Lecture 23: Gradient Boosting, Bagging, Decision Forest CS480/680 Intro to Machine Learning

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Gradient Boosting

- AdaBoost designed for classification
- How can we use boosting for regression?

Answer: Gradient Boosting



Gradient Boosting

Idea:

• Predictor f_k at stage k incurs loss $L(f_k(x), y)$

• Train h_{k+1} to approximate negative gradient:

$$h_{k+1}(\mathbf{x}) \approx -\frac{\partial L(f_k(\mathbf{x}), y)}{\partial f_k(\mathbf{x})}$$

• Update predictor by adding a multiple η_{k+1} of h_{k+1} :

$$f_{k+1}(x) \leftarrow f_k(x) + \eta_{k+1} h_{k+1}(x)$$



Squared Loss

Consider squared loss

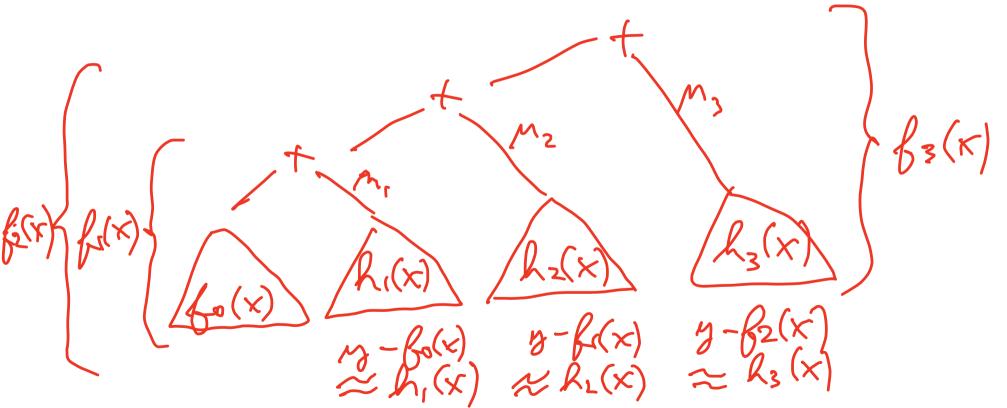
$$L(f_k(\mathbf{x}_n), y_n) = \frac{1}{2}(f_k(\mathbf{x}_n) - y_n)^2$$

Negative gradient corresponds to residual r

$$-\frac{\partial L(f_k(x_n), y_n)}{\partial f_k(x_n)} = y_n - f_k(x_n) = r_n$$

- Train base learner h_{k+1} with residual dataset $\{(x_n, r_n)_{\forall n}\}$
- Base learner h_{k+1} can be any **non-linear predictor** (often a small decision tree)

Illustration



Gradient Boosting Algorithm

• Initialize predictor with a constant *c*:

$$f_0(\mathbf{x}_n) = argmin_c \sum_n L(c, y_n)$$

- For k = 1 to K do
 - Compute pseudo residuals: $r_n = -\frac{\partial L(f_{k-1}(x_n), y_n)}{\partial f_{k-1}(x_n)}$
 - Train a base learner h_k with residual dataset $\{(x_n, r_n)_{\forall n}\}$
 - Optimize step length: $\eta_k = argmin_{\eta} \sum_n L(f_{k-1}(\boldsymbol{x}_n) + \eta h_k(\boldsymbol{x}_n), y_n)$
 - Update predictor: $f_k(x) \leftarrow f_{k-1}(x) + \eta_k h_k(x)$



XGBoost

- eXtreme Gradient Boosting
 - Package optimized for speed and accuracy
 - XGBoost used in >12 winning entries for various challenges
 https://github.com/dmlc/xgboost/tree/master/demo#machine-learning-challenge-winning-solutions

Boosting vs Bagging

Review Bagging . majority vote · Assumptions - independent hypotheses · hypothèses with similar accuracies

Boosting , weighted predictions . Allows: . (orrelated hypotheses . Hypotheses with imbalanced accuracies



Independent classifiers/predictors

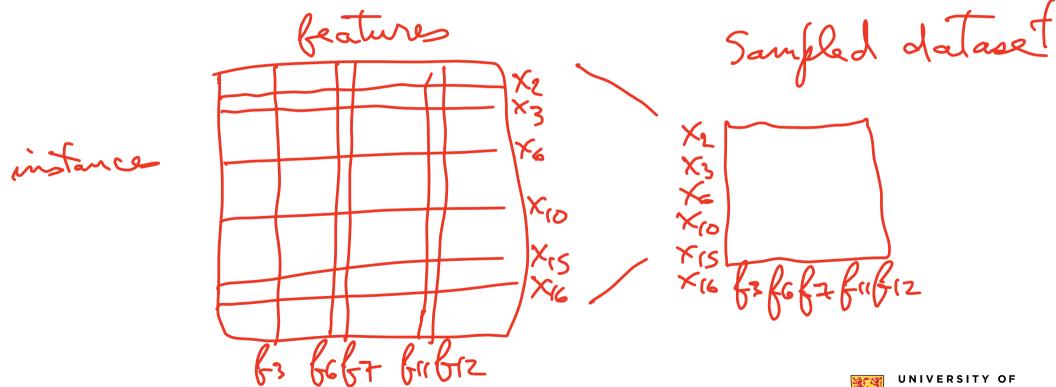
• How can we obtain independent classifiers/predictors for bagging?

- Bootstrap sampling
 - Sample (without replacement) subset of data
- Random projection
 - Sample (without replacement) subset of features

• Learn different classifiers/predictors based on each data subset and feature subset

Illustration of Bootstrap Sampling and Random Projection

Dataset



Bagging

For k = 1 to K

 $D_k \leftarrow \text{sample data subset}$

 $F_k \leftarrow \text{sample feature subset}$

 $h_k \leftarrow \text{train classifier/predictor based on } \boldsymbol{D}_k \text{ and } \boldsymbol{F}_k$

Classification: $majority(h_1(\mathbf{x}), ..., h_K(\mathbf{x}))$

Regression: $average(h_1(\mathbf{x}), ..., h_K(\mathbf{x}))$

Random forest: bag of decision trees



Application: Xbox 360 Kinect

- Microsoft Cambridge
- Body part recognition: supervised learning





Depth camera

Kinect



Infrared image



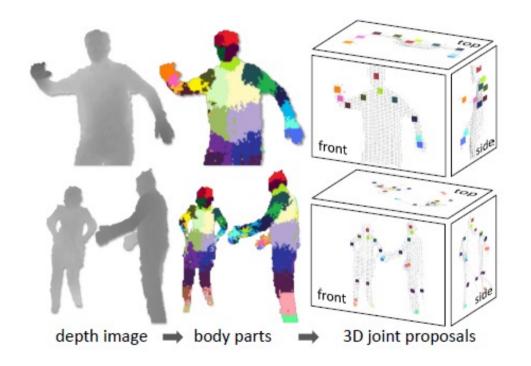
Gray scale depth map





Kinect Body Part Recognition

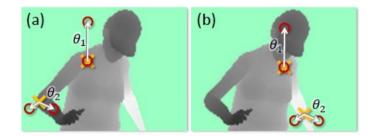
Problem: label each pixel with a body part



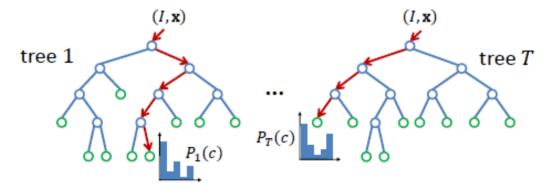


Kinect Body Part Recognition

• Features: depth differences between pairs of pixels



Classification: forest of decision trees





Large Scale Machine Learning

- Big data
 - Large number of data instances
 - Large number of features

- Solution: distribute computation (parallel computation)
 - GPU (Graphics Processing Unit)
 - Many cores



GPU computation

- Many Machine Learning algorithms consist of vector, matrix and tensor operations
 - A tensor is a multidimensional array

- GPU (Graphics Processing Units) can perform arithmetic operations on all elements of a tensor in parallel
- Packages that facilitate ML programming on GPUs: Keras, PyTorch, TensorFlow, MXNet, Theano, Caffe, DL4J



Multicore Computation

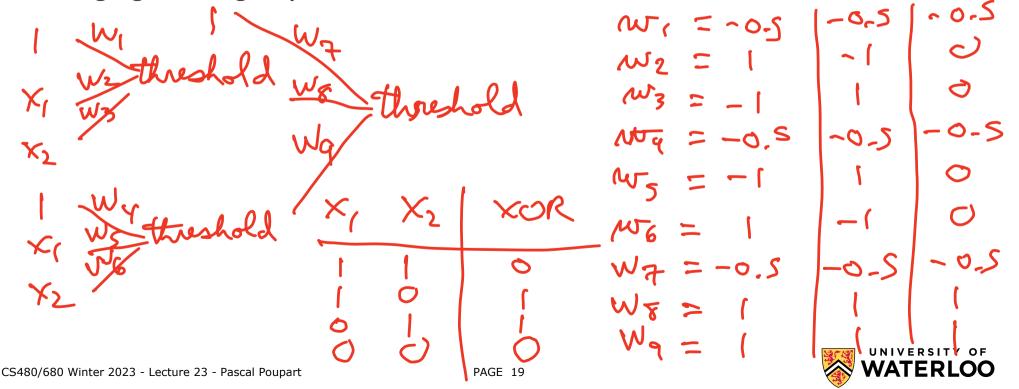
• Idea: Train a different classifier/predictor with a subset of the data on each core

- How can we combine the classifiers/predictors?
- Should we take the average of the parameters of the classifiers/predictors?

No, this might lead to a worse classifier/predictor. This is especially problematic for models with hidden variables/units such as neural networks and hidden Markov models

Bad case of parameter averaging

- Consider two threshold neural nets that encode the exclusive-or Boolean function
- Averaging the weights yields new neural net that does not encode exclusive-or



Safely Combining Predictions

 A safe approach to ensemble learning is to combine the predictions (not the parameters)

• **Classification:** majority vote of the classes predicted by the classifiers

• **Regression:** average of the predictions computed by the regressors



Knowledge Distillation

- Technique to train a **small student network** \tilde{h} from a **large teacher network** h.
 - Can be used to compress an ensemble of networks into a single network
- Idea: minimize negative log likelihood of target *y* and cross entropy between teacher and student:

$$\min_{\widetilde{h}} \sum_{(x,y)\in D} \left[-\log p_{\widetilde{h}}(y|x) - \lambda \sum_{y'} p_h(y'|x) \log p_{\widetilde{h}}(y'|x) \right]$$



Course Perception

• When you have a chance, please fill up the survey and provide feedback about the course (CS480/680) at

https://perceptions.uwaterloo.ca/

