CS 137 Part 3

Floating Numbers, Math Library, Polynomials and Root Finding

Floating Point Numbers

- How do we store decimal numbers in a computer?
- In scientific notation, we can represent numbers say by

$$-2.61202 \cdot 10^{30}$$

where -2.61202 is called the precision and 30 is called the range.

 On a computer, we can do a similar thing to help store decimal numbers.

Data Types

Туре	Size	Precision	Exponent
float	4 bytes	7 digits	±38
double	8 bytes	16 digits	±308

Note: You will almost always use the type double

Conversion Specifications

There are many different ways we can display these numbers using the printf command. They in general have the format $\%\pm$ m.pX where

- ullet is the right or left justification of the number depending on if the sign is positive or negative respectively
- m is the minimum field width, that is, how many spaces to leave for numbers
- p is the precision (this heavily depends on X as to what it means)
- X is a letter specifying the type (see next slide)

Conversion Specifications Continued

Some of the possible values for X

- %d refers to a decimal number. The precision here will refer to the minimum number of digits to display. Default is 1.
- %e refers to a float in exponential form. The precision here will refer to the number of digits to display after the decimal point. Default is 6.
- %f refers to a float in "fixed decimal" format. The precision here is the same as above.
- %g refers to a float in one of the two aforementioned forms depending on the number's size. The precision here is the maximum number of significant digits (not the number of decimal points!) to display. This is the most versatile option useful if you don't know the size of the number.

Example

```
#include <stdio.h>
int main(void) {
   double x = -2.61202e30;
   printf("%zu\n",
        sizeof(double));
   printf("%f\n", x);
   printf("%.2e\n",x);
   printf("%g\n",x);
   return 0;
}
```

Notice that on the %f line above we get some garbage at the end (it is tough for a computer to store floating numbers!).

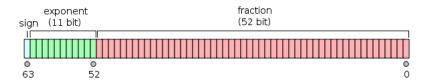
Exercise

Write the code that displays the following numbers (Ensure you get the white space correct as well!)

- 1. 3.14150e+10
- 2. 0436 (two leading white spaces)
- 3. 436 (three white spaces at the end)
- 4. 2.00001

IEEE 754 Floating Point Standard

IEEE - Institute of Electrical and Electronics Engineers



Number is

$$(-1)^{\text{sign}} \cdot \text{fraction} \cdot 2^{\text{exponent}}$$

(This is a bit of a lie but good enough for us - the details of this can get messy. See Wikipedia if you want more information)

(Picture courtesy of Wikipedia)

A Fun Aside

- How do I convert 0.1 as a decimal number to a decimal number in binary?
- Binary fractions are sometimes called 2-adic numbers.
- Idea: Write 0.1 as below where each a_i is one of 0 or 1 for all integers i.

$$0.1 = \frac{a_1}{2} + \frac{a_2}{4} + \frac{a_3}{8} + \dots + \frac{a_k}{2^k} + \dots$$

• Our fraction will be

$$0.1 = (0.a_1a_2a_3...)_2$$

once we determine what each of the a_i terms are.

Computing the Binary Representation

From

$$0.1 = \frac{a_1}{2} + \frac{a_2}{4} + \frac{a_3}{8} + \dots + \frac{a_k}{2^k} + \dots$$

Multiplying by 2 yields

$$0.2 = a_1 + \frac{a_2}{2} + \frac{a_3}{4} + ... + \frac{a_k}{2^{k-1}} + ... (Eqn1)$$

and so $a_1 = 0$ since 0.2 < 1.

Repeating gives

$$0.4 = a_2 + \frac{a_3}{2} + \frac{a_4}{4} + \dots + \frac{a_k}{2^{k-2}} + \dots$$

and again $a_2 = 0$.

Continuing

From

$$0.4 = 0 + \frac{a_3}{2} + \frac{a_4}{4} + \dots + \frac{a_k}{2^{k-2}} + \dots$$

multiplying by 2 gives

$$0.8 = a_3 + \frac{a_4}{2} + \frac{a_5}{4} \dots + \frac{a_k}{2^{k-3}}$$

and again $a_3 = 0$. Doubling again gives

$$1.6 = a_4 + \frac{a_5}{2} + \frac{a_6}{4} ... + \frac{a_k}{2^{k-4}}$$

and so $a_4 = 1$. Now, we subtract 1 from both sides and then repeat to see that... (see next slide)

Continuing

$$1.6 - 1 = \frac{a_5}{2} + \frac{a_6}{4} \dots + \frac{a_k}{2^{k-4}}$$
$$0.6 = \frac{a_5}{2} + \frac{a_6}{4} \dots + \frac{a_k}{2^{k-4}}$$
$$1.2 = a_5 + \frac{a_6}{2} + \frac{a_7}{4} \dots + \frac{a_k}{2^{k-4}}$$

giving $a_5=1$ as well. At this point, subtracting 1 from both sides gives

$$0.2 = \frac{a_6}{2} + \frac{a_7}{4} \dots + \frac{a_k}{2^{k-4}}$$

which is the same as (Eqn 1) from two slides ago and hence,

$$(0.1)_{10} = (0.0\overline{0011})_2$$

Short Hand

$$0.1 \cdot 2 = \mathbf{0}.2$$

 $0.2 \cdot 2 = \mathbf{0}.4$
 $0.4 \cdot 2 = \mathbf{0}.8$
 $0.8 \cdot 2 = \mathbf{1}.6$
 $0.6 \cdot 2 = \mathbf{1}.2$
 $0.2 \cdot 2 = \mathbf{0}.4$

and so $(0.1)_{10} = (0.0\overline{0011})_2$

Errors

- Notice that these floating point numbers only store rational numbers, that is, they cannot store real numbers (though there are CAS packages like Sage which try to).
- This for us is okay since the rationals can approximate real numbers as accurately as we need.
- When we discuss errors in approximation, we have two types of measures we commonly use, namely absolute error and relative error.

Errors (Continued)

- Let *r* be the real number we're approximating and let *p* be the approximate value.
- Absolute Error |p r|. Eg. $|3.14 \pi| \approx 0.0015927...$
- Relative Error $\frac{|p-r|}{|r|}$. Eg. $\frac{|3.14-\pi|}{|\pi|} = 0.000507$.
- Note: Relative error can be large when r is small even if the absolute error is small.

Errors (Continued)

Be wary of...

- Subtracting nearly equal numbers
- Dividing by very small numbers
- Multiplying by very large numbers
- Testing for equality

An Example

```
#include <stdio.h>
int main(void) {
  double a = 7.0/12.0;
  double b = 1.0/3.0;
  double c = 1.0/4.0;
  if (b+c==a) printf("Everything is Awesome!");
  else printf("Not cool... %g",b+c-a);
}
```

Watch out...

- Comparing x == y is often risky.
- To be safe, instead of using if (x==y) you can use if (x-y < 0.0001 && y-x < 0.0001) (or use absolute values)
- We sometimes call $\epsilon = 0.0001$ the **tolerance**.

One Note

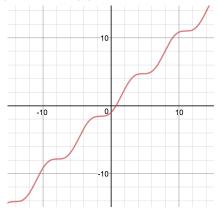
- What happens when you type double a = 1/3? Do you get 0.33333?
- In C, most operators are overloaded. When it sees 1/3, C reads this as integer division and so returns the value of 0.
- There are a few ways to fix this, one of them is to make at least one of the value a double (or a float) by writing double a = 1.0/3 (dividing a double by an integer or a double gives a double).
- Another way is by typecasting, that is, explicitly telling C to make a value something else.
- For example, double a = ((double)1)/3 will work as expected.

Math Library (Highlights)

- #include <math.h> see http://www.tutorialspoint.
 com/c_standard_library/math_h.htm
- Lots of interesting functions including:
 - double sin(double x) and similarly for cos, tan, asin, acos, atan etc.
 - double exp(double x) and similarly for log, log10, log2, sqrt, ceil, floor etc. (note log is the natural logarithm and fabs is the absolute value)
 - double fabs(double x) is the absolute value function for floats (integer abs is in stdlib)
 - double pow(double x, double y) gives x^y, the power function.
 - Constants (Caution! These next two lines are not in the basic standard!): M_PI, M_PI_2, M_PI_4, M_E, M_LN2, M_SQRT2
 - Other values: INFINITY, NAN, MAXFLOAT

Root Finding

- Given a function f(x), how can we determine a root?
- Example: $f(x) = x \cos(x)$. Courtesy: Desmos.



Formally

Claim: When $f(x) = x - \cos(x)$, there is a root in the interval [-10, 10].

Formally

Claim: When $f(x) = x - \cos(x)$, there is a root in the interval [-10, 10].

Proof: Notice that

$$f(-10) = -10 - \cos(-10) \le -9 < 0$$

and

$$f(10) = 10 - \cos(10) \ge 9 > 0$$

Thus, as f(x) is continuous and f(-10) < 0 < f(10), by the Intermediate Value Theorem, there exists a point c inside the interval [-10, 10] satisfying f(c) = 0.

Idea

- Notice that f(-10) < 0 < f(10) so a root must be in the interval of [-10, 10].
- Look at the midpoint of the interval (namely 0) and evaluate f(0).
- If f(0) > 0, look for a root in the interval [-10, 0]. Otherwise, look for a root in [0, 10].
- Repeat until a root is found.

Bisection Method

- For which types of functions is this method guaranteed to work?
- What cases should we worry about?
- Can we run forever?
- What is our stopping condition?

Bisection Method

- For which types of functions is this method guaranteed to work?
- What cases should we worry about?
- Can we run forever?
- What is our stopping condition?
- Two stopping conditions possible
 - Stop when $|f(m)| < \epsilon$ for some fixed $\epsilon > 0$ where m is the midpoint of the interval. (Not great since actual root might still be far away)
 - Stop when $|m_{n-1} m_n| < \epsilon$ (where m_n is the *n*th midpoint). (Much better)
- Should include a safety escape, namely some fixed number of iterations.

Algorithm Pseudocode

- Given some a and b with f(a) > 0 and f(b) < 0, set m = (a + b)/2.
- If f(m) < 0, set b = m.
- Otherwise, set a = m
- Loop until either $|f(m)| < \epsilon$, $|m_{n-1} m_n| < \epsilon$, or the number of iterations has been met.

Bisection.h

Bisection.h

```
#ifndef BISECTION H
#define BISECTION_H
/*
Pre: None
Post: Returns the value of x - \cos(x)
*/
double f(double x):
/*
Pre: epsilon > 0 is a tolerance, iterations > 0,
   f(x) has only one root in [a,b], f(a)f(b) < 0
Post: Returns an approximate root of f(x) using
   bisection method. Stops when either number of
   iterations is exceeded or |f(m)| < epsilon
*/
double bisect(double a, double b,
   double epsilon, int iterations);
#endif
```

```
Bisection.c (Note: Squished code at the bottom!)
#include <math.h>
#include "bisection.h"
double f(double x){return x - cos(x);}
double bisect(double a, double b,
   double epsilon, int iterations){
  double m=a;
  double fb = f(b); //Why is this a good idea?
  assert(epsilon > 0.0 && f(a)*f(b) < 0);
  for(int i=0; i<iterations; i++){</pre>
    m = (a+b)/2.0;
    if (fabs(b-a) < epsilon) return m;</pre>
    //Alternatively:
    //if (fabs(f(m)) < epsilon) return m;
    if (f(m)*fb > 0) \{ b = m; fb = f(b);
    } else { a=m; }
  return m;}
```

Main.c

```
#include <stdio.h>
#include "bisection.h"
int main(void) {
  printf("%g\n", bisect(-10,10,0.0001,50));
  return 0;
}
```

Calculating the Number of Iterations

- An advantage to using the condition $|m_n m_{n-1}| < \epsilon$ is that this gives us good accuracy on the actual root.
- Another is that we can compute the number of iterations fairly easily (and so don't necessarily need our iterations guard).
- After each iteration, the length of the interval is cut in half,
 so, we seek to find a value for n such that

$$\epsilon > \frac{b-a}{2^n}$$

rearranging gives

$$2^n > \frac{b-a}{\epsilon}$$

and so after logarithms

$$n \log 2 > \log(b-a) - \log(\epsilon)$$

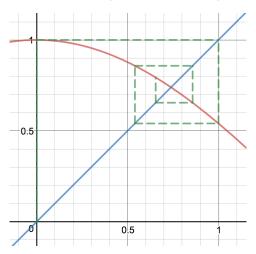
with b = 10, a = -10, $\epsilon = 0.0001$, we get n > 17.60964.

Another Method - Fixed Point Iteration

- Given a function g(x), we seek to find a value x_0 such that $g(x_0) = x_0$.
- We call such a point a fixed point.
- These are of significant importance in dynamical systems.
- In our example, looking for a root of $f(x) = x \cos(x)$ is the same problem as finding a fixed point of $g(x) = \cos(x)$.
- Note: Not all functions have fixed points (but we can transfer between root solving problems and fixed point problems).
- There is another more visual way to interpret this...

Cobwebbing

Also known as **Cobwebbing**. (Courtesy Desmos)



A Note

$$x_0 = 0$$
 $g(x_0) = 1$
 $g(g(x_0)) = g(1) = 0.540$
 $g(g(g(x_0))) = g(g(1)) = g(0.540) = 0.858$
 $g(g(g(g(x_0)))) = g(g(g(1))) = g(g(0.540)) = g(0.858) = 0.654$

 It turns out by the Banach Contraction Mapping Theorem (or the Banach Fixed Point Theorem) that if the slope of the tangent line at a fixed point has magnitude less than 1, this cobwebbing process will eventually converge to a suitable starting point.

Pseudocode

- Start with some point x_0 .
- Compute $x_1 = g(x_0)$.
- If $|x_1 x_0| < \epsilon$, stop.
- Otherwise go back to the beginning with $x_0 = x_1$.

Fixed.h

Fixed.h

```
#ifndef FIXED H
#define FIXED_H
/* Pre: None
   Post: Returns the value of cos(x) */
double g(double x);
/*
Pre: epsilon > 0 is a tolerance, iterations > 0,
 x0 is sufficiently close to a stable fixed point
Post: Returns an approximate fixed point of q(x)
 using cobwebbing. Stops when either number of
 iterations is exceeded or |q(xi)-xi| < epsilon
where xi is the value of x0 after i iterations.
*/
double fixed (double x0, double epsilon,
   int iterations);
#endif
```

Fixed.c

```
#include <assert.h>
#include <math.h>
#include "fixed.h"
double g(double x){return cos(x);}
double fixed (double x0,
   double epsilon, int iterations){
  double x1;
  assert(epsilon > 0.0);
  for(int i=0; i<iterations; i++){</pre>
    x1 = g(x0);
    if (fabs(x1-x0) < epsilon) return x1;</pre>
    x0 = x1;
  return x0;
```

Main.c

```
#include <stdio.h>
#include "fixed.h"
int main(void) {
  printf("%g\n", fixed(0,0.0001,50));
  return 0;
}
```

Improving the previous two codes

- Notice in each of the two previous examples, we hard coded a definition of a function.
- Ideally, the code would also have as a parameter the function itself.
- C lets us do this using function pointers.
- Syntax: Pass a parameter double (*f)(double) a pointer to a function that consumes a double and returns a double.
- Note: The brackets around (*f) are important to not confuse this with a function that returns a pointer.

Bisection2.h

Bisection2.h

```
#ifndef BISECTION2_H
#define BISECTION2_H
double bisect2(double a, double b,
    double epsilon, int iterations,
    double (*f)(double));
#endif
```

Bisection2.c

```
#include <assert.h>
#include <math.h>
#include "bisection2.h"
double bisect2(double a, double b,
   double epsilon, int iterations,
   double (*f)(double)){
  double m=a;
  double fb = f(b);
  assert(epsilon > 0.0 && f(a)*f(b) < 0);
  for(int i=0; i<iterations; i++){</pre>
    m = (a+b)/2.0:
    if (fabs(b-a) < epsilon) return m;</pre>
    //Alternatively:
    //if (fabs(f(m)) < epsilon) return m;
    if (f(m)*fb > 0) \{ b = m; fb = f(b);
    } else { a=m; }
```

Main.c

```
#include <stdio.h>
#include <math.h>
#include "bisection2.h"
double g(double x){return x - cos(x);}
double h(double x){return x*x*x-x+1;}
int main(void) {
  printf("%g\n", bisect2(-10,10,0.0001,50,g));
  printf("%g\n", bisect2(-10,10,0.0001,50,h));
 return 0;
```

Polynomials

- A polynomial is an expression with at least one indeterminate and coefficients lying in some set.
- For example, $3x^3 + 4x^2 + 9x + 2$.
- In general: $p(x) = a_0 + a_1 x + ... + a_n x^n$
- We will primarily use ints for the coefficients. (maybe doubles later)
- Question: Brainstorm some different ways we can represent polynomials in memory. Discuss the pros and cons of each.

Our Representation

- We will represent it as an array of n+1 coefficients where n is the degree.
- For our example $3x^3 + 4x^2 + 9x + 2$, we have double p[] = $\{2.0, 9.0, 4.0, 3.0\}$;
- How do we evaluate a polynomial? That is, how can we implement:

double eval(double p[], int n, double x);

Traditional Method

- Compute x, x^2 , x^3 ,... x^n for n-1 multiplications.
- Multiply each by $a_1, a_2, ..., a_n$ for another n multiplications.
- Add all the results $a_0 + a_1x + + a_nx^n$ for a final n multiplications.
- This gives a total of 2n-1 multiplications and n additions.
- A note: Multiplication is an expensive operation compared to addition. Is there a way to reduce the number of multiplication operations?

Horner's Method

- Named after William George Horner (1786-1837) but known long before him (dating back as early as pre turn of millennium Chinese mathematicians).
- Idea:

$$2 + 9x + 4x^2 + 3x^3 = 2 + x(9 + x(4 + 3x))$$

 Start inside out. Total operations are n multiplications and n additions.

Horner's Method

```
#include <stdio.h>
#include <assert.h>
double horner(double p[], int n, double x){
  assert(n > 0);
  double y = p[n-1];
  for(int i=n-2; i >= 0; i--)
    y = y*x + p[i];
  return y;
}
```

Note: the n above is the number of elements in the array (so your polynomial has degree n-1).

Horner's Method (Continued)

```
int main(void) {
  double p[] = {2,9,4,3};
  int len = sizeof(p)/sizeof(p[0]);
  printf("2 = %g\n",horner(p,len,0));
  printf("18 = %g\n",horner(p,len,1));
  printf("60 = %g\n",horner(p,len,2));
  printf("-6 = %g\n",horner(p,len,-1));
  return 0;
}
```