

CS 341 – Algorithms

Lecture 5 – Breadth First Search

26 May 2021

Today's Plan

1. Graph Connectivity
2. Breadth First Search
3. BFS Tree and Shortest Path
4. Bipartite Graphs

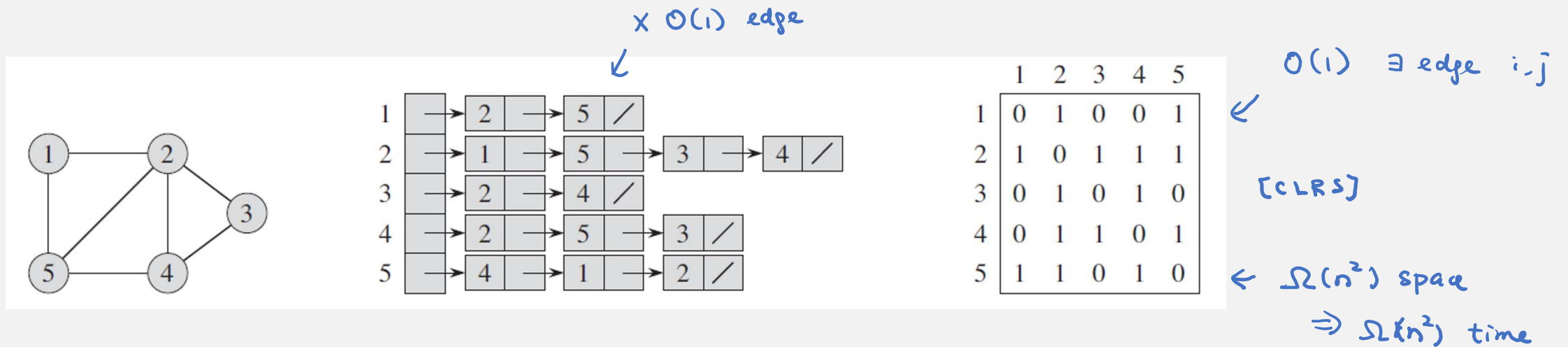
1. First tutorial on Tuesday

Graph Representation

Many problems in computer science can be modeled as graph problems.

There are two standard representations of an undirected graph $G = (V, E)$ with $n = |V|$ and $m = |E|$.

One is the **adjacency matrix**, and the other is the **adjacency list**.



We will mostly use adjacency list, as this allows us to design $O(n + m)$ -time algorithm.

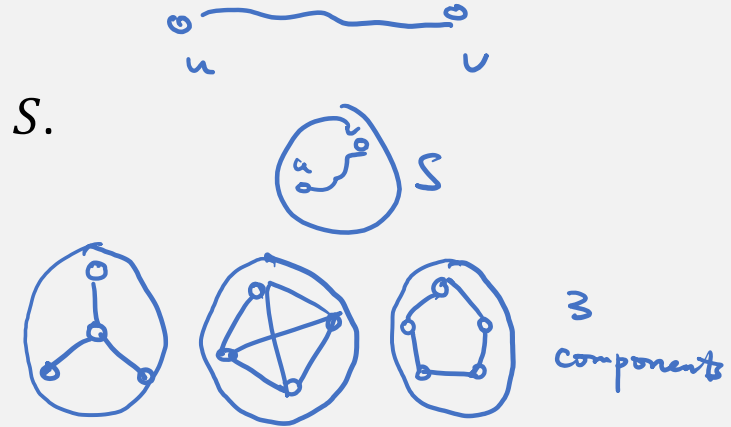
Graph Connectivity

We say two vertices u, v are connected if there is a path from u to v .

A subset of vertices $S \subseteq V$ is connected if u, v are connected for all $u, v \in S$.

A graph is connected if u, v are connected for all $u, v \in V$.

A connected component is a maximally connected subset of vertices.



Some of the most basic algorithmic questions about a graph are:

1. To determine whether a given graph is connected.
2. To find all the connected components of a given graph.
3. To determine whether two vertices u, v are connected.
4. To find a shortest path between two vertices u, v .

Breadth first search (BFS) can be used to answer all these questions in $O(n + m)$ time.

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Breadth First Search

To motivate BFS, imagine that we are searching a person in a social network.

A natural strategy is to ask for friends, then friends of friends, then friends of friends of friends, etc.

Input: $G = (V, E)$, $s \in V$. *source vertex*

Output: all vertices reachable from s .

Initialization: $visited[v] = false$ for all $v \in V$.

queue Q is empty. $enqueue(Q, s)$. $visited[s] = true$.

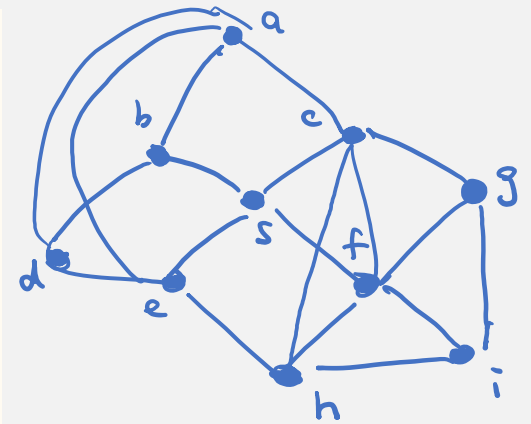
while $Q \neq empty$ do

$u = dequeue(Q)$

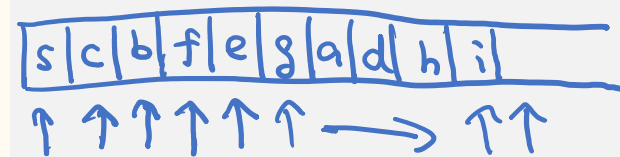
for each neighbor v of u

if $visited[v] = false$

$enqueue(Q, v)$. $visited[v] = true$.



Q



Time Complexity

Each vertex is enqueued at most once.

When we dequeue a vertex u , run for loop for $\deg(u)$ steps

total time complexity : $O(n + \sum_{v \in V} \deg(v)) = O(n + m)$. \square

MATH 239 . handshaking lemma

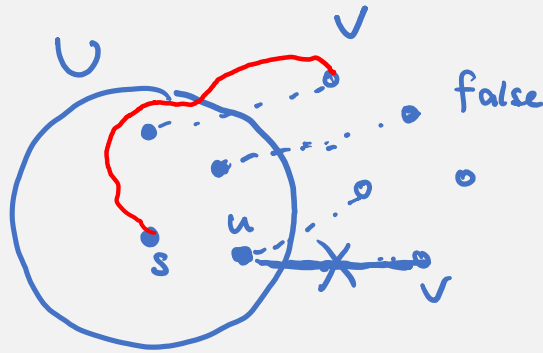
$$\sum_{v \in V} \deg(v) = 2m$$

Correctness

Lemma. There is a path from s to v if and only if $visited[v] = true$ at the end.

\Rightarrow contrapositive: if $visited[v] = false$, then \nexists path from s to v .

consider U set of all vertices that $visited[u] = true \forall u \in U$



Claim: no edges with one endpoint in U and another endpoint in $V \setminus U$.

proof Suppose uv exists.

In the for loop of u ,

we would have marked $visited[v] = true$.
contra. \square

so, for any $v \in V \setminus U$, \nexists a path from s to v
otherwise it would violate the claim. \square

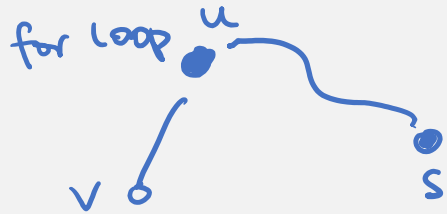
Correctness

Lemma. There is a path from s to v if and only if $visited[v] = true$ at the end.

Proof \Leftarrow if $visited[v] = true$, then there is a path from s to v .

induction: base case: $visited[s] = true$.

induction step: $visited[u] = true$. within a for loop for a vertex u

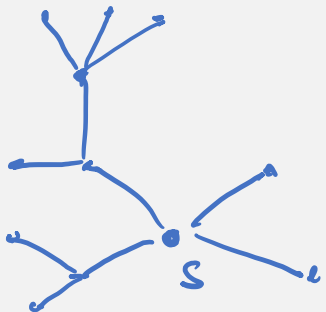


at that time, u was dequeued, was enqueued earlier

$visited[u] = true$

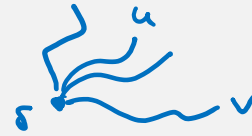
by I.H. $visited[u] = true \Rightarrow \exists$ a path from s to u

$\Rightarrow \exists$ a path from s to v , by extending by the edge uv .



Graph Connectivity

1. To determine whether a given graph is connected.



pick s . run BFS. graph is connected iff $visited[v] = true$ for $v \in V$.
 $O(m+n)$ ✓

2. To find all the connected components of a given graph.

Exercise. add an outer for loop. time complexity $O(n+m)$.

3. To determine whether two vertices u, v are connected.

pick u , run BFS - $visited[v] = true \Leftrightarrow u, v$ connected. ✓

4. To find a shortest path between two vertices u, v . ← next time.

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4. Bipartite Graphs

1. Homework 1 due on Monday
2. Homework 2 to be posted early next week

BFS Tree

How to trace out a path from s to v (if such a path exists)?



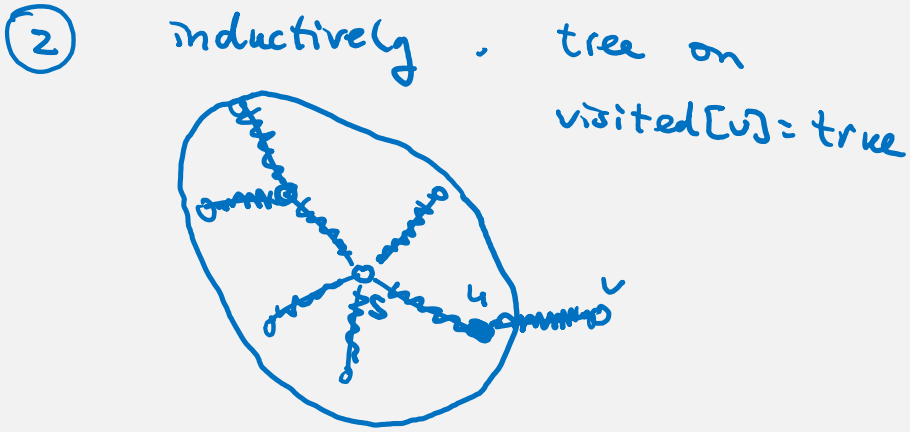
$$\text{parent}[v] = u$$

for loop to trace out the path

BFS tree : all the edges $(v, \text{parent}[v])$

Why the edges $(v, \text{parent}[v])$ form a tree?

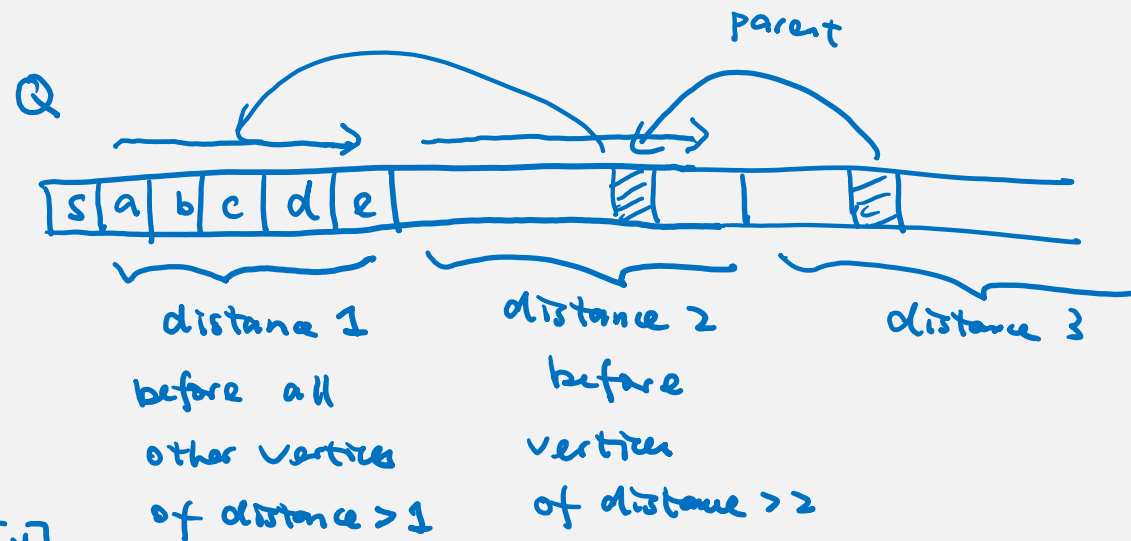
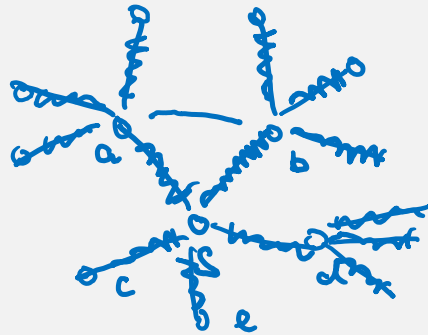
- ① every vertex v has one edge $(v, \text{parent}[v])$
 but not s
 total $n-1$ edges $\begin{matrix} \textcircled{1} \\ + \\ \textcircled{2} \end{matrix} \Rightarrow$ tree (MATH 239)
 no cycles because: $\text{parent}[v]$ is visited earlier than v
-



Shortest Path

Proposition. The path from v to s on a ~~DFS~~^{BFS} tree is a shortest path from v to s .

Induction v is of distance k to s if
the shortest paths from v to s have length k .



invariant: shortest path
distances computed
correctly for $visited[v]$
and keep a shortest
path in the tree so far

□

BFS with Shortest Path Distances

Input: $G = (V, E)$, $s \in V$.

Output: all vertices reachable from s and their shortest path distance from s .

Initialization: $visited[v] = false$ for all $v \in V$.

queue Q is empty. enqueue(Q, s). $visited[s] = true$. distance[s] = 0.

While $Q \neq empty$ do

$u = dequeue(Q)$

for each neighbor v of u

if $visited[v] = false$

enqueue(Q, v). $visited[v] = true$. parent[v] = u. distance[v] = distance[u] + 1.

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4. **Bipartite Graphs**

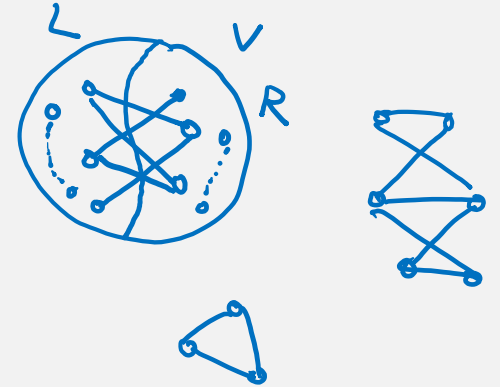
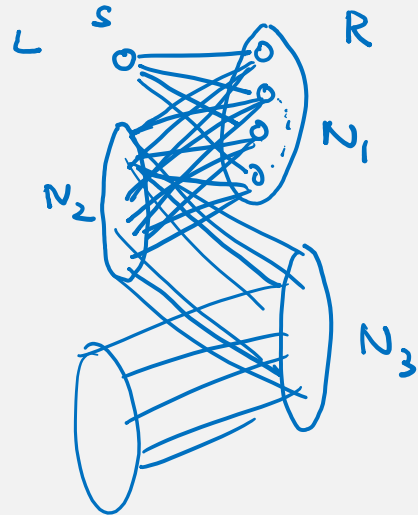
Bipartite Graphs

A graph $G = (V, E)$ is bipartite if there is a bipartition (L, R) of V such that all edges have one endpoint in L and one endpoint in R .

Question: Design an efficient algorithm to check whether a graph is bipartite.

trivial: try all bipartition (L, R) . time: $\Omega(2^n)$

idea :



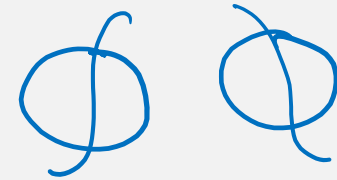
Algorithm

① $L = \{ v \mid \text{dist}(s, v) \text{ even} \}$ $R = \{ v \mid \text{dist}(s, v) \text{ odd} \}$

② If there is an edge with L or an edge within R,
then "Non-bipartite" $\text{side}[v] = L/R$

③ otherwise, output "bipartite".
for each uv

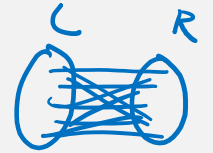
= assume graph is connected
solve components separately



Time complexity: ① BFS $O(n+m)$ ② $O(m+n)$

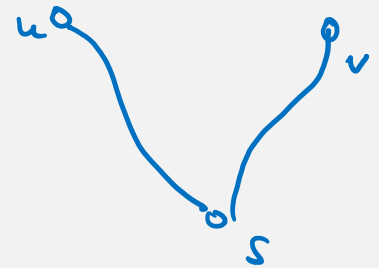
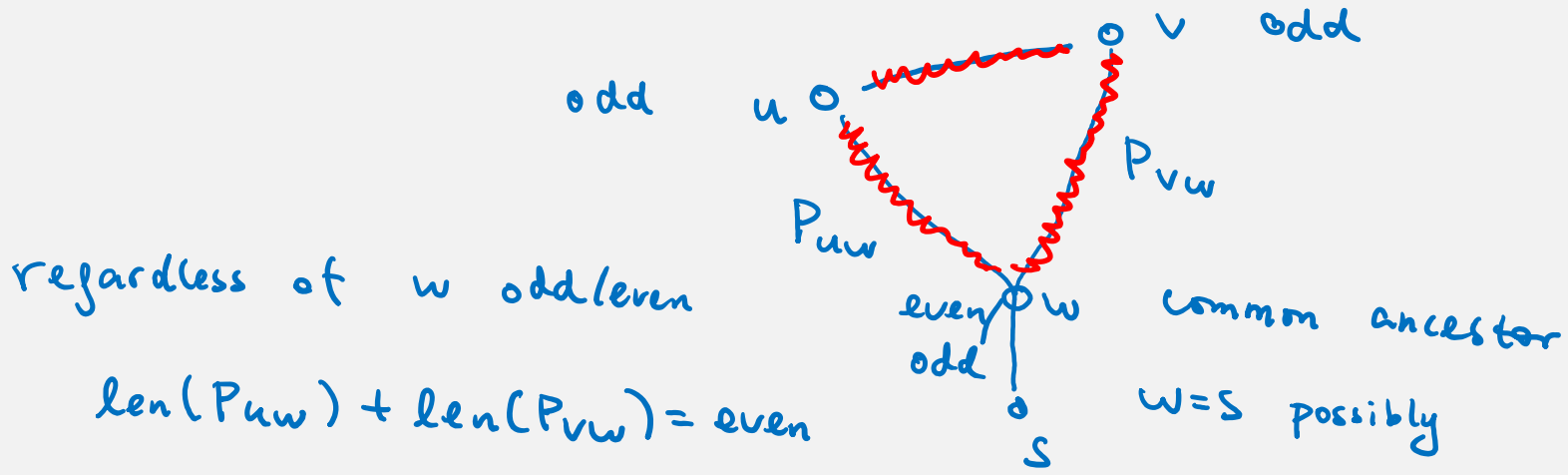
Correctness

① If the algorithm says "bipartite", correct ✓



② If the algorithm says "non-bipartite", correct?

MATH 239: graph bipartite \Leftrightarrow no odd cycles
 graph non-bipartite $\Leftrightarrow \exists$ odd cycle.



odd cycle $P_{uw} \cup P_{vw} \cup \{uv\}$.

non-bipartite $\Rightarrow \exists$ odd cycle. \square

Remarks

1. This provides an algorithmic proof that a graph is bipartite if and only if it has no odd cycles.
2. The BFS algorithm is also a linear time algorithm to find an odd cycle in an undirected graph.

bipartite : no odd cycles

otherwise, \exists an odd cycle.

3. Having an odd cycle is a “short” proof that a graph is non-bipartite.

3-coloring

- ❖ Remember BFS and its main feature is to find shortest paths.