

ne(s.s Mapping Big-Step Modeling Languages to SMV

Formal Verification for Model-Driven Engineering

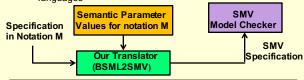
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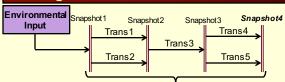
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1-Introduction

- Different behavioural modeling languages are used in model-driven methodologies
- √ How do we verify properties of models designed in different languages?
- ✓ Solution: transform a design model notation to the input language of an analyzer, such as a model checker
- Our contribution is a semantics-based translator from the family of big-step modeling languages (BSMLs) to the input language of SMV.
- · A BSML is described using parameter values for semantic aspects.
 - ✓ Using our translator, different combinations of options for semantic aspects will lead to generating new translators for specific languages

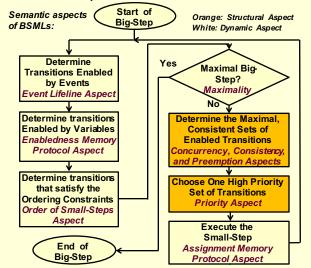


2- Background: BSMLs

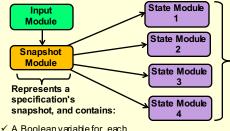


Big-Step: Reaction of model to an environmental Input, which consists of a sequence of small-steps

 Many BSMLs exist with different syntaxes and semantics, such as Statecharts, Argos, Reactive Modules, and SCR, so we use a normal-form syntax called CHTS.



3- Module Structure in SMV



- √ A Boolean variable for each basic state and a macro for every non-basic state representing whether they are active or not
- ✓ A Boolean variable and a variable with the appropriate type for each event and each variable in the original model
- ✓ A Boolean variable for each transition. in the model: execution variables

6- Example

One for each

and includes:

state's scope

state modules

and execution

✓ An instance of the

non-basic state.

✓ Enabledness flag for

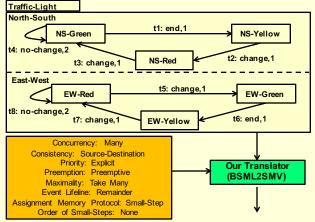
each transition in the

corresponding to the

state's direct children

Two flags (macros) for

the state enabledness



MODULE snapshot(){ --basic states NS_Green, NS_Yellow, NS_Red, EW_Green, EW_Yellow, EW_Red: boolean; --events end, change: boolean; -execution variables of transitions t1_exe,t2_exe,t3_exe,t4_exe,t5_exe t6_exe,t7_exe,t8_exe: boolean; DEFINE North-South := NS_Green NS_Yellow NS_Red; East-West := EW_Green|EW_Yellow|EW_Red; --next statements default {next(no-change) := no-change;} in{if(stable) next(no-change) := input.no-change;} -similar statements for "end" and "change" next(NS_Green) := case { t3 execute | t4 execute : 1; t1_execute: 0; 1: NS_Green; -similar statements for all basic states} MODULE main(){ -instance of the module snapshot

ss: snapshot; model root: Traffic Light(ss);} MODULE Traffic_Light(ss){ North South: North South(ss); East_West : East_West(ss); enabled := North Southenabled East West, enabled; execute := North_South.execute East West, execute; ss.stable := ~enabled: --invariants

MODULE North South(ss){

t1_enabled := ss.NS_green & end; t2_enabled := ss.NS_yellow & change; t3 enabled := ss.NS red & change; t4_enabled:=ss.NS_green& no-change; enabled := t1 enabled | t2 enabled | t3_enabled | t4_enabled; execute := ss.t1_execute ss.t2_execute | ss.t3_execute | ss.t4_execute; --invariants ~(ss.t1 execute & ss.t4 execute): execute → ((t1_enabled&~t4_execute) → t1 execute); execute -> ((t4_enabled&~t1_execute) → t4 execute); execute -> (t2_enabled -> t2_execute); execute -> (t3_enabled -> t3_execute) --priority invariant t4_enabled → ~t1_execute;} MODULE East West(ss){ t5_enabled := ss.EW_red & change; t6_enabled := ss.EW_green & end; t7_enabled := ss.EW_yellow & change; t8_enabled := ss.EW_red & no-change; enabled := t5 enabled | t6 enabled | t7 enabled | t8 enabled:

execute := ss.t5 execute | ss.t6 execute | ss.t7 execute | ss.t8_execute;

--invariants ~(ss.t5_execute & ss.t8_execute);

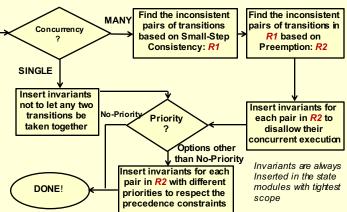
execute -> ((t5_enabled&~t8_execute) → t5_execute);

execute -> ((†8 enabled&~†5 execute) → t8 execute);

execute -> (t6_enabled -> t6_execute); execute → (t7 enabled → t7 execute) --priority invariant

t8_enabled → ~t5_execute; enabled → execute;}

4- Translating the Structural Semantic Aspects



5- Translating the Dynamic Semantic Aspects

- ✓ Using a bodean variable to indicate when the big-step concludes and the next. input should be read from the Input module
- · Event Lifeline
- ✓ Reflected in the next statement of events in the Snapshot module
- · Assignment Memory Protocol and Enabledness Memory Protocol
- ✓ If the option is Big-step, a copy of variable value at the beginning of the bigstep is needed and will be used accordingly.
- · Order of Small-Steps
- ✓ If the option is Explicit invariants are used to impose that a transition is enabled, only if none of its predecessors are enabled.