

CS 341: Algorithms

University of Waterloo

Éric Schost

eschost@uwaterloo.ca

Lecture 1: welcome

Staff

Instructors

- Armin Jamshidpey
- Lap Chi Lau
- Éric Schost

ISC

- Sylvie Davies (sldavies)

Office hours (ÉS, DC 3627)

- Tuesday, 12:30 - 1:30
- Thursday 1 - 2pm

Electronic communication

Piazza

- sign up using your uwaterloo email address
- <http://piazza.com/uwaterloo.ca/winter2023/cs341>
- posting solutions to assignments is forbidden

email

- use your uwaterloo address

Assignments, exams, project, etc

- **5 assignments** (40%)
 - include programming problems
 - due on Friday (Jan27, Feb10, Mar10, Mar24, Apr07)
- **Midterm** (20%)
 - Friday February 17, 04:30-06:00pm
- **Final** (40%)
 - TBA

References

- **Slides and notes**
 - posted before the lecture (expectedly) on learn
- **Textbooks**
 - **Introduction to Algorithms**, Cormen, Leiserson, Rivest, Stein
 - **Algorithm Design**, Kleinberg, Tardos
 - **Algorithms**, Dasgupta, Papadimitriou, Vazirani

This course

What you should know

- CS240-level data structures and algorithms
- big-O notation
- maybe a bit of math (matrices, for instance)

What we will do

- a lot of algorithms
- pseudo-code
- proofs for correctness and runtime

What we will not do

- read/write code in class

Tentative syllabus

- divide-and-conquer, master theorem
- breadth-first and depth-first search
- greedy algorithms
- dynamic programming
- flows and cuts
- NP-completeness

Cost of algorithms

Inputs

- parameterized by an integer n , called the **size**
- e.g., length of an array that we want to work with

$T(I)$ = runtime on input I

runtime of a particular instance

$T(n) = \max_{I \text{ of size } n} T(I)$

worst-case runtime

$T_{\text{avg}}(n) = \frac{\sum_{I \text{ of size } n} T(I)}{\text{number of inputs of size } n}$

average runtime, not used much in this course

Remark: we will sometimes use more than one parameter

- numbers of rows and columns in a matrix
- vertices and edges in a graph

Cost of algorithms

Inputs

- parameterized by an integer n , called the **size**
- e.g., length of an array that we want to work with

$T(I)$ = runtime on input I

runtime of a particular instance

$T(n) = \max_{I \text{ of size } n} T(I)$

worst-case runtime

$T_{\text{avg}}(n) = \frac{\sum_{I \text{ of size } n} T(I)}{\text{number of inputs of size } I}$

average runtime, not used much in this course

Remark: we will sometimes use more than one parameter

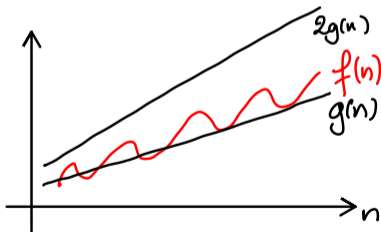
- numbers of rows and columns in a matrix
- vertices and edges in a graph

Asymptotic notation

Consider two functions $f(n), g(n)$ with values in $\mathbb{R}_{>0}$

big-O.

1. we say that $f(n) \in O(g(n))$ if
there exist $C > 0$ and n_0 , such that for $n \geq n_0$, $f(n) \leq Cg(n)$

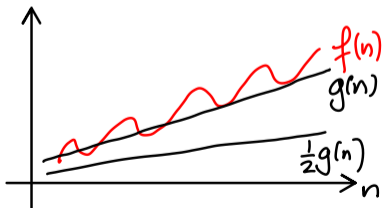


Asymptotic notation

Consider two functions $f(n), g(n)$ with values in $\mathbb{R}_{>0}$

big- Ω .

1. we say that $f(n) \in \Omega(g(n))$ if
there exist $C > 0$ and n_0 such that for $n \geq n_0$, $f(n) \geq Cg(n)$
2. equivalent to $g(n) \in O(f(n))$

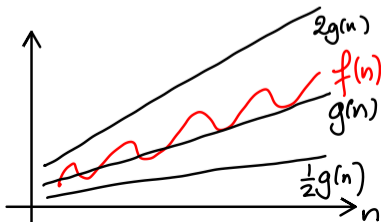


Asymptotic notation

Consider two functions $f(n), g(n)$ with values in $\mathbb{R}_{>0}$

Θ .

1. we say that $f(n) \in \Theta(g(n))$ if there exist $C, C' > 0$ and n_0 such that for $n \geq n_0$, $C'g(n) \leq f(n) \leq Cg(n)$
2. equivalent to $f(n) \in O(g(n))$ and $f(n) \in \Omega(g(n))$.
3. in particular true if $\lim_{\infty} f(n)/g(n) = C$ for some $0 < C < \infty$

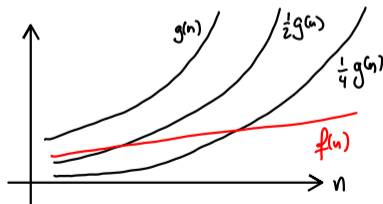


Asymptotic notation

Consider two functions $f(n), g(n)$ with values in $\mathbb{R}_{>0}$

little-o.

1. we say that $f(n) \in o(g(n))$ if
for all $C > 0$, there exists n_0 such that for $n \geq n_0$, $f(n) \leq Cg(n)$
2. equivalent to $\lim_{n \rightarrow \infty} f(n)/g(n) = 0$.

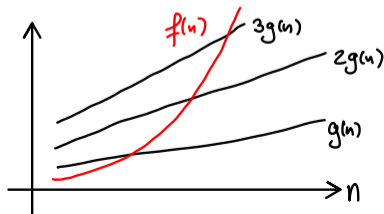


Asymptotic notation

Consider two functions $f(n), g(n)$ with values in $\mathbb{R}_{>0}$

little- ω .

1. we say that $f(n) \in \omega(g(n))$ if
for all $C > 0$, there exists n_0 such that for $n \geq n_0$, $f(n) > Cg(n)$
2. equivalent to $\lim_{n \rightarrow \infty} f(n)/g(n) = \infty$
3. equivalent to $g(n) \in o(f(n))$.



Examples

- $n^k + c_{k-1}n^{k-1} + \dots + c_0$ is in $\Theta(n^k)$
- $n^{O(1)}$ means **(at most) polynomial in n**
- $n \log(n)$ is in $O(n^2)$ and $\Omega(n)$
- 2^{n-1} is in $\Theta(2^n)$
- $(n-1)!$ is **not** in $\Theta(n!)$, it is in $o(n!)$

c_i and k constant!

Definitions for several parameters

terminology - What is the meaning of $SO(m+n)$? - Computer Science Stack Exchange - Google Chrome

terminology - W | x +

cs.stackexchange.com/questions/3149/what-is-the-meaning-of-omv/3151#3151

StackExchange Search on Computer Science... ? ☰ Log in Sign up

Home

PUBLIC

Questions

Tags

Users

Companies

Unanswered

TEAMS

Stack Overflow for Teams – Start collaborating and sharing organizational


32

Believe it or not, it seems (in my experience) that many algorithms people have actually not thought about what the big O notation formally means, and when asked about it, you can get several different answers. Some issues are discussed in the paper [On Asymptotic Notation with Multiple Variables](#) by Rodney R. Howell.

Curiously, it also seems that most introductory algorithms courses spend lots of time being very formal about big O notation with a single variable, and then the next weeks happily use the notation for graph algorithms with several variables in a casual way, without discussing what the notation actually means.

Share Cite Improve this answer Follow

answered Aug 13, 2012 at 19:49

 Kristoffer Arnsfelt Hansen

561 3 7

Definitions for several parameters

Consider two functions $f(n), g(n)$ with values in $\mathbb{R}_{>0}$

$f(n, m)$ is in $O(g(n, m))$ if there exist C, n_0, m_0 such that $f(n, m) \leq Cg(n, m)$ for $n \geq n_0$ **or** $m \geq m_0$

Remark:

- less strict definition: there exist C, n_0, m_0 such that $f(n, m) \leq Cg(n, m)$ for $n \geq n_0$ **and** $m \geq m_0$
- will not matter too much which one we choose

Computational model: word RAM

Rough definition:

- memory locations contain **integer words** of **b bits** each
- assume $b \geq \log(n)$ for input size n
- Random Access Memory: can **access any memory location** at unit cost
- **basic operations on words** have unit costs

No need to worry about loop counters, array indices, \dots , as long as they are $n^{O(1)}$.

Computational model: word RAM

Rough definition:

- memory locations contain **integer words** of **b bits** each
- assume $b \geq \log(n)$ for input size n
- Random Access Memory: can **access any memory location** at unit cost
- **basic operations on words** have unit costs

No need to worry about loop counters, array indices, \dots , as long as they are $n^{O(1)}$.

Sum($A[1..n]$)

1. $s \leftarrow 0$
2. **for** $i = 1, \dots, n$
3. $s \leftarrow s + A[i]$

If all entries of A fit in a word, time $O(n)$

Computational model: word RAM

Rough definition:

- memory locations contain **integer words** of **b bits** each
- assume $b \geq \log(n)$ for input size n
- Random Access Memory: can **access any memory location** at unit cost
- **basic operations on words** have unit costs

No need to worry about loop counters, array indices, \dots , as long as they are $n^{O(1)}$.

Product($A[1..n]$)

1. $s \leftarrow 1$
2. **for** $i = 1, \dots, n$
3. $s \leftarrow s \times A[i]$

All entries of A fit in a word. Runtime?

Computational model: word RAM

Rough definition:

- memory locations contain **integer words** of **b bits** each
- assume $b \geq \log(n)$ for input size n
- Random Access Memory: can **access any memory location** at unit cost
- **basic operations on words** have unit costs

No need to worry about loop counters, array indices, \dots , as long as they are $n^{O(1)}$.

More examples

- matrix multiplication algorithms (with word-size inputs) are OK
- other matrix algorithms (Gaussian elimination) need more care
- (weighted) graph algorithms (weights fit in a word) are usually OK

Practical relevance?

1. big-O is only an upper bound

- typical example: 1 is in $O(n^2)$ and n is in $O(n)$, but ...
- try to give Θ 's if possible

2. big-anything hides constants

- this is by design
- a $\Theta(n^2)$ will beat a $\Theta(n^3)$ algorithm **eventually**
- **galactic algorithms**: become practically relevant for astronomical input sizes (fast matrix or integer multiplication)

3. we use a simplified model

- artificial computational model
- focus on “operations”, forget memory requirements, data locality, ...

Case study: maximum subarray

Task

Given an array $A[1..n]$, find a contiguous subarray $A[i..j]$ that maximizes the sum $A[i] + \dots + A[j]$.

Example. Given

$$A = [10, -5, 4, 3, -5, 6, -1, -1]$$

the subarray

$$A[1..6] = [10, -5, 4, 3, -5, 6]$$

has sum $10 + \dots + 6 = 13$. It is the best we can do.

Convention. we also allow $A[i..j]$ empty, with sum equal to zero.

Brute force algorithm

Test2(A)

1. $\text{max} \leftarrow 0$
2. **for** $i \leftarrow 1$ **to** n **do**
3. **for** $j \leftarrow i$ **to** n **do**
4. $\text{sum} \leftarrow 0$
5. **for** $k \leftarrow i$ **to** j **do**
6. $\text{sum} \leftarrow A[k]$
7. **return** max

Brute force algorithm

BruteForce(A)

```
1.  opt  $\leftarrow$  0
2.  for  $i \leftarrow 1$  to  $n$  do
3.      for  $j \leftarrow i$  to  $n$  do
4.          sum  $\leftarrow$  0
5.          for  $k \leftarrow i$  to  $j$  do
6.              sum  $\leftarrow$  sum +  $A[k]$ 
7.          if sum > opt
8.              opt  $\leftarrow$  sum
9.  return opt
```

Brute force algorithm

BruteForce(A)

```
1.  opt  $\leftarrow$  0
2.  for  $i \leftarrow 1$  to  $n$  do
3.      for  $j \leftarrow i$  to  $n$  do
4.          sum  $\leftarrow$  0
5.          for  $k \leftarrow i$  to  $j$  do
6.              sum  $\leftarrow$  sum +  $A[k]$ 
7.              if sum > opt
8.                  opt  $\leftarrow$  sum
9.  return opt
```

Runtime: $\Theta(n^3)$

Remark: could also return the indices i, j giving the max

Improved brute force algorithm

Observation: we recompute the same sum many times in the j loop.

Improved brute force algorithm

Observation: we recompute the same sum many times in the j loop.

BetterBruteForce(A)

```
1.   opt ← 0
2.   for  $i \leftarrow 1$  to  $n$  do
3.       sum ← 0
4.       for  $j \leftarrow i$  to  $n$  do
5.           sum ← sum +  $A[j]$ 
6.           if sum > opt
7.               opt ← sum
8.   return opt
```

Runtime: $\Theta(n^2)$

Divide-and-conquer

Idea: solve the problem twice in size $n/2$ (we assume n is a power of 2).

Divide-and-conquer

Idea: solve the problem twice in size $n/2$ (we assume n is a power of 2). Then the optimal subarray (if not empty)

1. is completely in the left half $A[1..n/2]$
2. or is completely in the right half $A[n/2 + 1..n]$
3. or contains **both** $A[n/2]$ **and** $A[n/2 + 1]$

(cases mutually exclusive.)

Divide-and-conquer

Idea: solve the problem twice in size $n/2$ (we assume n is a power of 2). Then the optimal subarray (if not empty)

1. is completely in the left half $A[1..n/2]$
2. or is completely in the right half $A[n/2 + 1..n]$
3. or contains **both** $A[n/2]$ **and** $A[n/2 + 1]$

(cases mutually exclusive.)

To find the optimal subarray in case **3**, write

$$A[i] + \cdots + A[j] = A[i] + \cdots + A[n/2] + A[n/2 + 1] + \cdots + A[j]$$

Divide-and-conquer

Idea: solve the problem twice in size $n/2$ (we assume n is a power of 2). Then the optimal subarray (if not empty)

1. is completely in the left half $A[1..n/2]$
2. or is completely in the right half $A[n/2 + 1..n]$
3. or contains **both** $A[n/2]$ **and** $A[n/2 + 1]$

(cases mutually exclusive.)

To find the optimal subarray in case **3**, write

$$A[i] + \cdots + A[j] = A[i] + \cdots + A[n/2] + A[n/2 + 1] + \cdots + A[j]$$

more abstractly: $F(i, j) = f(i) + g(j)$, for i in $1, \dots, n/2$ and j in $n/2 + 1, \dots, n$

To maximize $F(i, j)$, maximize $f(i)$ and $g(j)$ **independently**.

Divide-and-conquer

Idea: solve the problem twice in size $n/2$ (we assume n is a power of 2). Then the optimal subarray (if not empty)

1. is completely in the left half $A[1..n/2]$
2. or is completely in the right half $A[n/2 + 1..n]$
3. or contains **both** $A[n/2]$ **and** $A[n/2 + 1]$

(cases mutually exclusive.)

To find the optimal subarray in case **3**, write

$$A[i] + \cdots + A[j] = A[i] + \cdots + A[n/2] + A[n/2 + 1] + \cdots + A[j]$$

more abstractly: $F(i, j) = f(i) + g(j)$, for i in $1, \dots, n/2$ and j in $n/2 + 1, \dots, n$

To maximize $F(i, j)$, maximize $f(i)$ and $g(j)$ **independently**.

Exercise: can we use $A[i] + \cdots + A[j] = A[i] + \cdots + A[n] - A[n] - \cdots - A[j + 1]$?

Maximizing half-sums

MaximizeLowerHalf(A)

1. $\text{opt} \leftarrow A[n/2]$
2. $\text{sum} \leftarrow A[n/2]$
3. **for** $i = n/2 - 1, \dots, 1$ **do**
4. $\text{sum} \leftarrow \text{sum} + A[i]$
5. **if** $\text{sum} > \text{opt}$
6. $\text{opt} \leftarrow \text{sum}$
7. **return** opt

Runtime: $\Theta(n)$

Maximizing half-sums

MaximizeLowerHalf(A)

1. $\text{opt} \leftarrow A[n/2]$
2. $\text{sum} \leftarrow A[n/2]$
3. **for** $i = n/2 - 1, \dots, 1$ **do**
4. $\text{sum} \leftarrow \text{sum} + A[i]$
5. **if** $\text{sum} > \text{opt}$
6. $\text{opt} \leftarrow \text{sum}$
7. **return** opt

Runtime: $\Theta(n)$

MaximizeUpperHalf(A)

1. ...

Runtime: $\Theta(n)$

Main algorithm

DivideAndConquer($A[1..n]$)

1. **if** $n = 1$ **return** $\max(A[1], 0)$
2. $\text{opt}_{\text{lo}} \leftarrow \text{DivideAndConquer}(A[1..n/2])$
3. $\text{opt}_{\text{hi}} \leftarrow \text{DivideAndConquer}(A[n/2 + 1..n])$
4. $\text{opt}_{\text{middle}} \leftarrow \text{MaximizeLowerHalf}(A) + \text{MaximizeUpperHalf}(A)$
5. **return** $\max(\text{opt}_{\text{lo}}, \text{opt}_{\text{hi}}, \text{opt}_{\text{middle}})$

Runtime: $T(n) = 2T(n/2) + \Theta(n)$ so $T(n) \in \Theta(n \log(n))$

Proof: same as MergeSort. Details in next module.

Dynamic programming

Idea: solve the problem in nested subarrays $A[1..j]$ of sizes $1, \dots, n$.

Dynamic programming

Idea: solve the problem in nested subarrays $A[1..j]$ of sizes $1, \dots, n$. The optimal subarray

1. is either a subarray of $A[1..n - 1]$,
2. or contains $A[n]$

(cases mutually exclusive!)

Dynamic programming

Idea: solve the problem in nested subarrays $A[1..j]$ of sizes $1, \dots, n$. The optimal subarray

1. is either a subarray of $A[1..n - 1]$,
2. or contains $A[n]$

(cases mutually exclusive!)

Translation: write $M(j) = \max$ sum for subarrays of $A[1..j]$. Then

$$M(j) = \max(M(j - 1), \overline{M}(j)) \quad j \geq 2$$

with $\overline{M}(j) = \max$ sum for subarrays of $A[1..j]$ that include j .

Dynamic programming

How can we compute $\overline{M}(1), \dots, \overline{M}(n)$?

Idea. As before: the optimal subarray that contains $A[n]$

1. is of the form $A[i..n-1, n]$, for some $i \leq n-1$
2. or is exactly $[A[n]]$

(cases mutually exclusive)

Dynamic programming

How can we compute $\overline{M}(1), \dots, \overline{M}(n)$?

Idea. As before: the optimal subarray that contains $A[n]$

1. is of the form $A[i..n-1, n]$, for some $i \leq n-1$
2. or is exactly $[A[n]]$

(cases mutually exclusive)

Translation: $\overline{M}(j) = \max(\overline{M}(j-1) + A[j], A[j]) = A[j] + \max(\overline{M}(j-1), 0)$ for $j \geq 2$

Dynamic programming

How to implement this?

- **direct translation:** two recursive functions. Many repeated operations.

Exercise: $\Theta(n^2)$ for $M(n)$

Dynamic programming

How to implement this?

- **direct translation:** two recursive functions. Many repeated operations.
Exercise: $\Theta(n^2)$ for $M(n)$
- **better:** store all values $M(j)$ and $\overline{M}(j)$: $\Theta(n)$

Dynamic programming

How to implement this?

- **direct translation:** two recursive functions. Many repeated operations.
Exercise: $\Theta(n^2)$ for $M(n)$
- **better:** store all values $M(j)$ and $\overline{M}(j)$: $\Theta(n)$
- **best:** $\Theta(n)$ with no extra storage, using a loop.

DynamicProgramming($A[1..n]$)

1. $\overline{M} \leftarrow A[1]$
2. $M \leftarrow \max(\overline{M}, 0)$
3. **for** $i = 2, \dots, n$ **do**
4. $\overline{M} \leftarrow A[i] + \max(\overline{M}, 0)$
5. $M \leftarrow \max(M, \overline{M})$
6. **return** M