

CS 341: Algorithms

University of Waterloo

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Module 3: breadth-first search, depth-first search

Goals

This module:

- basics on **undirected graphs**
- undirected BFS and applications (shortest paths, bipartite graphs, connected components)
- undirected DFS and applications (cut vertices)
- basics on **directed graphs**
- directed DFS and applications (testing for cycles, topological sort, strongly connected components)

Undirected graphs

Definition, notation: a graph G is pair (V, E) :

- V is a finite set, whose elements are called **vertices**
- E is a finite set, whose elements are **unordered pairs of distinct vertices**, and are called **edges**.

Convention: n is the number of vertices, m is the number of edges.

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Data structures:

- **adjacency list:** an array $A[1..n]$ s.t. $A[v]$ is the **linked list** of all edges connected to v .
 $2m$ list cells, total size $\Theta(n + m)$, but testing if an edge exists is not $O(1)$
- **adjacency matrix:** a $(0, 1)$ matrix M of size $n \times n$, with $M[v, w] = 1$ iff $\{v, w\}$ is an edge.
size $\Theta(n^2)$, but testing if an edge exists is $O(1)$

Connected graphs, path, cycles, trees

Definition:

- **path**: a sequence v_1, \dots, v_k of vertices, with $\{v_i, v_{i+1}\}$ in E for all i . $k = 1$ is OK.
- **connected graph**: $G = (V, E)$ such that for all v, w in V , there is a path $v \rightsquigarrow w$
- **cycle**: a path v_1, \dots, v_k, v_1 with $k \geq 3$ and v_i 's pairwise distinct
- **tree**: a connected graph without any cycle
- **rooted tree**: a tree with a special vertex called **root**

Subgraphs, connected components

Definition:

- **subgraph** of $G = (V, E)$: a graph $G' = (V', E')$, where
 - $V' \subset V$
 - $E' \subset E$, with all edges E' joining vertices from V'
- **connected component** of $G = (V, E)$
 - a connected subgraph of G
 - that is not contained in a larger connected subgraph of G

Let $G_i = (V_i, E_i)$, $i = 1, \dots, s$ be the connected components of $G = (V, E)$.

- the V_i 's are a partition of V , with $\sum_i n_i = n$ $n_i = |V_i|$
- the E_i 's are a partition of E , with $\sum_i m_i = m$ $m_i = |E_i|$

Breadth-first search

Breadth-first exploration of a graph

BFS(G, s)

G : a graph with n vertices, given by adjacency lists

s : a vertex from G

1. let Q be an empty queue
2. let **visited** be an array of size n , with all entries set to **false**
3. enqueue(s, Q)
4. **visited**[s] \leftarrow **true**
5. **while** Q not empty **do**
6. $v \leftarrow$ dequeue(Q)
7. **for all** w neighbours of v **do**
8. **if** **visited**[w] is **false**
9. enqueue(w, Q)
10. **visited**[w] \leftarrow **true**

Complexity

Analysis:

- each vertex is enqueued at most once
- so each vertex is dequeued at most once
- so each adjacency list is read at most once

$O(n)$ for steps 5-6

For all v , write d_v = number of neighbours of v = length of $A[v]$ = **degree** of v .

Then total cost at step 7 is

$$O\left(\sum_v d_v\right) = O(m)$$

cf. the adjacency array A has $2m$ cells

(handshaking lemma)

Total: $O(n + m)$

Correctness

Claim

For all vertices v , if $\text{visited}[v]$ is true at the end, there is a path $s \rightsquigarrow v$ in G

Proof. Let $s = v_0, \dots, v_K$ be the vertices for which **visited** is set to true, in this order. We prove: **for all i , there is a path $s \rightsquigarrow v_i$** , by induction.

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- OK for $i = 0$
- suppose true for v_0, \dots, v_{i-1} .

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 $j < i$.

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because $\{v_j, v_i\}$ is in E , there is a path $s \rightsquigarrow v_i$

Correctness

Claim

For all vertices v , if there is a path $s \rightsquigarrow v$ in G , $\text{visited}[v]$ is true at the end

Proof. Let $v_0 = s, \dots, v_k = v$ be a path $s \rightsquigarrow v$. We prove $\text{visited}[v_i]$ is true for all i , by induction.

- $\text{visited}[v_0]$ is true
- if $\text{visited}[v_i]$ is true, we will examine all neighbours v of v_i

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so at the end of Step 7, all $\text{visited}[v]$ will be true, for v neighbour of v_i
in particular, $\text{visited}[v_{i+1}]$ will be true

Correctness

Summary

For all vertices v , there is a path $s \rightsquigarrow v$ in G **if and only if** $\text{visited}[v]$ is true at the end

Applications

- testing if there is a path $s \rightsquigarrow v$
- testing if G is connected

in $O(n + m)$.

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Summary

For all vertices v , there is a path $s \rightsquigarrow v$ in G **if and only if** $\text{visited}[v]$ is true at the end

Applications

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in $O(n + m)$.

Exercise

For a connected graph, $m \geq n - 1$.

Keeping track of parents and levels

BFS(G, s)

1. let Q be an empty queue
2. let **parent** be an array of size n , with all entries set to **NIL**
3. let **level** be an array of size n , with all entries set to ∞
4. enqueue(s, Q)
5. **parent**[s] $\leftarrow s$
6. **level**[s] $\leftarrow 0$
7. **while** Q not empty **do**
8. $v \leftarrow \text{dequeue}(Q)$
9. **for all** w neighbours of v **do**
10. **if** **parent**[w] is **NIL**
11. enqueue(w, Q)
12. **parent**[w] $\leftarrow v$
13. **level**[w] $\leftarrow \text{level}[v] + 1$

BFS tree

Definition: the **BFS tree** T is the subgraph made of:

- all w such that $\text{parent}[w] \neq \mathbf{NIL}$.
- all edges $\{w, \text{parent}[w]\}$, for w as above (except $w = s$)

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The BFS tree T is a tree

Proof: by induction on the vertices for which $\text{parent}[v]$ is not **NIL**

- when we set $\text{parent}[s] \leftarrow s$, only one vertex, no edge.
- suppose true before we set $\text{parent}[w] \leftarrow v$

v was in T before, w was not, so we add one vertex w and one edge $\{v, w\}$ to T

so T remains a tree

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so T remains a tree

Remark: we make it a **rooted** tree by choosing s as root

Shortest paths from the BFS tree

Sub-claim 1

The levels in the queue are non-decreasing

Proof: by induction, they are always as $[\ell, \dots, \ell]$ or as $[\ell, \dots, \ell, \ell + 1, \dots, \ell + 1]$

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Sub-claim 2

For all vertices u, v , if there is an edge $\{u, v\}$, then $\text{level}[v] \leq \text{level}[u] + 1$.

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For all vertices u, v , if there is an edge $\{u, v\}$, then $\text{level}[v] \leq \text{level}[u] + 1$.

Proof: when we dequeue u ,

- either we already saw the parent of v
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$$\text{level}[\text{parent}[v]] \leq \text{level}[u]$$

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Proof: when we dequeue u ,

- either we already saw the parent of v
- or u becomes the parent of v
- but $\text{level}[\text{parent}[v]] = \text{level}[v] - 1$

$$\text{level}[\text{parent}[v]] \leq \text{level}[u]$$

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Claim

For all v in G :

- there is a path $s \rightsquigarrow v$ in G iff there is a path $s \rightsquigarrow v$ in T
- if so, the path in T is a shortest path and $\text{level}[v] = \text{dist}(s, v)$

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Proof. First item: \implies was proved before

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- $\text{dist}(s, v) \leq \text{level}[v]$ (follow the path on T)

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- $\text{dist}(s, v) \leq \text{level}[v]$ (follow the path on T)
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 so $\text{level}[v_1] \leq 1$ sub-claim 2

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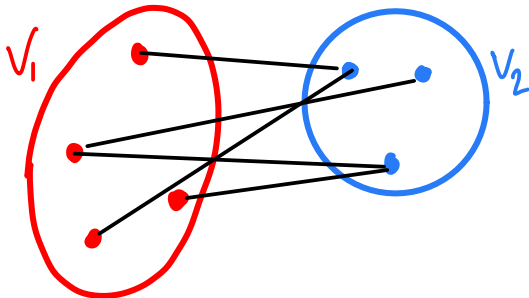
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 ... so $\text{level}[v_k] \leq k = \text{dist}(s, v)$ sub-claim 2

Bipartite graphs

Definition

- a graph $G = (V, E)$ is **bipartite** if there is a partition $V = V_1 \cup V_2$ such that all edges have **one end in V_1** and **one end in V_2** .



Using BFS to test bipartite-ness

Claim.

Suppose G connected, run BFS from any s , and set

- V_1 = vertices with odd level
- V_2 = vertices with even level.

Then G is bipartite if and only if all edges have one end in V_1 and one end in V_2 (testable in $O(n + m)$)

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Proof. \Leftarrow obvious.

For \Rightarrow , let W_1, W_2 be a bipartition. Because paths alternate between W_1, W_2 :

- V_1 (= vertices with odd level) is included in W_1 (say)
- V_2 (= vertices with even level) is included in W_2

So $V_1 = W_1$ and $V_2 = W_2$.

Computing the connected components

Idea: add an outer loop that runs BFS on successive vertices

Exercise

Fill in the details.

Complexity:

- each pass of BFS $O(n_i + m_i)$, if $G_i(V_i, E_i)$ is the i th connected component
- total $O(n + m)$

Depth-first search

Going depth-first

The idea:

- travel as deep as possible, as long as you can
- when you can't go further, backtrack.

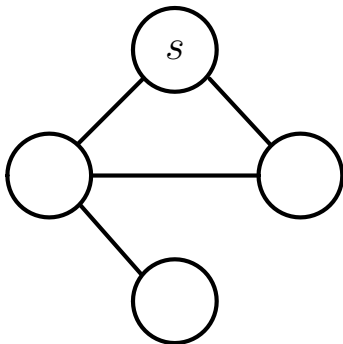
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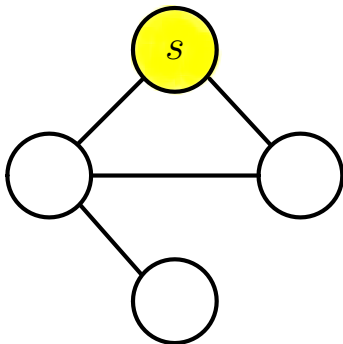


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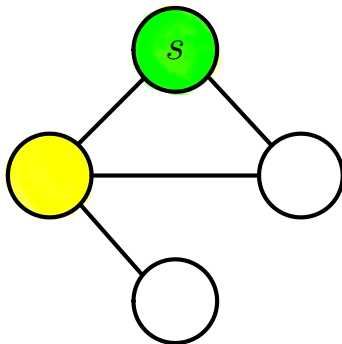


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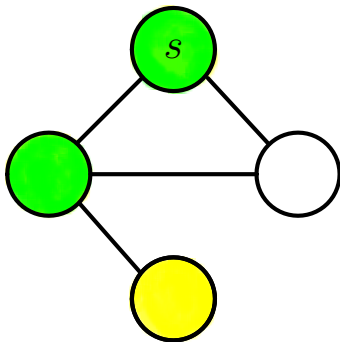


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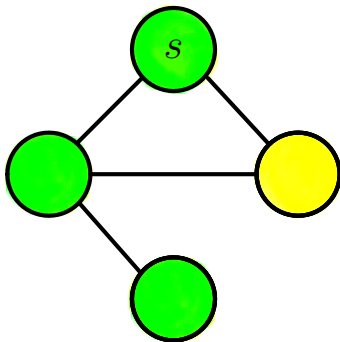


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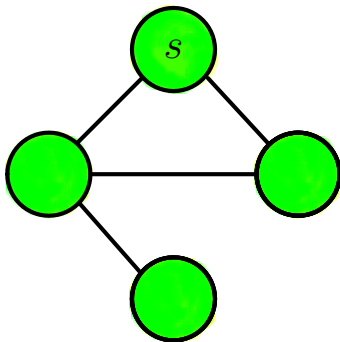


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Recursive algorithm

DFS(G)

G : a graph with n vertices, given by adjacency lists

1. let `visited` be an array of size n , with all entries set to **false**
2. **for all** v in G
3. **if** `visited`[v] is **false**
4. **explore**(v)

explore(v)

1. `visited`[v] = **true**
2. **for all** w neighbour of v **do**
3. **if** `visited`[w] = **false**
4. **explore**(w)

Remark: can add parent array as in BFS

The white path lemma

Claim

When we start exploring a vertex v , any w that can be connected to v by an **unvisited** path will be visited **explore**(v) is finished.

The white path lemma

Claim

When we start exploring a vertex v , any w that can be connected to v by an **unvisited** path will be visited **before** $\text{explore}(v)$ is finished.

Proof. Let $v_0 = v, \dots, v_k = w$ be a path $v \rightsquigarrow w$, with v_1, \dots, v_k not visited yet.

We prove: all v_i 's are visited before $\text{explore}(v)$ is finished.

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True for $i = 0$.

The white path lemma

Claim

When we start exploring a vertex v , any w that can be connected to v by an **unvisited** path will be visited **before** $\text{explore}(v)$ is finished.

Proof. Let $v_0 = v, \dots, v_k = w$ be a path $v \rightsquigarrow w$, with v_1, \dots, v_k not visited yet.

We prove: all v_i 's are visited before $\text{explore}(v)$ is finished.

True for $i = 0$.

Suppose true for $i < k$.

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- **if visited[v_{i+1}] is true when we reach Step 3**

OK: it means we visited it

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- **if visited[v_{i+1}] is true when we reach Step 3**
OK: it means we visited it
- **else, we will visit it just now**
OK: it will be done before $\text{explore}(v)$ is finished

Another basic property

Claim

If w is visited during **explore**(v), there is a path $v \rightsquigarrow w$.

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Proof. Same as for BFS.

Consequences

Previous properties: after we call **explore** at v_1, \dots, v_k in **DFS**, we have visited exactly the connected components containing v_1, \dots, v_k

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Shortest paths: no

Runtime: still $O(n + m)$

Iterative version?

explore(s)

1. let S be an empty stack
2. push(s, S)
3. visited[s] \leftarrow **true**
4. **while** S not empty **do**
5. $v \leftarrow$ pop(S)
6. **for all** w neighbours of v **do**
7. **if** visited[w] is **false**
8. push(w, S)
9. visited[w] \leftarrow **true**

Still depth-first?

Iterative version?

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9. visited[w] \leftarrow **true**

Still depth-first?

Exercise: fix this.

Trees, forest, ancestors and descendants

Previous observation:

- $\text{DFS}(G)$ gives a partition of G into vertex-disjoint rooted trees T_1, \dots, T_k
(DFS forest)

Definition. Suppose the DFS forest is T_1, \dots, T_k and let u, v be two vertices

- u is an **ancestor** of v if they are on the same T_i and u is on the path $\text{root} \rightsquigarrow v$
- equivalent: v is a **descendant** of u

Key property

Claim

All edges in G connect a vertex to one of its descendants or ancestors.

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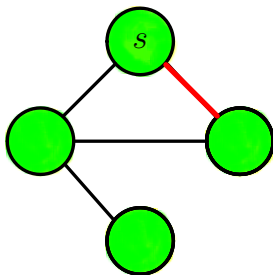
Proof. Let $\{v, w\}$ be an edge, and suppose we visit v first.

Then when we visit v , (v, w) is an unvisited path between v and w , so w will become a descendant of v (white path lemma)

Back edges

Definition.

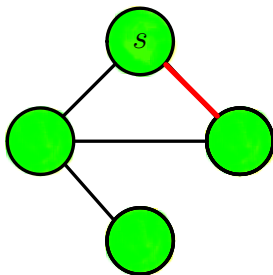
- a **back edge** is an edge in G connecting an ancestor to a descendant, which is **not** a tree edge.



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Observation

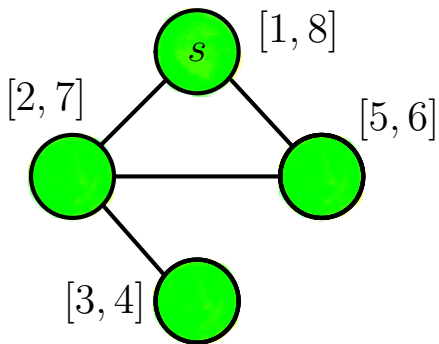
All edges are either **tree edges** or **back edges** (key property).

Start and finish times

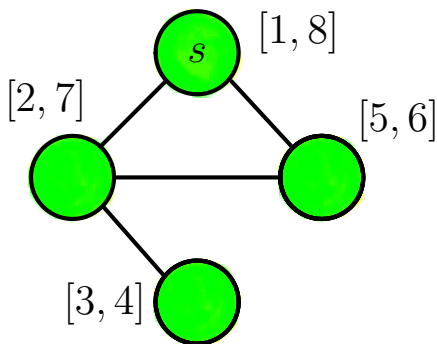
Set a variable t to 1 initially, create two arrays **start** and **finish**, and change **explore**:

```
explore( $v$ )  
1.   visited[ $v$ ] = true  
2.   start[ $v$ ] =  $t$   
3.    $t++$   
4.   for all  $w$  neighbour of  $v$  do  
5.       if visited[ $w$ ] = false  
6.           explore( $w$ )  
7.   finish[ $v$ ] =  $t$   
8.    $t++$ 
```

Example



Example



Observation:

- these intervals are either contained in one another, or disjoint

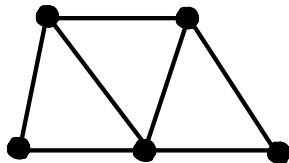
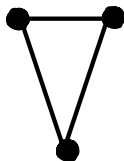
Cut vertices

Biconnectivity

Definition: $G = (V, E)$ **biconnected** if

- G is connected
- G stays connected if we remove any vertex (and all edges that contain it)

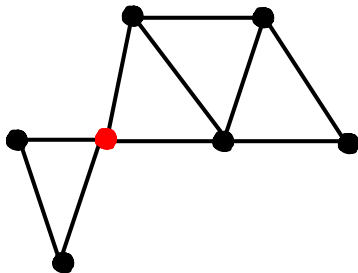
Two biconnected graphs:



Cut vertices

Definition: for G connected, a vertex v in G is a **cut vertex** if removing v (and all edges that contain it) makes G disconnected.

Also called **articulation points**

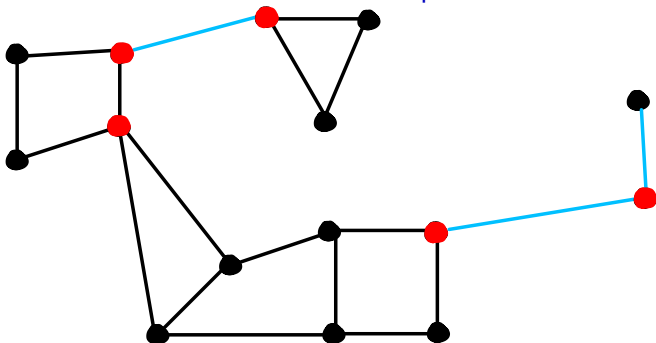


biconnected \iff no cut vertex

Aside: the shape of a connected undirected graph

Call **biconnected component** a biconnected subgraph that is not contained in a larger one

Then G can be seen as a **tree** of **biconnected components** connected at **cut vertices**



Blue edges are **cut edges**: removing them makes the graph disconnected

Finding the cut vertices (G connected)

Setup: we start from a **rooted DFS tree** T , knowing parent and level.

Warm-up

The root s is a cut vertex if and only if **it has more than one child**.

Proof.

- if s has one child, removing s leaves T connected. So s not a cut vertex.

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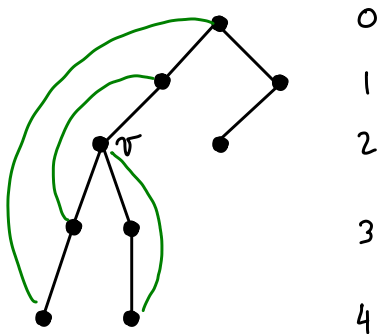
- if s has one child, removing s leaves T connected. So s not a cut vertex.
- suppose s has subtrees S_1, \dots, S_k , $k > 1$.

Key property: no edge connecting S_i to S_j for $i \neq j$. So removing s creates k connected components.

Finding the cut vertices (G connected)

Definition: for a vertex v , let

- $a(v) = \min\{\text{level}[w], \{v, w\} \text{ edge}\}$
- $m(v) = \min\{a(w), w \text{ descendant of } v\}$



$$a(v) = 1$$
$$m(v) = 0$$

Using the values $m(v)$

Claim

For any v (except the root), v is a cut vertex if and only if it has a child w with $m(w) \geq \text{level}[v]$.

Proof

- Take a child w of v , let T_w be the subtree at w . Let also T_v be the subtree at v .

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- Take a child w of v , let T_w be the subtree at w . Let also T_v be the subtree at v .
- If $m(w) < \text{level}[v]$, then there is an edge from T_w to a vertex above v . After removing v , T_w remains connected to the root.

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- If $m(w) \geq \text{level}[v]$, then all edges originating from T_w end in T_v .

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Proof: any edge originating from a vertex x in T_w ends at a level at least $\text{level}[v]$, and connects x to one of its ancestors or descendants (key property)

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Proof: any edge originating from a vertex x in T_w ends at a level at least $\text{level}[v]$, and connects x to one of its ancestors or descendants (key property)

So after removing v , T_w is disconnected from the root (except if v is the root)

Computing the values $m(v)$

Observation:

- if v has children w_1, \dots, w_k , then $m(v) = \min\{a(v), m(w_1), \dots, m(w_k)\}$

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Consequence:

- computing $a(v)$ is $O(d_v)$ $d_v = \text{degree of } v$
- knowing all $m(w_1), \dots, m(w_k)$, we get $m(v)$ in $O(d_v)$
- so all values $m(v)$ can be computed in $O(m)$
(remember $O(n + m) = O(m)$ when G connected)

Computing the values $m(v)$

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(remember $O(n + m) = O(m)$ when G connected)

testing the cut-vertex condition at v is $O(d_v)$, total $O(m)$

Exercise

write the pseudo-code

Directed graphs

Directed graphs basics

Definition:

- $G = (V, E)$ as in the undirected case, with the difference that edges are **(directed)** pairs (v, w)
 - edges also called **arcs**
 - usually, we allow **loops**, with $v = w$
 - v is the **source** node, w is the **target**
- a **path** is a sequence v_1, \dots, v_k of vertices, with (v_i, v_{i+1}) in E for all i . $k = 1$ is OK.
- a **cycle** is a path v_1, \dots, v_k, v_1 , $k \geq 1$
- a **directed acyclic graph** (DAG) is a directed graph with no cycle



Directed graphs basics

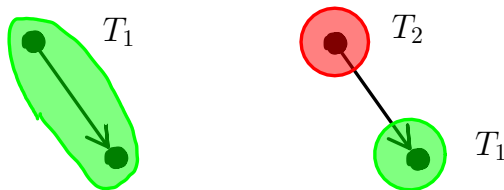
Data structures

- adjacency lists
- adjacency matrix (not symmetric anymore)

BFS and DFS for directed graphs

The algorithms work **without any change**. We will focus on **DFS**. Still true:

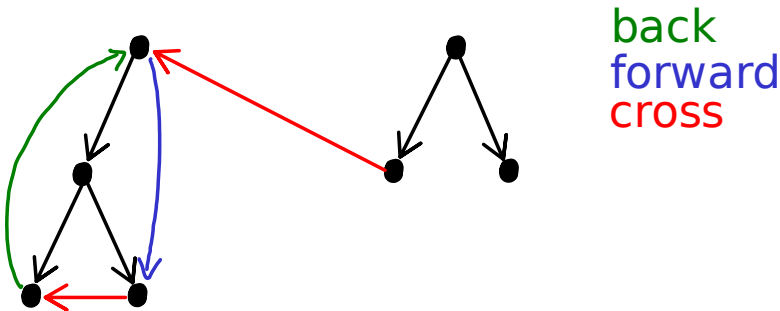
- we obtain a partition of V into **vertex-disjoint trees** T_1, \dots, T_k
- when we start exploring a vertex v , any w with an **unvisited path** $v \rightsquigarrow w$ becomes a descendant of v (white path lemma)
- properties of start and finish times
- but there can exist edges connecting the trees T_i



Classification of edges

Suppose we have a DFS forest. Edges of G are one of the following:

- **tree edges**
- **back edges:** from descendant to ancestor
- **forward edges:** from ancestor to descendant (but not tree edge)
- **cross edges:** all others



(depends on the order of vertices we chose in the main DFS loop)

Classification of edges

explore(v)

- ```

1. visited[v] = true
2. start[v] = t, t++
3. for all w neighbour of v do
4. if visited[w] = false
5. explore(w) (v, w) tree edge
6. finish[v] = t, t++

```

If  $w$  was visited:

- if  $w$  not finished,  $(v, w)$  **back edge**
- else if  $\text{start}[v] < \text{start}[w] < \text{finish}[w]$ ,  $(v, w)$  **forward edge**
- else,  $\text{start}[w] < \text{finish}[w] < \text{start}[v]$ ,  $(v, w)$  **cross edge**



# Testing acyclicity

## Claim

$G$  has a cycle if and only if there is a back edge in the DFS forest

## Proof

- Suppose there is a back edge  $(v, w)$ . Then  $v$  is a descendant of  $w$ , so there is a path  $w \rightsquigarrow v$ , and a cycle  $w \rightsquigarrow v \rightarrow w$
- Suppose there is a cycle  $v_1, \dots, v_{k-1}, v_k = v_1$ . Up to renumbering, assume we find  $v_1$  first in the DFS.

Starting from  $v_1$ , we will reach  $v_{k-1}$  (white path lemma). We check the edge  $(v_{k-1}, v_1)$ , and  $v_1$  is not finished. So back edge.

**Consequence:** acyclicity test in  $O(n + m)$

## Strong connectivity

**Definition.** A directed graph  $G$  is **strongly connected** if for all  $v, w$  in  $G$ , there is a path  $v \rightsquigarrow w$  (and thus a path  $w \rightsquigarrow v$ ).

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## Algorithm:

- call **explore twice**, starting from a same vertex  $s$
- edges reversed the second time

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## Algorithm:

- call **explore twice**, starting from a same vertex  $s$
- edges reversed the second time

## Correctness:

- first run tells whether for all  $v$ , there is a path  $s \rightsquigarrow v$
- second one tells whether for all  $v$ , there is a path  $s \rightsquigarrow v$  in the reverse graph (which is a path  $v \rightsquigarrow s$  in  $G$ )

**Consequence:** test in  $O(n + m)$

# Structure of directed graphs

**Definition:** a **strongly connected component** of  $G$  is

- a subgraph of  $G$
- which is strongly connected
- but not contained in a larger strongly connected subgraph of  $G$ .

## Exercise

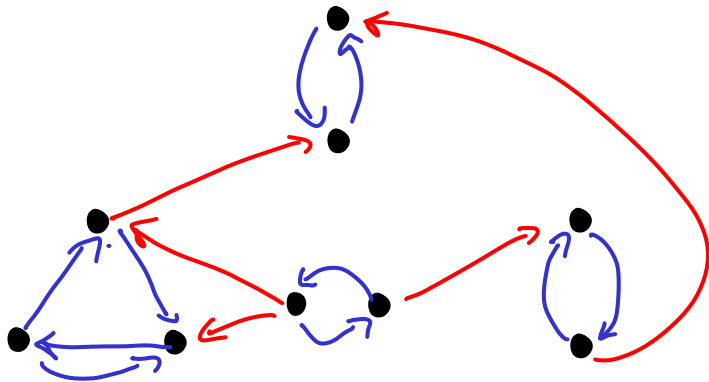
The vertices of strongly connected components form a partition of  $V$ .

## Exercise

$v$  and  $w$  are in the same strongly connected component if and only if there are paths  $v \rightsquigarrow w$  and  $w \rightsquigarrow v$ .

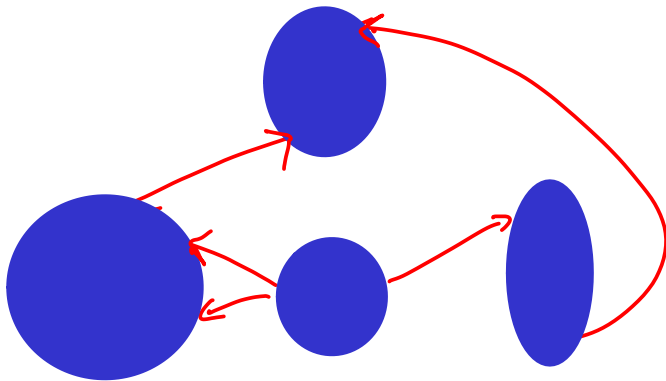
## Structure of directed graphs

A directed graph  $G$  can be seen as a **DAG** of disjoint **strongly connected components**.



## Structure of directed graphs

A directed graph  $G$  can be seen as a DAG of disjoint strongly connected components.



# Kosaraju's algorithm for strongly connected components

**Definition:** for a directed graph  $G = (V, E)$ , the **reverse** (or **transpose**) graph  $G^T = (V, E^T)$  is the graph with same vertices, and reversed edges.

**SCC**( $G$ )

1. run a DFS on  $G$  and record finish times
2. run a DFS on  $G^T$ , with vertices ordered in **decreasing finish time**
3. return the trees in the DFS forest of  $G^T$

**Complexity:**  $O(n + m)$  (don't forget the time to reverse  $G$ )

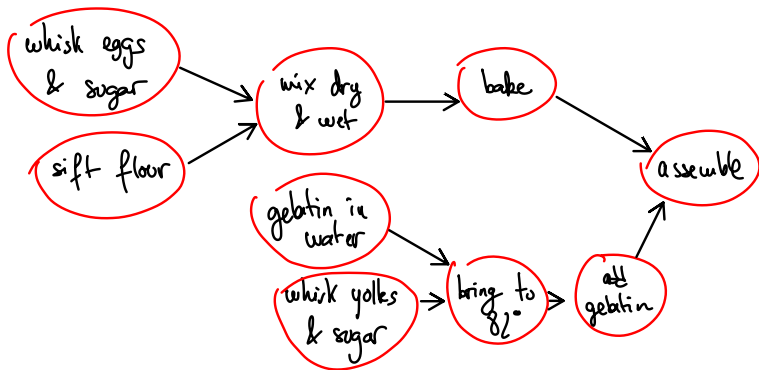
## Exercise

check that the strongly connected components of  $G$  and  $G^T$  are the same



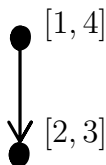
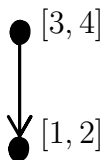
## Topological ordering

**Definition:** Suppose  $G = (V, E)$  is a DAG. A **topological order** is an ordering  $<$  of  $V$  such that for any edge  $(v, w)$ , we have  $v < w$ .



No such order if there are cycles.

## From a DFS forest



### Observation:

- start times do not help
- finish times do, but we have to reverse their order

## From a DFS forest

### Claim

Suppose that  $V$  is ordered using the reverse of the finishing order:  
 $v < w \iff \text{finish}[w] < \text{finish}[v]$ .

This is a topological order.

**Proof.** Have to prove: for any edge  $(v, w)$ ,  $\text{finish}[w] < \text{finish}[v]$ .

- if we discover  $v$  before  $w$ ,  $w$  will become a descendant of  $v$  (white path lemma), and we finish exploring it before we finish  $v$ .
- if we discover  $w$  before  $v$ , because there is no path  $w \rightsquigarrow v$  ( $G$  is a DAG), we will finish  $w$  before we start  $v$ .

**Consequence:** topological order in  $O(n + m)$ .

# Kosaraju's algorithm: proof of correctness (bonus material)

## Correctness 1/3

**Want to prove:** for any vertices  $v, w$ , the following are equivalent.

- (1)  $v$  and  $w$  are in the same strongly connected component of  $G$
- (2)  $v$  and  $w$  are in the same tree in the DFS forest of  $G^T$  (with vertices ordered in decreasing finish time)

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**Proof of 1  $\implies$  2** (order of the vertices does not matter here)

Let  $C$  be the strongly connected component of  $G$  that contains  $v$  and  $w$

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**Proof of 1  $\implies$  2** (order of the vertices does not matter here)

Let  $C$  be the strongly connected component of  $G$  that contains  $v$  and  $w$

Let  $s$  be the first vertex of  $C$  that we visit in the DFS of  $G^T$

- there is a path  $s \rightsquigarrow v$  in  $G^T$
- all vertices on this path are in  $C$  (easy)
- so they are all unvisited when we arrive at  $s$
- so  $v$  becomes a descendant of  $s$
- same for  $w$

**white path lemma**

## Correctness 2/3

**Proof of 2  $\implies$  1.**

Let  $T$  be the tree in the DFS forest of  $G^T$  that contains  $v$  and  $w$ , with root  $s$

We prove that for **every** vertex  $t$  in  $T$ ,  $s$  **and**  $t$  **are in the same strongly connected component of**  $G$ .



## Correctness 2/3

### Proof of 2 $\implies$ 1.

Let  $T$  be the tree in the DFS forest of  $G^T$  that contains  $v$  and  $w$ , with root  $s$

We prove that for every vertex  $t$  in  $T$ ,  $s$  and  $t$  are in the same strongly connected component of  $G$ .

(1) for all  $t$  in  $T$ , there is a path  $s \rightsquigarrow t$  in  $G^T$ , so there is a path  $t \rightsquigarrow s$  in  $G$

## Correctness 2/3

### Proof of 2 $\implies$ 1.

Let  $T$  be the tree in the DFS forest of  $G^T$  that contains  $v$  and  $w$ , with root  $s$

We prove that for every vertex  $t$  in  $T$ ,  $s$  and  $t$  are in the same strongly connected component of  $G$ .

- (1) for all  $t$  in  $T$ , there is a path  $s \rightsquigarrow t$  in  $G^T$ , so there is a path  $t \rightsquigarrow s$  in  $G$
- (2) now we prove: for all  $t$  in  $T$ ,  $t$  is a descendant of  $s$  in the DFS forest of  $G$  (this gives a path  $s \rightsquigarrow t$  in  $G$ )

## Correctness 3/3

**Want to prove:** for all  $t$  in  $T$ ,  $t$  is a descendant of  $s$  in the DFS forest of  $G$ .

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**By induction:** suppose it is true for some  $t$  in  $T$ , and prove it is true for its children.

So let  $u$  be a child of  $t$  in  $T$ .

## Correctness 3/3

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- since  $(t, u)$  is in  $T$ ,  $(u, t)$  is in  $G$ . With previous item, we get:  $t$  is a descendant of  $u$  in the DFS of  $G$  (white path)

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- so (2) impossible, and we must have (1)
- shows that  $u$  is a descendant of  $s$  in the DFS forest of  $G$