

# On Simultaneous Row and Column Reduction of Higher-Order Linear Differential Systems

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Consider system of differential equations

$$a_n(x)\vec{y}^n(x) + \cdots + a_1(x)\vec{y}'(x) + a_0(x)\vec{y}(x) = \vec{f}(x)$$

with  $a_i(x) \in \mathbb{K}^{m \times n}[[x]]$  and  $\vec{y}(x) \in \mathbb{K}^n[[x]]$ . (i.e. working locally about point 0).

## Motivation

Consider system of differential equations

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Usually convert to 1<sup>st</sup> order systems

$$A(t)Y'(t) = B(t)Y(t) + C(t)$$

Various techniques used to build solutions or solution types (e.g. existence of rational function or exponential solutions).

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with  $a_i(x) \in \mathbb{K}^{m \times n}[[x]]$  and  $\vec{y}(x) \in \mathbb{K}^n[[x]]$ . (i.e. working locally about point 0).

We instead want to work **directly** with the higher order system.

View problem as

$$L(D)\vec{y}(x) = \vec{f}(x)$$

with  $L(D) \in \mathbb{K}^{m \times n}[[x]][D]$  and transform  $L(D)$ .

# Outline

- 1 Motivation
- 2 Tools : Matrix Normal Forms
- 3 Higher Order Reduction
- 4 Example
- 5 Future Work

## Matrix Normal Forms

Given :  $\mathbf{L}(D) \in \mathbb{K}^{m \times m}[D]$ .

Do row and column operations

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Do row and column operations  $\mathbf{U}(D)$  and  $\mathbf{V}(D)$  so that

$$\mathbf{U}(D)\mathbf{L}(D)\mathbf{V}(D) = \text{easier}$$

(easier =  $\mathbf{L}^*(D) \in \mathbb{K}^{m \times m}[D]$  in some sort of normal form)

$\mathbf{U}(D), \mathbf{V}(D) \in \mathbb{K}^{m \times m}[D]$  invertible



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$\mathbf{U}(D), \mathbf{V}(D) \in \mathbb{K}^{m \times m}[D]$  invertible

Gives  $\mathbf{L}^*(D)\vec{y}^*(x) = \vec{f}^*(x)$  with  $\mathbf{L}^*(D) \in \mathbb{K}^{m \times m}[[x]][D]$

## Normal Forms : Hermite

Hermite forms of  $\mathbf{L}$ .

$$\mathbf{U} \cdot \mathbf{L} = \begin{bmatrix} h_{11} & \cdots & \cdots & h_{1k} \\ 0 & h_{22} & & \vdots \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & h_{kk} \end{bmatrix}$$

with  $h_{ii}$  larger than  $h_{ij}$ .

Problem : Degrees of elements growth

Smith form of  $\mathbf{L}$ .

$$\mathbf{U} \cdot \mathbf{L} \cdot \mathbf{V} = \begin{bmatrix} s_{11} & 0 & & 0 \\ 0 & s_{22} & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & s_{kk} \end{bmatrix}$$

with  $s_{i,i}$  dividing  $s_{i+1,i+1}$ .

Problem : Trivial in case of differential domain, i.e.

$$s_{11} = \cdots = s_{k-1,k-1} = 1 \text{ (Johannes Middeke)}$$

## Normal Forms : Popov

Popov form of  $\mathbf{L}$ .

$$\mathbf{U} \cdot \mathbf{L} = \begin{bmatrix} p_{11} & \cdots & \cdots & p_{1k} \\ \vdots & & & \vdots \\ \vdots & & & \vdots \\ p_{k1} & \cdots & \cdots & p_{kk} \end{bmatrix}$$

with each row having a highest degree pivot

Problem :

## Normal Forms : Popov

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with each row having a highest degree pivot

No Problem : We like this one.

## Example : Algorithms Based on Popov Forms

Popov transforms  $L(D)$  so that  $L(D)\vec{y}(x) = \vec{f}(x)$  converts naturally to larger first order system.

- Popov to First Order
- Solution method of First Order
- Convert first order solution method back to original higher order system  
(possible since conversion to Popov is reversible)

## First Order System : Harris Algorithm (1968)

$$L(D) = a_1(x)D + a_2(x) \quad \text{with } a_i(x) \in \mathbb{K}^{n \times n}[[x]]$$

Harris algorithm produces matrices  $S, T \in \mathbb{K}^{n \times n}[[x]]$  such that

$$S \cdot L(D) \cdot T = \begin{bmatrix} L_1(D) & 0 & \cdots & \cdots & 0 \\ 0 & c_1(x) & 0 & & \\ & & \ddots & & \\ & & & c_k(x) & \\ 0 & \cdots & & & 0 \end{bmatrix}$$

with  $L_1(D) = x^p I_q D + b(x)$ ,  $b(x) \in \mathbb{K}^{q \times q}[[x]]$  and  $c_i(x) \in \mathbb{K}^{n_i \times n_i}((x))$  invertible for all  $i$ .

## Second Order System

$$L(D) = a_2(x)D^2 + a_1(x)D + a_0(x) \quad \text{with } a_i(x) \in \mathbb{K}^{n \times n}[[x]]$$

Theorem: Barkatou, El Bacha, Pflügel (ISSAC 2010)

There exist  $S \in \mathbb{K}((x))^{m \times m}[D]$  and  $T \in \mathbb{K}((x))^{n \times n}[D]$  invertible such that

$$S \cdot L(D) \cdot T = \begin{bmatrix} a_{11}(x)D^2 + b_{11}(x)D + c_{11}(x) & c_{12}(x) & 0 & 0 \\ c_{21}(x) & b_{22}(x)D + c_{22}(x) & 0 & 0 \\ 0 & 0 & c_{33}(x) & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix},$$

with  $a_{11}(x)$ ,  $b_{22}(x)$  and  $c_{33}(x)$  invertible matrices.



## Second Order System (cont.)

Thus second order system  $L(D)\vec{y}(x) = \vec{f}(x)$  is converted to

$$\begin{bmatrix} a_{11}(x)D^2 + b_{11}(x)D + c_{11}(x) & c_{12}(x) & 0 & 0 \\ c_{21}(x) & b_{22}(x)D + c_{22}(x) & 0 & 0 \\ 0 & 0 & c_{33}(x) & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \vec{z}_1 \\ \vec{z}_2 \\ \vec{z}_3 \\ \vec{z}_4 \end{bmatrix} = \begin{bmatrix} \vec{f}_1 \\ \vec{f}_2 \\ \vec{f}_3 \\ \vec{f}_4 \end{bmatrix}.$$

Resulting system is decoupled into differential, algebraic and arbitrary components.

## Decoupling?

The decoupled system

$$\begin{bmatrix} a_{11}(x)D^2 + b_{11}(x)D + c_{11}(x) & c_{12}(x) \\ c_{21}(x) & b_{22}(x)D + c_{22}(x) \end{bmatrix} \begin{bmatrix} \vec{z}_1 \\ \vec{z}_2 \end{bmatrix} = 0,$$

can be transformed to the first-order systems of ODEs:

$$\left( \begin{bmatrix} I & & \\ & a_{11}(x) & \\ & & b_{22}(x) \end{bmatrix} D + \begin{bmatrix} 0 & -I & 0 \\ c_{11}(x) & b_{11}(x) & c_{12}(x) \\ c_{21}(x) & 0 & c_{22}(x) \end{bmatrix} \right) \begin{bmatrix} \vec{z}_1 \\ \vec{z}_1' \\ \vec{z}_2 \end{bmatrix} = 0.$$

**Definition:**  $L(D), \tilde{L}(D) \in \mathbb{K}((x))^{m \times n}[D]$  are said to be **equivalent** if there exist  $U(D) \in \mathbb{K}((x))^{m \times m}[D]$  and  $V(D) \in \mathbb{K}((x))^{n \times n}[D]$  invertible s.t.  $L(\tilde{D}) = U(D) \cdot L(D) \cdot V(D)$ .

Row operations on our operator  $L(D)$ :

- 1 multiplying a row of  $L(D)$  by a nonzero element of  $\mathbb{K}((x))$ ,
- 2 adding to any row of  $L(D)$  another row multiplied by an element of  $\mathbb{K}((x))[D]$ ,
- 3 interchanging any two rows of  $L(D)$ .

Want to find  $\mathbf{U}(D) \in \mathbb{K}^{m \times m}[[x]][D]$ , invertible, such that

$$\mathbf{L}^*(D) = \mathbf{U}(D) \cdot \mathbf{L}(D) = D^{\vec{n}} \ell_{\vec{n}}(x) + \text{l.o.t. s}$$

where  $\ell_{\vec{n}}(x) \in \mathbb{K}^{m \times m}[[x]]$  is nonsingular.

- $\mathbf{L}^*(D)$  is said to be in row-reduced form
- $\vec{n}$  is the row order of  $\mathbf{L}^*(D)$
- $\ell_{\vec{n}}(x)$  is the leading row coefficient matrix

## Reducing Row Degree

If  $L(D)$  not row-reduced implies : there exists nonzero vector of the form  $v = (v_1, \dots, v_m) \in \mathbb{K}[[x]]^{1 \times m}$  such that  $v \ell_{\vec{n}} = 0$ .

$$U_{11}(D) = \begin{bmatrix} & 1 & & & & & & \\ & & \ddots & & & & & \\ & & & 1 & & & & \\ v_1 D^{n_j - n_1} & \dots & v_{j-1} D^{n_j - n_{j-1}} & v_j & v_{j+1} D^{n_j - n_{j+1}} & \dots & v_m D^{n_j - n_m} & \\ & & & & 1 & & & \\ & & & & & \ddots & & \\ & & & & & & 1 & \end{bmatrix}.$$

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Need  $n_j \geq n_i$  whenever  $v_i \neq 0$ . Tells us how to choose  $j$  !

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Note:  $U_{11}(D)L(D)$  has lower row degree. Continue until row reduced.

B-L (1997), Abramov-Bronstein (2001), B-C-L (2006)

## Simultaneous Row and Column Reduction

Row reduction followed by column reduction does not imply simultaneous Row and Column reduction.

We have two algorithms for computing simultaneous row-column reduced forms

- Row then column then row then ...
- A better use row, column combinations

Both depend on : Leading row and column matrix becomes

$$\begin{bmatrix} \ell c(L_{11}) & 0 \\ * & * \end{bmatrix} \text{ and } \begin{bmatrix} \ell c(L_{11}) & * \\ 0 & * \end{bmatrix},$$

Then iterate.



Consider the matrix differential operator given by

$$L = \begin{bmatrix} D^3 + x & 2D^2 & x^2 + x \\ D^2 & xD^2 & 2x^2 + 1 \\ D & xD & 1 \end{bmatrix},$$

Row reduction gives:

$$L^{(1)} = U_1 L = \begin{bmatrix} D^3 + x & 2D^2 & x^2 + x \\ 0 & -D & -D + 2x^2 + 1 \\ D & xD & 1 \end{bmatrix}.$$

Not column reduced.

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Column reduction then gives;

$$L^{(2)} = L^{(1)}V_1 = \begin{bmatrix} 2x & 2D^2 & x^2 + x \\ D^2 & -D & -D + 2x^2 + 1 \\ -xD^2 + 2D & xD & 1 \end{bmatrix}.$$

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Consider the matrix differential operator given by

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Row reduction then gives;

$$L^{(3)} = U_2 L^{(2)} = \begin{bmatrix} 2x & 2D^2 & x^2 + x \\ 2D & 0 & -xD + 2x^3 + x + 1 \\ -xD^2 + 2D & xD & 1 \end{bmatrix}.$$

Now row and column reduced.

# Form of Simultaneous Row-Column Form

## Theorem

Let  $L(D) \in \mathbb{K}[[x]]^{m \times n}[D]$  be simultaneous row-column reduced.  
Can permute the rows and columns of  $L(D)$  so it has block form :

$$\left[ \begin{array}{ccc|c} L_{11} & \cdots & L_{1k} & 0 \\ \vdots & \ddots & \vdots & \vdots \\ L_{k1} & \cdots & L_{kk} & 0 \\ \hline 0 & \cdots & 0 & 0 \end{array} \right]$$

$L_{ii}$  are block square matrices satisfying

- (a)  $L_{ii}$  row & column reduced, same row and column degree,
- (b)  $\deg(L_{ii}) > \deg(L_{i+1,i+1})$  for all  $i$ ,
- (c)  $\deg(L_{ij}) \leq \deg(L_{ii})$  for  $j < i$ ,  $\deg(L_{ij}) < \deg(L_{ii})$  for  $j > i$ ,
- (d)  $\deg(L_{ij}) \leq \deg(L_{jj})$  for  $i < j$ ,  $\deg(L_{ij}) < \deg(L_{jj})$  for  $i > j$ .

## Example : Operator of Degree 8

$$\begin{bmatrix} 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 \\ 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 & 8 \end{bmatrix}$$

## Example; Row Reduced Form

8	8	8	8	8	8	8	8	8	8	8	8	8
8	8	8	8	8	8	8	8	8	8	8	8	8
8	8	8	8	8	8	8	8	8	8	8	8	8
8	8	8	8	8	8	8	8	8	8	8	8	8
6	6	6	6	6	6	6	6	6	6	6	6	6
6	6	6	6	6	6	6	6	6	6	6	6	6
5	5	5	5	5	5	5	5	5	5	5	5	5
3	3	3	3	3	3	3	3	3	3	3	3	3
3	3	3	3	3	3	3	3	3	3	3	3	3
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2

## Example; Row Reduced Form

8	8	8	8	8	8	8	8	8	8	8	8	8
8	8	8	8	8	8	8	8	8	8	8	8	8
8	8	8	8	8	8	8	8	8	8	8	8	8
8	8	8	8	8	8	8	8	8	8	8	8	8
6	6	6	6	6	6	6	6	6	6	6	6	6
6	6	6	6	6	6	6	6	6	6	6	6	6
5	5	5	5	5	5	5	5	5	5	5	5	5
3	3	3	3	3	3	3	3	3	3	3	3	3
3	3	3	3	3	3	3	3	3	3	3	3	3
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2

# Example

8	8	8	8	8	8	8	8	8	8	8	8	8
8	8	8	8	8	8	8	8	8	8	8	8	8
8	8	8	8	8	8	8	8	8	8	8	8	8
8	8	8	8	8	8	8	8	8	8	8	8	8
6	6	6	6	6	6	6	6	6	6	6	6	6
6	6	6	6	6	6	6	6	6	6	6	6	6
5	5	5	5	5	5	5	5	5	5	5	5	5
3	3	3	3	3	3	3	3	3	3	3	3	3
3	3	3	3	3	3	3	3	3	3	3	3	3
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2



# Example

8	8	8	8		7	7	7	7	7	7	7	7	7
8	8	8	8		7	7	7	7	7	7	7	7	7
8	8	8	8		7	7	7	7	7	7	7	7	7
8	8	8	8		7	7	7	7	7	7	7	7	7
6	6	6	6		6	6	6	6	6	6	6	6	6
6	6	6	6		6	6	6	6	6	6	6	6	6
5	5	5	5		5	5	5	5	5	5	5	5	5
3	3	3	3		3	3	3	3	3	3	3	3	3
3	3	3	3		3	3	3	3	3	3	3	3	3
2	2	2	2		2	2	2	2	2	2	2	2	2
2	2	2	2		2	2	2	2	2	2	2	2	2
2	2	2	2		2	2	2	2	2	2	2	2	2
2	2	2	2		2	2	2	2	2	2	2	2	2

# Form of Leading Coefficient

*	*	*	*		0	0	0	0	0	0	0	0	0	0
*	*	*	*		0	0	0	0	0	0	0	0	0	0
*	*	*	*		0	0	0	0	0	0	0	0	0	0
*	*	*	*		0	0	0	0	0	0	0	0	0	0
*	*	*	*		0	0	0	0	0	0	0	0	0	0
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*	*	*	*		*	*	*	*	*	*	*	*	*	*
*	*	*	*		*	*	*	*	*	*	*	*	*	*

# Example

8	8	8	8		7	7	7	7	7	7	7	7	7
8	8	8	8		7	7	7	7	7	7	7	7	7
8	8	8	8		7	7	7	7	7	7	7	7	7
8	8	8	8		7	7	7	7	7	7	7	7	7
6	6	6	6		6	6	6	6	6	6	6	6	6
6	6	6	6		6	6	6	6	6	6	6	6	6
5	5	5	5		5	5	5	5	5	5	5	5	5
3	3	3	3		3	3	3	3	3	3	3	3	3
3	3	3	3		3	3	3	3	3	3	3	3	3
2	2	2	2		2	2	2	2	2	2	2	2	2
2	2	2	2		2	2	2	2	2	2	2	2	2
2	2	2	2		2	2	2	2	2	2	2	2	2
2	2	2	2		2	2	2	2	2	2	2	2	2

# Form of Leading Coefficient

*	*	*	*	0	0	0	0	0	0	0	0	0
*	*	*	*	0	0	0	0	0	0	0	0	0
*	*	*	*	0	0	0	0	0	0	0	0	0
*	*	*	*	0	0	0	0	0	0	0	0	0
*	*	*	*	0	0	0	0	0	0	0	0	0
*	*	*	*	*	*	0	0	0	0	0	0	0
*	*	*	*	*	*	0	0	0	0	0	0	0
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# Example

8	8	8	8	7	7	7	7	7	7	7	7	7
8	8	8	8	7	7	7	7	7	7	7	7	7
8	8	8	8	7	7	7	7	7	7	7	7	7
8	8	8	8	7	7	7	7	7	7	7	7	7
6	6	6	6	6	6	5	5	5	5	5	5	5
6	6	6	6	6	6	5	5	5	5	5	5	5
5	5	5	5	5	5	5	5	5	5	5	5	5
3	3	3	3	3	3	3	3	3	3	3	3	3
3	3	3	3	3	3	3	3	3	3	3	3	3
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2

# Example

8	8	8	8	7	7	7	7	7	7	7	7	7
8	8	8	8	7	7	7	7	7	7	7	7	7
8	8	8	8	7	7	7	7	7	7	7	7	7
8	8	8	8	7	7	7	7	7	7	7	7	7
6	6	6	6	6	6	5	5	5	5	5	5	5
6	6	6	6	6	6	5	5	5	5	5	5	5
5	5	5	5	5	5	5	4	4	4	4	4	4
3	3	3	3	3	3	3	3	3	2	2	2	2
3	3	3	3	3	3	3	3	3	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2	2	2	2	2	2

## Example : Block Form

$$\begin{bmatrix} 8 & 7 & 7 & 7 & 7 \\ 6 & 6 & 5 & 5 & 5 \\ 5 & 5 & 5 & 4 & 4 \\ 3 & 3 & 3 & 3 & 2 \\ 2 & 2 & 2 & 2 & 2 \end{bmatrix}$$

## Example : Block Form

$$\begin{bmatrix} 8 & 7 & 7 & 7 & 6 \\ 6 & 6 & 5 & 5 & 4 \\ 5 & 5 & 5 & 4 & 3 \\ 3 & 3 & 3 & 3 & 1 \\ 2 & 2 & 2 & 2 & 2 \end{bmatrix}$$



## Example : Block Form

$$\begin{bmatrix} 8 & 7 & 7 & 7 & 5 \\ 6 & 6 & 5 & 5 & 3 \\ 5 & 5 & 5 & 4 & 2 \\ 3 & 3 & 3 & 3 & 1 \\ 2 & 2 & 2 & 2 & 2 \end{bmatrix}$$

## Example : Block Form

$$\begin{bmatrix} 8 & 7 & 7 & 7 & 5 \\ 6 & 6 & 5 & 5 & 3 \\ 5 & 5 & 5 & 2 & 1 \\ 3 & 3 & 3 & 3 & 1 \\ 2 & 2 & 2 & 2 & 2 \end{bmatrix}$$

## Example : Block Form

$$\begin{bmatrix} 8 & 7 & 7 & 7 & 5 \\ 6 & 6 & 4 & 3 & 2 \\ 5 & 5 & 5 & 2 & 1 \\ 3 & 3 & 3 & 3 & 1 \\ 2 & 2 & 2 & 2 & 2 \end{bmatrix}$$

## Example : Block Form

$$\begin{bmatrix} 8 & 7 & 7 & 7 & 5 \\ 6 & 6 & 4 & 2 & 1 \\ 5 & 5 & 5 & 2 & 1 \\ 3 & 3 & 3 & 3 & 1 \\ 2 & 2 & 2 & 2 & 2 \end{bmatrix}$$

## Example : Block Form

$$\begin{bmatrix} 8 & 6 & 6 & 5 & 4 \\ 6 & 6 & 4 & 2 & 1 \\ 5 & 5 & 5 & 2 & 1 \\ 3 & 3 & 3 & 3 & 1 \\ 2 & 2 & 2 & 2 & 2 \end{bmatrix}$$

## Example : Block Form

$$\begin{bmatrix} 8 & 6 & 5 & 3 & 2 \\ 6 & 6 & 4 & 2 & 1 \\ 5 & 5 & 5 & 2 & 1 \\ 3 & 3 & 3 & 3 & 1 \\ 2 & 2 & 2 & 2 & 2 \end{bmatrix}$$

## Example : Block Form

$$\begin{bmatrix} 8 & 5 & 4 & 2 & 1 \\ 6 & 6 & 4 & 2 & 1 \\ 5 & 5 & 5 & 2 & 1 \\ 3 & 3 & 3 & 3 & 1 \\ 2 & 2 & 2 & 2 & 2 \end{bmatrix}$$

## Example : Block Form

$$\begin{bmatrix} 8 & 5 & 4 & 2 & 1 \\ 5 & 6 & 4 & 2 & 1 \\ 4 & 4 & 5 & 2 & 1 \\ 2 & 2 & 2 & 3 & 1 \\ 1 & 1 & 1 & 1 & 2 \end{bmatrix}$$



## Example : Block Form

$$\begin{bmatrix} 8 & 5 & 4 & 2 & 1 \\ 5 & 6 & 4 & 2 & 1 \\ 4 & 4 & 5 & 2 & 1 \\ 2 & 2 & 2 & 3 & 1 \\ 1 & 1 & 1 & 1 & 2 \end{bmatrix}$$

- Handle coefficient growth in computation
  - Do all arithmetic in  $\mathbb{K}[[x]][D]$  (not  $\mathbb{K}((x))[D]$ )
  - Control growth via fraction-free algorithm
  - Method : structured linear systems of equations
  - Difficulties : everything mentioned in Mark's talk
- Direct methods for higher order eqns via normal forms
  - Translate : convert (H)  $\rightarrow$  solve (F)  $\rightarrow$  convert (H)