

Bayes Nets

CS 486/686: Introduction to Artificial Intelligence

Outline

Inference in Bayes Nets

Variable Elimination

Inference in Bayes Nets

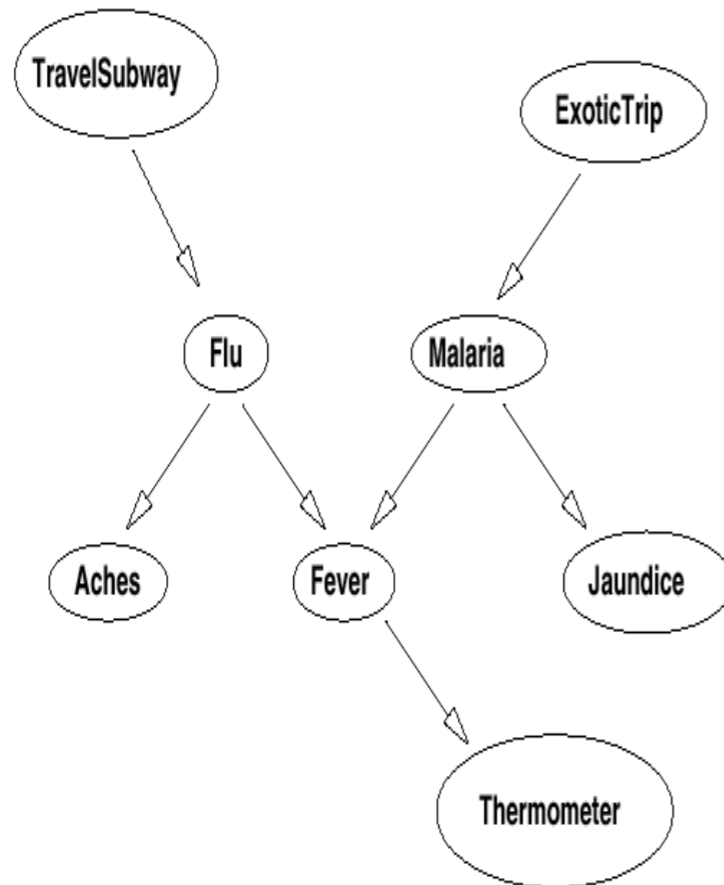
Independence allows us to compute prior and posterior probabilities quite effectively

We will start with a couple simple examples

Networks without loops

A loop is a cycle in the underlying undirected graph

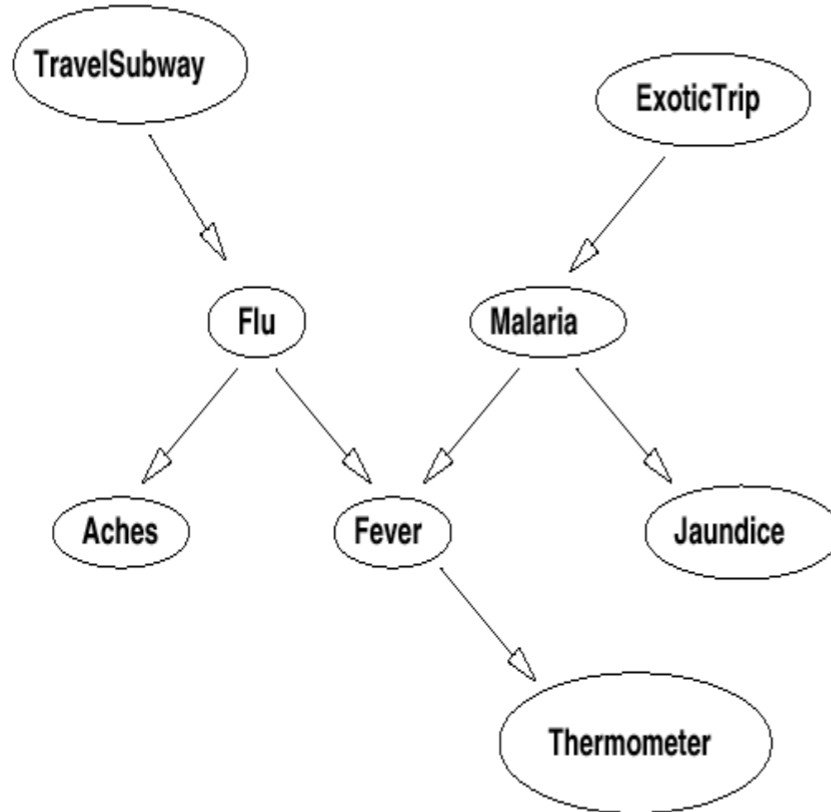
Forward Inference



$P(J)=$

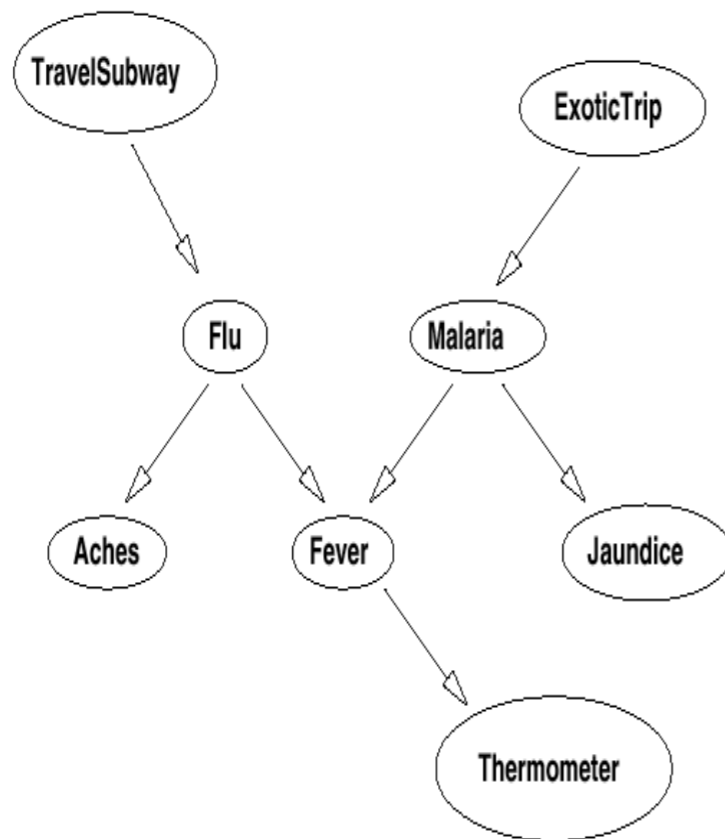
Note: all (final) terms are CPTs in the BN
Note: only ancestors of J considered

Forward Inference with “Upstream Evidence”



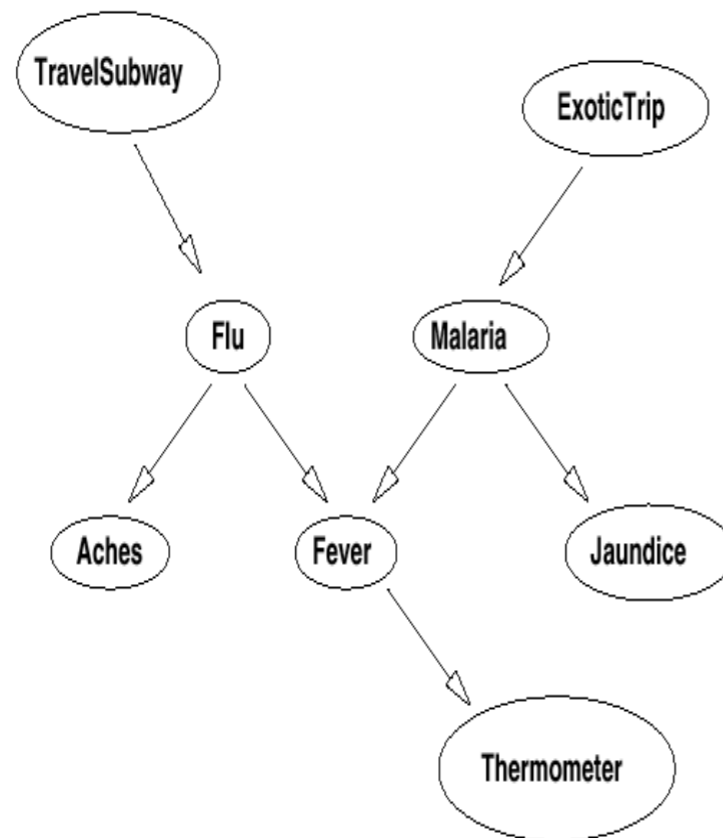
$$P(J|ET) =$$

Forward Inference with Multiple Parents



$P(\text{Fev})=?$

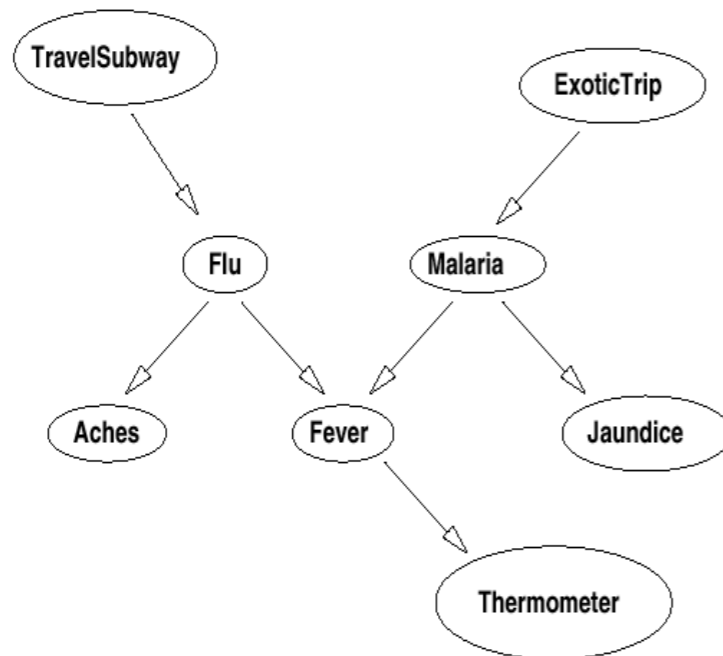
Forward Inference with Evidence



$$P(\text{Fev} | \text{ts}, \sim m) = ?$$

Simple Backward Inference

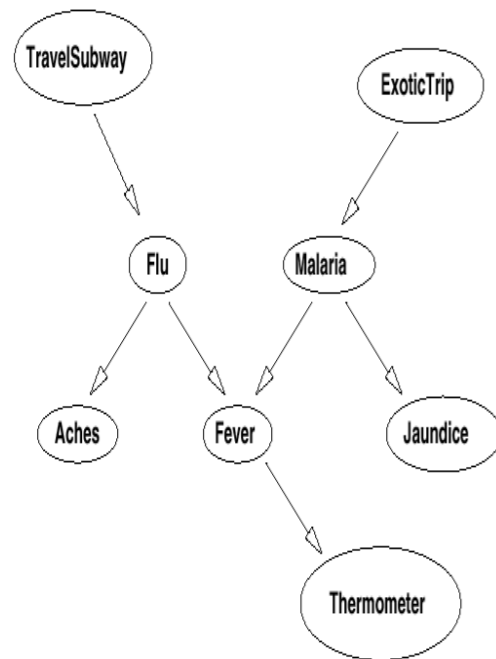
When evidence is downstream of a query variable, must reason “backwards”. This requires Bayes Rule



$$P(ET | j) =$$

Backward Inference

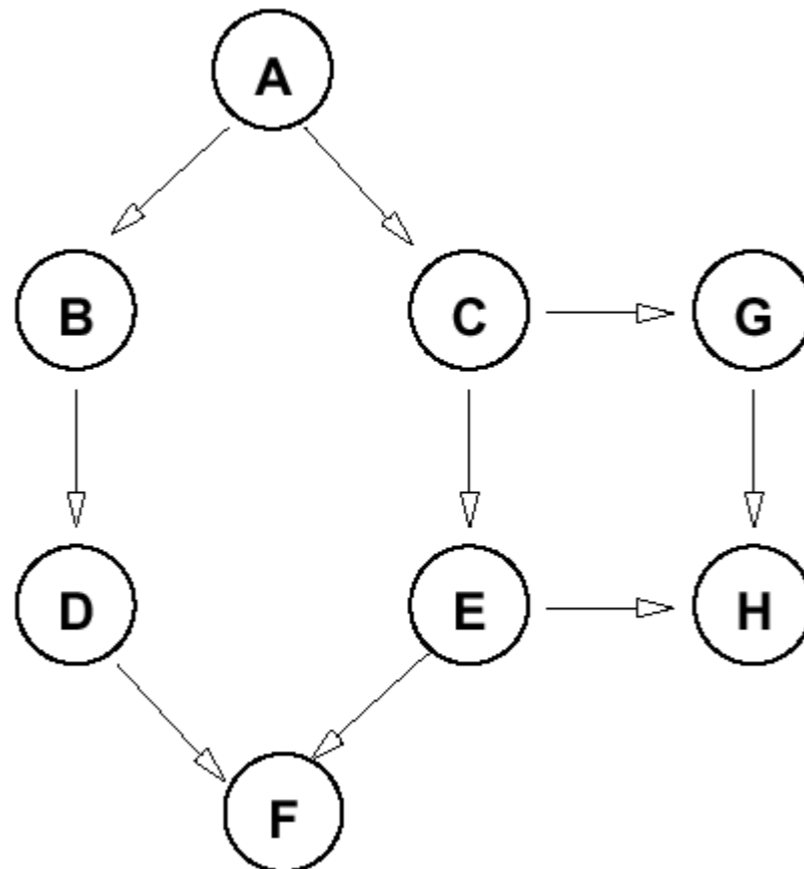
Same idea applies when several pieces of evidence lie “downstream”



$$P(ET | j, fev) = ?$$

Variable Elimination

What about general BN?



$$P(H|A,F)=?$$

Variable Elimination

Simply applies the summing-out rule (marginalization) repeatedly

Exploits independence in network and distributes the sum inward

Basically doing dynamic programming

Factors

- A function $f(X_1, \dots, X_k)$ is called a factor
 - View this as a table of numbers, one for each instantiation of the variables
 - Exponential in k
- Each CPT in a BN is a factor
 - $P(C|A,B)$ is a function of 3 variables, A, B, C
 - Represented as $f(A,B,C)$
- Notation: $f(\mathbf{X}, \mathbf{Y})$ denotes a factor over variables **XUY**
 - **X** and **Y** are sets of variables

Product of Two Factors

- Let $f(\mathbf{X},\mathbf{Y})$ and $g(\mathbf{Y},\mathbf{Z})$ be two factors with variables \mathbf{Y} in common
- The product of f and g , denoted by $h=fg$ is
 - $h(\mathbf{X},\mathbf{Y},\mathbf{Z})=f(\mathbf{X},\mathbf{Y}) \times g(\mathbf{Y},\mathbf{Z})$

f(A,B)		g(B,C)		h(A,B,C)			
ab	0.9	bc	0.7	abc	0.63	ab~c	0.27
a~b	0.1	b~c	0.3	a~bc	0.08	a~b~c	0.02
~ab	0.4	~bc	0.8	~abc	0.28	~ab~c	0.12
~a~b	0.6	~b~c	0.2	~a~bc	0.48	~a~b~c	0.12

Summing a Variable Out of a Factor

- Let $f(X, Y)$ be a factor with variable X and variable set Y
- We sum out variable X from f to produce $h = \sum_x f$ where $h(Y) = \sum_{x \in \text{Dom}(X)} f(x, Y)$

f(A,B)		h(B)	
ab	0.9	b	1.3
a~b	0.1	~b	0.7
~ab	0.4		
~a~b	0.6		

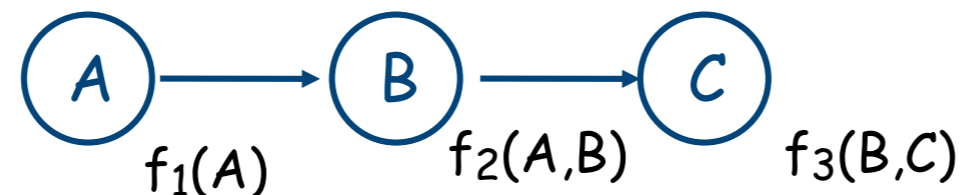
Restricting a Factor

- Let $f(X,Y)$ be a factor with variable X
- We restrict factor f to $X=x$ by setting X to the value x and “deleting”. Define $h=f_{X=x}$ as: $h(Y)=f(x,Y)$

$f(A,B)$		$h(B) = f_{A=a}$	
ab	0.9	b	0.9
a~b	0.1	~b	0.1
~ab	0.4		
~a~b	0.6		

Variable Elimination: No Evidence

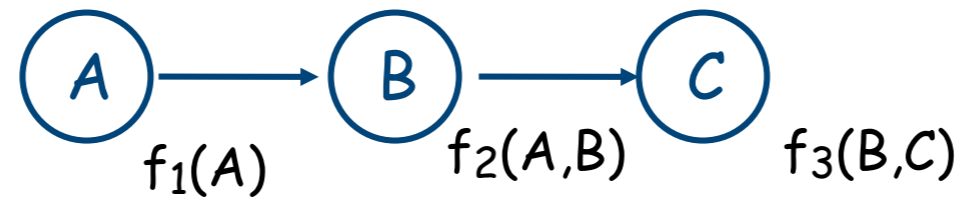
- Computing prior probability of query variable X can be seen as applying these operations on factors



- $$\begin{aligned} P(C) &= \sum_{A,B} P(C|B) P(B|A) P(A) \\ &= \sum_B P(C|B) \sum_A P(B|A) P(A) \\ &= \sum_B f_3(B,C) \sum_A f_2(A,B) f_1(A) \\ &= \sum_B f_3(B,C) f_4(B) \\ &= f_5(C) \end{aligned}$$

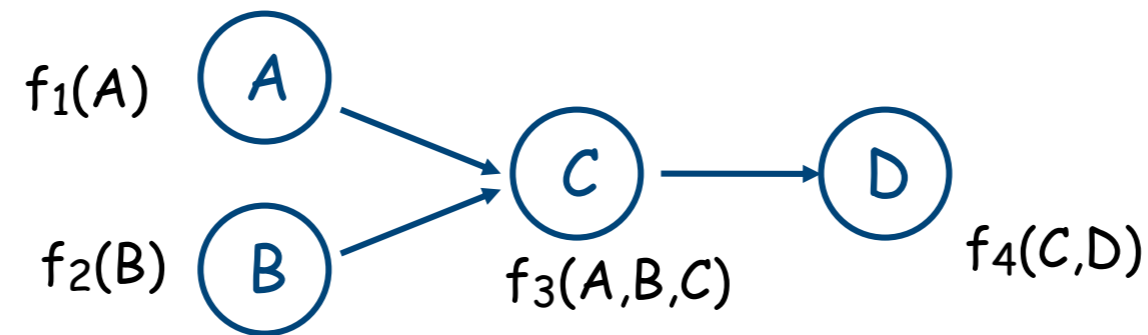
Define new factors: $f_4(B) = \sum_A f_2(A,B) f_1(A)$ and $f_5(C) = \sum_B f_3(B,C)$

Variable Elimination: No Evidence



$f_1(A)$		$f_2(A,B)$		$f_3(B,C)$		$f_4(B)$		$f_5(C)$	
a	0.9	ab	0.9	bc	0.7	b	0.85	c	0.625
$\sim a$	0.1	$a\sim b$	0.1	$b\sim c$	0.3	$\sim b$	0.15	$\sim c$	0.375
		$\sim ab$	0.4	$\sim bc$	0.2				
		$\sim a\sim b$	0.6	$\sim b\sim c$	0.8				

Variable Elimination: No Evidence



$$\begin{aligned} P(D) &= \sum_{A,B,C} P(D|C) P(C|B,A) P(B) P(A) \\ &= \sum_C P(D|C) \sum_B P(B) \sum_A P(C|B,A) P(A) \\ &= \sum_C f_4(C,D) \sum_B f_2(B) \sum_A f_3(A,B,C) f_1(A) \\ &= \sum_C f_4(C,D) \sum_B f_2(B) f_5(B,C) \\ &= \sum_C f_4(C,D) f_6(C) \\ &= f_7(D) \end{aligned}$$

Define new factors: $f_5(B,C)$, $f_6(C)$, $f_7(D)$, in the obvious way

Variable Elimination: One View

- Write out desired computation using chain rule, exploiting independence relations in networks
- Arrange terms in convenient fashion
- Distribute each sum (over each variable) in as far as it will go
- Apply operations “inside out”, repeatedly elimination and creating new factors
 - Note that each step eliminates a variable

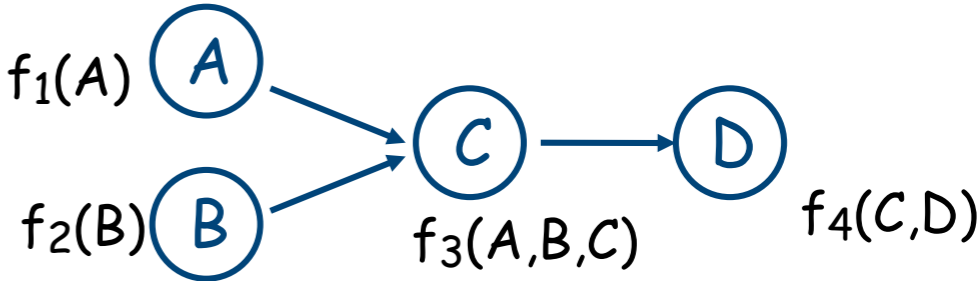
The Algorithm

- Given query variable Q , remaining variables \mathbf{Z} . Let F be the set of factors corresponding to CPTs for $\{Q\} \cup \mathbf{Z}$.

1. Choose an elimination ordering Z_1, \dots, Z_n of variables in \mathbf{Z} .
2. For each Z_j -- in the order given -- eliminate $Z_j \in \mathbf{Z}$ as follows:
 - (a) Compute new factor $g_j = \sum_{Z_j} f_1 \times f_2 \times \dots \times f_k$, where the f_i are the factors in F that include Z_j
 - (b) Remove the factors f_i (that mention Z_j) from F and add new factor g_j to F
3. The remaining factors refer only to the query variable Q . Take their product and normalize to produce $P(Q)$

Example Again

Factors: $f_1(A)$ $f_2(B)$ $f_3(A,B,C)$
 $f_4(C,D)$
Query: $P(D)$?
Elim. Order: A, B, C



Step 1: Add $f_5(B,C) = \sum_A f_3(A,B,C) f_1(A)$

Remove: $f_1(A), f_3(A,B,C)$

Step 2: Add $f_6(C) = \sum_B f_2(B) f_5(B,C)$

Remove: $f_2(B), f_5(B,C)$

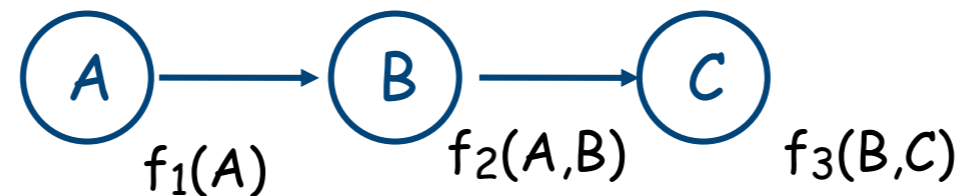
Step 3: Add $f_7(D) = \sum_C f_4(C,D) f_6(C)$

Remove: $f_4(C,D), f_6(C)$

Last factor $f_7(D)$ is (possibly unnormalized) probability $P(D)$

Variable Elimination: Evidence

- Computing posterior of query variable given evidence is similar; suppose we observe $C=c$:



$$\begin{aligned} P(A|c) &= \alpha P(A) P(c|A) \\ &= \alpha P(A) \sum_B P(c|B) P(B|A) \\ &= \alpha f_1(A) \sum_B f_3(B,c) f_2(A,B) \\ &= \alpha f_1(A) \sum_B f_4(B) f_2(A,B) \\ &= \alpha f_1(A) f_5(A) \\ &= \alpha f_6(A) \end{aligned}$$

New factors: $f_4(B) = f_3(B,c)$; $f_5(A) = \sum_B f_2(A,B) f_4(B)$;

$$f_6(A) = f_1(A) f_5(A)$$

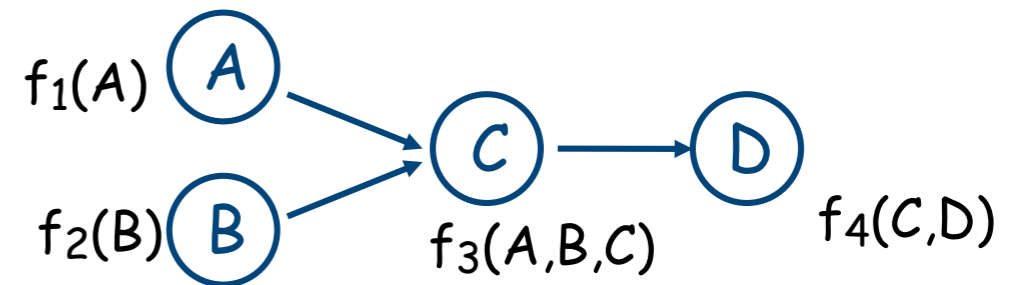
The Algorithm (with Evidence)

- Given query variable Q , evidence variables E (observed to be e), remaining variables Z . Let F be the set of factors corresponding to CPTs for $\{Q\} \cup Z$.

1. Replace each factor $f \in F$ that mentions a variable(s) in E with its restriction $f_{E=e}$ (somewhat abusing notation)
2. Choose an elimination ordering Z_1, \dots, Z_n of variables in Z .
3. Run variable elimination as above.
4. The remaining factors refer only to the query variable Q .
Take their product and normalize to produce $P(Q)$

Example

Factors: $f_1(A)$ $f_2(B)$
 $f_3(A,B,C)$ $f_4(C,D)$
Query: $P(A)?$
Evidence: $D = d$
Elim. Order: C, B



Some Notes on VE

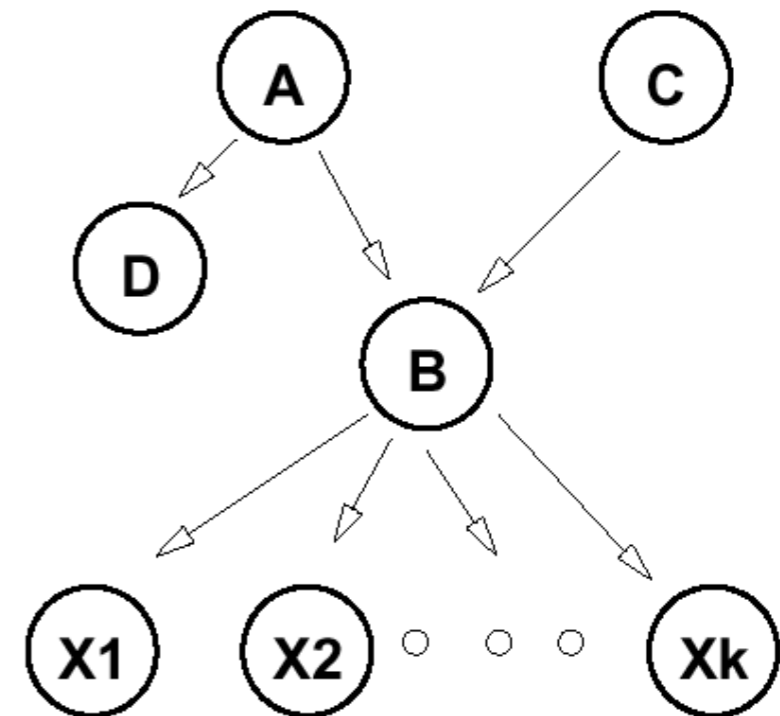
- After each iteration j (elimination of Z_j) factors remaining in set F refer only to variables Z_{j+1}, \dots, Z_n and Q
 - No factor mentions an evidence variable after the initial restriction
- Number of iterations is linear in number of variables

Some Notes on VE

- Complexity is linear in number of variables and exponential in size of the largest factor
 - Recall each factor has exponential size in its number of variables
 - Can't do any better than size of BN (since its original factors are part of the factor set)
 - When we create new factors, we might make a set of variables larger

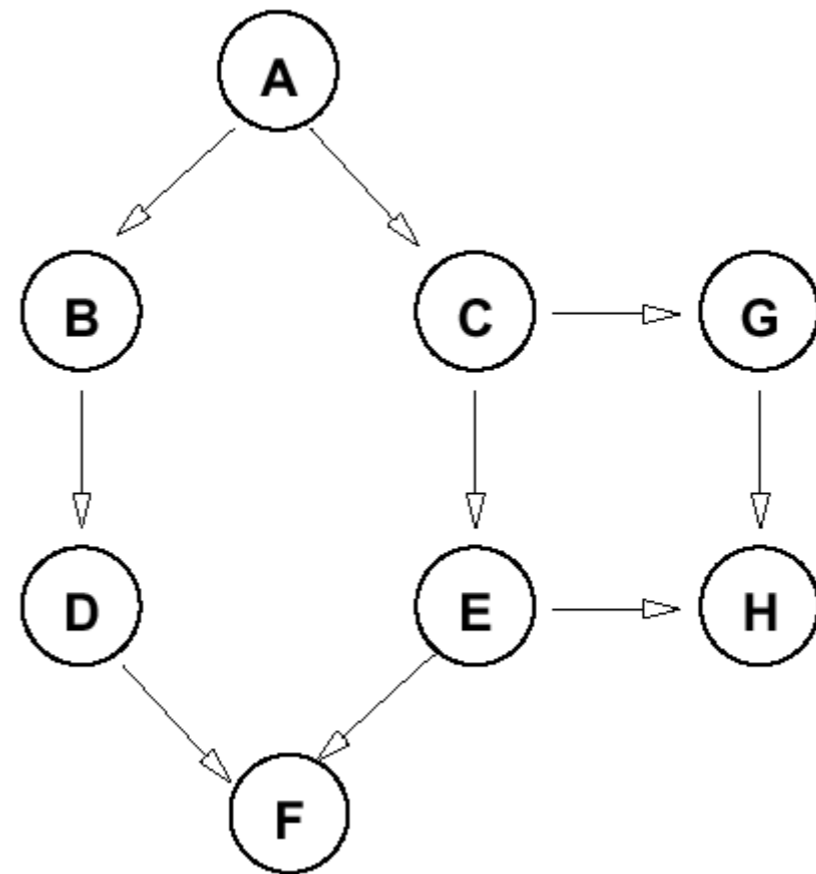
Elimination Ordering: Polytrees

- Inference is linear in size of the network
 - Ordering: eliminate only “singly-connected” nodes
 - Result: no factor ever larger than original CPTs
 - What happens if we eliminate B first?



Effect of Different Orderings

- Suppose query variable is D. Consider different orderings for this network
 - A,F,H,G,B,C,E: Good
 - E,C,A,B,G,H,F: Bad



Relevance

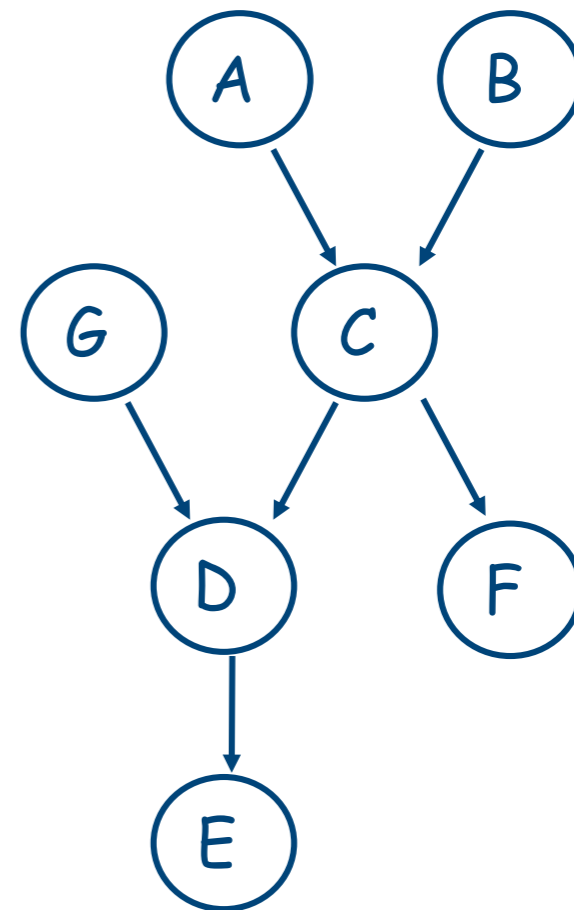
- Certain variables have no impact on the query
 - In ABC network, computing $P(A)$ with no evidence requires elimination of B and C
 - But when you sum out these variables, you compute a trivial factor
 - Eliminating C: $g(C) = \sum_c f(B, C) = \sum_c \Pr(C | B)$.
 - Note that $P(c | b) + P(\sim c | b) = 1$ and $P(c | \sim b) + P(\sim c | \sim b) = 1$

Relevance: A Sound Approximation

- Can restrict our attention to **relevant** variables
- Given query Q , evidence E
 - Q is relevant
 - If any node Z is relevant, its parents are relevant
 - If $E \in E$ is a descendant of a relevant node, then E is relevant

Example

- $P(F)$
- $P(F|E)$
- $P(F|E,C)$



Probabilistic Inference

- Applications of BN in AI are virtually limitless
- Examples
 - mobile robot navigation
 - speech recognition
 - medical diagnosis, patient monitoring
 - fault diagnosis (e.g. car repairs)
 - etc

Where do BNs Come From?

- Handcrafted
 - Interact with a domain expert to
 - Identify dependencies among variables (causal structure)
 - Quantify local distributions (CPTs)
- Empirical data, human expertise often used as a guide

Where do BNs Come From?

- Recent emphasis on learning BN from data
 - Input: a set of cases (instantiations of variables)
 - Output: network reflecting empirical distribution
 - Issues: identifying causal structure, missing data, discovery of hidden (unobserved) variables, incorporating prior knowledge (bias) about structure