Lecture 4: Statistical Learning CS480/680 Intro to Machine Learning

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Statistical Learning

View: we have uncertain knowledge of the world

Idea: learning simply reduces this uncertainty



Terminology

Probability distribution:

- A specification of a probability for each event in our sample space
- Probabilities must sum to 1

- Assume the world is described by two (or more) random variables
 - Joint probability distribution
 - Specification of probabilities for all combinations of events



Joint distribution

- Given two random variables *A* and *B*:
- Joint distribution:

$$Pr(A = a \land B = b)$$
 for all a, b

Marginalisation (sumout rule):

$$Pr(A = a) = \Sigma_b Pr(A = a \wedge B = b)$$

$$Pr(B = b) = \Sigma_a Pr(A = a \land B = b)$$



Example: Joint Distribution

sunny ~sunny

	cold	~cold		cold	~cold
headache	0.108	0.012	headache	0.072	0.008
~headache	0.016	0.064	~headache	0.144	0.576

 $P(headache \land sunny \land cold) =$

 $P(\sim headache \land sunny \land \sim cold) =$

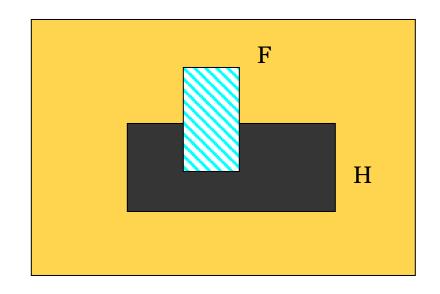
P(headache) =





Conditional Probability

• Pr(A|B): fraction of worlds in which B is true that also have A true



H="Have headache" F="Have Flu"

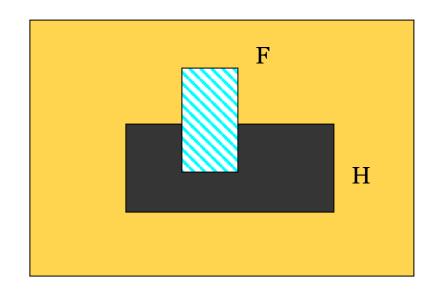
$$Pr(H) = 1/10$$

 $Pr(F) = 1/40$
 $Pr(H|F) = 1/2$

Headaches are rare and flu is rarer, but if you have the flu, then there is a 50-50 chance you will have a headache



Conditional Probability



H="Have headache" F="Have Flu"

$$Pr(H) = 1/10$$

 $Pr(F) = 1/40$
 $Pr(H|F) = 1/2$

Pr(H|F) = Fraction of flu inflicted worlds in which you have a headache

= (# worlds with flu and headache)/(# worlds with flu)

= (Area of "H and F" region)/(Area of "F" region)

= $Pr(H \wedge F) / Pr(F)$

Conditional Probability

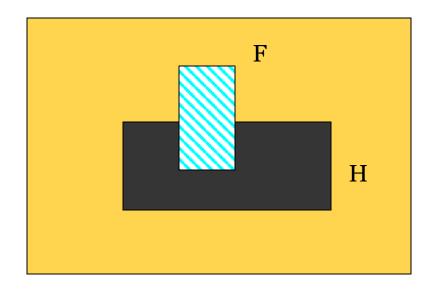
• Definition: $Pr(A|B) = Pr(A \land B) / Pr(B)$

• Chain rule: $Pr(A \land B) = Pr(A|B) Pr(B)$

Memorize these rules!



Inference



H="Have headache" F="Have Flu"

$$Pr(H) = 1/10$$

 $Pr(F) = 1/40$
 $Pr(H|F) = 1/2$

One day you wake up with a headache. You think "Drat! 50% of flues are associated with headaches so I must have a 50-50 chance of coming down with the flu"

Is your reasoning correct?

$$Pr(F\Lambda H) =$$

$$Pr(F|H) =$$



Example: Joint Distribution

sunny ~sunny

	cold	~cold		cold	~cold
headache	0.108	0.012	headache	0.072	0.008
~headache	0.016	0.064	~headache	0.144	0.576

 $Pr(headache \land cold \mid sunny) =$

 $Pr(headache \land cold \mid \sim sunny) =$



Bayes Rule

• Note: $Pr(A|B)Pr(B) = Pr(A\Lambda B) = Pr(B\Lambda A) = Pr(B|A)Pr(A)$

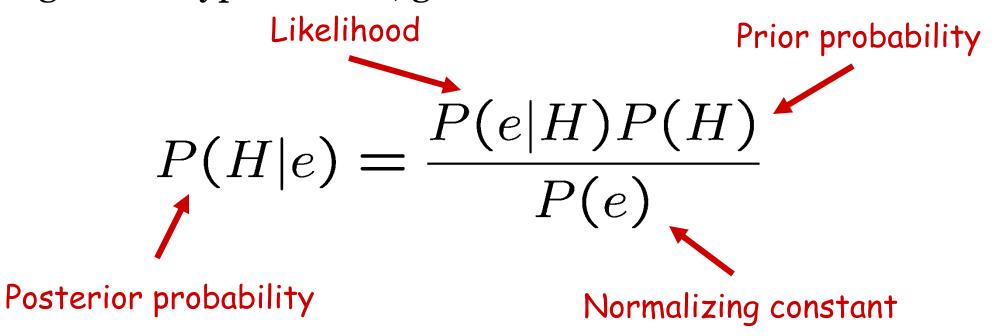
■ Bayes Rule:
$$Pr(B|A) = \frac{Pr(A|B)Pr(B)}{Pr(A)}$$

Memorize this!



Using Bayes Rule for inference

- Often, we want to form a hypothesis about the world based on what we have observed
- Bayes rule is vitally important when viewed in terms of stating the belief given to hypothesis *H*, given evidence *e*



Bayesian Learning

- **Prior:** Pr(*H*)
- Likelihood: Pr(e|H)
- Evidence: $e = \langle e_1, e_2, ..., e_N \rangle$

 Bayesian Learning amounts to computing the posterior using Bayes' Theorem:

$$Pr(H|e) = k Pr(e|H)Pr(H)$$



Bayesian Prediction

Suppose we want to make a prediction about an unknown quantity X

•
$$Pr(X|\mathbf{e}) = \Sigma_i Pr(X|\mathbf{e}, h_i) P(h_i|\mathbf{e})$$

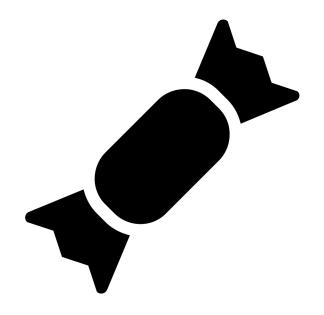
= $\Sigma_i Pr(X|h_i) P(h_i|\mathbf{e})$

- Predictions are weighted averages of the predictions of the individual hypotheses
- Hypotheses serve as "intermediaries" between raw data and prediction



Candy Example

- Favorite candy sold in two flavors:
 - Lime (hugh)
 - Cherry (yum)
- Same wrapper for both flavors
- Sold in bags with different ratios:
 - 100% cherry
 - 75% cherry + 25% lime
 - 50% cherry + 50% lime
 - 25% cherry + 75% lime
 - 100% lime





Candy Example

You bought a bag of candy but don't know its flavor ratio

- After eating *k* candies:
 - What's the flavor ratio of the bag?
 - What will be the flavor of the next candy?



Statistical Learning

- **Hypothesis H:** probabilistic theory of the world
 - h_1 : 100% cherry
 - *h*₂: 75% cherry + 25% lime
 - h_3 : 50% cherry + 50% lime
 - *h*₄: 25% cherry + 75% lime
 - *h*₅: 100% lime
- Examples E: evidence about the world
 - e_1 : 1st candy is cherry
 - e_2 : 2nd candy is lime
 - e_3 : 3rd candy is lime
 - **-** ...



Candy Example

- Assume prior Pr(H) = < 0.1, 0.2, 0.4, 0.2, 0.1 >
- Assume candies are i.i.d. (identically and independently distributed)

$$Pr(\boldsymbol{e}|h) = \Pi_n P(e_n|h)$$

Suppose first 10 candies all taste lime:

$$Pr(\boldsymbol{e}|h_5) =$$

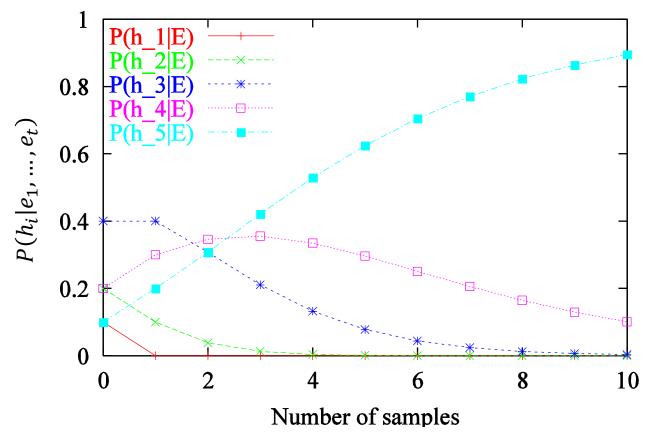
$$Pr(\boldsymbol{e}|h_3) =$$

$$Pr(\boldsymbol{e}|h_1) =$$



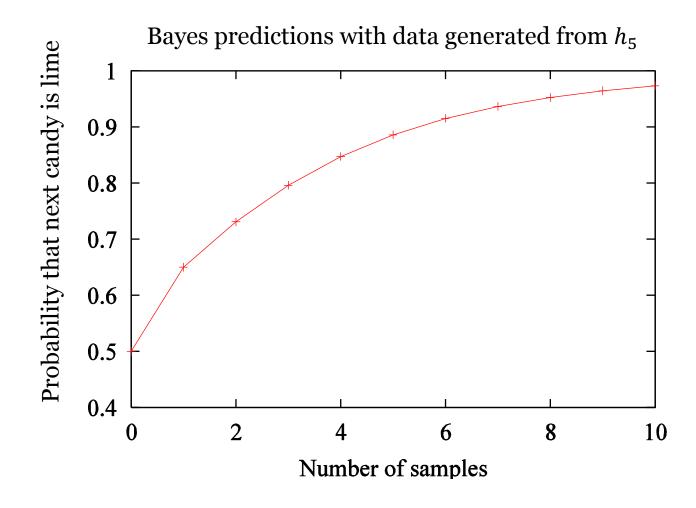
Posterior

Posteriors given data generated from h_5





Prediction





Bayesian Learning

- Bayesian learning properties:
 - **Optimal** (i.e., given prior, no other prediction is correct more often than the Bayesian one)
 - No overfitting (all hypotheses are considered and weighted)
- There is a price to pay:
 - When hypothesis space is large, Bayesian learning may be intractable
 - i.e., sum (or integral) over hypothesis often intractable
- Solution: approximate Bayesian learning



Maximum a posteriori (MAP)

• Idea: make prediction based on **most probable hypothesis** h_{MAP}

$$h_{MAP} = argmax_{h_i} \Pr(h_i | \boldsymbol{e})$$

$$\Pr(X | \boldsymbol{e}) \approx \Pr(X | h_{MAP})$$

 In contrast, Bayesian learning makes prediction based on all hypotheses weighted by their probability



MAP properties

- MAP prediction **less accurate** than Bayesian prediction since it relies only on **one** hypothesis h_{MAP}
- But MAP and Bayesian predictions converge as data increases
- **Controlled overfitting** (prior can be used to penalize complex hypotheses)
- Finding h_{MAP} may be intractable:
 - $\bullet h_{MAP} = argmax_h \Pr(h|\boldsymbol{e})$
 - Optimization may be difficult



Maximum Likelihood (ML)

■ Idea: simplify MAP by assuming uniform prior (i.e., $Pr(h_i) = Pr(h_j) \forall i, j$) $h_{MAP} = argmax_h Pr(h) Pr(e|h)$ $h_{ML} = argmax_h Pr(e|h)$

• Make prediction based on h_{ML} only:

$$\Pr(X|\boldsymbol{e}) \approx \Pr(X|h_{ML})$$



Maximum Likelihood (ML) properties

- ML prediction **less accurate** than Bayesian and MAP predictions since it ignores prior info and relies only on **one** hypothesis h_{ML}
- But ML, MAP and Bayesian predictions converge as data increases
- Subject to **overfitting** (no prior to penalize complex hypothesis that could exploit statistically insignificant data patterns)
- Finding h_{ML} is often easier than h_{MAP} $h_{ML} = argmax_h \Sigma_n \log \Pr(e_n|h)$

