

# Lecture 16: Attention, Transformers and Structured State Space Sequence (S4)

## CS480/680 Intro to Machine Learning

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# Attention

- Attention in Computer Vision
  - 2014: Attention used to highlight important parts of an image that contribute to a desired output
- Attention in NLP
  - 2015: Aligned machine translation
  - 2017: Language modeling with **Transformer networks**



# Sequence Modeling

## Challenges with RNNs

- Long range dependencies
- Gradient vanishing and explosion
- Large # of training steps
- Recurrence prevents parallel computation

## Transformer Networks

- Facilitate long range dependencies
- No gradient vanishing and explosion
- Fewer training steps
- No recurrence that facilitate parallel computation

# Attention Mechanism

- Mimics the retrieval of a **value**  $v_i$  for a **query**  $q$  based on a **key**  $k_i$  in database
- Picture

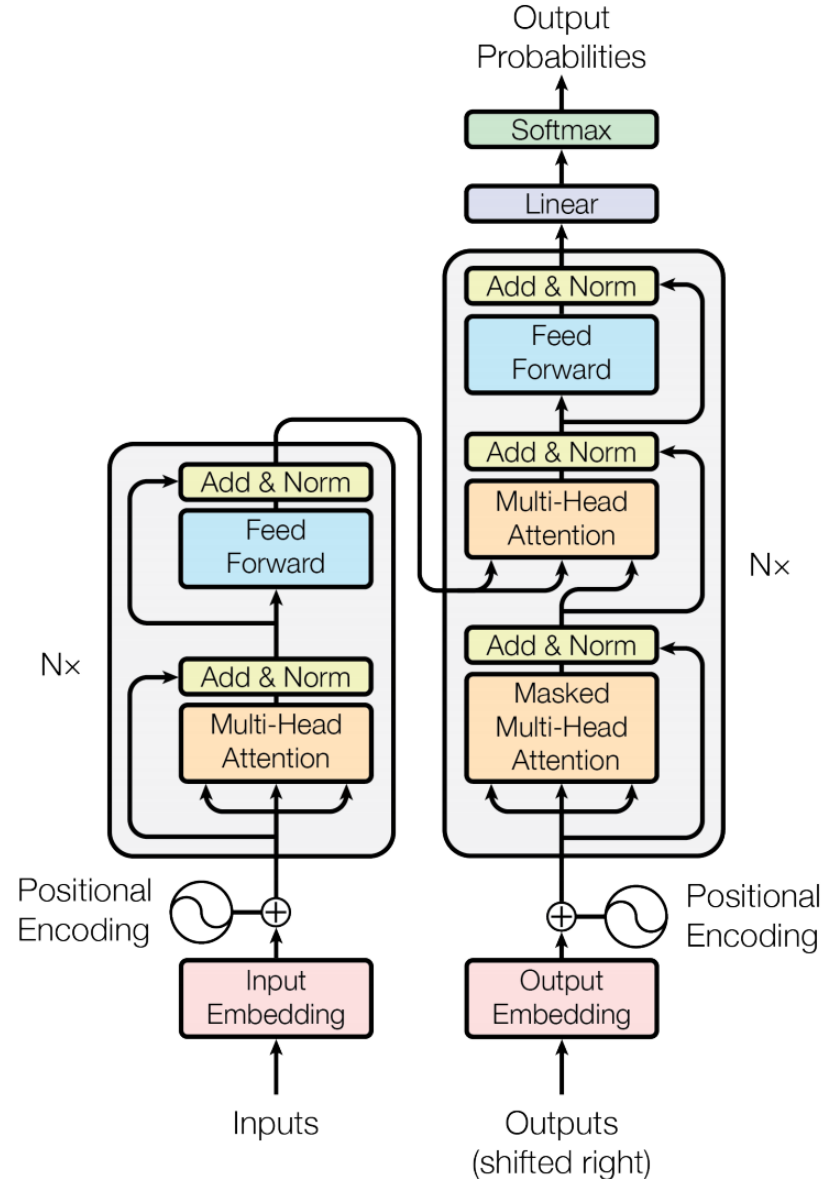
$$attention(q, \mathbf{k}, \mathbf{v}) = \sum_i similarity(q, k_i) \times v_i$$

# Attention Mechanism (Neural Architecture)

- Example: machine translation
  - Query:  $s_{i-1}$  (hidden vector for  $i - 1^{th}$  output word)
  - Key:  $h_j$  (hidden vector for  $j^{th}$  input word)
  - Value:  $h_j$  (hidden vector for  $j^{th}$  input word)

# Transformer Network

- Vaswani et al., (2017)  
Attention is all you need.
- Encoder-decoder based on attention (no recurrence)



# Multihead attention

- Multihead attention: compute multiple attentions per query with different weights

$$\text{multihead}(Q, K, V) = W^O \text{concat}(\text{head}_1, \text{head}_2, \dots, \text{head}_h)$$

$$\text{head}_i = \text{attention}(W_i^Q Q, W_i^K K, W_i^V V)$$

$$\text{attention}(Q, K, V) = \text{softmax}\left(\frac{Q^T K}{\sqrt{d_k}}\right) V$$

# Masked Multi-head attention

- Masked multi-head attention: multi-head where some values are masked (i.e., probabilities of masked values are nullified to prevent them from being selected).
- When decoding, an output value should only depend on previous outputs (not future outputs). Hence we mask future outputs.

$$\textit{attention}(Q, K, V) = \textit{softmax} \left( \frac{Q^T K}{\sqrt{d_k}} \right) V$$

$$\textit{maskedAttention}(Q, K, V) = \textit{softmax} \left( \frac{Q^T K + M}{\sqrt{d_k}} \right) V$$

where  $M$  is a mask matrix of 0's and  $-\infty$ 's



# Other layers

- Layer normalization:

- Normalize values in each layer to have 0 mean and 1 variance
- For each hidden unit  $h_i$  compute  $h_i \leftarrow \frac{g}{\sigma}(h_i - \mu)$

where  $g$  is a variable,  $\mu = \frac{1}{H} \sum_{i=1}^H h_i$  and  $\sigma = \sqrt{\frac{1}{H} \sum_{i=1}^H (h_i - \mu)^2}$

- This reduces “covariate shift” (i.e., gradient dependencies between each layer) and therefore fewer training iterations are needed

- Positional embedding (embedding to distinguish each position):

$$PE_{position,2i} = \sin(position/10000^{2i/d})$$

$$PE_{position,2i+1} = \cos(position/10000^{2i/d})$$

# Comparison

- Attention reduces sequential operations and maximum path length, which facilitates long range dependencies

Table 1: Maximum path lengths, per-layer complexity and minimum number of sequential operations for different layer types.  $n$  is the sequence length,  $d$  is the representation dimension,  $k$  is the kernel size of convolutions and  $r$  the size of the neighborhood in restricted self-attention.

Layer Type	Complexity per Layer	Sequential Operations	Maximum Path Length
Self-Attention	$O(n^2 \cdot d)$	$O(1)$	$O(1)$
Recurrent	$O(n \cdot d^2)$	$O(n)$	$O(n)$
Convolutional	$O(k \cdot n \cdot d^2)$	$O(1)$	$O(\log_k(n))$
Self-Attention (restricted)	$O(r \cdot n \cdot d)$	$O(1)$	$O(n/r)$

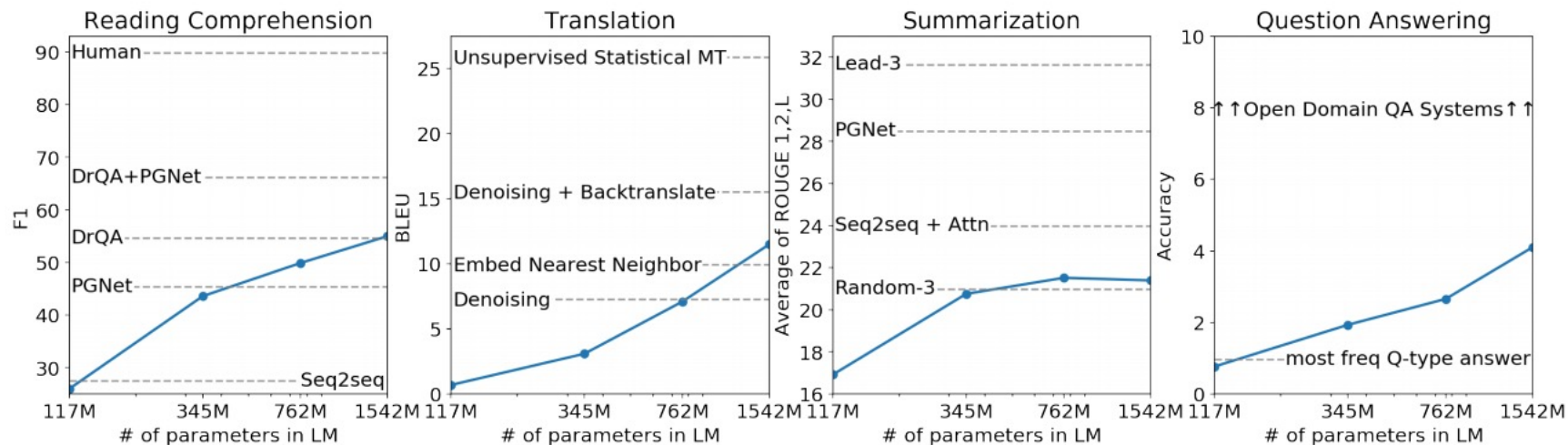
# Results

Table 2: The Transformer achieves better BLEU scores than previous state-of-the-art models on the English-to-German and English-to-French newstest2014 tests at a fraction of the training cost.

Model	BLEU		Training Cost (FLOPs)	
	EN-DE	EN-FR	EN-DE	EN-FR
ByteNet [15]	23.75			
Deep-Att + PosUnk [32]		39.2		$1.0 \cdot 10^{20}$
GNMT + RL [31]	24.6	39.92	$2.3 \cdot 10^{19}$	$1.4 \cdot 10^{20}$
ConvS2S [8]	25.16	40.46	$9.6 \cdot 10^{18}$	$1.5 \cdot 10^{20}$
MoE [26]	26.03	40.56	$2.0 \cdot 10^{19}$	$1.2 \cdot 10^{20}$
Deep-Att + PosUnk Ensemble [32]		40.4		$8.0 \cdot 10^{20}$
GNMT + RL Ensemble [31]	26.30	41.16	$1.8 \cdot 10^{20}$	$1.1 \cdot 10^{21}$
ConvS2S Ensemble [8]	26.36	<b>41.29</b>	$7.7 \cdot 10^{19}$	$1.2 \cdot 10^{21}$
Transformer (base model)	27.3	38.1	<b><math>3.3 \cdot 10^{18}</math></b>	
Transformer (big)	<b>28.4</b>	<b>41.0</b>	$2.3 \cdot 10^{19}$	

# GPT and GPT-2

- Radford et al., (2018) Language models are unsupervised multitask learners
  - Decoder transformer that predicts next word based on previous words by computing  $P(x_t|x_{1..t-1})$
  - SOTA in “zero-shot” setting for 7/8 language tasks (where zero-shot means no task training, only unsupervised language modeling)



# BERT (Bidirectional Encoder Representations from Transformers)

- Devlin et al., (2019) BERT: Pre-training of Deep Bidirectional Transformers for Language Understanding
  - Decoder transformer that predicts a missing word based on surrounding words by computing  $P(x_t|x_{1..t-1,t+1..T})$
  - Mask missing word with masked multi-head attention
  - Improved state of the art on 11 tasks

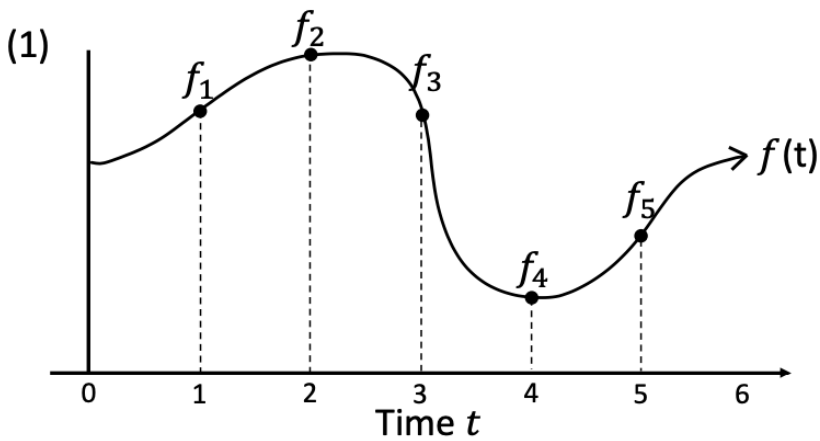
System	MNLI-(m/mm) 392k	QQP 363k	QNLI 108k	SST-2 67k	CoLA 8.5k	STS-B 5.7k	MRPC 3.5k	RTE 2.5k	Average
Pre-OpenAI SOTA	80.6/80.1	66.1	82.3	93.2	35.0	81.0	86.0	61.7	74.0
BiLSTM+ELMo+Attn	76.4/76.1	64.8	79.8	90.4	36.0	73.3	84.9	56.8	71.0
OpenAI GPT	82.1/81.4	70.3	87.4	91.3	45.4	80.0	82.3	56.0	75.1
BERT <sub>BASE</sub>	84.6/83.4	71.2	90.5	93.5	52.1	85.8	88.9	66.4	79.6
BERT <sub>LARGE</sub>	<b>86.7/85.9</b>	<b>72.1</b>	<b>92.7</b>	<b>94.9</b>	<b>60.5</b>	<b>86.5</b>	<b>89.3</b>	<b>70.1</b>	<b>82.1</b>

# Limitation

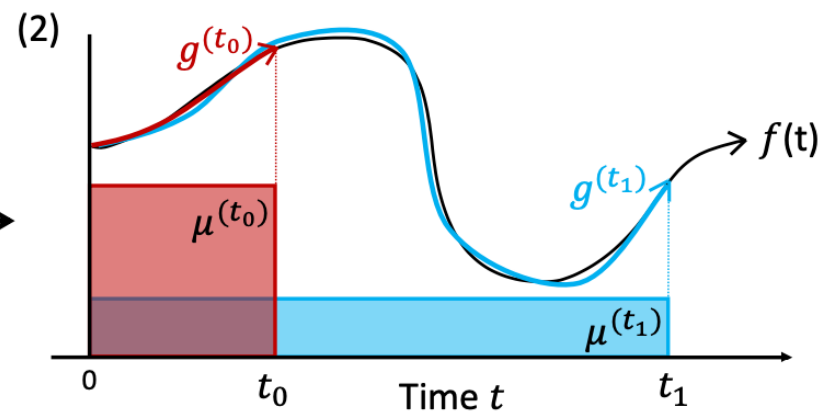
- Transformers **scale quadratically** with sequence length
  - In practice, sequence length often limited to 512 tokens
- How can we process long sequences?
  - Hierarchy of transformers (i.e., words→sentences→documents→corpus)
  - Approximate transformers (i.e., longformer, reformer, performer, etc.)
  - **Structured State Space Sequence (S4) model**
- S4: Very recent approach (Gu, Goel & Re, ICLR 2022)
  - Potential to displace transformers
  - S4 achieved state of the art on Long Range Arena benchmark
  - Scales linearly with sequence length

# Structured State Space Sequence (S4) Model

- HiPPO: high-order polynomial projection operators (Gu et al., 2020)



$\text{proj}_t$



(4) Discrete-time HiPPO Recurrence

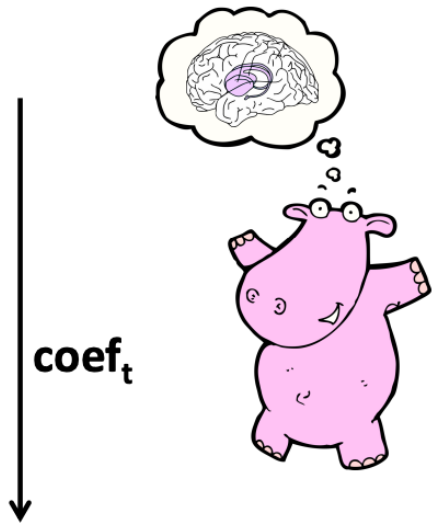
$$c_{k+1} = A_k c_k + B_k f_k$$

discretize

(3) Continuous-time HiPPO ODE

$$\frac{d}{dt} c(t) = A(t)c(t) + B(t)f(t)$$

$c(t_0) = \begin{bmatrix} 0.1 \\ -1.1 \\ 3.7 \\ 2.5 \end{bmatrix}$ 
 $c(t_1) = \begin{bmatrix} 1.5 \\ 2.9 \\ -0.3 \\ 2.0 \end{bmatrix}$



$\text{coef}_t$

# Measures (importance given to past history)

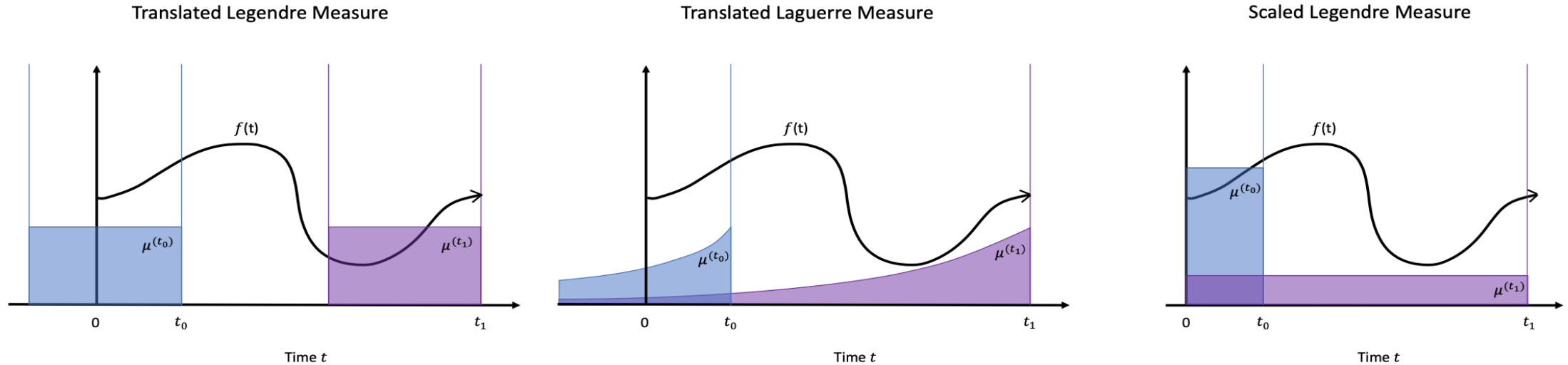
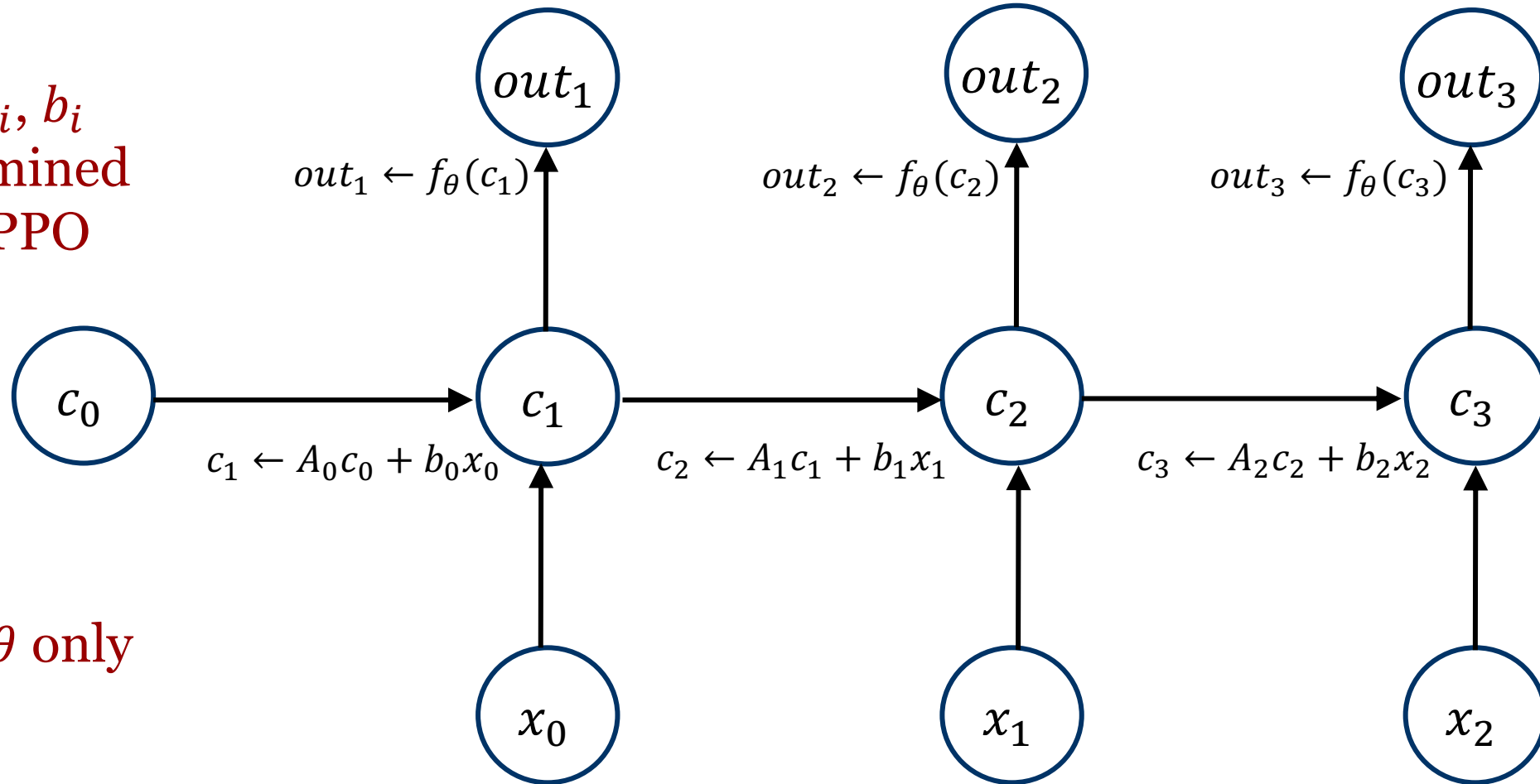


Figure 5: **Illustration of HiPPO measures.** At time  $t_0$ , the history of a function  $f(x)_{x \leq t_0}$  is summarized by polynomial approximation with respect to the measure  $\mu^{(t_0)}$  (blue), and similarly for time  $t_1$  (purple). (Left) The Translated Legendre measure (**LegT**) assigns weight in the window  $[t - \theta, t]$ . For small  $t$ ,  $\mu^{(t)}$  is supported on a region  $x < 0$  where  $f$  is not defined. When  $t$  is large, the measure is not supported near  $0$ , causing the projection of  $f$  to forget the beginning of the function. (Middle) The Translated Laguerre (**LagT**) measure decays the past exponentially. It does not forget, but also assigns weight on  $x < 0$ . (Right) The Scaled Legendre measure (**LegS**) weights the entire history  $[0, t]$  uniformly.



# RNN with HiPPO

NB:  $A_i, b_i$   
determined  
by HiPPO



Train  $\theta$  only

# Computational Complexity

- S4 scales better than CNNs, RNNs and Transformers

Table 1: Complexity of various sequence models in terms of sequence length ( $L$ ), batch size ( $B$ ), and hidden dimension ( $H$ ); tildes denote log factors. Metrics are parameter count, training computation, training space requirement, training parallelizability, and inference computation (for 1 sample and time-step). For simplicity, the state size  $N$  of S4 is tied to  $H$ . Bold denotes model is theoretically best for that metric. Convolutions are efficient for training while recurrence is efficient for inference, while SSMs combine the strengths of both.

	Convolution <sup>3</sup>	Recurrence	Attention	S4
Parameters	$LH$	$H^2$	$H^2$	$H^2$
Training	$\tilde{L}H(B + H)$	$BLH^2$	$B(L^2H + LH^2)$	$BH(\tilde{H} + \tilde{L}) + B\tilde{L}H$
Space	$BLH$	$BLH$	$B(L^2 + HL)$	$BLH$
Parallel	<b>Yes</b>	No	<b>Yes</b>	<b>Yes</b>
Inference	$LH^2$	$H^2$	$L^2H + H^2L$	$H^2$

From Gu, Goel & Re (2022)

# Results: Long Range Arena

MODEL	LISTOPS	TEXT	RETRIEVAL	IMAGE	PATHFINDER	PATH-X	AVG
Transformer	36.37	64.27	57.46	42.44	71.40	X	53.66
Reformer	<u>37.27</u>	56.10	53.40	38.07	68.50	X	50.56
BigBird	36.05	64.02	59.29	40.83	74.87	X	54.17
Linear Trans.	16.13	<u>65.90</u>	53.09	42.34	75.30	X	50.46
Performer	18.01	65.40	53.82	42.77	77.05	X	51.18
FNet	35.33	65.11	59.61	38.67	<u>77.80</u>	X	54.42
Nyströmformer	37.15	65.52	<u>79.56</u>	41.58	70.94	X	57.46
Luna-256	37.25	64.57	79.29	<u>47.38</u>	77.72	X	<u>59.37</u>
<b>S4</b>	<b>59.60</b>	<b>86.82</b>	<b>90.90</b>	<b>88.65</b>	<b>94.20</b>	<b>96.35</b>	<b>86.09</b>

From Gu, Goel & Re (2022)

# Results: Speech and Images

Table 5: (**SC10 classification**) Transformer, CTM, RNN, CNN, and SSM models. (*MFCC*) Standard pre-processed MFCC features (length 161). (*Raw*) Unprocessed signals (length 16000). (*0.5x*) Frequency change at test time. **X** denotes not applicable or computationally infeasible on single GPU. *Please read Appendix D.5 before citing this table.*

	MFCC	RAW	0.5x
Transformer	90.75	<b>X</b>	<b>X</b>
Performer	80.85	30.77	30.68
ODE-RNN	65.9	<b>X</b>	<b>X</b>
NRDE	89.8	16.49	15.12
ExpRNN	82.13	11.6	10.8
LipschitzRNN	88.38	<b>X</b>	<b>X</b>
CKConv	<b>95.3</b>	71.66	<u>65.96</u>
WaveGAN-D	<b>X</b>	<u>96.25</u>	<b>X</b>
LSSL	93.58	<b>X</b>	<b>X</b>
<b>S4</b>	<u>93.96</u>	<b>98.32</b>	<b>96.30</b>

From Gu, Goel & Re (2022)

Table 6: (**Pixel-level 1-D image classification**) Comparison against reported test accuracies from prior works (Transformer, RNN, CNN, and SSM models). Extended results and citations in Appendix D.

	sMNIST	pMNIST	sCIFAR
Transformer	98.9	97.9	62.2
LSTM	98.9	95.11	63.01
r-LSTM	98.4	95.2	72.2
UR-LSTM	99.28	96.96	71.00
UR-GRU	99.27	96.51	74.4
HiPPO-RNN	98.9	98.3	61.1
LMU-FFT	-	98.49	-
LipschitzRNN	99.4	96.3	64.2
TCN	99.0	97.2	-
TrellisNet	99.20	98.13	73.42
CKConv	99.32	98.54	63.74
LSSL	<u>99.53</u>	<b>98.76</b>	<u>84.65</u>
<b>S4</b>	<b>99.63</b>	<u>98.70</u>	<b>91.13</b>