# Multiagent Systems: Intro to Mechanism Design 

CS 486/686: Introduction to Artificial Intelligence

## Introduction

- So far almost everything we have looked at has been in a single-agent setting
- Today - Multiagent Decision Making!
- For participants to act optimally, they must account for how others are going to act
- We want to
- Understand the ways in which agents interact and behave
- Design systems so that agents behave the way we would like them to

Hint for the final exam: MAS is my main research area. I like MAS problems. I even enjoy marking MAS questions. Two of the TAs for this course do MAS research. They also like marking MAS questions. There will be an MAS question on the final exam.

## Mechanism Design

- Game Theory asks
- Given a game, what should rational agents do?
- Mechanism Design asks
- Given rational agents, what sort of games should we design?
- Can we guarantee that agents will reach an outcome with properties we want


## Fundamentals

- Set of possible outcomes: O
- Set of agents: $N,|N|=n$
- Each agent has a type $\theta_{i}$ from $\boldsymbol{\theta}_{\mathbf{i}}$
- The type captures all private information relevant to the agent's decision making
- Utility functions: $u_{i}\left(0, \theta_{i}\right)$
- Social choice function: f: $\boldsymbol{\theta}_{1} \mathrm{X}$...X $\boldsymbol{\theta}_{\mathbf{n}} \rightarrow \mathbf{O}$


## Examples of Social Choice Functions

- Voting
- Choose a candidate from amongst a group
- Public Project
- Decide whether to build a road whose cost must be funded by the agents themselves
- Allocation
- Allocate an item or resource to one agent in the group


## Scenario

- Network routing problem to allocate resources to minimize the total cost of delay over all agents


My unit cost of delay for sending messages from $A$ to $D$ is $\$ 1$

My unit cost of delay
for sending messages between E and D is $\$ 5$

## A Potential Problem

- Agents' types are not public, and agents are acting in their own self-interest


I like the bear the most!


## Mechanism Design Problem

- By having agents interact through an "institution" we might be able to solve this problem
- Mechanism

$$
M=\left(S_{1}, \ldots, S_{n}, g(\cdot)\right)
$$

- $\mathrm{S}_{\mathrm{i}}$ is the strategy space of agent i
$-\mathrm{g}: \mathrm{S}_{1} \times \ldots \times \mathrm{S}_{\mathrm{n}} \rightarrow \mathrm{O}$ is the outcome function


## Implementation

- A mechanism $M=\left(S_{1}, \ldots, S_{n}, g()\right)$ implements social choice function $f(\theta)$ if there is an equilibrium s*
such that

$$
s^{*}=\left(s_{1}^{*}\left(\theta_{1}\right), \ldots, s_{n}^{*}\left(\theta_{n}\right)\right)
$$

for all

$$
\begin{gathered}
g\left(s_{1}^{*}\left(\theta_{1}\right), \ldots, s_{n}^{*}\left(\theta_{n}\right)\right)=f\left(\theta_{1}, \ldots, \theta_{n}\right) \\
\left(\theta_{1}, \ldots, \theta_{n}\right) \in \Theta_{1} \times \Theta_{n}
\end{gathered}
$$

## Direct Mechanisms

- A direct mechanism is a mechanism where

$$
S_{i}=\Theta_{i} \text { for all } i
$$

and

$$
g(\theta)=f(\theta) \text { for all } \theta \in \Theta_{1} \times \Theta_{n}
$$

## Incentive Compatibility

- A direct mechanism is incentive compatible if it has an equilibrium s* where

$$
s_{i}^{*}\left(\theta_{i}\right)=\theta_{i}
$$

for all $\theta_{\mathrm{i}}$ in $\theta_{\mathrm{i}}$ and for all i .

- A direct mechanism is strategy proof if the equilibrium above is a dominant strategy equilibrium


## Revelation Principle

- Theorem: Suppose there exists a mechanism $M$ that implements social choice function $f$ in dominant strategies. Then there is a direct strategy-proof mechanism $\mathrm{M}^{\prime}$ which also implements f .



## Quick Review

- We know
- What a mechanism is
- What it means for a SCF to be (dominant-strategy) implementable
- Revelation Principle
- We do not yet know
- What types of SCF are dominant-strategy implementable


## Gibbard-Satterthwaite Theorem

- Theorem: Assume that
- $O$ is finite and $|O|>2$
- Each $o$ in $O$ can be achieved by $\operatorname{SCF} f$ for some $\theta$
- $\theta$ includes all possible strict orderings over $O$

Then $f$ is implementable in dominant strategies if and only if $f$ is dictatorial.

## Circumventing Gibbard-Satterthwaite

- Use a weaker equilibrium concept
- Design mechanisms where computing manipulations is computationally hard
- Restrict the structure of agents' preferences



## Single-Peaked Preferences

- Median-Voter rule is strategy proof for single-peaked preferences


## Quasilinear Preferences

- Outcome $0=\left(x, t_{1}, \ldots, t_{n}\right)$
- $\quad \mathrm{x}$ is a "project choice"
- $t_{i}$ in $\mathbb{R}$ are transfers ("money")
- Utility functions: $\mathrm{u}_{\mathrm{i}}\left(\mathrm{o}, \theta_{\mathrm{i}}\right)=\mathrm{V}_{\mathrm{i}}\left(\mathrm{x}, \theta_{\mathrm{i}}\right)-\mathrm{t}_{\mathrm{i}}$
- Quasilinear mechanism $\mathrm{M}=\left(\mathrm{S}_{1}, \ldots, \mathrm{~S}_{\mathrm{n}}, \mathrm{g}()\right)$ where
- $g()=\left(x(), t_{1}, \ldots, t_{n}\right)$


## Groves Mechanisms

- Choice rule

$$
x^{*}(\theta)=\arg \max _{x} \sum_{i} v_{i}\left(x, \theta_{i}\right)
$$

- Transfer rules

$$
t_{i}(\theta)=h_{i}\left(\theta_{-i}\right)-\sum_{j \neq i} v_{j}\left(x^{*}(\theta), \theta_{j}\right)
$$

## Groves Mechanisms

- Theorem: Groves mechanisms are strategy-proof and efficient.
- Theorem: Groves mechanisms are unique (up to $h_{i}\left(\theta_{-i}\right)$ )


## Vickrey-Clarke-Groves Mechanism

- Outcome

$$
x^{*}=\arg \max _{x} \sum_{i} v_{i}\left(x, \theta_{i}\right)
$$

- Transfers

$$
t_{i}(\theta)=\sum_{j \neq i} v_{j}\left(x^{-i}, \theta_{j}\right)-\sum_{j \neq i} v_{j}\left(x^{*}(\theta), \theta_{j}\right)
$$

- VCG is an example of a Groves mechanism
- Efficient and strategy-proof
- Agents' equilibrium utility is their marginal contribution to the welfare of the system


## Example: Allocation Problem

- Social choice function
- Maximize social welfare (i.e. give item to agent who values it the most)
- Utility functions: $u_{i}=v_{i}(0)-t_{i}$
- Mechanism (Vickrey Auction)
- $\mathrm{S}_{\mathrm{i}}$ : a bid of any non-negative number
- Outcome function g:
- Give item to agent who submits highest bid
- Highest bidder pays amount of second highest bid, all else pay nothing


## Vickrey Auction



## Another Application: Sponsored Search

| Slot 1 |
| :--- |
| Slot 2 |
| Slot 3 |
| Slot 4 |
| Slot 5 |

## Ranking

## - Rank-by-relevance

- Assign slots of order of (quality score)*(bid)

| Bidder | Bid | Quality <br> Score |
| :--- | :--- | :--- |
| $A$ | 1.50 | 0.5 |
| $B$ | 1.00 | 0.9 |
| $C$ | 0.75 | 1.5 |$\quad$| Ranking |
| :--- |
| $C(1.25)$ |
| $B(0.9)$ |
| $A(0.75)$ |

## Pricing

- An advertiser only pays when its ad is clicked on
- How much does it pay?
- The lowest price it could have bid and still been in the same position


## Example

| Bidder | Bid | Quality <br> Score |
| :--- | :--- | :--- |
| $A$ | 1.50 | 0.5 |
| $B$ | 1.00 | 0.9 |
| C | 0.75 | 1.5 |$\quad$| Ranking |
| :--- | :--- |
| $\mathrm{C}(1.25)$ |
| $\mathrm{B}(0.9)$ |
| $A(0.75)$ |

C will pay $\mathrm{p}=0.9 / 1.5=0.6$
$B$ will pay $p=0.75 / 0.9=0.83$
How much will A pay?

## Sponsored Search

- How would you design a bidding agent for sponsored search?
- Different from the Vickrey auction
- There is no single best strategy
- It depends on the strategies of others


## Summary

- Definition of a mechanism
- What it means for a mechanism to implement a social choice function
- Revelation Principle
- Gibbard-Satterthwaite Theorem
- Possibility results
- Groves mechanisms

