

CS475 / CS675

Lecture 10: June 2, 2016

Least Squares Problems

Reading: [TB] Chapt 11

Least Squares Problems

- First posed and formulated by Gauss.
- Surveyors tried to identify boundaries by measuring certain angles and distances from known landmarks.
- To update the location of landmarks, new measurements of angles and distances between landmarks are made.

Surveying Example

- Given a set of old locations $\{(x_i, y_i)\}$, find correction $\{(\delta x_i, \delta y_i)\}$ such that $\{(x_i + \delta x_i, y_i + \delta y_i)\}$ better match new measurements
- Picture:

Surveying Example

- Non-linear constraint:

$$\cos^2 \theta_i = \textit{measurement}$$

$$= \frac{\left[(z_j - z_i)^T (z_k - z_i) \right]^2}{(z_j - z_i)^T (z_j - z_i) (z_k - z_i)^T (z_k - z_i)}$$

- Suppose $(\delta x_i, \delta y_i) \ll (x_i, y_i)$
 - Multiply through the denominator
 - Multiply out all the terms to get a quartic polynomial in all δ -variables
 - Throw away all terms containing $\delta^2, \delta^3, \delta^4$ \Rightarrow linear constraint

Surveying example

- Collect all linear constraints for all angles and distance measurements
⇒ overdetermined linear system
- In general:

$$\text{constraints} \left\{ \begin{array}{l} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m \end{array} \right\} \text{observations}$$

Picture: $Ax = b$

Solving LS Problems

- Geometric interpretation:

Solving LS Problems

- Theorem: Let $A \in \mathfrak{R}^{m \times n}$, $b \in \mathfrak{R}^m$, $m \geq n$. A vector $x \in \mathfrak{R}^n$ minimizes

$$\|r\|_2^2 = \|b - Ax\|_2^2$$

if and only if $r \perp \text{range}(A)$

- $\therefore r^T A = 0 \iff A^T r = 0$
 $\iff A^T (b - Ax) = 0$
 $\iff A^T Ax = A^T b$

Pseudoinverse

- Def: $A^\dagger = (A^T A)^{-1} A^T$ is called the pseudoinverse of A
- The least squares solution is given by
$$x = (A^T A)^{-1} A^T b = A^\dagger b$$
- Why is x the minimizer of $\|b - Ax\|^2$?

Pseudoinverse

- Let $x' = x + e$ be another point

$$\begin{aligned} \|b - Ax'\|_2^2 &= (b - Ax')^T (b - Ax') \\ &= (b - Ax - Ae)^T (b - Ax - Ae) \\ &= (b - Ax)^T (b - Ax) + 2(Ae)^T (b - Ax) + (Ae)^T Ae \\ &= \|b - Ax\|^2 + \|Ae\|^2 + 2e^T (A^T b - A^T Ax) \\ &= \|b - Ax\|^2 + \|Ae\|^2 \end{aligned}$$

$$\therefore \|b - Ax'\|^2 > \|b - Ax\|^2 \quad \text{if } e \neq 0$$

Pseudoinverse

- Picture:

Method 1: Normal Equations

- Solve $A^T A x = A^T b$
- Compute Cholesky factorization
 - i.e., $A^T A = G G^T$, $G = \text{lower } \Delta$

$$G G^T x = A^T b$$

- Compute x by forward and backward solves
- Complexity:
 - $\text{flops}(A^T A) \sim mn^2$, $\text{flops}(G G^T) \sim n^3/3$
 - $\therefore \text{total flops} \sim mn^2 + n^3/3$ ($m \geq n$)

Method 2: QR Factorization

- Def: Q is orthogonal if $Q^{-1} = Q^T$
 - i.e., $Q^T Q = Q Q^T = I$
- Theorem: $\|Qx\|_2 = \|x\|_2$
- Proof:

Orthogonal Q

- Note: multiplication by Q

$$Q = \begin{cases} \text{rotation} & \text{if } \det(Q) = 1 \\ \text{reflection} & \text{if } \det(Q) = -1 \end{cases}$$

- Picture:

QR Factorization (reduced version)

- Let $A = [a_1 \ a_2 \ \dots \ a_n]$. Want to find orthonormal vectors $\{q_i\}$ such that
$$\text{span}\{q_1, \dots, q_j\} = \text{span}\{a_1, \dots, a_j\} \quad j = 1, 2, \dots, n$$
- This amounts to:

- Matrix form: $A = \hat{Q}\hat{R}$
 - \hat{Q} has orthonormal columns, \hat{R} is upper Δ

QR Factorization (full version)

- Append additional $m - n$ orthogonal cols to \hat{Q}
 - i.e., $[q_{n+1} \ q_{n+2} \ \dots \ q_m] \equiv \hat{Q}_{m-n}$
 - Then
-
- Usually for theoretical purpose

QR Factorization

- Theorem: Suppose $A \in \mathfrak{R}^{m \times n}$ has full rank. \exists unique orthogonal matrix $\hat{Q} \in \mathfrak{R}^{m \times n}$ ($\hat{Q}^T \hat{Q} = I$) and a unique upper Δ matrix $\hat{R} \in \mathfrak{R}^{n \times n}$ with positive diagonals ($r_{ii} > 0$) such that $A = \hat{Q}\hat{R}$
- Picture:
- Note: Cols of \hat{Q} are orthogonal to each other and their norm = 1

QR Factorization

- Consider the LS problem:

$$\min_x \|Ax - b\|^2$$

- Then $Ax - b = \hat{Q}\hat{R}x - b$
 $= \hat{Q}\hat{R}x - (\hat{Q}\hat{Q}^T + I - \hat{Q}\hat{Q}^T)b$
 $= \hat{Q}(\hat{R}x - \hat{Q}^T b) - (I - \hat{Q}\hat{Q}^T)b$
- Note: $\hat{Q}(\hat{R}x - \hat{Q}^T b) \perp (I - \hat{Q}\hat{Q}^T)b$

QR Factorization

- Note: $\hat{Q}(\hat{R}x - \hat{Q}^T b) \perp (I - \hat{Q}\hat{Q}^T)b$
- Proof:
$$\begin{aligned} & [\hat{Q}(\hat{R}x - \hat{Q}b)]^T (I - \hat{Q}\hat{Q}^T)b \\ &= (\hat{R}x - \hat{Q}b)^T \hat{Q}^T (I - \hat{Q}\hat{Q}^T)b \\ &= (\hat{R}x - \hat{Q}b)^T (\hat{Q}^T - \hat{Q}^T \hat{Q}\hat{Q}^T)b \\ &= 0 \quad \text{(since } \hat{Q}^T \hat{Q} = I) \end{aligned}$$
- Picture:

QR Factorization

- Pythagoras theorem:

$$\begin{aligned} \|Ax - b\|^2 &= \|\hat{Q}(\hat{R}x - \hat{Q}^T b)\|^2 + \|(I - \hat{Q}\hat{Q}^T)b\|^2 \\ &= \|\hat{R}x - \hat{Q}^T b\|^2 + \|(I - \hat{Q}\hat{Q}^T)b\|^2 \end{aligned}$$

- The RHS is minimized if the first term is 0

– i.e., $\hat{R}x = \hat{Q}^T b \Rightarrow x = \hat{R}^{-1}\hat{Q}^T b$

- Notes

1. $A^\dagger = \hat{R}^{-1}\hat{Q}^T$

2. $A^T Ax = A^T b \Leftrightarrow (\hat{R}^T \hat{Q}^T)(\hat{Q} \hat{R})x = (\hat{R}^T \hat{Q}^T)b$

$$\begin{aligned} \hat{R}^T \hat{R}x &= \hat{R}^T \hat{Q}^T b \\ \hat{R}x &= \hat{Q}^T b \\ x &= \hat{R}^{-1} \hat{Q}^T b \end{aligned}$$