

# Modal Logic

## Summary of Definitions and Main Results

CS 245

### 1 Syntax of Modal Logic

The alphabet for *modal (propositional) logic* is the same as for propositional logic with the addition of an additional unary connectives “ $\Box$ ” (called *necessarily* or *always*) and “ $\Diamond$ ” (called *possibly* or *eventually*).

#### Definition 1 (Well formed Formulæ (wff))

Let  $P$  be a set of propositional symbols. We define the set of formulæ of modal logic (WFMF) inductively as follows:

1.  $P \subseteq \text{WFMF}$ ;
2.  $\varphi \in \text{WFMF}$  then  $(\neg\varphi) \in \text{WFMF}$ ,  $(\Box\varphi) \in \text{WFMF}$ , and  $(\Diamond\varphi) \in \text{WFMF}$ ; and
3.  $\varphi, \psi \in \text{WFMF}$  then  $(\varphi \star \psi) \in \text{WFMF}$  for  $\star \in \{\wedge, \vee, \rightarrow\}$ ;

and no other strings (formed in the alphabet of propositional logic) are elements of WFMF.

In the following we assume that  $\varphi \vee \psi$  is a shorthand for  $(\neg\varphi) \rightarrow \psi$ ,  $\varphi \wedge \psi$  for  $\neg(\varphi \rightarrow (\neg\psi))$ , and  $\Diamond\varphi$  for  $\neg\Box\neg\varphi$ .

### 2 Interpretations and Models

#### Definition 2 (Modal Interpretations (Kripke Structures))

Let  $P$  be a set of propositional symbols. A modal interpretation  $I$  (or Kripke structure, or interpretation for short) is a triple  $(W, R, V)$  where

- $W$  is a non empty set (whose elements are called *of worlds*);
- $R \subseteq W \times W$  a binary relation over  $W$  (called the *visibility* or the *accessibility* relation); and
- $V : W \rightarrow (P \rightarrow \{0, 1\})$  a function that assigns a *propositional interpretation to each world*.

The pair  $(W, R)$  is called the frame of  $I$ .

#### Definition 3 (Satisfaction Relation)

The satisfaction relation  $\models$  between a modal interpretation  $I$ , a world  $w$ , and a formula  $\varphi \in \text{WFMF}$ , written  $I, w \models \varphi$ , is defined as follows:

- $I, w \models p$  if  $V(w)(p) = 1$  for  $p \in P$ ;
- $I, w \models (\neg\varphi)$  if  $I, w \not\models \varphi$ ;
- $I, w \models (\Box\varphi)$  if  $I, v \models \varphi$  for all  $v \in W$  such that  $(w, v) \in R$ ;
- $I, w \models (\varphi \rightarrow \psi)$  if whenever  $I, w \models \varphi$  then also  $I, w \models \psi$ .

A pair  $(I, w)$  such that  $I, w \models \varphi$  is called a (pointed) model of  $\varphi$ . We define  $\text{mod}(\varphi)$  to be the  $\text{mod}(\varphi) = \{(I, w) \mid (I, w) \models \varphi\}$ .

Note: in many presentations the term *model* and *interpretation* are used as synonyms; such a terminology, however, makes defining validity, satisfiability, and logical implication cumbersome.

#### Definition 4 (Satisfiability and Validity)

A modal formula  $\varphi$  is

- valid if  $I, w \models \varphi$  for all interpretations  $I$  and all  $w \in W$  (i.e., true in all pointed models);
- satisfiable if  $I, w \models \varphi$  for some interpretation  $I$  and  $w \in W$  (i.e., has a pointed model); and
- unsatisfiable otherwise.

Definitions of *logical implication* ( $\Sigma \models \varphi$ ) and *equivalence*, and their properties are now the same as for propositional logic.

## 2.1 Characterization of Frames/Correspondence Theory

#### Definition 5

A modal formula  $\varphi$  characterizes a class of frames  $\mathcal{F}$  if

- $I, w \models \varphi$  for all  $I = (W, R, V)$  and  $w \in W$  where the frame  $(W, R) \in \mathcal{F}$ ; and
- for every frame  $(W, R) \notin \mathcal{F}$  there is  $J = (W, R, V)$  and  $w \in W$  such that  $J, w \not\models \varphi$ .

Modal formulae that characterize classes of frames:

$\Box p \rightarrow p$	(T)	reflexive	$\Box p \rightarrow \Diamond p$	(D)	serial
$\Box p \rightarrow \Box \Box p$	(4)	transitive	$\Box \Box p \rightarrow \Box p$		dense
$p \rightarrow \Box \Diamond p$	(B)	symmetric	$\Diamond p \rightarrow \Box p$		unique

In addition  $S4$  denotes the formulae  $\{K, T, 4\}$  and  $S5$  (frames that are equivalence relations) denotes the three formulae  $\{K, T, 4, B\}$ . Here  $K$  is the formula in Ax K below.

## 3 Proof System K

#### Definition 6 (System K)

The System K is a deduction system for propositional modal logic defined by the tuples

Ax 1–3, MP Hilbert system axioms and inference rules  
Ax K  $\langle \Box(\varphi \rightarrow \psi) \rightarrow (\Box\varphi \rightarrow \Box\psi) \rangle$ ; and  
Nec  $\langle \varphi, \Box\varphi \rangle$  only applicable to  $\varphi$  deduced from axioms (i.e., without assumptions).

**Theorem 7 (Soundness and Completeness ( $K$  and extensions))**

$\vdash_K \varphi$  iff  $\models \varphi$  (all frames)

$\vdash_{K+T} \varphi$  iff  $\models \varphi$  in all reflexive frames

$\vdash_{S4} \varphi$  iff  $\models \varphi$  in all transitive frames

$\vdash_{S5} \varphi$  iff  $\models \varphi$  in all frames that are equivalence relations