Uncertainty

CS 486/686: Introduction to Artificial Intelligence Fall 2013

Introduction

- Logical agents make epistemological commitments that propositions are true, false, or unknown
 - Once an agent has enough facts it can derive plans that are guaranteed to work

Introduction

• But

 Agents rarely have access to the full truth about their environment

Introduction

- The logical approach breaks down when dealing with uncertainty
- Example: Diagnosis
 - ∀ p Symptom(p, Toothache)⇒Disease(p,Cavity)
 - → p Symptom(p, Toothache) ⇒ Disease(p,Cavity)∨
 Disease(p,HitInTheJaw) ∨ Disease(p,GumDisease)∨
 - ∀ p Disease(p, Cavity)⇒Symptom(p,Toothache)

First Order Logic Fails Because

- We are lazy
 - Too much work to write down all antecedents and consequences
- Theoretical ignorance
 - Sometimes there is no complete theory
- Practical ignorance
 - Even if we knew all the rules, we might be uncertain about a particular instance (not enough information yet)

Probability to the Rescue

- Allows us to deal with uncertainty that comes from laziness or ignorance
- Clear semantics
- Provides principled answers for
 - combining evidence, predictive and diagnostic reasoning, incorporation of new evidence
- Can be learned from data

Discrete Random Variables

- Random variable A describes an outcome that can not be determined in advance (ie. roll of a dice)
- Discrete random variable: possible values come from a countable domain (sample space)
 - If X is the outcome of a dice throw then $X \in \{1, 2, 3, 4, 5, 6\}$
- **Boolean random variable:** A∈{True, False}
 - A=The Canadian PM in 2040 will be male
 - A=You have Ebola
 - A=You wake up tomorrow with a headache

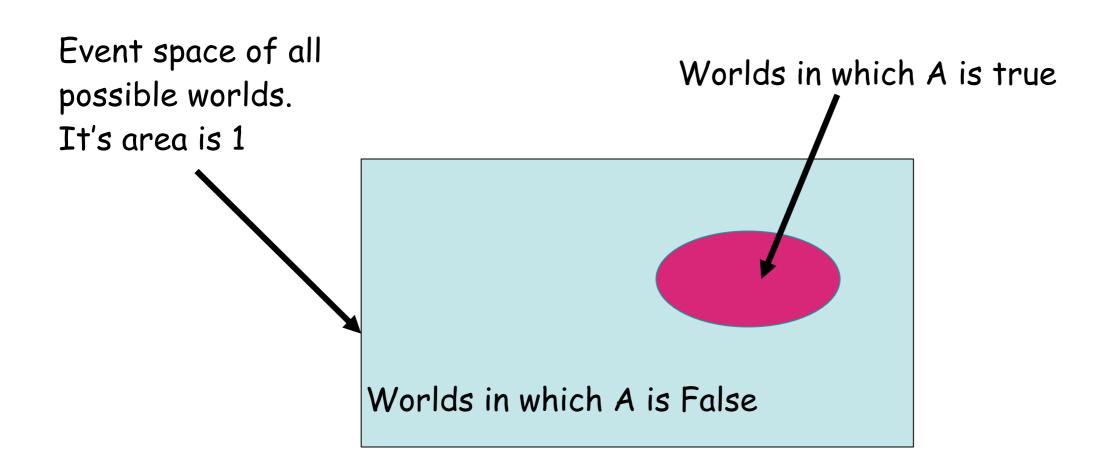


- An event is a complete specification of the state of the world in which an agent is uncertain
 - Subset of the sample space
- Example
 - (Cavity=True) \lapha(Toothache=True)
 - Dice=2
- Events must be
 - Mutually exclusive
 - Exhaustive

Probabilities

- We let P(A) denote the "degree of belief" we have that statement A is true
 - "The fraction of possible worlds in which A is true"
- Note: P(A) DOES NOT correspond to a degree of truth

Visualizing A



P(A) = Area of oval

Axioms of Probability

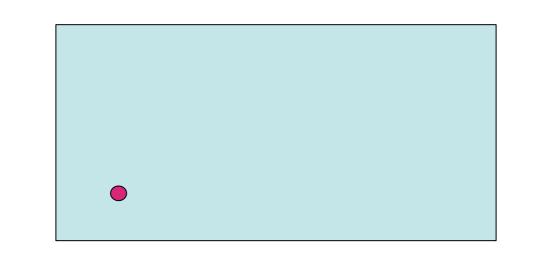
- 0≤P(A)≤1
- P(True)=1
- P(False)=0
- $P(A \lor B) = P(A) + P(B) P(A \land B)$

 These axioms limit the class of functions that can be considered as probability functions

Interpreting the Axioms

- 0≤P(A)≤1
- P(True)=1
- P(False)=0
- $P(A \lor B) = P(A) + P(B) P(A \land B)$

The area of A can't be smaller than 0



A zero area would mean no world could ever have A as true

Interpreting the Axioms

- 0≤P(A)≤1
- P(True)=1
- P(False)=0
- P(A∨B)=P(A)+P(B)-P(A∧B)

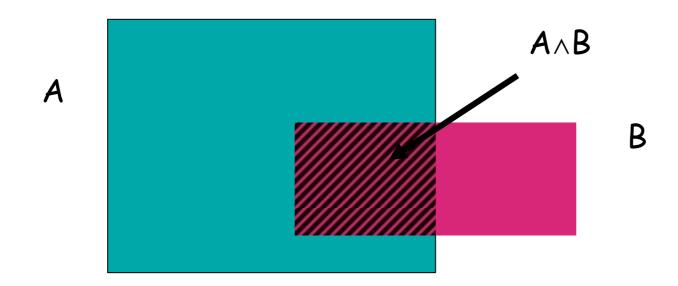
The area of A can't be larger than 1



An area of 1 would mean no world could ever have A as false

Interpreting the Axioms

- 0≤P(A)≤1
- P(True)=1
- P(False)=0
- **P(A**∨B)=**P(A)**+**P(B)**-**P(A**∧B)



Take the Axioms Seriously

- There have been attempts to use different methodologies for uncertainty
 - Fuzzy logic
 - Three-valued logic
 - Dempster-Shafer
 - ...
- But if you follow the axioms of probability then no one can take advantage of you :)

Theorems from the Axioms

Multivalued Random Variables

- Assume domain of A (sample space) is $\{v_1, v_2, \, ..., v_k\}$
- A can take on exactly one value out of this set
 - $P(A=v_i, A=v_j)=0$ if i not equal to j
 - $P(A=v_1 \text{ or } A=v_2 \text{ or } ... \text{ or } A=v_k)=1$

Useful Fact

- Given axioms of probability and P(A=v_i,A=v_j)=0 for i ≠ j, and P(A=v₁ or A=v₂ or ... or A=v_k)=1 then
 - $P(A=v_1 \text{ or } A=v_2 \text{ or } ... \text{ or } A=v_i)=\sum_{j=1}^{i}P(A=v_j)$
 - $\sum_{j=1}^{k} P(A=v_j)=1$

Terminology

Probability Distribution

- A specification of a probability for each event in the sample space
- Assume the world is described by two or more random variables
 - Joint probability distribution
 - Specification of probabilities for all combinations of events

Useful Fact

- Given axioms of probability and P(A=v_i,A=v_j)=0 for i ≠ j, and P(A=v₁ or A=v₂ or ... or A=v_k)=1 then
 - P(B, (A=v₁ or A=v₂ or ... or A=v_i)= $\sum_{j=1}^{i} P(B, A=v_j)$
 - $\sum_{j=1}^{k} P(B, A=v_j) = 1$

Marginalization

Example: Joint Distribution

sunny			~sunny			
	cold	~cold		cold	~cold	
headache	0.108	0.012	headache	0.072	0.008	
~headache	0.016	0.064	~headache	0.144	0.576	

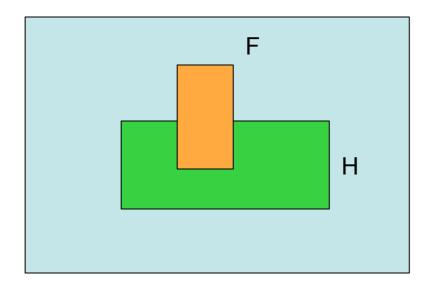
P(headache^sunny^cold)=0.108 P(~headache^sunny^~cold)=0.064

P(headache V sunny) = 0.108 + 0.012 + 0.072 + 0.008 + 0.016 + 0.064 = 0.28

P(headache)=0.108+0.012+0.072+0.008=0.2

marginalization

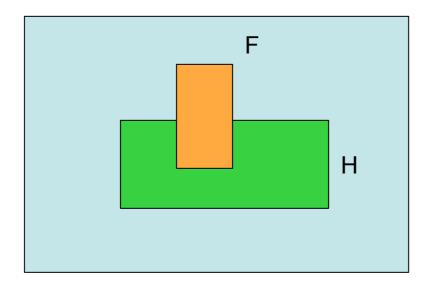
 P(AIB): fraction of worlds in which B is true that also have A true



H="Have headache" F="Have Flu"

P(H)=1/10 P(F)=1/40 P(H|F)=1/2

Headaches are rare and flu is rarer, but if you have the flu that there is a 50-50 chance you will have a headache



H="Have headache" F="Have Flu"

P(H)=1/10 P(F)=1/40 P(H|F)=1/2 P(H|F)= Fraction of flu inflicted worlds in which you have a headache

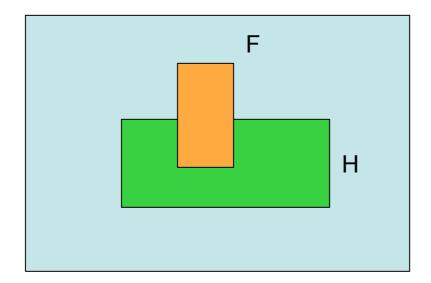
- =(# worlds with flu and headache)/
 (# worlds with flu)
- = (Area of "H and F" region)/ (Area of "F" region)

= P(H ^ F)/ P(F)

Headaches are rare and flu is rarer, but if you have the flu that there is a 50-50 chance you will have a headache

- $P(A|B)=P(A \land B)/P(B)$
- Chain Rule:
 - $P(A \land B) = P(A|B)P(B)$

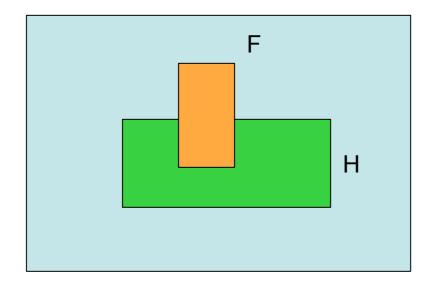
<u>Memorize these!</u>



H="Have headache" F="Have Flu"

P(H)=1/10 P(F)=1/40 P(H|F)=1/2 One day you wake up with a headache. You think "Drat! 50% of flues are associated with headaches so I must have a 50-50 chance of coming down with the flu"

Is your reasoning correct?



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P(F∧H)=

P(F|H)=

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headache	0.108	0.012	headache	0.072	0.008	
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P(headache ^ cold | sunny)= P(headache ^ cold ^ sunny)/P(sunny)

= 0.108/(0.108+0.012+0.016+0.064)

= 0. 54

P(headache ^ cold | ~sunny)= P(headache ^ cold ^ ~sunny)/P(~sunny)

= 0.072/(0.072+0.008+0.144+0.576)

= 0.09

Bayes Rule

- Note:
 - $P(A|B)P(B)=P(A \land B)=P(B \land A)=P(B|A)P(A)$

- Bayes Rule:
 - P(B|A)=[P(A|B)P(B)]/P(A)

<u>Memorize this!</u>

General Forms of Bayes Rule

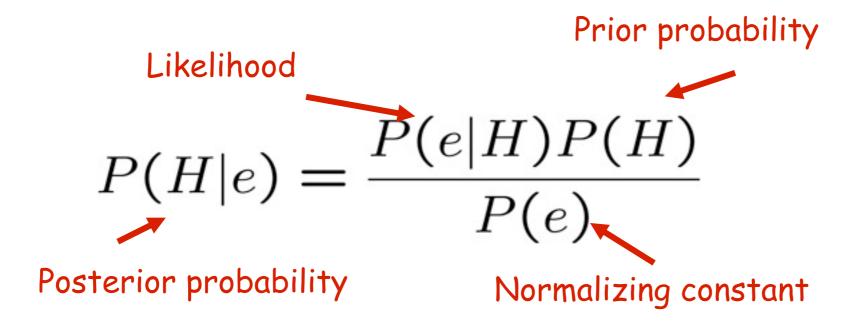
$$P(A|B) = \frac{P(B|A)P(A)}{P(B|A)P(A) + P(B|\neg A)P(\neg A)}$$

$$P(A|B \wedge X) = \frac{P(B|A \wedge X)P(A \wedge X)}{P(B \wedge X)}$$

$$P(A = v_i|B) = \frac{P(B|A = v_i)P(A = v_i)}{\sum_{k=1}^{n} P(B|A = v_k)P(A = v_k)}$$

Using Bayes Rule for Inference

- Often we want to form a hypothesis about the world based on what we have observed
- Bayes rule is vitally important when viewed in terms of stating the belief given to hypothesis **H**, given evidence **e**



Example

- A doctor knows that H1N1 causes a fever 95% of the time. She knows that if a person is selected at random from the population, they have a 10⁻⁷ chance of having H1N1. 1 in 100 people suffer from a fever.
- You go to the doctor complaining about a fever. What is the probability that H1N1 is the cause of the fever?

Computing Conditional Probabilities

- Often we are interested in the posterior joint distribution of some query variable Y given specific evidence e for evidence variables E
 - Hidden variables: X-Y-E
- If we had the joint prob. distribution then could marginalize
 - $P(Y|E=e)=\alpha\sum_{h}P(Y \land (E=e) \land (H=h))$

Computing Conditional Probabilities

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Problem: Joint distribution is usually too big to handle

Independence

- Two variables A and B are independent if knowledge of A does not change uncertainty of B (and vice versa)
 - P(A|B)=P(A)
 - P(B|A)=P(B)
 - $P(A \land B) = P(A)P(B)$
 - In general: $P(X_1, X_2, ..., X_n) = \prod_i P(X_i)$

- Full independence is often too strong a requirement
- Two variables A and B are conditionally independent given C if
 - P(alb,c)=P(alc) for all a,b,c
 - i.e. knowing the value of B does not change the prediction of A *if the value of C is known*

- Diagnosis problem
 - FI=Flu, Fv=Fever, C=Cough
- Full joint dist. has 2³-1=7 independent entries
- If someone has the flu, we can assume that the probability of a cough does not depend on having a fever (P(C | FI,Fv)=P(C | FI))
- If the same condition holds if the patient does not have the Flu then C and Fv are conditionally independent given FL (P(C I ~FI, Fv)=P(C I ~FI))

• Full distribution can be written as

$$P(C, Fl, FC) = P(C, Fv|Fl)P(Fl)$$

= $P(C|Fl)P(Fv|Fl)P(Fl)$

- We only need 5 numbers!
- Huge savings if there are lots of variables

 Such a probability distribution is sometimes called a Naive Bayes model

 In practice they work well - even when the independence assumption is not true

Summary

- What you should know
 - Basic definitions and axioms
 - Marginalization
 - Conditional Probabilities
 - Chain Rule and Bayes Rule
 - Independence and Conditional Independence