|    | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|----|---------------------|--------------|-------------|------------|--------------------------|
| 00 |                     | 000000       | 000         |            |                          |
|    |                     | 0000000000   | 0000000     |            |                          |
| 00 | 00                  |              |             |            |                          |
|    |                     |              |             |            |                          |

# Negociating with bounded rational agents in environments with incomplete information using an automated agent

Raz Lin, Sarit Kraus, Jonathan Wilkenfeld, James Barry

Stéphane Bonardi

November 2008

イロト イポト イヨト イヨト 一日

Stéphane Bonardi

| Introduction               | Problem description | Agent Design          | Experiments    | Conclusion | Discussion & Future work |
|----------------------------|---------------------|-----------------------|----------------|------------|--------------------------|
| • <b>0</b><br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>00000000000 | 000<br>0000000 |            |                          |
| Example                    |                     |                       |                |            |                          |
|                            |                     |                       |                |            |                          |

© 2002 Stu All Rights Reserved www.stus.com



Bob said, "Let's negotiate." I said, "Over my dead body."

Stéphane Bonardi

Negociating with bounded rational agents in environments with incomplete information using an automated agent

Stu's Views

| Introduction | Problem description | Agent Design          | Experiments    | Conclusion | Discussion & Future work |
|--------------|---------------------|-----------------------|----------------|------------|--------------------------|
|              | 0<br>0<br>00<br>0   | 000000<br>00000000000 | 000<br>0000000 |            |                          |
| Example      |                     |                       |                |            |                          |

- 2 agents: Alice and Bob
- 2 activities: Basketball game (B) and Movie (M)
- 2 days: Friday (F) and Saturday (S)
- Preferences:



ヘロア 人間 アメヨア 人間 アー

æ

#### Stéphane Bonardi

| Introduction  | Problem description | Agent Design          | Experiments    | Conclusion | Discussion & Future work |
|---------------|---------------------|-----------------------|----------------|------------|--------------------------|
| 00<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>00000000000 | 000<br>0000000 |            |                          |
| Outline       |                     |                       |                |            |                          |
|               |                     |                       |                |            |                          |



- 2 Agent Design
- 3 Experiments
- 4 Conclusion
- 5 Discussion & Future work

◆□ > ◆□ > ◆臣 > ◆臣 > 善臣 - のへで

Stéphane Bonardi

| Introduction       | Problem description | Agent Design          | Experiments    | Conclusion | Discussion & Future work |
|--------------------|---------------------|-----------------------|----------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>00000000000 | 000<br>0000000 |            |                          |
| Definition         |                     |                       |                |            |                          |
|                    |                     |                       |                |            |                          |



Type of negotiation:

- Finite horizon: finite history
- Bilateral: 2 agents involved
- Incomplete information: uncertainty regarding the preferences of the opponent

- Multi-issue
- Time constraint

Stéphane Bonardi

| Introduction       | Problem description | Agent Design          | Experiments    | Conclusion | Discussion & Future work |
|--------------------|---------------------|-----------------------|----------------|------------|--------------------------|
| 00<br>0<br>0●<br>0 | 0<br>0<br>00<br>0   | 000000<br>00000000000 | 000<br>0000000 |            |                          |
| Definition         |                     |                       |                |            |                          |

# Introduction

## Bounded rational agent (Herbert Simon 1957)

The agents behave in a manner that is **nearly** optimal with respect to its goals as its resources will allow.

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

They gain or lose utility over time

Stéphane Bonardi

| Introduction       | Problem description | Agent Design          | Experiments    | Conclusion | Discussion & Future work |
|--------------------|---------------------|-----------------------|----------------|------------|--------------------------|
| 00<br>0<br>00<br>• | 0<br>0<br>00<br>0   | 000000<br>00000000000 | 000<br>0000000 |            |                          |
| Goals & Means      |                     |                       |                |            |                          |
|                    |                     |                       |                |            |                          |



- Create an automated agent for negotiation
- Goals:
  - Train people
  - Assist in e-commerce
  - Modelling negotiation process
  - ....
- Means:
  - Learning mechanism: Bayesian learning algorithm
  - Decision making mechanism: bounded rationality assumption

#### Stéphane Bonardi

# Outline

## 1 Problem description

- Notations
- Example
- Agreements & Actions
- Assumptions

## 2 Agent Design



- 4 Conclusion
- 5 Discussion & Future work

<ロト <回ト < 注ト < 注ト = 注

|                    | Problem description | Agent Design          | Experiments    | Conclusion | Discussion & Future work |
|--------------------|---------------------|-----------------------|----------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | •<br>0<br>00<br>0   | 000000<br>00000000000 | 000<br>0000000 |            |                          |
| Notations          |                     |                       |                |            |                          |

Notations:

- I set of issues
- $\forall i \in I$   $O_i$  set of values
- *O* finite set of values  $(O_1 \times ... \times O_{|I|})$
- $\overrightarrow{o} \in O$  an offer
- $Time = \{0, ..., dl\}$  set of time period
- Time costs which influence utility as time passes

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

Stéphane Bonardi

|                    | Problem description | Agent Design          | Experiments     | Conclusion | Discussion & Future work |
|--------------------|---------------------|-----------------------|-----------------|------------|--------------------------|
| 00<br>0<br>00<br>0 |                     | 000000<br>00000000000 | 000<br>00000000 |            |                          |
| Example            |                     |                       |                 |            |                          |

- 2 agents: Alice and Bob
- Question: "What to do over the weekend ?"
- **2** issues: Activity and Night:  $I = \{A, N\}$
- *O<sub>Activity</sub>* = {Movie (M), Basketball game (B)}
- $O_{Night} = \{ Friday (F), Saturday (S) \}$
- Offers:

$$\overrightarrow{o_1} = \{M, S\}$$
$$\overrightarrow{o_2} = \{M, F\}$$
$$\overrightarrow{o_2} = \{B, S\}$$
$$\overrightarrow{o_4} = \{B, F\}$$

Stéphane Bonardi

Negociating with bounded rational agents in environments with incomplete information using an automated agent

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

|                | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|----------------|---------------------|--------------|-------------|------------|--------------------------|
| 00             |                     | 000000       | 000         |            |                          |
|                | 0<br>0              |              |             |            |                          |
| Agreements & A | ctions              |              |             |            |                          |

## Types of agreement

- Partial: agreement over a subset of issues
- Full: agreement over the set of issues

## Types of action

- Accept: end of the negotiation
- Reject
- Opt out: end of the negotiation

Stéphane Bonardi

Negociating with bounded rational agents in environments with incomplete information using an automated agent

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

|                      | Problem description | Agent Design          | Experiments    | Conclusion | Discussion & Future work |  |  |
|----------------------|---------------------|-----------------------|----------------|------------|--------------------------|--|--|
| 00<br>0<br>00<br>0   |                     | 000000<br>00000000000 | 000<br>0000000 |            |                          |  |  |
| Agreements & Actions |                     |                       |                |            |                          |  |  |
|                      |                     |                       |                |            |                          |  |  |

A default value is assigned to each attribute

## 3 possible ends for a negotiation

- Full agreement
- 2 One of the agent opt out (OPT is the corresponding outcome)

- 3 The deadline *dl* is reached
  - Partial agreement (subset of the issues)
  - No agreement: status quo (outcome SQ)

Stéphane Bonardi

|                    | Problem description | Agent Design          | Experiments    | Conclusion | Discussion & Future work |
|--------------------|---------------------|-----------------------|----------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>00000000000 | 000<br>0000000 |            |                          |
| Assumptions        |                     |                       |                |            |                          |

| Utility                |  |
|------------------------|--|
| $\forall I \in Types,$ | $u_l: O \bigcup \{SQ\} \bigcup \{OPT\} \longmapsto \mathfrak{R}$ |

## **Reservation price**

Minimum value  $r_l$  of the utility of an offer under which an agent of type l is unwilling to accept the offer

- Assumptions:
  - The agent knows the finite set of types:  $Types = \{1, ..., k\}$
  - The agent doesn't know the exact utility of the opponent
  - The agent has a probabilistic belief of the opponent's type

・ロト ・ 日 ・ ・ ヨ ・ ・ ヨ ・ ・

3

Stéphane Bonardi

# Outline

## 1 Problem description

- 2 Agent Design
  - Learning mechanism
    - Bayes formula
    - Luce numbers
    - Example
  - Decision mechanism
    - Generating offers
    - Example
    - Accepting/Rejecting offers
    - Example



4 Conclusion



<ロト <回ト < 注ト < 注ト = 注

| Introduction | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|--------------|---------------------|--------------|-------------|------------|--------------------------|
| 00           |                     | 000000       | 000         |            |                          |
|              |                     | 0000000000   | 0000000     |            |                          |
| 00           | 00                  |              |             |            |                          |
|              |                     |              |             |            |                          |



## 2 mechanisms:

- Learning mechanism
- 2 Decision making mechanism

Stéphane Bonardi

Negociating with bounded rational agents in environments with incomplete information using an automated agent

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

|    | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|----|---------------------|--------------|-------------|------------|--------------------------|
| 00 |                     | 000000       | 000         |            |                          |
|    |                     | 0000000000   | 0000000     |            |                          |
| 00 | 00                  |              |             |            |                          |
|    |                     |              |             |            |                          |

Stu's Views © 2002 Stu All Rights Reserved www.stus.com



・ロット語 ・ キョ・ キョ・ ヨー ろくの



#### Stéphane Bonardi

|    | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|----|---------------------|--------------|-------------|------------|--------------------------|
| 00 |                     | 000000       | 000         |            |                          |
|    |                     | 0000000000   | 0000000     |            |                          |
| 00 | 00                  |              |             |            |                          |
|    |                     |              |             |            |                          |

Stu's Views © 2002 Stu All Rights Reserved www.stus.com

Attorneys rarely survive in the wild



"But I came here to negotiate."

#### Stéphane Bonardi

| Introduction<br>00<br>00<br>00 | Problem description<br>O<br>O<br>O<br>O | Agent Design | Experiments<br>000<br>000000 | Conclusion | Discussion & Future work |
|--------------------------------|---|--------------|------------------------------|------------|--------------------------|
| Learning mechanism             |   |              |                              |            |                          |

# Bayes formula

# Goal: to allow an agent to update its belief regarding the opponent's type

## **Bayes Formula**

$$P(A|B) = rac{P(B|A)P(A)}{P(B)}$$

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

#### where:

P(A|B) conditional probability of A given B P(A), P(B) prior probability of A and B respectively

#### Stéphane Bonardi

|                    | Problem description | Agent Design                              | Experiments     | Conclusion | Discussion & Future work |
|--------------------|---------------------|---|-----------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>0000000000000000000000000000000 | 000<br>00000000 |            |                          |
|                    |                     |   |                 |            |                          |

# **Bayes** formula

- k different types for the opponent
- $\forall i \in Types$   $P(type_{t=0}^i) = \frac{1}{k}$

Bayes Formula with agents' types

For each period of time:

$$\forall i \in \textit{Types} \quad \forall \overrightarrow{o_t} \in O \quad \textit{P}(\textit{type}^i | \overrightarrow{o_t}) = \frac{\textit{P}(\overrightarrow{o_t} | \textit{type}_t^i)\textit{P}(\textit{type}_t^i)}{\textit{P}(\overrightarrow{o_t})}$$

where:  $P(\overrightarrow{o_t}) = \sum_{i=1}^{i=k} P(\overrightarrow{o_t} | type_t^i) P(type_t^i)$ 

## Problem

How to compute  $P(\overrightarrow{o_t}/type_t^i)$  ?

#### Stéphane Bonardi

| Introduction | Problem description |
|--------------|---------------------|
| 00           |                     |
|              |                     |
| 00           | 00                  |
|              |                     |

| Agent Design | Exp |
|--------------|-----|
| 00000        | 00  |
|              |     |

Conclusio

Discussion & Future work

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

Learning mechanism

## Luce numbers

## Luce numbers

$$\forall o \in O \quad lu(\overrightarrow{o_t}) = \frac{u(\overrightarrow{o_t})}{\sum_{\overrightarrow{x} \in O} u(\overrightarrow{x})}$$

## Theorem

$$\forall \overrightarrow{x}, \overrightarrow{y} \quad u(\overrightarrow{x}) \geq u(\overrightarrow{y}) \Longleftrightarrow lu(\overrightarrow{x}) \geq lu(\overrightarrow{y})$$

## **Estimation** of the acceptance rate of the opponent's offer

Stéphane Bonardi

|    | Problem descripti |
|----|-------------------|
| 00 |                   |
|    |                   |
| 00 | 00                |
|    |                   |

| Agent Design                            |
|---|
| 000000                                  |
| 000000000000000000000000000000000000000 |

xperiments

Conclusior

Discussion & Future work

◆□ > ◆□ > ◆豆 > ◆豆 > ̄豆 − のへで

Learning mechanism

# Believed type

Believed type

For each  $t \in Times$ :

$$BT(t) = arg \max_{i \in Types} P(type^i / \overrightarrow{o_t})$$

Given the fact that:

$$P(\overrightarrow{o_t}/type_t^i) \simeq lu(\overrightarrow{o_t}/type_t^i)$$

Stéphane Bonardi

|                    | Problem description | Agent Design           | Experiments    | Conclusion | Discussion & Future work |
|--------------------|---------------------|------------------------|----------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>000000000000 | 000<br>0000000 |            |                          |
| Learning mechani   | ism                 |                        |                |            |                          |

# Example

2 types for Alice (ie 2 types of utility)

- Type 1 (*t*<sub>1</sub>): *M* ≻ *B*
- Type 2 ( $t_2$ ): (M, F)  $\succ$  (B, F)

• Initially (t=0): 
$$P(t_1) = P(t_2) = \frac{1}{2}$$

Alice's offer (t=1): 
$$\overrightarrow{o_t} = \{B, F\}$$

Table 3

Example: Calculating Alice's believed type

|   |                                       | $\vec{o}_1 = \{M, S\}$ | $\vec{o}_2 = \{M, F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4=\{B,F\}$ |
|---|---------------------------------------|------------------------|------------------------|------------------------|---------------------|
| 1 | $u_a(\vec{o}_i)$ , type <sup>1</sup>  | 10                     | 9                      | 4                      | 6                   |
| 2 | $u_a(\vec{o}_i)$ , type <sup>2</sup>  | 10                     | 7                      | 5                      | 9                   |
| 3 | $lu_a(\vec{o}_i)$ , type <sup>1</sup> | 10/29 = 0.34           | 9/29 = 0.31            | 4/29 = 0.14            | 6/29 = 0.21         |
| 4 | $lu_a(\vec{o}_i)$ , type <sup>2</sup> | 10/31 = 0.32           | 7/31 = 0.23            | 5/31 = 0.16            | 9/31 = 0.29         |
|   |                                       |                        |                        |                        |                     |
|   |                                       |                        |                        |                        | er ker e            |

#### Stéphane Bonardi

|                 | Problem description | Agent Design         | Experiments    | Conclusion | Discussion & Future work |
|-----------------|---------------------|----------------------|----------------|------------|--------------------------|
| 00              | 0                   | 000000<br>0000000000 | 000<br>0000000 |            |                          |
| 00              | 00                  |                      |                |            |                          |
| Learning mechai | nism                |                      |                |            |                          |

#### Table 3 Example: Calculating Alice's believed type

|   |                                       | $\vec{o}_1 = \{M, S\}$ | $\vec{o}_2 = \{M, F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
|---|---------------------------------------|------------------------|------------------------|------------------------|------------------------|
| 1 | $u_a(\vec{o}_i)$ , type <sup>1</sup>  | 10                     | 9                      | 4                      | 6                      |
| 2 | $u_a(\vec{o}_i)$ , type <sup>2</sup>  | 10                     | 7                      | 5                      | 9                      |
| 3 | $lu_a(\vec{o}_i)$ , type <sup>1</sup> | 10/29 = 0.34           | 9/29 = 0.31            | 4/29 = 0.14            | 6/29 = 0.21            |
| 4 | $lu_a(\vec{o}_i)$ , type <sup>2</sup> | 10/31 = 0.32           | 7/31 = 0.23            | 5/31 = 0.16            | 9/31 = 0.29            |
|   |                                       |                        |                        |                        |                        |

$$P(t_1 | \overrightarrow{o_4}) = \frac{lu_a(\overrightarrow{o_4} | t_1) P(t_1)}{P(\overrightarrow{o})} = \frac{0.21 \times 0.5}{0.21 \times 0.5 + 0.29 \times 0.5} = 0.42$$
$$P(t_2 | \overrightarrow{o_4}) = \frac{lu_a(\overrightarrow{o_4} | t_2) P(t_2)}{P(\overrightarrow{o})} = \frac{0.29 \times 0.5}{0.21 \times 0.5 + 0.29 \times 0.5} = 0.58$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ● ●

Stéphane Bonardi

|                    | Problem description | Agent Design                              | Experiments   | Conclusion | Discussion & Future work |
|--------------------|---------------------|---|---------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>0000000000000000000000000000000 | 000<br>000000 |            |                          |

# Decision mechanism

## Used for:

- 1 Accepting/rejecting offers
- 2 Generating offers (only 1 offer for a given period)

## Use of 2 methods:

- Maximin method
- 2 Ranking of offers
- Take into account:
  - Utility function of the agent
  - Believed type of the opponent

#### Stéphane Bonardi

Negociating with bounded rational agents in environments with incomplete information using an automated agent

▲口▶▲圖▶▲≣▶▲≣▶ ■ のQの

|                    | Problem description | Agent Design                                      | Experiments   | Conclusion | Discussion & Future work |
|--------------------|---------------------|---|---------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>0 <b>0</b> 0000000000000000000000000000 | 000<br>000000 |            |                          |
| Decision mechanisn | ı                   |   |               |            |                          |



Stéphane Bonardi

|         | Problem description | Agent Design          | Experiments      | Conclusion | Discussion & Future work |
|---------|---------------------|-----------------------|------------------|------------|--------------------------|
| 00      |                     | 000000<br>00000000000 | 000<br>000000000 |            |                          |
| 00<br>0 | 00<br>0             |                       |                  |            |                          |
|         |                     |                       |                  |            |                          |

# Generating offers

- The generating mechanism is based on:
  - The utility of the offer for the agent
  - The probability the opponent accepts it

## Notion of rank for an offer

$$rank(\overrightarrow{o}) = rac{order(\overrightarrow{o}, O)}{|O|}$$

where order is a ranking of the offer using their normalized utility

We use the Luce number to estimate the probability of an agent accepting the offer

<ロ> (四) (四) (三) (三) (三)

#### Stéphane Bonardi

|    | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|----|---------------------|--------------|-------------|------------|--------------------------|
| 00 |                     | 000000       | 000         |            |                          |
|    |                     | 0000000000   | 0000000     |            |                          |
| 00 | 00                  |              |             |            |                          |
|    |                     |              |             |            |                          |

# Generating offers

Notations

Notations:

- $u_{opp}^{BT(t)}$  utility function corresponding to the believed type of the opponent (noted  $u_{opp}$ )
- rank<sup>BT(t)</sup><sub>opp</sub> rank function corresponding to the believed type of the opponent (noted rank<sub>opp</sub>)
- $lu_{opp}(\overrightarrow{o}|u_{opp}^{BT(t)}) = lu_{opp}(\overrightarrow{o})$  Luce number corresponding to the believed type

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへで

•  $lu_{agent}(\vec{o})$  Luce number corresponding to the agent type

Stéphane Bonardi

| Introduction | Problem description | Agent Design | Experiments | Conclusion | Discussion & Futu |
|--------------|---------------------|--------------|-------------|------------|-------------------|
| 00           |                     | 000000       | 000         |            |                   |
|              |                     | 00000000000  | 0000000     |            |                   |
| 00           | 00                  |              |             |            |                   |
|              |                     |              |             |            |                   |

# Generating offers

Function Qualitative Offer

## Function Qualitative Offer

$$QO(t) = arg \max_{\overrightarrow{o} \in O} min\{lpha, eta\}$$

where:

$$\begin{aligned} \alpha &= \operatorname{rank}(\overrightarrow{o}).\operatorname{lu_{agent}}(\overrightarrow{o}) \\ \beta &= [\operatorname{lu_{opp}}(\overrightarrow{o}) + \operatorname{lu_{agent}}(\overrightarrow{o})]\operatorname{rank_{opp}}(\overrightarrow{o}) \end{aligned}$$

Pessimistic assumption

The offer is accepted based on the agent that favors the offer the least

Equivalence: 
$$lu_{opp}(\overrightarrow{o}) + lu_{agent}(\overrightarrow{o}) \sim \text{social welfare}$$

#### Stéphane Bonardi

|                    | Problem description | Agent Design          | Experiments    | Conclusion | Discussion & Future work |
|--------------------|---------------------|-----------------------|----------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>00000000000 | 000<br>0000000 |            |                          |
|                    |                     |                       |                |            |                          |

# Generating offers

Steps

## 3 steps:

- **1** Computation of the believed type of the opponent BT(t)
- 2 Computation of the Luce numbers using *u*opp and *u*agent
- 3 Choice of the best offer using the Qualitative Offer QO function

#### Stéphane Bonardi

|    | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future wo |
|----|---------------------|--------------|-------------|------------|------------------------|
| 00 |                     | 000000       | 000         |            |                        |
|    |                     | 00000000000  | 0000000     |            |                        |
| 00 | 00                  |              |             |            |                        |
|    |                     |              |             |            |                        |

# Generating offers

Example

The agent plays the role of Bob.

## Assumptions:

- Alice has only one possible type
- The utilities are time independent

Stéphane Bonardi

Negociating with bounded rational agents in environments with incomplete information using an automated agent

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

|                 | Problem description | Agent Design             | Experiments | Conclusion | Discussion & Future work |
|-----------------|---------------------|--------------------------|-------------|------------|--------------------------|
| 00              |                     | 000000<br>00000000000000 | 000         |            |                          |
| 00              | 00<br>0             |                          |             |            |                          |
| Decision mechar | nism                |                          |             |            |                          |

|    |   | $\vec{o}_1 = \{M,S\}$ | $\vec{o}_2 = \{M,F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
|----|---|-----------------------|-----------------------|------------------------|------------------------|
| 1  | $u_b(\vec{o}_i)$  | 4                     | 6                     | 10                     | 8                      |
| 2  | $u_a(\vec{o}_i)$  | 10                    | 9                     | 4                      | 6                      |
| 3  | $lu_b(\vec{o}_i)$   | 4/28 = 0.14           | 6/28 = 0.21           | 10/28 = 0.36           | 8/28 = 0.29            |
| 4  | $lu_a(\vec{o}_i)$   | 10/29 = 0.34          | 9/29 = 0.31           | 4/29 = 0.14            | 6/29 = 0.21            |
| 5  | $rank_b(\vec{o}_i)$   | 1/4 = 0.25            | 2/4 = 0.50            | 4/4 = 1.00             | 3/4 = 0.75             |
| 6  | $rank_{\alpha}(\vec{a}_{i})$                                  | 4/4 = 1.00            | 3/4 = 0.75            | 1/4 = 0.25             | 2/4 = 0.50             |
| 7  | $lu_b(\vec{o}_i) \cdot rank_b(\vec{o}_i)$                     | 0.04                  | 0.11                  | 0.36                   | 0.21                   |
| 8  | $lu_{\alpha}(\vec{o}_{i}) \cdot rank_{\alpha}(\vec{o}_{i})$   | 0.34                  | 0.23                  | 0.03                   | 0.10                   |
| 9  | $[lu_b(\vec{o}_i) + lu_a(\vec{o}_i)] \cdot rank_a(\vec{o}_i)$ | 0.49                  | 0.39                  | 0.12                   | 0.25                   |
| 10 | $[lu_a(\vec{o}_i) + lu_b(\vec{o}_i)] \cdot rank_b(\vec{o}_i)$ | 0.12                  | 0.26                  | 0.49                   | 0.37                   |

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ● ●

#### Stéphane Bonardi

|                 | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|-----------------|---------------------|--------------|-------------|------------|--------------------------|
| 00              |                     | 000000       | 000         |            |                          |
|                 |                     | 00000000000  | 0000000     |            |                          |
| 00              | 00                  |              |             |            |                          |
|                 |                     |              |             |            |                          |
| Decision mechar | nism                |              |             |            |                          |

|    |   | $\vec{o}_1 = \{M, S\}$ | $\vec{o}_2=\{M,F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
|----|---|------------------------|---------------------|------------------------|------------------------|
| 1  | $u_b(\vec{o}_i)$  | 4                      | 6                   | 10                     | 8                      |
| 2  | $u_a(\vec{o}_i)$  | 10                     | 9                   | 4                      | 6                      |
| 3  | $lu_b(\vec{o}_i)$   | 4/28 = 0.14            | 6/28 = 0.21         | 10/28 = 0.36           | 8/28 = 0.29            |
| 4  | $lu_a(\vec{o}_i)$   | 10/29 = 0.34           | 9/29 = 0.31         | 4/29 = 0.14            | 6/29 = 0.21            |
| 5  | $rank_b(\vec{o}_i)$   | 1/4 = 0.25             | 2/4 = 0.50          | 4/4 = 1.00             | 3/4 = 0.75             |
| 6  | $rank_a(\vec{o}_i)$   | 4/4 = 1.00             | 3/4 = 0.75          | 1/4 = 0.25             | 2/4 = 0.50             |
| 7  | $lu_b(\vec{o}_i) \cdot rank_b(\vec{o}_i)$                     | 0.04                   | 0.11                | 0.36                   | 0.21                   |
| 8  | $lu_a(\vec{o}_i) \cdot rank_a(\vec{o}_i)$                     | 0.34                   | 0.23                | 0.03                   | 0.10                   |
| 9  | $[lu_b(\vec{o}_i) + lu_a(\vec{o}_i)] \cdot rank_a(\vec{o}_i)$ | 0.49                   | 0.39                | 0.12                   | 0.25                   |
| 10 | $[lu_a(\vec{o}_i) + lu_b(\vec{o}_i)] \cdot rank_b(\vec{o}_i)$ | 0.12                   | 0.26                | 0.49                   | 0.37                   |

## Function QO

$$QO(t) = \arg\max_{\overrightarrow{\alpha} \in O} \min\{\alpha, \beta\}$$

ヘロン 人間 とくぼ とくぼう

#### Stéphane Bonardi

|                 | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|-----------------|---------------------|--------------|-------------|------------|--------------------------|
| 00              |                     | 000000       | 000         |            |                          |
|                 |                     | 00000000000  | 0000000     |            |                          |
| 00              | 00                  |              |             |            |                          |
|                 |                     |              |             |            |                          |
| Decision mechar | nism                |              |             |            |                          |

|    |   | $\vec{o}_1 = \{M, S\}$ | $\vec{o}_2 = \{M,F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
|----|---|------------------------|-----------------------|------------------------|------------------------|
| 1  | $u_b(\vec{o}_i)$  | 4                      | 6                     | 10                     | 8                      |
| 2  | $u_a(\vec{o}_i)$  | 10                     | 9                     | 4                      | 6                      |
| 3  | $lu_b(\vec{o}_i)$   | 4/28 = 0.14            | 6/28 = 0.21           | 10/28 = 0.36           | 8/28 = 0.29            |
| 4  | $lu_a(\vec{o}_i)$   | 10/29 = 0.34           | 9/29 = 0.31           | 4/29 = 0.14            | 6/29 = 0.21            |
| 5  | $rank_b(\vec{o}_i)$   | 1/4 = 0.25             | 2/4 = 0.50            | 4/4 = 1.00             | 3/4 = 0.75             |
| 6  | $rank_a(\vec{o}_i)$   | 4/4 = 1.00             | 3/4 = 0.75            | 1/4 = 0.25             | 2/4 = 0.50             |
| 7  | $lu_b(\vec{o}_i) \cdot rank_b(\vec{o}_i)$                     | 0.04                   | 0.11                  | 0.36                   | 0.21                   |
| 8  | $lu_a(\vec{o}_i) \cdot rank_a(\vec{o}_i)$                     | 0.34                   | 0.23                  | 0.03                   | 0.10                   |
| 9  | $[lu_b(\vec{o}_i) + lu_a(\vec{o}_i)] \cdot rank_a(\vec{o}_i)$ | 0.49                   | 0.39                  | 0.12                   | 0.25                   |
| 10 | $[lu_a(\vec{o}_i) + lu_b(\vec{o}_i)] \cdot rank_b(\vec{o}_i)$ | 0.12                   | 0.26                  | 0.49                   | 0.37                   |

## Function QO

$$QO(t) = \arg\max_{\overrightarrow{o} \in O} \min\{\alpha, \beta\}$$

ヘロン 人間 とくぼ とくぼう

#### Stéphane Bonardi

|                 | Problem description | Agent Design                            | Experiments | Conclusion | Discussion & Future work |
|-----------------|---------------------|---|-------------|------------|--------------------------|
| 00              |                     | 000000000000000000000000000000000000000 | 000         |            |                          |
| 00              | 00<br>0             |   |             |            |                          |
| Desision mechan | ie me               |   |             |            |                          |

#### Table 1 Example of calculating QO

|    |   | $\vec{o}_1 = \{M, S\}$ | $\vec{o}_2 = \{M, F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
|----|---|------------------------|------------------------|------------------------|------------------------|
| 1  | $u_b(\vec{o}_i)$  | 4                      | 6                      | 10                     | 8                      |
| 2  | $u_a(\vec{o}_i)$  | 10                     | 9                      | 4                      | 6                      |
| 3  | $lu_b(\vec{o}_i)$   | 4/28 = 0.14            | 6/28 = 0.21            | 10/28 = 0.36           | 8/28 = 0.29            |
| 4  | $lu_a(\vec{o}_i)$   | 10/29 = 0.34           | 9/29 = 0.31            | 4/29 = 0.14            | 6/29 = 0.21            |
| 5  | $rank_b(\vec{o}_i)$   | 1/4 = 0.25             | 2/4 = 0.50             | 4/4 = 1.00             | 3/4 = 0.75             |
| 6  | $rank_a(\vec{o}_i)$   | 4/4 = 1.00             | 3/4 = 0.75             | 1/4 = 0.25             | 2/4 = 0.50             |
| 7  | $lu_b(\vec{o}_i) \cdot rank_b(\vec{o}_i)$                     | 0.04                   | 0.11                   | 0.36                   | 0.21                   |
| 8  | $lu_a(\vec{o}_i) \cdot rank_a(\vec{o}_i)$                     | 0.34                   | 0.23                   | 0.03                   | 0.10                   |
| 9  | $[lu_b(\vec{o}_i) + lu_a(\vec{o}_i)] \cdot rank_a(\vec{o}_i)$ | 0.49                   | D.39                   | 0.12                   | 0.25                   |
| 10 | $[lu_a(\vec{o}_i) + lu_b(\vec{o}_i)] \cdot rank_b(\vec{o}_i)$ | 0.12                   | 0.26                   | 0.49                   | 0.37                   |

## Function QO

$$QO(t) = \arg\max_{\overrightarrow{o} \in O} \min\{\alpha, \beta\}$$

ヘロン 人間 とくぼ とくぼう

#### Stéphane Bonardi

|                 | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|-----------------|---------------------|--------------|-------------|------------|--------------------------|
| 00              |                     | 000000       | 000         |            |                          |
|                 |                     | 00000000000  | 0000000     |            |                          |
| 00              | 00                  |              |             |            |                          |
|                 |                     |              |             |            |                          |
| Decision mechar | nism                |              |             |            |                          |

|    |   | $\vec{o}_1 = \{M, S\}$ | $\vec{o}_2 = \{M,F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
|----|---|------------------------|-----------------------|------------------------|------------------------|
| 1  | $u_b(\vec{o}_i)$  | 4                      | 6                     | 10                     | 8                      |
| 2  | $u_a(\vec{o}_i)$  | 10                     | 9                     | 4                      | 6                      |
| 3  | $lu_b(\vec{o}_i)$   | 4/28 = 0.14            | 6/28 = 0.21           | 10/28 = 0.36           | 8/28 = 0.29            |
| 4  | $lu_a(\vec{o}_i)$   | 10/29 = 0.34           | 9/29 = 0.31           | 4/29 = 0.14            | 6/29 = 0.21            |
| 5  | $rank_b(\vec{o}_i)$   | 1/4 = 0.25             | 2/4 = 0.50            | 4/4 = 1.00             | 3/4 = 0.75             |
| 6  | $rank_a(\vec{o}_i)$   | 4/4 = 1.00             | 3/4 = 0.75            | 1/4 = 0.25             | 2/4 = 0.50             |
| 7  | $lu_b(\vec{o}_i) \cdot rank_b(\vec{o}_i)$                     | 0.04                   | 0.11                  | 0.36                   | 0.21                   |
| 8  | $lu_a(\vec{o}_i) \cdot rank_a(\vec{o}_i)$                     | 0.34                   | 0.23                  | 0.03                   | 0.10                   |
| 9  | $[lu_b(\vec{o}_i) + lu_a(\vec{o}_i)] \cdot rank_a(\vec{o}_i)$ | 0.49                   | 0.39                  | 0.12                   | 0.25                   |
| 10 | $[lu_a(\vec{o}_i) + lu_b(\vec{o}_i)] \cdot rank_b(\vec{o}_i)$ | 0.12                   | 0.26                  | 0.49                   | 0.37                   |

## Function QO

$$QO(t) = \arg\max_{\overrightarrow{o} \in O} \min\{\alpha, \beta\}$$

ヘロン 人間 とくぼ とくぼう

#### Stéphane Bonardi

|                 | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|-----------------|---------------------|--------------|-------------|------------|--------------------------|
| 00              |                     | 000000       | 000         |            |                          |
|                 |                     | 00000000000  | 0000000     |            |                          |
| 00              | 00                  |              |             |            |                          |
|                 |                     |              |             |            |                          |
| Decision mechar | nism                |              |             |            |                          |

|    |   | $\vec{o}_1 = \{M, S\}$ | $\vec{o}_2 = \{M,F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
|----|---|------------------------|-----------------------|------------------------|------------------------|
| 1  | $u_b(\vec{o}_i)$  | 4                      | 6                     | 10                     | 8                      |
| 2  | $u_a(\vec{o}_i)$  | 10                     | 9                     | 4                      | 6                      |
| 3  | $lu_b(\vec{o}_i)$   | 4/28 = 0.14            | 6/28 = 0.21           | 10/28 = 0.36           | 8/28 = 0.29            |
| 4  | $lu_a(\vec{o}_i)$   | 10/29 = 0.34           | 9/29 = 0.31           | 4/29 = 0.14            | 6/29 = 0.21            |
| 5  | $rank_b(\vec{o}_i)$   | 1/4 = 0.25             | 2/4 = 0.50            | 4/4 = 1.00             | 3/4 = 0.75             |
| 6  | $rank_a(\vec{o}_i)$   | 4/4 = 1.00             | 3/4 = 0.75            | 1/4 = 0.25             | 2/4 = 0.50             |
| 7  | $lu_b(\vec{o}_i) \cdot rank_b(\vec{o}_i)$                     | 0.04                   | 0.11                  | 0.36                   | 0.21                   |
| 8  | $lu_a(\vec{o}_i) \cdot rank_a(\vec{o}_i)$                     | 0.34                   | 0.23                  | 0.03                   | 0.10                   |
| 9  | $[lu_b(\vec{o}_i) + lu_a(\vec{o}_i)] \cdot rank_a(\vec{o}_i)$ | 0.49                   | 0.39                  | 0.12                   | 0.25                   |
| 10 | $[lu_a(\vec{o}_i) + lu_b(\vec{o}_i)] \cdot rank_b(\vec{o}_i)$ | 0.12                   | 0.26                  | 0.49                   | 0.37                   |

## Function QO

$$QO(t) = \arg\max_{\overrightarrow{o} \in O} \min\{\alpha, \beta\}$$

ヘロン 人間 とくぼ とくぼう

#### Stéphane Bonardi

|    | Problem description | Agent Design                            | Experiments | Conclusion | Discussion & Future work |
|----|---------------------|---|-------------|------------|--------------------------|
| 00 |                     | 000000                                  | 000         |            |                          |
| 00 | 00                  | 000000000000000000000000000000000000000 | 000000000   |            |                          |
|    |                     |   |             |            |                          |
|    |                     |   |             |            |                          |

#### Table 1 Example of calculating QO

|    |   | $\vec{o}_1 = \{M, S\}$ | $\vec{o}_2 = \{M,F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
|----|---|------------------------|-----------------------|------------------------|------------------------|
| 1  | $u_b(\vec{o}_i)$  | 4                      | 6                     | 10                     | 8                      |
| 2  | $u_a(\vec{o}_i)$  | 10                     | 9                     | 4                      | 6                      |
| 3  | $lu_b(\vec{o}_i)$   | 4/28 = 0.14            | 6/28 = 0.21           | 10/28 = 0.36           | 8/28 = 0.29            |
| 4  | $lu_a(\vec{o}_i)$   | 10/29 = 0.34           | 9/29 = 0.31           | 4/29 = 0.14            | 6/29 = 0.21            |
| 5  | $rank_b(\vec{o}_i)$   | 1/4 = 0.25             | 2/4 = 0.50            | 4/4 = 1.00             | 3/4 = 0.75             |
| 6  | $rank_a(\vec{o}_i)$   | 4/4 = 1.00             | 3/4 = 0.75            | 1/4 = 0.25             | 2/4 = 0.50             |
| 7  | $lu_b(\vec{o}_i) \cdot rank_b(\vec{o}_i)$                     | 0.04                   | 0.11                  | 0.36                   | 0.21                   |
| 8  | $lu_a(\vec{o}_i) \cdot rank_a(\vec{o}_i)$                     | 0.34                   | 0.23                  | 0.03                   | 0.10                   |
| 9  | $[lu_b(\vec{o}_i) + lu_a(\vec{o}_i)] \cdot rank_a(\vec{o}_i)$ | 0.49                   | 0.39                  | 0.12                   | 0.25                   |
| 10 | $[lu_a(\vec{o}_i) + lu_b(\vec{o}_i)] \cdot rank_b(\vec{o}_i)$ | 0.12                   | 0.26                  | 0.49                   | 0.37                   |

## Function QO

$$QO(t) = \arg\max_{\overrightarrow{o} \in O} \min\{\alpha, \beta\}$$

ヘロン 人間と 人間と 人間と

2

#### Stéphane Bonardi

|                    | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|--------------------|---------------------|--------------|-------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000       | 000         |            |                          |



"I never accept a first offer."

Stéphane Bonardi

|    | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future |
|----|---------------------|--------------|-------------|------------|---------------------|
| 00 |                     | 000000       | 000         |            |                     |
|    |                     | 0000000000   | 0000000     |            |                     |
| 00 | 00                  |              |             |            |                     |
|    |                     |              |             |            |                     |

# Accepting/Rejecting offers

Notations:

- **a**,  $b \sim$  agent a,  $b \sim$  type a, b
- a automated agent
- b opponent
- $\overrightarrow{o_i}$  offer received from agent *i*
- t current time
- T threshold

Stéphane Bonardi

Negociating with bounded rational agents in environments with incomplete information using an automated agent

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

| Introduction | Problem description | Agent Design | Experiments | Conclusion | Discussion & Fu |
|--------------|---------------------|--------------|-------------|------------|-----------------|
| 00           |                     | 000000       | 000         |            |                 |
|              |                     | 0000000000   | 0000000     |            |                 |
| 00           | 00                  |              |             |            |                 |
|              |                     |              |             |            |                 |

# Accepting/Rejecting offers

Rules

## Rule 1

# If $u_a(\overrightarrow{o_b}) \ge u_a(QO(t+1))$ then $\overrightarrow{o_b}$ is accepted

where QO(t+1) is the best offer the agent will be able to do for the next period

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

Stéphane Bonardi

|    | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future wo |
|----|---------------------|--------------|-------------|------------|------------------------|
| 00 |                     | 000000       | 000         |            |                        |
|    |                     | 0000000000   | 000000      |            |                        |
| 00 | 00                  |              |             |            |                        |
|    |                     |              |             |            |                        |

# Accepting/Rejecting offers

Otherwise:

$$u_a(\overrightarrow{o_b}) < u_a(QO(t+1))$$

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

Take into account the probability that its counter offer will be accepted by the opponent:

### Rule 2

If 
$$|u_b(QO(t+1)) - u_b(\overrightarrow{o_b})| \leq T$$
 then  $\overrightarrow{o_b}$  is rejected

## The two offers are quasi equivalent for the opponent

BUT: QO(t+1) is more valuable for the agent

#### Stéphane Bonardi

|    | Problem description | Agent Design | Experiments | Conclusion | Discussion & |
|----|---------------------|--------------|-------------|------------|--------------|
| 00 |                     | 000000       | 000         |            |              |
|    |                     | 0000000000   | 0000000     |            |              |
| 00 | 00                  |              |             |            |              |
|    |                     |              |             |            |              |

# Accepting/Rejecting offers

Otherwise:

$$u_a(\overrightarrow{o_b}) < u_a(QO(t+1))$$
  
 $|u_b(QO(t+1)) - u_b(\overrightarrow{o_b})| > T$ 

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

Take into account its reservation price:

## Rule 3

If  $u_a(\overrightarrow{o_b}) \ge r_a$  then  $\overrightarrow{o_b}$  is rejected with the probability  $rank(\overrightarrow{o_b})$ 

Stéphane Bonardi

|                    | Problem description | Agent Design                               | Experiments   | Conclusion | Discussion & Future work |
|--------------------|---------------------|--|---------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>00000000000000000000000000000000 | 000<br>000000 |            |                          |

Table 1

- Alice suggests to Bob:  $\overrightarrow{o_2} = (M, F)$
- We suppose that  $r_{bob} = 5$  and T = 0.05

| Exai | nple of calculating QO  |                        |                        |                        |                        |
|------|---|------------------------|------------------------|------------------------|------------------------|
|      |   | $\vec{o}_1 = \{M, S\}$ | $\vec{o}_2 = \{M, F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
| 1    | $u_b(\vec{o}_i)$  | 4                      | 6                      | 10                     | 8                      |
| 2    | $u_a(\vec{o}_i)$  | 10                     | 9                      | 4                      | 6                      |
| 3    | $lu_b(\vec{o}_i)$   | 4/28 = 0.14            | 6/28 = 0.21            | 10/28 = 0.36           | 8/28 = 0.29            |
| 4    | $lu_a(\vec{o}_i)$   | 10/29 = 0.34           | 9/29 = 0.31            | 4/29 = 0.14            | 6/29 = 0.21            |
| 5    | $rank_b(\vec{o}_i)$   | 1/4 = 0.25             | 2/4 = 0.50             | 4/4 = 1.00             | 3/4 = 0.75             |
| 6    | $rank_a(\vec{o}_i)$   | 4/4 = 1.00             | 3/4 = 0.75             | 1/4 = 0.25             | 2/4 = 0.50             |
| 7    | $lu_b(\vec{o}_i) \cdot rank_b(\vec{o}_i)$                     | 0.04                   | 0.11                   | 0.36                   | 0.21                   |
| 8    | $lu_a(\vec{o}_i) \cdot rank_a(\vec{o}_i)$                     | 0.34                   | 0.23                   | 0.03                   | 0.10                   |
| 9    | $[lu_b(\vec{o}_i) + lu_a(\vec{o}_i)] \cdot rank_a(\vec{o}_i)$ | 0.49                   | 0.39                   | 0.12                   | 0.25                   |
| 10   | $[lu_a(\vec{o}_i) + lu_b(\vec{o}_i)] \cdot rank_b(\vec{o}_i)$ | 0.12                   | 0.26                   | 0.49                   | 0.37                   |
|      |   |                        |                        |                        |                        |

#### ◆□ > ◆□ > ◆豆 > ◆豆 > ̄豆 - のへで

#### Stéphane Bonardi

|                    | Problem description | Agent Design                               | Experiments   | Conclusion | Discussion & Future work |
|--------------------|---------------------|--|---------------|------------|--------------------------|
| 00<br>0<br>00<br>0 |                     | 000000<br>00000000000000000000000000000000 | 000<br>000000 |            |                          |
| Besteller mereken  |                     |  |               |            |                          |

|    |   | $\vec{o}_1 = \{M,S\}$ | $\vec{o}_2 = \{M,F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
|----|---|-----------------------|-----------------------|------------------------|------------------------|
| 1  | $u_b(\vec{o}_i)$  | 4                     | 6                     | 10                     | 8                      |
| 2  | $u_a(\vec{o}_i)$  | 10                    | 9                     | 4                      | 6                      |
| 3  | $lu_b(\vec{o}_i)$   | 4/28 = 0.14           | 6/28 = 0.21           | 10/28 = 0.36           | 8/28 = 0.29            |
| 4  | $lu_a(\vec{o}_i)$   | 10/29 = 0.34          | 9/29 = 0.31           | 4/29 = 0.14            | 6/29 = 0.21            |
| 5  | $rank_b(\vec{o}_i)$   | 1/4 = 0.25            | 2/4 = 0.50            | 4/4 = 1.00             | 3/4 = 0.75             |
| 6  | $rank_a(\vec{o}_i)$   | 4/4 = 1.00            | 3/4 = 0.75            | 1/4 = 0.25             | 2/4 = 0.50             |
| 7  | $lu_b(\vec{o}_i) \cdot rank_b(\vec{o}_i)$                     | 0.04                  | 0.11                  | 0.36                   | 0.21                   |
| 8  | $lu_a(\vec{o}_i) \cdot rank_a(\vec{o}_i)$                     | 0.34                  | 0.23                  | 0.03                   | 0.10                   |
| 9  | $[lu_b(\vec{o}_i) + lu_a(\vec{o}_i)] \cdot rank_a(\vec{o}_i)$ | 0.49                  | 0.39                  | 0.12                   | 0.25                   |
| 10 | $[lu_a(\vec{o}_i) + lu_b(\vec{o}_i)] \cdot rank_b(\vec{o}_i)$ | 0.12                  | 0.26                  | 0.49                   | 0.37                   |

▲□▶▲圖▶▲≣▶▲≣▶ = の�?

## Bob checks his own utility

Bob knows that  $\overrightarrow{o_4}$  is the best offer he can do

Stéphane Bonardi

|                 | Problem description | Agent Design                            | Experiments | Conclusion | Discussion & Future work |
|-----------------|---------------------|---|-------------|------------|--------------------------|
| 00              |                     | 000000                                  | 000         |            |                          |
| 00              | 00                  | 000000000000000000000000000000000000000 | 00000000    |            |                          |
|                 |                     |   |             |            |                          |
| Decision mechan | niem                |   |             |            |                          |

#### Table 1

Example of calculating QO

|    |   | $\vec{o}_1 = \{M, S\}$ | $\vec{o}_2 = \{M,F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
|----|---|------------------------|-----------------------|------------------------|------------------------|
| 1  | $u_b(\vec{o}_i)$  | 4                      | 6                     | 10                     | 8                      |
| 2  | $u_a(\vec{o}_i)$  | 10                     | 9                     | <                      | 6                      |
| 3  | $lu_b(\vec{o}_i)$   | 4/28 = 0.14            | 6/28 = 0.21           | 28 = 0.36              | 8/28 = 0.29            |
| 4  | $lu_a(\vec{o}_i)$   | 10/29 = 0.34           | 9/29 = 0.31           | 4/29 = 0.14            | 6/29 = 0.21            |
| 5  | $rank_b(\vec{o}_i)$   | 1/4 = 0.25             | 2/4 = 0.50            | 4/4 = 1.00             | 3/4 = 0.75             |
| 6  | $rank_a(\vec{o}_i)$   | 4/4 = 1.00             | 3/4 = 0.75            | 1/4 = 0.25             | 2/4 = 0.50             |
| 7  | $lu_b(\vec{o}_i) \cdot rank_b(\vec{o}_i)$                     | 0.04                   | 0.11                  | 0.36                   | 0.21                   |
| 8  | $lu_a(\vec{o}_i) \cdot rank_a(\vec{o}_i)$                     | 0.34                   | 0.23                  | 0.03                   | 0.10                   |
| 9  | $[lu_b(\vec{o}_i) + lu_a(\vec{o}_i)] \cdot rank_a(\vec{o}_i)$ | 0.49                   | 0.39                  | 0.12                   | 0.25                   |
| 10 | $[lu_a(\vec{o}_i) + lu_b(\vec{o}_i)] \cdot rank_b(\vec{o}_i)$ | 0.12                   | 0.26                  | 0.49                   | 0.37                   |

▲□▶▲圖▶▲圖▶▲圖▶ ▲圖 ショルの

## Rule 1

If 
$$u_a(\overrightarrow{o_b}) \ge u_a(QO(t+1))$$
 then  $\overrightarrow{o_b}$  is accepted

Rule 1 is violated: 
$$u_b(\overrightarrow{o_2}) < u_b(\overrightarrow{o_4})$$

#### Stéphane Bonardi

|                  | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|------------------|---------------------|--------------|-------------|------------|--------------------------|
| 00               |                     | 000000       | 000         |            |                          |
|                  |                     | 0000000000   | 0000000     |            |                          |
|                  |                     |              |             |            |                          |
|                  |                     |              |             |            |                          |
| Decision mechani | iom                 |              |             |            |                          |

### Table 1

#### Example of calculating QO

|    |   | $\vec{o}_1 = \{M, S\}$ | $\vec{o}_2 = \{M,F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
|----|---|------------------------|-----------------------|------------------------|------------------------|
| 1  | $u_b(\vec{o}_i)$  | 4                      | 6                     | 10                     | 8                      |
| 2  | $u_a(\vec{o}_i)$  | 10                     | 9                     | -4                     | 6                      |
| 3  | $lu_b(\vec{o}_i)$   | 4/28 = 0.14            | 6/28 = 0.21           | >> = 0.36              | 8/28 = 0.29            |
| 4  | $lu_a(\vec{o}_i)$   | 10/29 = 0.34           | 9/29 = 0.31           | 0.14                   | 6/29 = 0.21            |
| 5  | $rank_b(\vec{o}_i)$   | 1/4 = 0.25             | 2/4 = 0.50            | 4/4 = 1.00             | 3/4 = 0.75             |
| 6  | $rank_a(\vec{o}_i)$   | 4/4 = 1.00             | 3/4 = 0.75            | 1/4 = 0.25             | 2/4 = 0.50             |
| 7  | $lu_b(\vec{o}_i) \cdot rank_b(\vec{o}_i)$                     | 0.04                   | 0.11                  | 0.36                   | 0.21                   |
| 8  | $lu_a(\vec{o}_i) \cdot rank_a(\vec{o}_i)$                     | 0.34                   | 0.23                  | 0.03                   | 0.10                   |
| 9  | $[lu_b(\vec{o}_i) + lu_a(\vec{o}_i)] \cdot rank_a(\vec{o}_i)$ | 0.49                   | 0.39                  | 0.12                   | 0.25                   |
| 10 | $[lu_a(\vec{o}_i) + lu_b(\vec{o}_i)] \cdot rank_b(\vec{o}_i)$ | 0.12                   | 0.26                  | 0.49                   | 0.37                   |

## Rule 2

I

If 
$$|u_b(QO(t+1)) - u_b(\overrightarrow{o_b})| \leq T$$
 then  $\overrightarrow{o_b}$  is rejected

■ Rule 2 is violated: 
$$|u_a(\overrightarrow{o_4}) - u_a(\overrightarrow{o_2})| > 0.05$$

#### Stéphane Bonardi

|                 | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|-----------------|---------------------|--------------|-------------|------------|--------------------------|
|                 |                     |              |             |            |                          |
|                 |                     | 0000000000   | 000000      |            |                          |
| 00              | 00                  |              |             |            |                          |
|                 |                     |              |             |            |                          |
| Decision mechan | viem                |              |             |            |                          |

#### Table 1

Example of calculating QO

|    |   | $\vec{o}_1 = \{M, S\}$ | $\vec{o}_2 = \{M, F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
|----|---|------------------------|------------------------|------------------------|------------------------|
| 1  | $u_b(\vec{o}_i)$  | 4                      | 6                      | 10                     | 8                      |
| 2  | $u_a(\vec{o}_i)$  | 10                     | 9                      | 4                      | 6                      |
| 3  | $lu_b(\vec{o}_i)$   | 4/28 = 0.14            | 6/28 = 0.21            | 10/28 = 0.36           | 8/28 = 0.29            |
| 4  | $lu_a(\vec{o}_i)$   | 10/29 = 0.34           | 9/29 = 0.31            | 4/29 = 0.14            | 6/29 = 0.21            |
| 5  | $rank_b(\vec{o}_i)$   | 1/4 = 0.25             | 2/4 = 0.50             | 4/4 = 1.00             | 3/4 = 0.75             |
| 6  | $rank_a(\vec{o}_i)$   | 4/4 = 1.00             | 3/4 = 0.75             | 1/4 = 0.25             | 2/4 = 0.50             |
| 7  | $lu_b(\vec{o}_i) \cdot rank_b(\vec{o}_i)$                     | 0.04                   | 0.11                   | 0.36                   | 0.21                   |
| 8  | $lu_a(\vec{o}_i) \cdot rank_a(\vec{o}_i)$                     | 0.34                   | 0.23                   | 0.03                   | 0.10                   |
| 9  | $[lu_b(\vec{o}_i) + lu_a(\vec{o}_i)] \cdot rank_a(\vec{o}_i)$ | 0.49                   | 0.39                   | 0.12                   | 0.25                   |
| 10 | $[lu_a(\vec{o}_i) + lu_b(\vec{o}_i)] \cdot rank_b(\vec{o}_i)$ | 0.12                   | 0.26                   | 0.49                   | 0.37                   |

## Rule 3

If  $u_a(\overrightarrow{o_b}) \ge r_a$  then  $\overrightarrow{o_b}$  is rejected with the probability  $rank(\overrightarrow{o_b})$ 

▲□▶▲圖▶▲≣▶▲≣▶ = の�?

Rule 3 is enforced: 
$$u_b(\overrightarrow{o_2}) \ge 5$$

#### Stéphane Bonardi

|                | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|----------------|---------------------|--------------|-------------|------------|--------------------------|
|                |                     |              |             |            |                          |
|                |                     | 0000000000   | 000000      |            |                          |
| 00             | 00                  |              |             |            |                          |
|                |                     |              |             |            |                          |
| Desision mesha | -1                  |              |             |            |                          |

Table 1 Example of calculating QO

|    |   | $\vec{o}_1 = \{M,S\}$ | $\vec{o}_2 = \{M,F\}$ | $\vec{o}_3 = \{B, S\}$ | $\vec{o}_4 = \{B, F\}$ |
|----|---|-----------------------|-----------------------|------------------------|------------------------|
| 1  | $u_b(\vec{o}_i)$  | 4                     | 6                     | 10                     | 8                      |
| 2  | $u_a(\vec{o}_i)$  | 10                    | 9                     | 4                      | 6                      |
| 3  | $lu_b(\vec{o}_i)$   | 4/28 = 0.14           | 6/28 = 0.21           | 10/28 = 0.36           | 8/28 = 0.29            |
| 4  | $lu_a(\vec{o}_i)$   | 10/29 = 0.34          | 9/29 = 0.31           | 4/29 = 0.14            | 6/29 = 0.21            |
| 5  | $rank_b(\vec{o}_i)$   | 1/4 = 0.25            | 2/4 = 0.50            | 4/4 = 1.00             | 3/4 = 0.75             |
| 6  | $rank_a(\vec{o}_i)$   | 4/4 = 1.00            | 3/4 = 0.75            | 1/4 = 0.25             | 2/4 = 0.50             |
| 7  | $lu_b(\vec{o}_i) \cdot rank_b(\vec{o}_i)$                     | 0.04                  | 0.11                  | 0.36                   | 0.21                   |
| 8  | $lu_a(\vec{o}_i) \cdot rank_a(\vec{o}_i)$                     | 0.34                  | 0.23                  | 0.03                   | 0.10                   |
| 9  | $[lu_b(\vec{o}_i) + lu_a(\vec{o}_i)] \cdot rank_a(\vec{o}_i)$ | 0.49                  | 0.39                  | 0.12                   | 0.25                   |
| 10 | $[lu_a(\vec{o}_i) + lu_b(\vec{o}_i)] \cdot rank_b(\vec{o}_i)$ | 0.12                  | 0.26                  | 0.49                   | 0.37                   |

Bob accepts Alice's offer with probability  $1 - rank_b(\vec{o_2}) = 0.5$ 

◆□ > ◆□ > ◆豆 > ◆豆 > ̄豆 − のへで

Stéphane Bonardi

# Outline

## 1 Problem description

2 Agent Design

## 3 Experiments

- Protocol
- Results
  - Automated agent vs human

 Automated agent vs automated agent

## 4 Conclusion



|                    | Problem description | Agent Design         | Experiments              | Conclusion | Discussion & Future work |
|--------------------|---------------------|----------------------|--------------------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>0000000000 | • <b>00</b><br>000 00000 |            |                          |
| Protocol           |                     |                      |                          |            |                          |
|                    |                     |                      |                          |            |                          |



- Scenario 2: a job candidate and an employer
- 5 issues:
  - Salary
  - 2 Job description
  - 3 Social benefits
  - 4 Promotion possibilities
  - 5 Working hours
- Number of possible agreements: 1296
- Time constraint: < 28 minutes

Negociating with bounded rational agents in environments with incomplete information using an automated agent

| Introduction<br>O<br>O<br>OO<br>O | Problem description<br>O<br>O<br>O<br>O<br>O | Agent Design<br>000000<br>0000000000 | Experiments<br>0●0<br>0000000 | Conclusion | Discussion & Future work |
|-----------------------------------|--|--------------------------------------|-------------------------------|------------|--------------------------|
| Protocol                          |  |                                      |                               |            |                          |
|                                   |  |                                      |                               |            |                          |



Domain 2:

- Both agents lose as time advances
- Status quo SQ is similar for both agents
- Three possible types
- Assigned utility for each negotiator
- Precise opponent type unknown
- The different possible types are public
- At most 14 time periods of 2 minutes

Stéphane Bonardi

Negociating with bounded rational agents in environments with incomplete information using an automated agent

|                    | Problem description | Agent Design              | Experiments          | Conclusion | Discussion & Future work |
|--------------------|---------------------|---------------------------|----------------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>000000000000000 | <b>00</b><br>0 00000 |            |                          |
| Protocol           |                     |                           |                      |            |                          |



## Protocol:

|               | Utility range (min-max) | Status Quo outcome |
|---------------|-------------------------|--------------------|
| Employer      | 170-620                 | 240                |
| Job candidate | 60-635                  | -160               |

Fixed loss per time period:

- -6 units for the employer
- -8 units for the job candidate

44 simulations

Stéphane Bonardi

|         | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|---------|---------------------|--------------|-------------|------------|--------------------------|
| 00      |                     | 000000       | 000         |            |                          |
| 00      | 00                  |              | 00000000    |            |                          |
|         |                     |              |             |            |                          |
| Results |                     |              |             |            |                          |
|         |                     |              |             |            |                          |



In a nutshell:

- Automated Agent (AA) achieves better agreement
- The social welfare increases if an AA is involved

Statistical tests:

- t-test: to compare utility value
- Wilcoxon signed-rank test: to compare discrete samples
- Fisher's exact test: correlation between the type of agreement and the type of negotiator

Stéphane Bonardi

|         | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|---------|---------------------|--------------|-------------|------------|--------------------------|
| 00      |                     | 000000       | 000         |            |                          |
| õo      | õo                  |              | 00000000    |            |                          |
|         |                     |              |             |            |                          |
| Results |                     |              |             |            |                          |

## Automated agent vs human

- Utility value for the AA: Higher
- Sum of the utility: Higher
- Full agreement: 86% instead of 72% (Human vs Human)
- Probability of reaching a full agreement: Higher

But: the results are significantly higher for only one of the two roles (in this case for the job candidate)

イロト イポト イヨト イヨト 二日

|                    | Problem description | Agent Design          | Experiments             | Conclusion | Discussion & Future work |
|--------------------|---------------------|-----------------------|-------------------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>00000000000 | 000<br>000 <b>00 00</b> |            |                          |
| Results            |                     |                       |                         |            |                          |

# Automated agent vs automated agent

## Opponents:

- The same automated agent
- A Bayesian Equilibrium Agent (BEA)

AA vs AA:

- Average and sum of utility: Higher
- Kind of agreement: Better

AA vs BEA:

- QO higher than when humans are involved
- Ended early

#### Stéphane Bonardi

Negociating with bounded rational agents in environments with incomplete information using an automated agent

| Introduction<br>00<br>00<br>00 | Problem description<br>O<br>O<br>O<br>O | Agent Design<br>000000<br>00000000000000000000000000000 | Experiments | Conclusion | Discussion & Future work |
|--------------------------------|---|---|-------------|------------|--------------------------|
| Results                        |   |   |             |            |                          |

## Reasons



◆□▶ ◆□▶ ◆ □▶ ◆ □ ● ● ● ●

Stéphane Bonardi

|                    | Problem description | Agent Design                               | Experiments            | Conclusion | Discussion & Future work |
|--------------------|---------------------|--|------------------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>00000000000000000000000000000000 | 000<br>0 <b>0000</b> 0 |            |                          |
| Results            |                     |  |                        |            |                          |

## Reasons



#### 

#### Stéphane Bonardi

|                    | Problem description | Agent Design          | Experiments            | Conclusion | Discussion & Future work |
|--------------------|---------------------|-----------------------|------------------------|------------|--------------------------|
| 00<br>0<br>00<br>0 | 0<br>0<br>00<br>0   | 000000<br>00000000000 | 000<br>000 <b>0000</b> |            |                          |
| Results            |                     |                       |                        |            |                          |
|                    |                     |                       |                        |            |                          |



How to explain these results ?

AA is rational: it considers the offers that are good for it AND reasonable for the opponent

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

AA pays more attention to the gain/lose as time advances

Stéphane Bonardi

# Outline



2 Agent Design







◆□▶ ◆圖▶ ◆臣▶ ◆臣▶ 三臣…

|    | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|----|---------------------|--------------|-------------|------------|--------------------------|
|    |                     |              |             |            |                          |
|    |                     |              |             |            |                          |
| 00 | 00                  |              |             |            |                          |
|    |                     |              |             |            |                          |



- Flexibility of the automated agent
- Effective outcomes
- No constraints on the model induced by the domain

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

Stéphane Bonardi

# Outline



2 Agent Design







◆□▶ ◆御▶ ◆臣▶ ◆臣▶ 三臣 - の�?

|    | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|----|---------------------|--------------|-------------|------------|--------------------------|
| 00 |                     | 000000       | 000         |            |                          |
|    |                     |              |             |            |                          |
| 00 | 00                  |              |             |            |                          |
|    |                     |              |             |            |                          |

# Future work

- Improve the offer generating mechanism: most of the reached agreements are based on human made offers
- Make more than one offer per turn:
  - More interaction with the opponent
  - Use the pressure of time
- Experiments with real negotiators
- Take into account more than one future step
- Introduce the notion of power for the agent
- Use other learning techniques (more flexible): neural networks, genetic algorithms,...

#### Stéphane Bonardi

|    | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|----|---------------------|--------------|-------------|------------|--------------------------|
| 00 |                     | 000000       | 000         |            |                          |
|    |                     | 0000000000   | 0000000     |            |                          |
|    |                     |              |             |            |                          |
|    |                     |              |             |            |                          |

# Pros and Cons

## Pros:

- Interesting examples
- Agent design

## Cons:

- Theoretical justifications
- Related work
- Use of only utility as a measurement of quality
- No clear justification for their experimental choices

◆□ > ◆□ > ◆ □ > ◆ □ > ● □ ● ● ●

#### Stéphane Bonardi

|    | Problem description | Agent Design | Experiments | Conclusion | Discussion & Future work |
|----|---------------------|--------------|-------------|------------|--------------------------|
| 00 |                     | 000000       | 000         |            |                          |
|    |                     | 0000000000   | 0000000     |            |                          |
| 00 | 00                  |              |             |            |                          |
|    |                     |              |             |            |                          |

## Questions

# Thank you very much for your attention



#### Stéphane Bonardi