

HASHING

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Other ways to Implement a Dictionary

IDEA1: Store in an *array* indexed by the *keys*

⇒ really fast lookups/insertions/...

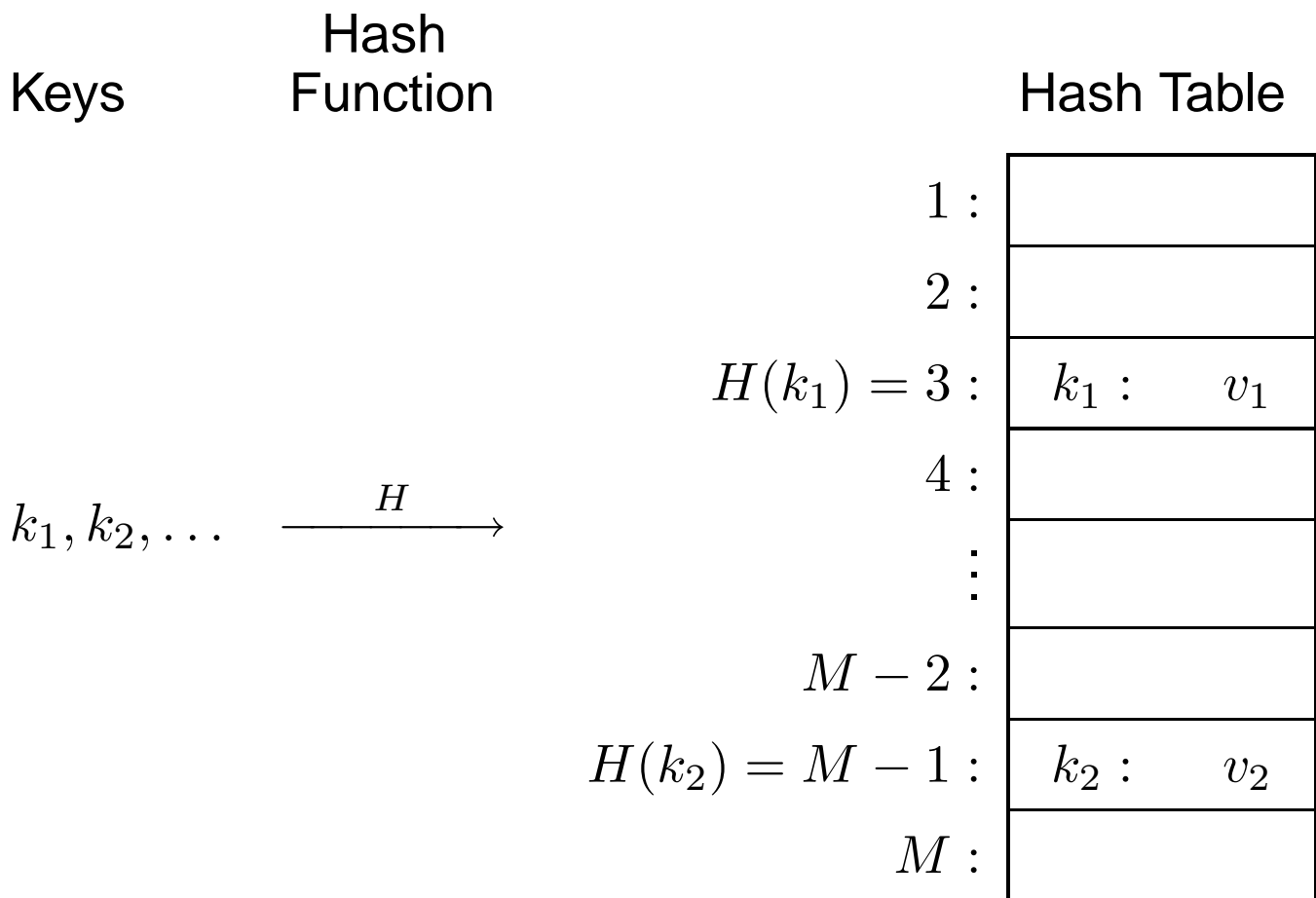
PROBLEM: VERY poor utilization of space

IDEA2: Store in an *array* indexed by results of applying
a **(hash) function** H on the keys

⇒ requirement: $0 \leq f(k) < M$ or $0 < f(k) \leq M$
where M is the size of the **hash table**.

Example

Let H be a *hash function* with range $\{1, \dots, M\}$:



k_i : *keys*

v_i : *values* associated with the keys

Considerations

We need to solve two problems:

1. How do we design the *hash function*?
 - static case (we know all the keys in advance):
perfect hash functions
 - ⇒ every key is mapped to a separate value
 - ⇒ the table size is $O(\text{number of keys})$
 - dynamic case (we don't know the keys in advance)
 - ⇒ “mostly injective”
2. What do we do if two or more records “hash” to the same place (a **collision** occurs)?
 - ⇒ conflict (collision) resolution

Hash Functions

- Selection-based Hash Function

Choose a part of the key to be the hash value

⇒ common choices:

- first couple of bits
- fixed pattern of bits

⇒ problems with non-uniformly distributed keys

- Division-based Hash Function

Take the key *modulo* the table size

⇒ choose table size to be *prime number*

- Folding-based Hash Function

Take bit patterns and add them together

⇒ may need an adjustment to match the table size

Collision Resolution

How good is a particular hashing scheme?

⇒ measured by **load factor**

$$\text{load factor} = \frac{\text{number of stored items}}{\text{size of table}}$$

The number of **probes** (accesses needed to locate a key) is compared against the load factor.

⇒ load factor closer to 1

⇒ more **collisions**

⇒ more **probes**

Separate Chaining

IDEA: buckets contain **lists** of elements

- use H to determine bucket
- retrieve by searching the bucket (a list!)
- insert by adding to the list

Advantages:

- ⇒ flexible size of buckets
- ⇒ deletion is easy (how?)

Disadvantages:

- ⇒ worst case: linear search
- ⇒ pointers take space

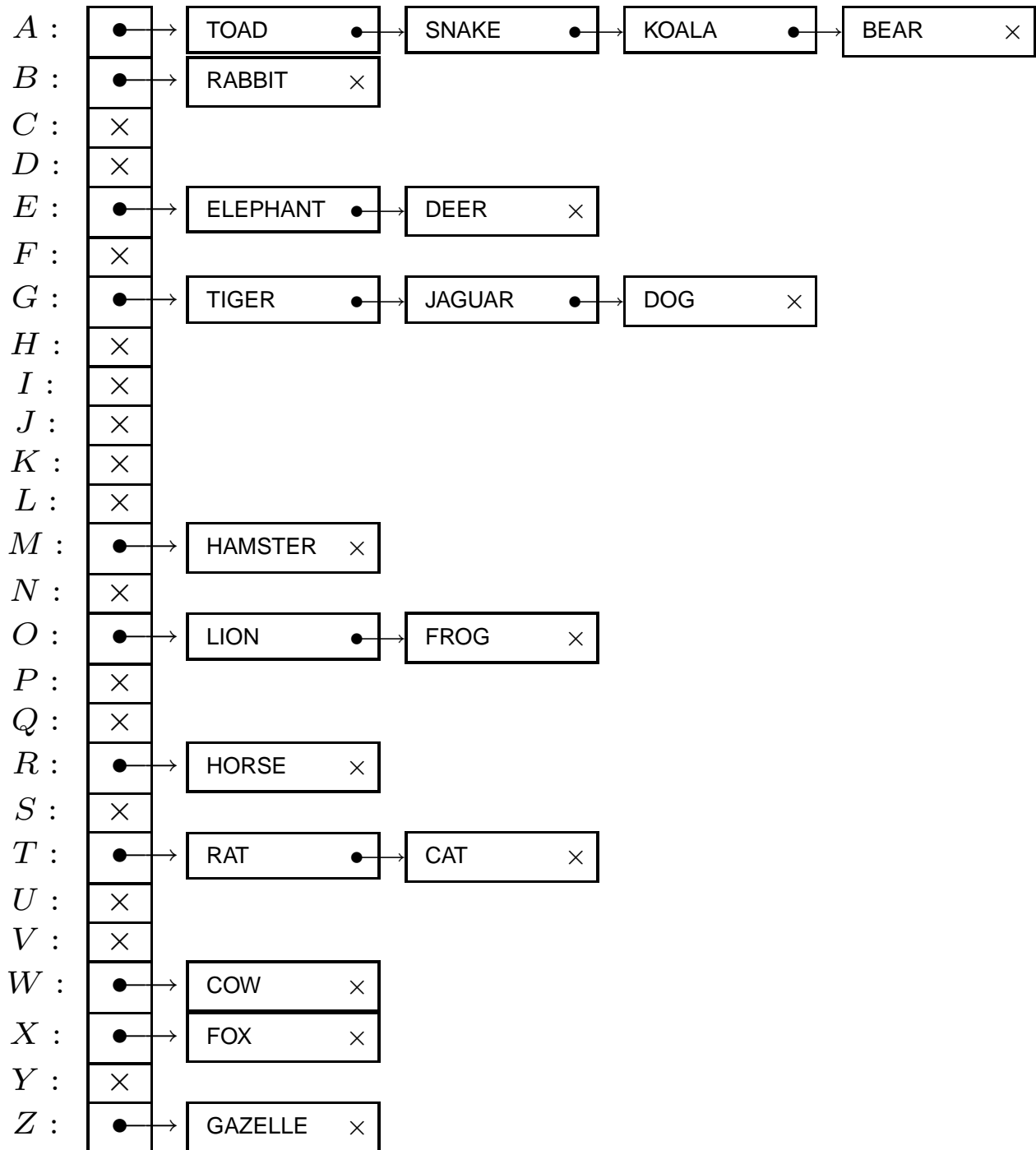
Example Data

Insert

BEAR	HORSE
CAT	JAGUAR
COW	KOALA
DOG	LION
ELEPHANT	RABBIT
FOX	RAT
FROG	SNAKE
GAZELLE	TIGER
HAMSTER	TOAD

into a 26-bucket *Hash table* based on a Hash function $H(k) = \text{the 3rd letter of } k$.

Example



Coalesced Chaining

IDEA: Store “overflow” in empty cells of the table
⇒ and remember where you put it
 a pointer from the “original” bucket

- Lookup k :
 - look at $H(k)$,
 - if different from k follow pointers till you find it
 - or till you find a *nil* (k not found)
- Insert k :
 - similar, if not found
 - store in the next **free** cell
 - update the last pointer

Problem: deletion is quite difficult.

Example

<i>A</i> :	BEAR	D
<i>B</i> :	ELEPHANT	H
<i>C</i> :	JAGUAR	K
<i>D</i> :	KOALA	J
<i>E</i> :	DEER	B
<i>F</i> :	LION	
<i>G</i> :	DOG	C
<i>H</i> :	RABBIT	
<i>I</i> :	RAT	
<i>J</i> :	SNAKE	L
<i>K</i> :	TIGER	
<i>L</i> :	TOAD	
<i>M</i> :	HAMSTER	
<i>N</i> :		
<i>O</i> :	FROG	F
<i>P</i> :		
<i>Q</i> :		
<i>R</i> :	HORSE	
<i>S</i> :		
<i>T</i> :	CAT	I
<i>U</i> :		
<i>V</i> :		
<i>W</i> :	COW	
<i>X</i> :	FOX	
<i>Y</i> :		
<i>Z</i> :	GAZELLE	

Open Addressing

IDEA don't use pointers

⇒ use *fixed probe sequence*

⇒ $H(k, i)$ is a hash function used for the i -th probe

⇒ $H(k, i)$ should *cover* the whole table for varying i

Most common version: **Sequential (linear) probing**:

$$H(k, 1) = H(k)$$

$$H(k, i + 1) = (H(k, i) + 1) \bmod M$$

Problem: *primary clustering*

⇒ “clogging” parts of the table

⇒ long chains of *probes*

to insert “TOAD” we need 10 probes

⇒ using different “offset” doesn't help

and may miss parts of the table

one reason to pick M prime

Another problem: deletion

⇒ only possibility: mark as deleted.

Example

<i>A</i> :	BEAR
<i>B</i> :	KOALA
<i>C</i> :	RABBIT
<i>D</i> :	SNAKE
<i>E</i> :	DEER
<i>F</i> :	ELEPHANT
<i>G</i> :	DOG
<i>H</i> :	JAGUAR
<i>I</i> :	TIGER
<i>J</i> :	TOAD
<i>K</i> :	
<i>L</i> :	
<i>M</i> :	HAMSTER
<i>N</i> :	
<i>O</i> :	FROG
<i>P</i> :	LION
<i>Q</i> :	
<i>R</i> :	HORSE
<i>S</i> :	
<i>T</i> :	CAT
<i>U</i> :	RAT
<i>V</i> :	
<i>W</i> :	COW
<i>X</i> :	FOX
<i>Y</i> :	
<i>Z</i> :	GAZELLE

Double Hashing

IDEA: use 2nd hash function to determine the probe sequence for k

$$H(k, 1) = H_1(k)$$

$$H(k, i + 1) = (H(k, i) + H_2(k)) \bmod M$$

$\Rightarrow H_2(k)$ must be relatively prime to M !

In our Example:

$H_2(k) = i$ if the first letter of k is i^{th} in alphabet.

Example

<i>A</i> :	BEAR
<i>B</i> :	RABBIT
<i>C</i> :	
<i>D</i> :	
<i>E</i> :	DEER
<i>F</i> :	
<i>G</i> :	DOG
<i>H</i> :	
<i>I</i> :	RAT
<i>J</i> :	ELEPHANT
<i>K</i> :	TIGER
<i>L</i> :	KOALA
<i>M</i> :	HAMSTER
<i>N</i> :	
<i>O</i> :	FROG
<i>P</i> :	
<i>Q</i> :	JAGUAR
<i>R</i> :	HORSE
<i>S</i> :	
<i>T</i> :	CAT
<i>U</i> :	TOAD
<i>V</i> :	
<i>W</i> :	COW
<i>X</i> :	FOX
<i>Y</i> :	
<i>Z</i> :	GAZELLE
0 :	LION
1 :	
2 :	SNAKE

Probe Sequences

Key	Probes
BEAR	A,C,E,G,...
CAT	T,W,Z,2,...
COW	W,Z,2,C,...
DOG	G,K,O,S,...
ELEPHANT	E,J,O T,...
FOX	X,A,G,M...
FROG	O,U,0,D,...
GAZELLE	Z,D,J,P,...
HAMSTER	M,U,2,H,...
...	

Summary

- Fast array-like search
 - ⇒ degenerates for high load factors ($> .7$)
- Easy implementation
 - ⇒ no pointer overhead
- Many versions
 - ⇒ extensible/linear hashing
 - the table grows/shrinks with inserts/deletes
 - disk (block-based) versions