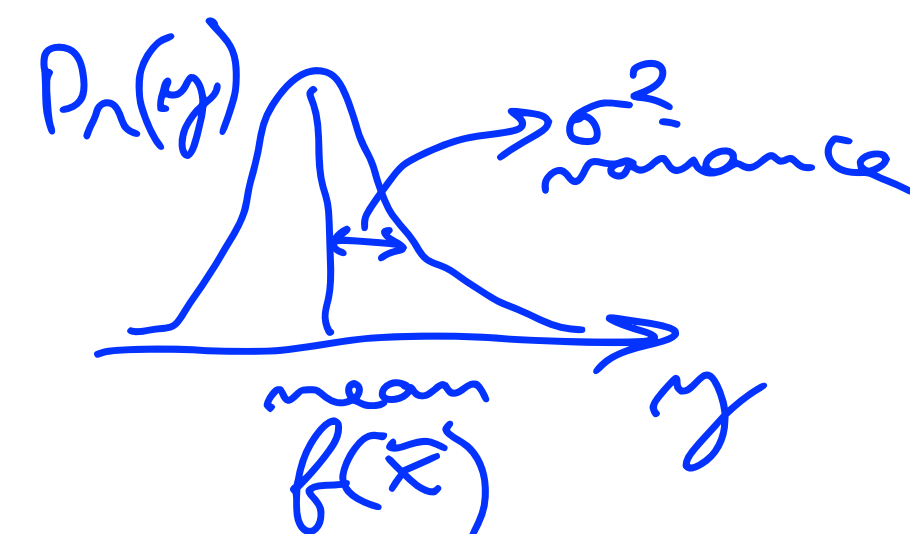
Noisy Linear Regression

- Assume y is obtained from \mathbf{x} by a deterministic function f that has been perturbed (i.e., noisy measurement)

- Gaussian noise:

$$y = f(\bar{\mathbf{x}}) + \epsilon$$

\downarrow \downarrow
 $w^T \bar{\mathbf{x}}$ $N(0, \sigma^2)$



$$\Pr(\mathbf{y} | \bar{\mathbf{X}}, \mathbf{w}, \sigma) = N(\mathbf{y} | \mathbf{w}^T \bar{\mathbf{X}}, \sigma^2)$$

$$= \prod_{n=1}^N \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(y_n - w^T \bar{\mathbf{x}}_n)^2}{2\sigma^2}}$$

normalization constant

mean variance

Maximum Likelihood

- Possible objective: find best \mathbf{w}^* by maximizing the likelihood of the data

$$\mathbf{w}^* = \operatorname{argmax}_{\mathbf{w}} \Pr(\mathbf{y}|\bar{\mathbf{X}}, \mathbf{w}, \sigma)$$

take log

$$\begin{aligned} &= \operatorname{argmax}_{\mathbf{w}} \prod_n e^{-\frac{(y_n - \mathbf{w}^T \bar{\mathbf{x}}_n)^2}{2\sigma^2}} \\ &= \operatorname{argmax}_{\mathbf{w}} \sum_n -\frac{(y_n - \mathbf{w}^T \bar{\mathbf{x}}_n)^2}{2\sigma^2} \\ &= \operatorname{argmin}_{\mathbf{w}} \sum_n (y_n - \mathbf{w}^T \bar{\mathbf{x}}_n)^2 \end{aligned}$$

- We arrive at the original least square problem!

Maximum A Posteriori

- Alternative objective: find \mathbf{w}^* with highest posterior probability

- Consider Gaussian prior: $\Pr(\mathbf{w}) = N(\mathbf{0}, \Sigma)$ \rightarrow $\begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$ (matrix)

- Posterior:

$$\Pr(\mathbf{w}|\mathbf{X}, \mathbf{y}) \propto \Pr(\mathbf{w}) \Pr(\mathbf{y}|\mathbf{X}, \mathbf{w})$$

$$= k e^{-\frac{\mathbf{w}^T \Sigma^{-1} \mathbf{w}}{2}} e^{-\frac{\sum_n (y_n - \mathbf{w}^T \mathbf{x}_n)^2}{2\sigma^2}}$$

Maximum A Posteriori

- Optimization:

$$\begin{aligned} \mathbf{w}^* &= \operatorname{argmax}_{\mathbf{w}} \Pr(\mathbf{w} | \bar{\mathbf{X}}, \mathbf{y}) \\ &= \operatorname{argmax}_{\mathbf{w}} - \sum_n (y_n - \mathbf{w}^T \bar{\mathbf{x}}_n)^2 - \mathbf{w}^T \boldsymbol{\Sigma}^{-1} \mathbf{w} \\ &= \operatorname{argmin}_{\mathbf{w}} \sum_n (y_n - \mathbf{w}^T \bar{\mathbf{x}}_n)^2 + \mathbf{w}^T \boldsymbol{\Sigma}^{-1} \mathbf{w} \end{aligned}$$

take log and drop constants

Let $\boldsymbol{\Sigma}^{-1} = \lambda \mathbf{I}$ then

$$= \operatorname{argmin}_{\mathbf{w}} \sum_n (y_n - \mathbf{w}^T \bar{\mathbf{x}}_n)^2 + \lambda \|\mathbf{w}\|_2^2$$

$$\boldsymbol{\Sigma}^{-1} = \begin{pmatrix} \lambda & & & 0 \\ & \lambda & & 0 \\ & & \ddots & \\ 0 & & & \lambda \end{pmatrix}$$
$$\boldsymbol{\Sigma} = \begin{pmatrix} \frac{1}{\lambda} & & & 0 \\ & \frac{1}{\lambda} & & 0 \\ & & \ddots & \\ 0 & & & \frac{1}{\lambda} \end{pmatrix}$$

- We arrive at the original **regularized** least square problem!

Expected Squared Loss

- Even though we use a statistical framework, it is interesting to evaluate the expected squared loss

$$\begin{aligned} E[L] &= \int_{\mathbf{x}, y} \Pr(\mathbf{x}, y) (y - \mathbf{w}^T \bar{\mathbf{x}})^2 d\mathbf{x} dy \\ &= \int_{\mathbf{x}, y} \Pr(\mathbf{x}, y) (y - f(\mathbf{x}) + f(\mathbf{x}) - \mathbf{w}^T \bar{\mathbf{x}})^2 d\mathbf{x} dy \\ &= \int_{\mathbf{x}, y} \Pr(\mathbf{x}, y) \left[(y - f(\mathbf{x}))^2 + \underbrace{2(y - f(\mathbf{x}))(f(\mathbf{x}) - \mathbf{w}^T \bar{\mathbf{x}})}_{\text{Expectation with respect to } y \text{ is } 0} + (f(\mathbf{x}) - \mathbf{w}^T \bar{\mathbf{x}})^2 \right] d\mathbf{x} dy \end{aligned}$$

Expectation with respect to y is 0

$$E[L] = \underbrace{\int_{\mathbf{x}, y} \Pr(\mathbf{x}, y) (y - f(\mathbf{x}))^2 d\mathbf{x} dy}_{\text{noise (constant)}} + \underbrace{\int_{\mathbf{x}} \Pr(\mathbf{x}) (f(\mathbf{x}) - \mathbf{w}^T \bar{\mathbf{x}})^2 d\mathbf{x}}_{\text{error (depends on } \mathbf{w} \text{)}}$$

Expected Squared Loss

- Let's focus on the error part, which depends on \mathbf{w}

$$E_{\mathbf{x}}[(f(\mathbf{x}) - \mathbf{w}^T \bar{\mathbf{x}})^2] = \int_{\mathbf{x}} \text{Pr}(\mathbf{x}) (f(\mathbf{x}) - \mathbf{w}^T \bar{\mathbf{x}})^2 d\mathbf{x}$$

- But the choice of \mathbf{w} depends on the dataset S
- Instead consider expectation with respect to S

$$E_S[(f(\mathbf{x}) - \mathbf{w}_S^T \bar{\mathbf{x}})^2]$$

where \mathbf{w}_S is the weight vector obtained based on S

Bias-Variance Decomposition

- Decompose squared loss

$$\begin{aligned} & E_S[(f(\mathbf{x}) - \mathbf{w}_S^T \bar{\mathbf{x}})^2] \\ &= E_S[f(\mathbf{x}) - E_S[\mathbf{w}_S^T \bar{\mathbf{x}}] + E_S[\mathbf{w}_S^T \bar{\mathbf{x}}] - \mathbf{w}_S^T \bar{\mathbf{x}}]^2 \\ &= E_S \left[(f(\mathbf{x}) - E_S[\mathbf{w}_S^T \bar{\mathbf{x}}])^2 + 2(f(\mathbf{x}) - E_S[\mathbf{w}_S^T \bar{\mathbf{x}}]) \underbrace{(E_S[\mathbf{w}_S^T \bar{\mathbf{x}}] - \mathbf{w}_S^T \bar{\mathbf{x}})}_{\text{Expectation is 0}} + (E_S[\mathbf{w}_S^T \bar{\mathbf{x}}] - \mathbf{w}_S^T \bar{\mathbf{x}})^2 \right] \\ &= \underbrace{(f(\mathbf{x}) - E_S[\mathbf{w}_S^T \bar{\mathbf{x}}])^2}_{\text{bias}^2} + \underbrace{E_S \left[(E_S[\mathbf{w}_S^T \bar{\mathbf{x}}] - \mathbf{w}_S^T \bar{\mathbf{x}})^2 \right]}_{\text{variance}} \end{aligned}$$

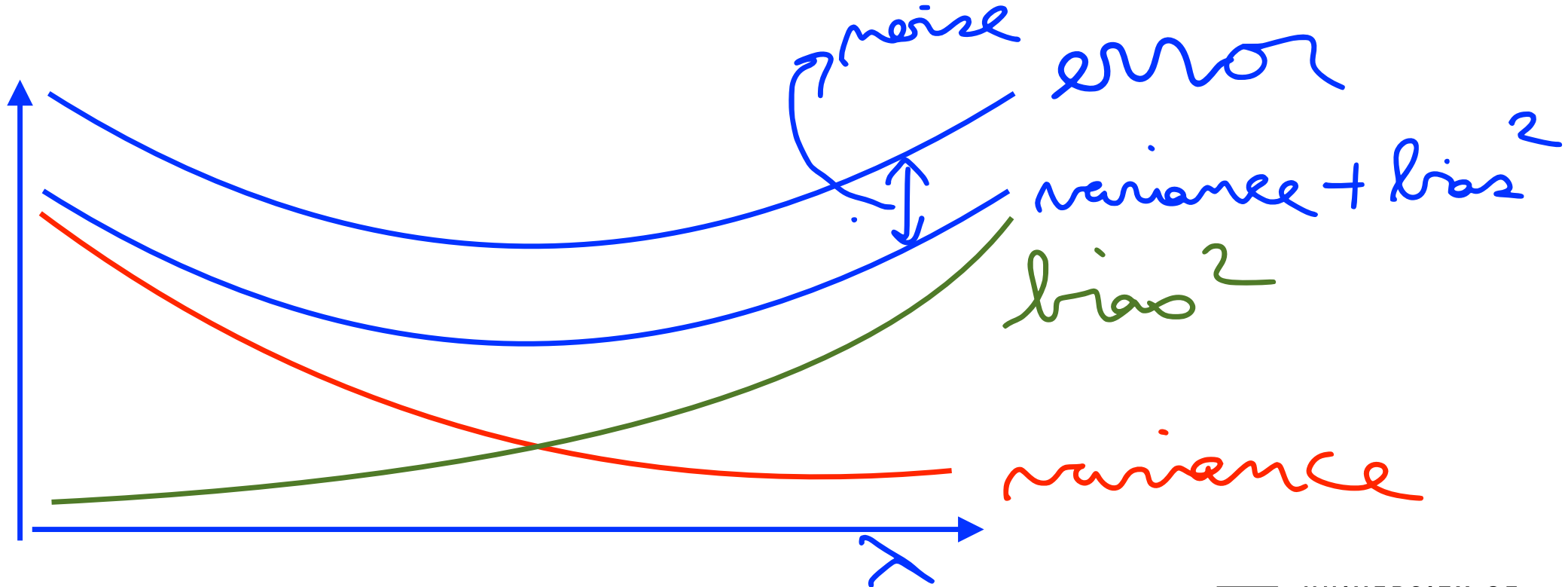
Bias-Variance Decomposition

- Hence:

$$E[\text{loss}] = (\text{bias})^2 + \text{variance} + \text{noise}$$

- Picture:

$E(L)$

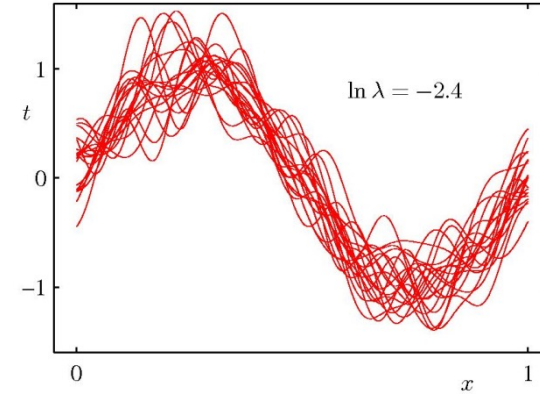
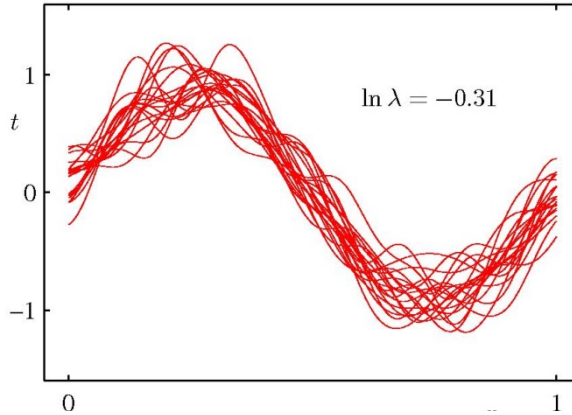
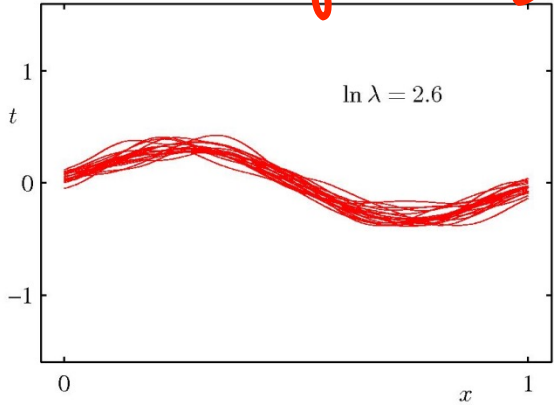


Bias-Variance Decomposition

- Example

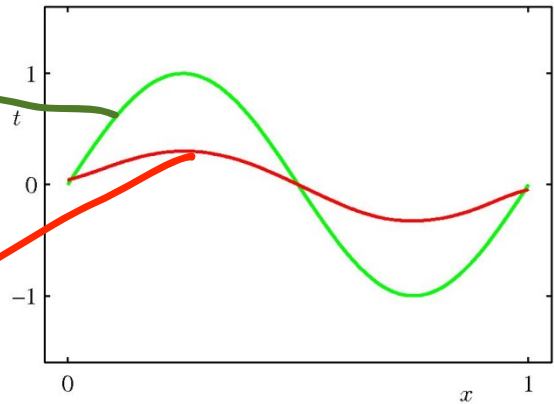
underfitting

overfitting

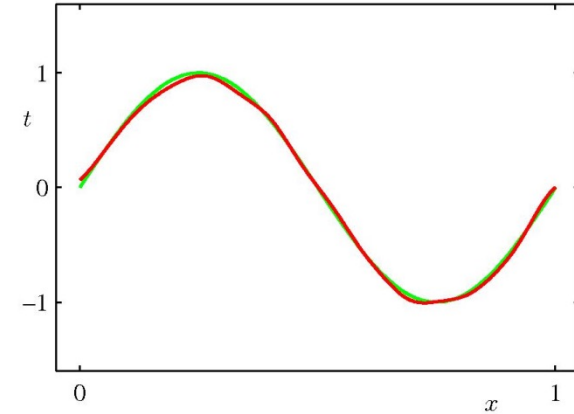
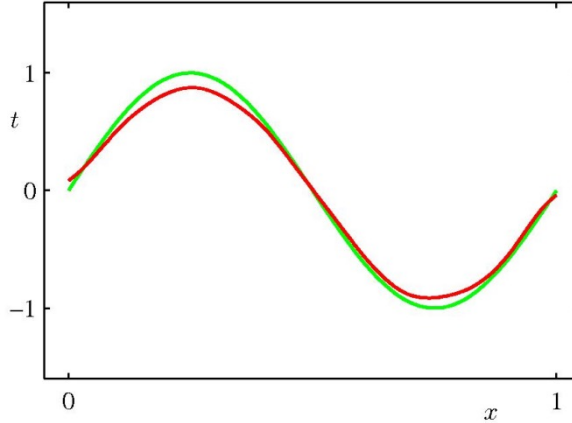


variance

*$f(x)$
true fn*



*estimate
 $E(y^T x)$*



bias

Bayesian Linear Regression

- We don't know if \mathbf{w}^* is the true underlying \mathbf{w}
- Instead of making predictions according to \mathbf{w}^* , compute the weighted average prediction according to $\Pr(\mathbf{w}|\bar{\mathbf{X}}, \mathbf{y})$

$$\begin{aligned}\Pr(\mathbf{w}|\bar{\mathbf{X}}, \mathbf{y}) &= k e^{-\frac{\mathbf{w}^T \Sigma^{-1} \mathbf{w}}{2}} e^{-\frac{\sum_n (y_n - \mathbf{w}^T \bar{\mathbf{x}}_n)^2}{2\sigma^2}} \\ &= k e^{-\frac{1}{2}(\mathbf{w} - \bar{\mathbf{w}})^T \mathbf{A}(\mathbf{w} - \bar{\mathbf{w}})} = N(\bar{\mathbf{w}}, \mathbf{A}^{-1})\end{aligned}$$

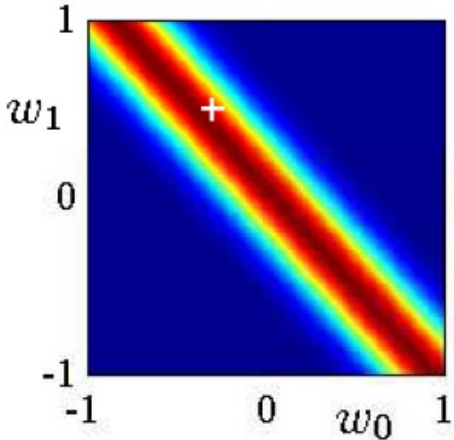
mean (pointing to $\bar{\mathbf{w}}$)
covariance (pointing to \mathbf{A}^{-1})

where $\bar{\mathbf{w}} = \sigma^{-2} \mathbf{A}^{-1} \bar{\mathbf{X}} \mathbf{y}$

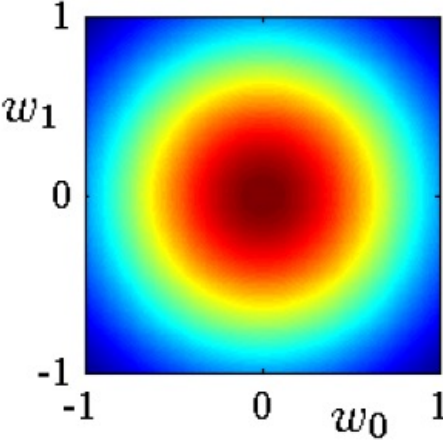
$$\mathbf{A} = \sigma^{-2} \bar{\mathbf{X}} \bar{\mathbf{X}}^T + \Sigma^{-1}$$

Bayesian Learning

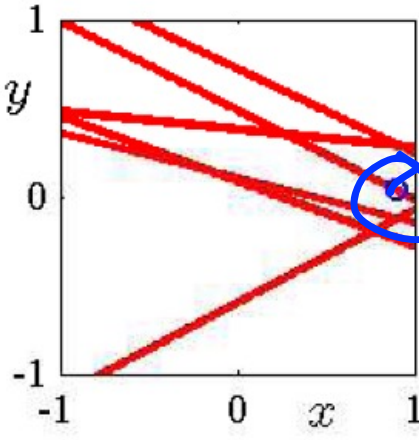
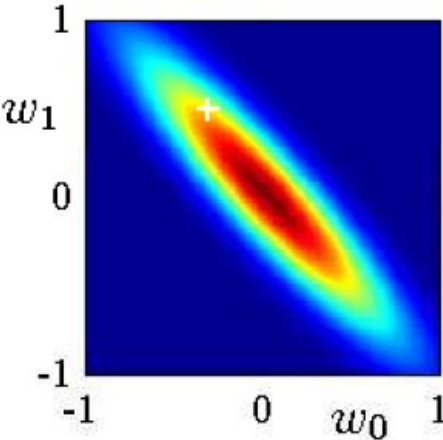
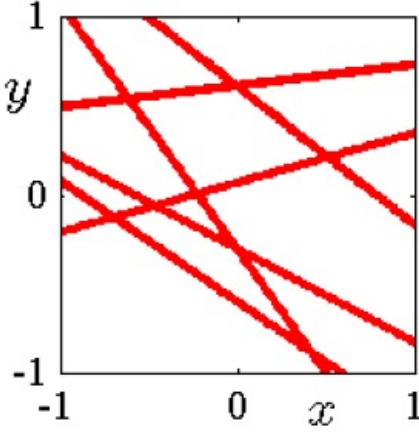
likelihood



prior/posterior



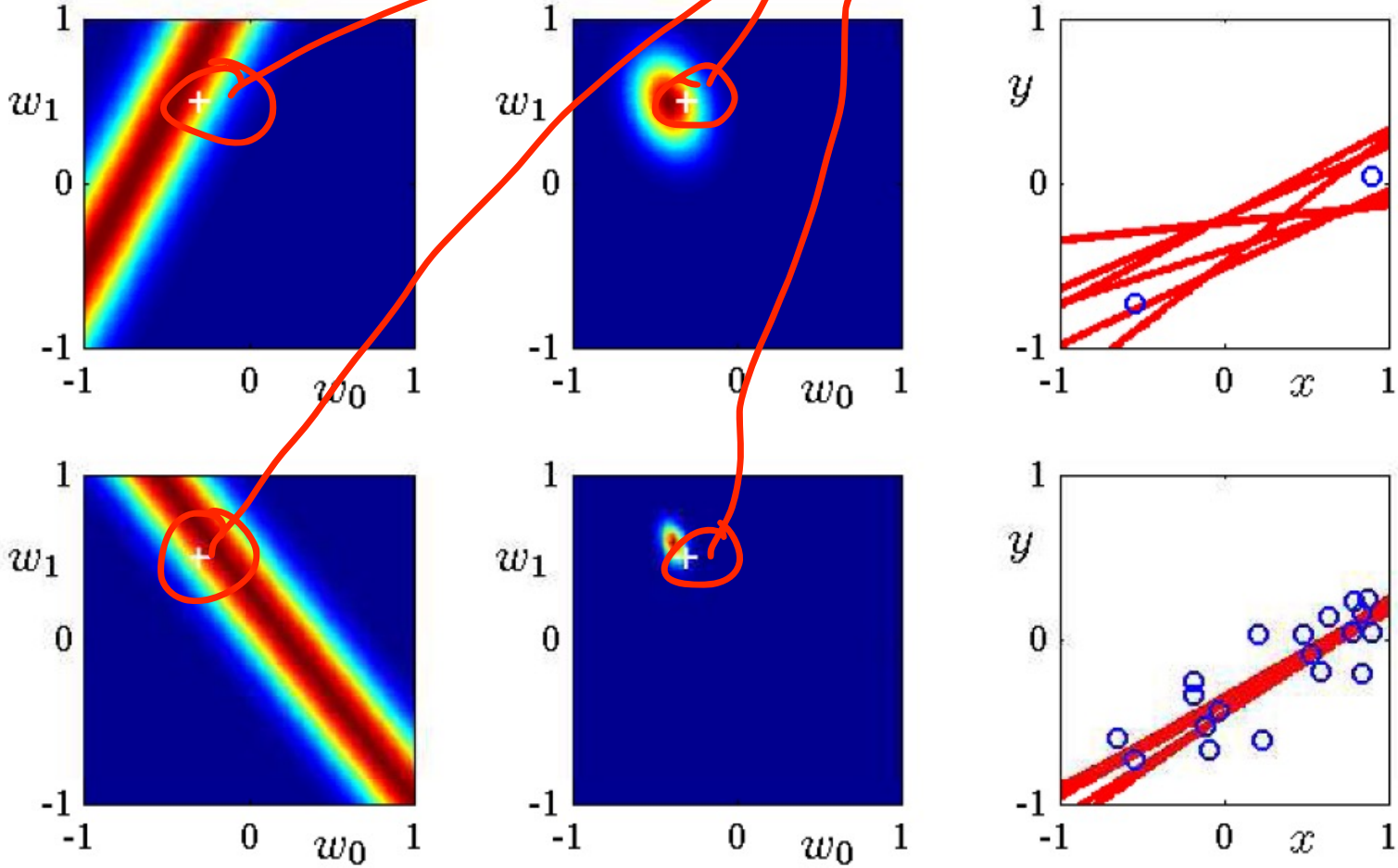
data space



data point

Bayesian Learning

true weights



Bayesian Prediction

- Let \mathbf{x}_* be the input for which we want a prediction and y_* be the corresponding prediction

$$\Pr(y_* | \bar{\mathbf{x}}_*, \bar{\mathbf{X}}, \mathbf{y}) = \int_{\mathbf{w}} \Pr(y_* | \bar{\mathbf{x}}_*, \mathbf{w}) \Pr(\mathbf{w} | \bar{\mathbf{X}}, \mathbf{y}) d\mathbf{w}$$

$$= k \int_{\mathbf{w}} e^{-\frac{(y_* - \bar{\mathbf{x}}_*^T \mathbf{w})^2}{2\sigma^2}} e^{-\frac{1}{2}(\mathbf{w} - \bar{\mathbf{w}})^T \mathbf{A}(\mathbf{w} - \bar{\mathbf{w}})} d\mathbf{w}$$

$$= N(\underbrace{\sigma^{-2} \bar{\mathbf{x}}_*^T \mathbf{A}^{-1} \bar{\mathbf{X}} \mathbf{y}}_{\text{mean}}, \underbrace{\sigma^2 + \bar{\mathbf{x}}_*^T \mathbf{A}^{-1} \bar{\mathbf{x}}_*}_{\text{variance}})$$