

# Dealing with the integer solutions of, possibly parametric, systems of linear equations and inequalities in Maple

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## Recommended Reference Format:

Yuzhuo Lei, Rui-Juan Jing, Christopher Maligec, and Lin-Xiao Wang. 2024. Dealing with the integer solutions of, possibly parametric, systems of linear equations and inequalities in Maple. 1, 1 (May 2024), 8 pages. <https://doi.org/10.1145/nnnnnnnn.nnnnnnnn>

## 1 Overview

When solving systems of polynomial equations and inequalities, the task of computing their solutions with integer coordinates is a much harder problem than that of computing their real solutions or that of computing all their solutions. In fact, in the presence of non-linear constraints this task may simply become an undecidable problem. However, studying the integer solutions of systems of equations and inequalities is of practical importance in various areas of scientific computing. Two such areas are *combinatorial optimization* (in particular integer linear programming) and *compiler optimization* (in particular, the analysis, transformation and scheduling of for-loop nests in computer programs), where a variety of algorithms solve questions related to the points with integer coordinates belonging to a given polyhedron. Another area is at the crossroads of computer algebra and polyhedral geometry, with topics such as toric ideals and Hilbert bases, see [19] as well the manipulation of Laurent series, see [1].

One can ask different questions about the integer points of a polyhedral set, ranging from “whether or not a given rational polyhedron has integer points” to “describing all such points”. Answers to that latter question can take various forms, depending on the targeted application. For plotting purposes, one may want to enumerate all the integer points of a 2D or 3D polytope. Meanwhile, in the context of combinatorial optimization or compiler optimization, more concise descriptions are sufficient and more effective. For a rational convex polyhedron  $P \subseteq \mathbb{Q}^d$ , defined either by the set of its facets or that of its vertices, one such description is the *integer hull*  $P_I$  of  $P$ , that is, the convex hull of  $P \cap \mathbb{Z}^d$ . The set  $P_I$  is itself polyhedral and can be described either by its facets, or its vertices.

Another concise description was proposed in [9, 8] where the integer points of a polyhedral set are represented by (finitely many) triangular systems with specialization properties similar to those of regular chains and lexicographical Gröbner bases.

An even more concise answer is given by counting the number of integer points of a polytope. This problem has efficient algorithmic solutions, in particular Barvinok’s algorithm [2], as well as

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<https://doi.org/10.1145/nnnnnnnn.nnnnnnnn>

numerous applications, such as counting the number of memory locations (or cache lines) accessed by a for-loop nest, see [15, 6].

Over the past 10 years, a series of projects has equipped the computer algebra system Maple with a number of tools for dealing with the integer points of systems of linear equations and inequalities, even in the presence of parameters. These tools implement novel and effective algorithms; they are part in the PolyhedralSets library and they are the main subject of this paper.

With these tools, one can either decide whether integer point solutions exist, or count them. One can also describe them in a compact way, or enumerate them, see Sections 2 and 3. Last but not least, one can deal with parametric polytopes and count the number of their integer points, see Section 4.

## 2 Computing integer hulls

One important family of algorithms for computing the vertex set of the integer hull  $P_I$  of the polyhedral set  $P \subseteq \mathbb{Q}^d$ , relies on the so-called *cutting plane method*, originally introduced by Gomory in [7] to solve integer linear programs. Chvátal [5] and Schrijver [17] developed a procedure to compute  $P_I$  based on that latter method. Schrijver gave a full proof and a complexity study of this method in [16]. Another approach for computing  $P_I$  uses the *branch and bound method*, introduced by Land and Doig in the early 1960s in [10]. This method recursively divides  $P$  into sub-polyhedra, then the vertices of the integer hull of each part of the partition are computed. Yet another approach for computing  $P_I$  is used in the software Normaliz [4]: by embedding  $P$  in dimension  $d + 1$ , the problem of computing  $P_I$  is reduced to that of computing generators (with integer coordinates) of a rational polyhedral cone  $C$ ; indeed, once those generators are known, [Gordan's lemma](#) produces a generating set of the affine monoid  $C \cap \mathbb{Z}^{d+1}$  to which a convex hull algorithm is applied to finally deduce  $P_I$ ; hence, the bulk of the work is to compute generators of  $C$ , which is achieved by [Fourier-Motzkin Elimination \(FME\)](#).

```

> with(PolyhedralSets):
> ineqs := [2*x + 5*y ≤ 64, 7*x + 5*y ≥ 20, 3*x - 6*y ≤ -7]:
> poly := PolyhedralSet(ineqs, [x, y]);
      poly := {
      Coordinates : [x, y]
      Relations   : [-x - 5/7*y ≤ -20/7, x - 2*y ≤ -7/3, x + 5/2*y ≤ 32]
      }
(1)
> IntegerHull(poly);
      [[ [12, 8], [-8, 16], [-7, 14], [-5, 11], [0, 4], [1, 3], [3, 3], [11, 7] ], [] ]
(2)
> IntegerHull(poly, returntype = polyhedralset);
      {
      Coordinates : [x, y]
      Relations   : [-y ≤ -3, -x - y ≤ -4, -x - 5/7*y ≤ -20/7, -x - 2/3*y ≤ -7/3, -x - y/2 ≤ 0, x - 2*y ≤ -3, x - y ≤ 4, x + 5/2*y ≤ 32]
      }
>

```

Fig. 1. Using the IntegerHull command

In [13], the authors proposed a new algorithm for computing  $P_I$ , which is implemented as in the command IntegerHull of the PolyhedralSets library. This new algorithm has three main steps:

- *normalization*, during which  $P$  is replaced by a rational polyhedron  $Q \subseteq \mathbb{Q}^d$  so that the supporting hyperplane of each facet of  $Q$  has integer points and  $P_I = Q_I$  holds;
- *partitioning*, during which we search for integer points inside  $Q$  and use them to partition  $Q$  into “smaller polyhedral sets”, the integer hulls of which can easily be computed;

- *merging*, during which the integer hulls of the parts of the partition are merged by means of the convex hull algorithm.

The efficiency of this algorithm depends mainly on the shape of the input while the size of the input has little impact. Comparative experimentation shows this new algorithm can deal with inputs of very large volumes that algorithms depending on enumeration, such as those of `Normaliz` can not process. Figure 1 illustrates the use of the `IntegerHull` command of the `PolyhedralSets` library.

### 3 Describing $\mathbb{Z}$ -polyhedra

Following [18], we call *integer lattice* of  $\mathbb{Z}^d$  any set of the form

$$\{ \mathbf{Ax} + \mathbf{b} \mid \mathbf{x} \in \mathbb{Z}^d \}$$

where  $A \in \mathbb{Z}^{d \times d}$  is a full-rank matrix and  $\mathbf{b} \in \mathbb{Z}^d$  is a vector; such a set is denoted by  $\mathcal{L}(A, \mathbf{b})$ .

Following [18] again, we call a  *$\mathbb{Z}$ -Polyhedron* the intersection of a polyhedron with an integer lattice. The purpose of this notion is, for us, to support the description of the integer points of a polyhedron  $P \subseteq \mathbb{Q}^n$ , that is, the description of the set  $P \cap \mathbb{Z}^n$ .

To understand why lattices appear naturally when solving for the integer points of a polyhedron, consider a couple of elementary examples. First, consider the problem of solving a Diophantine equation over  $\mathbb{Z}$ , say in 2 variables  $x$  and  $y$ . For instance, consider  $3x - 4y = 7$ ; its solutions, as computed by `MAPLE`, are of the form

$$x = 5 + 4\_Z1, y = 2 + 3\_Z1,$$

the description of which requires the use of the auxiliary variable `_Z1`.

In his Omega test [14, 15] William Pugh extended that idea for solving arbitrary systems of linear equations over  $\mathbb{Z}$ . For instance, for the system

$$\begin{cases} 7x + 12y + 31z = 17 \\ 3x + 5y + 14z = 7 \end{cases}$$

the Omega test produces

$$\begin{cases} z = -t_0 - 1 \\ y = -5t_0 - 3 \\ x = 13t_0 + 12 \end{cases}$$

Of course, the introduction of the parameter  $t_0$  can be avoided by re-writing  $x$  and  $z$  as a function of  $z$ , (simply by using Hermite normal forms) leading to:

$$\begin{cases} x = -1 - 13z \\ y = 2 + 5z \end{cases}$$

Consider now this other polyhedron  $P$  of  $\mathbb{Q}^3$ :

$$\begin{cases} x = 19 \\ y = 25 + (1/2)z \\ z \leq 18 \\ -z \leq 0 \end{cases}$$

Because of the presence of the rational number  $1/2$ , the above input system cannot be considered as a description of the set  $P \cap \mathbb{Z}^3$  and the Omega test produces:

$$\begin{cases} x = 19 \\ y = 25 + t_0 \\ z = 2 t_0 \\ -t_0 \leq 0 \\ t_0 \leq 9 \end{cases}$$

Inspired by the work[18], and the Omega test, we have designed and implemented an algorithm [9, 8] for representing  $\mathbb{Z}$ -polyhedra. In particular, for the above example, we obtain in a MAPLE session, the result shown on Figure 2. On the left-hand side of Figure 2, we retrieve our original polyhedron

$$\left( \begin{array}{l} x = 19 \\ y = 25 + \frac{z}{2} \\ z \leq 18 \\ -z \leq 0 \end{array} \right), \left( \begin{array}{l} x \\ y \\ z \end{array} \right), \left( \begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{array} \right), \left( \begin{array}{l} 0 \\ 0 \\ 0 \end{array} \right)$$

Fig. 2. A  $\mathbb{Z}$ -Polyhedron in PL format.

$P$  and on the right-hand side, we have the lattice  $\mathcal{L}$  of  $\mathbb{Z}^n$  consisting of the points  $(x, y, z)$  where  $z/2$  is integer. The intersection  $P \cap \mathcal{L}$  is exactly  $P \cap \mathbb{Z}^3$ . More generally, encoding the integer points of a polyhedron using the above format, that we call the *PL format*, and thus using lattices, allows us to totally avoid the recourse to auxiliary variables. In addition, it is easy to convert any set of the form  $P \cap \mathbb{Z}^n$  (where  $P \subseteq \mathbb{Q}^n$  is a polyhedron) from PL format, say  $P \cap \mathcal{L}(C, \cdot)$ , to the Omega test format, simply by substitution.

The subpackage `ZPolyhedralSets` of the `PolyhedralSets` library is dedicated to the manipulation of  $\mathbb{Z}$ -Polyhedra. This subpackage offers a number of functionalities, among them:

- `EnumerateIntegerPoints` for enumerating the points of a  $\mathbb{Z}$ -Polytope,
- `PlotIntegerPoints3d` for plotting 3D  $\mathbb{Z}$ -Polyhedra,
- `IsContained` to test inclusion between  $\mathbb{Z}$ -Polyhedra.

The core operation is `IntegerPointDecomposition` which, given an input  $\mathbb{Z}$ -Polyhedron  $K$  computes a finite partition of  $K$  into  $\mathbb{Z}$ -Polyhedra  $K_1, \dots, K_e$  with additional properties, see [9, 8]. In particular, none of the  $\mathbb{Z}$ -Polyhedra  $K_1, \dots, K_e$  is empty. Under genericity assumptions, `IntegerPointDecomposition` runs in single exponential time (w.r.t. the number of variables); its worst case complexity is doubly exponential.

We conclude this section with an example of a decomposition computed by `IntegerPointDecomposition`. Since for each of the involved  $\mathbb{Z}$ -Polyhedra, except the last one, the lattice part is simply the entire  $\mathbb{Z}^3$ , we do not print it. For the last  $\mathbb{Z}$ -Polyhedron, we use the Omega test format.

$$\text{For } K : \left\{ \begin{array}{l} 3x_1 - 2x_2 + x_3 \leq 7 \\ -2x_1 + 2x_2 - x_3 \leq 12 \\ -4x_1 + x_2 + 3x_3 \leq 15 \\ -x_2 \leq -25 \end{array} \right. , \text{ with } x_1 > x_2 > x_3, \text{ the output consists of 5 } \mathbb{Z}\text{-polyhedra } K_1, K_2, K_3, K_4, K_5:$$

$$\left\{ \begin{array}{l} 3x_1 - 2x_2 + x_3 \leq 7 \\ -2x_1 + 2x_2 - x_3 \leq 12 \\ -4x_1 + x_2 + 3x_3 \leq 15 \\ 2x_2 - x_3 \leq 48 \\ -5x_2 + 13x_3 \leq 67 \\ -x_2 \leq -25 \\ 2 \leq x_3 \leq 17 \end{array} \right. , \left\{ \begin{array}{l} x_1 = 15 \\ x_2 = 27 \\ x_3 = 16 \end{array} \right. , \left\{ \begin{array}{l} x_1 = 18 \\ x_2 = 33 \\ x_3 = 18 \end{array} \right. , \left\{ \begin{array}{l} x_1 = 14 \\ x_2 = 25 \\ x_3 = 15 \end{array} \right. , \left\{ \begin{array}{l} x_1 = 19 \\ x_2 = 50 + t \\ x_3 = 50 + 2t \\ -25 \leq t \leq -16 \end{array} \right.$$

To use the terminology of William Pugh, the  $\mathbb{Z}$ -polyhedron  $K_1$  corresponds to the dark shadow of the input polyhedron  $K$ , while  $K_2, K_3, K_4, K_5$  correspond to its grey shadow.

#### 4 Dealing with parameters

In practice, polyhedral sets are often *parametric*. Consider for instance the for-loop nest, written in a programming language (say C) of a dense matrix multiplication algorithm. At compile time, the upper bound of the value range of each loop counter is a symbol. To be more precise, the iterations of that for-loop nest are the integer points of a polyhedral set  $P$  given by a system of linear inequalities  $A\vec{x} \leq \vec{b}$  where  $A$  is a matrix with integer coefficients,  $\vec{b}$  is a vector of symbols (actually the parameters of the polyhedral set) and  $\vec{x}$  is the vector of the loop counters. At execution time, different values of  $\vec{b}$  yield different shapes and numbers of vertices for  $P$ . So what can be done at compile time to answer a question like what is the number of memory accesses performed by that for-loop nest?

For non-parametric polyhedral sets, the most studied method for counting the integer points of a polytope is certainly due to Alexander Barvinok in [2]. The Authors of [11] and [21] report on an implementation of Barvinok's algorithm respectively in the software libraries `LattE` and `barvinok`, both developed in C/C++. Moreover, the latter library has an adaptation of Barvinok's algorithm to parametric polyhedral sets.

The `PolyhedralSets` also offers an implementation of Barvinok's algorithm adapted to count the integer points of parametric polyhedral sets. This led us to implement various MAPLE packages which are interesting in their own right.

At the core of Barvinok's algorithm, one finds the computation of the generating function of a polytope. In the parametric case, such a function is a multivariate rational function where some exponents of some monomials depend on the parameters. To manipulate those expressions in a convenient way, we have implemented quasi-polynomials in MAPLE. A *quasi-polynomial* is a polynomial-like object, the coefficients of which are instead periodic functions with integral period.

A second challenge in adapting Barvinok's algorithm from non-parametric to parametric polytopes is due to the complexity of the case discussion. To make that observation clear, let us first recall how one solves a parametric linear system, say by Gaussian elimination: the search for pivots, one after another, dynamically unfolds a *decision tree* where:

- internal nodes are candidate pivots (with a left child for the “non-zero” case and a right child for the “zero” case), and
- leaves are solutions.

Let us now return to the integer point counting of a parametric polytope  $\mathcal{P}(\mathbf{b})$ . One must first determine the vertices of  $\mathcal{P}(\mathbf{b})$ . This leads to a number of parametric problems which can be solved independently, thus leading to a number of decision trees. Once all these decision trees are computed, they must be merged into a single decision tree. Next, the vertex cone of each vertex must be determined. This again creates a number of decision trees, which must be merged into a single decision tree.

At this point, one is essentially ready to apply Barvinok's algorithm, up to the issue solved by the usage of the quasi-polynomials. After doing so, one usually observes a number of cases which are specializations of the same more general case. We are in the process of implementing an algorithm to detect such a pattern and replace those specializations by a single more general case.

```

> relations := [1 ≤ i, j ≤ n, i ≤ m, 3 * i ≤ 5 * j];
   vars := [i, j];
   paras := [m, n];
      relations := [1 ≤ i, j ≤ n, i ≤ m, 3 i ≤ 5 j]
      vars := [i, j]
      paras := [m, n]
=
> test_number_of_points := NumberOfIntegerPoints(relations, vars, paras, false, true);
test_number_of_points := [[ [ [  $\frac{3m}{10} - \frac{3m^2}{10} + Q\left([m, 5, [0, 0, -\frac{2}{5}, -\frac{1}{5}, -\frac{2}{5}]]\right)$ 
+ nm ], [0 ≤ m - 2, 0 ≤ 5n - 7, 0 ≤ -3m + 5n - 1] ], [ {n}, [m - 1 = 0, 0
≤ 5n - 4] ], [ [  $\frac{5n^2}{6} + \frac{n}{2} + Q\left([n, 3, [0, -\frac{1}{3}, -\frac{1}{3}]]\right)$  ], [3m - 5n = 0, 0
≤ 5n - 4] ], [ [  $\frac{5n^2}{6} + \frac{n}{2} + Q\left([n, 3, [0, -\frac{1}{3}, -\frac{1}{3}]]\right)$  ], [0 ≤ 5n - 4, 0 ≤ 3m
- 5n - 1] ] ] ]
=

```

Fig. 3. Using the NumberOfIntegerPoints command

Figure 3 shows the computation of the number of integer points of the parametric polytope given by

$$\begin{cases} 1 & \leq & i \\ i & \leq & m \\ j & \leq & n \\ 3i & \leq & 5j \end{cases} \quad (1)$$

in the coordinates  $(i, j)$  and with  $m, n$  as parameters. The output of the command `NumberOfIntegerPoints` consists of 4 pairs *value-constraints*. For the first, the third and the fourth pairs, the value part uses a quasi-polynomial. For instance, the value part of the first pair is:

$$\frac{3m}{10} - \frac{3m^2}{10} + Q([m, 5, [0, 0, -2/5, -1/5, -2/5]]) + nm,$$

which uses the quasi-polynomial

$$Q([m, 5, [0, 0, -2/5, -1/5, -2/5]]),$$

which must be read as follows:

$$\begin{cases} 0 & \text{if } m \equiv 0 \pmod{5} \\ 0 & \text{if } m \equiv 1 \pmod{5} \\ -2/5 & \text{if } m \equiv 2 \pmod{5} \\ -1/5 & \text{if } m \equiv 3 \pmod{5} \\ -2/5 & \text{if } m \equiv 4 \pmod{5} \end{cases}$$

We observe that the third and fourth pairs [value-constraints] shown on Figure 3 can be replaced by a single pair [value-constraints], namely:

$$\left[ \left\{ \frac{5n^2}{6} + n/2 + Q([n, 3, [0, -1/3, -1/3]]) \right\}, [3m - 5n = 0, 0 \leq 5n - 4] \right].$$

As mentioned above, we are in the process of implementing this type of recombination of cases.

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