

Model Checking Timed Automata

Material from “Principles of Model Checking” by C. Baier and J.-P. Katoen

Borzoo Bonakdarpour

School of Computer Science
University of Waterloo

November 24, 2013

Outline

- 1 Timed Computation Tree Logic (TCTL)
- 2 TCTL Model Checking

Presentation outline

1 Timed Computation Tree Logic (TCTL)

2 TCTL Model Checking

Timed Computation Tree Logic (TCTL)

Definition (Syntax of TCTL)

Formulae in TCTL are either state or path formulae. TCTL **state formulae** over the set AP of atomic propositions and set C of clocks are formed according to the following grammar:

$$\Phi ::= true \mid a \mid g \mid \Phi \wedge \Phi \mid \mathbf{E}\varphi \mid \mathbf{A}\varphi$$

where $a \in AP$, $g \in ACC(C)$ and φ is a **path formula** defined by:

$$\varphi ::= \Phi \mathbf{U}^J \Phi$$

where $J \subseteq \mathbb{R}_{\geq 0}$ is an interval whose bounds are natural numbers.

Timed Computation Tree Logic (TCTL)

TCTL Temporal Abbreviations

$$\diamond^J \phi = \text{true } \mathbf{U}^J \phi$$

$$\mathbf{E} \square^J \phi = \neg \mathbf{A} \diamond^J \neg \phi$$

$$\mathbf{A} \square^J \phi = \neg \mathbf{E} \diamond^J \neg \phi$$

Timed Computation Tree Logic (TCTL)

TCTL Temporal Abbreviations

$$\diamond^J \phi = \text{true } \mathbf{U}^J \phi$$

$$\mathbf{E} \square^J \phi = \neg \mathbf{A} \diamond^J \neg \phi$$

$$\mathbf{A} \square^J \phi = \neg \mathbf{E} \diamond^J \neg \phi$$

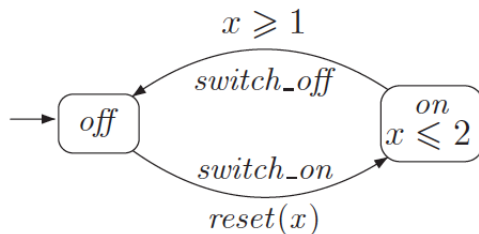
TCTL Interval Abbreviations

Intervals are often denoted by shorthand, e.g., $\diamond^{\leq 2}$ denotes $\diamond^{[0,2]}$ and $\square^{>8}$ denotes $\square^{(8,\infty)}$

Example

Example

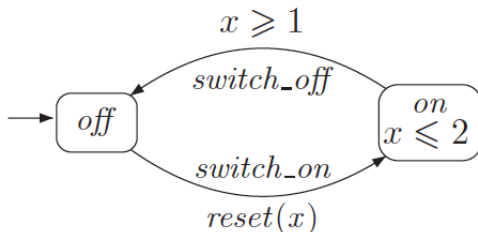
Consider the following timed automata



Example

Example

Consider the following timed automata



Example

The property:

"the light cannot be continuously switched on for more than 2 minutes"

is expressed by the TCTL formula:

$$\mathbf{A}\square(on \rightarrow \mathbf{A}\diamond^{>2}\neg on)$$

Definition (Satisfaction relation for TCTL)

Let $TA = (L, \Sigma, E, C, L^0, I)$ be a timed automaton, $a \in AP$, $g \in ACC(C)$, and $J \subseteq \mathbb{R}_{\geq 0}$. For state $s = \langle l, \nu \rangle$ in $TS(TA)$ and TCTL formulae Φ and Ψ , and TCTL path formula φ , the **satisfaction relation** \models is defined for state formulae by

$$s \models true$$

$$s \models a \quad \text{iff} \quad a \in Label(l)$$

$$s \models g \quad \text{iff} \quad \nu \models g$$

$$s \models \neg\Phi \quad \text{iff} \quad \text{not } s \models \Phi$$

$$s \models \Phi \wedge \Psi \quad \text{iff} \quad (s \models \Phi) \wedge (s \models \Psi)$$

$$s \models \mathbf{E}\varphi \quad \text{iff} \quad \pi \models \varphi \text{ for some } \pi \in Paths_{div}(s)$$

$$s \models \mathbf{A}\varphi \quad \text{iff} \quad \pi \models \varphi \text{ for all } \pi \in Paths_{div}(s)$$

Semantics of TCTL (cont'd)

Definition (Satisfaction relation for TCTL (con'd))

For a time-divergent path $\pi = s_0 \xrightarrow{d_0} s_1 \xrightarrow{d_1} \dots$, the satisfaction relation \models for path formulae is defined by:

$$\pi \models \Phi \mathbf{U}^J \Psi \quad \text{iff} \quad \exists i \geq 0. s_i + d \models \Psi \text{ for some } d \in [0, d_i] \text{ with}$$

$$\sum_{k=0}^{i-1} d_k + d \in J \quad \text{and}$$

$$\forall j \leq i. s_j + d' \models \Phi \vee \Psi \text{ for any } d' \in [0, d_j] \text{ with}$$

$$\sum_{k=0}^{j-1} d_k + d' \leq \sum_{k=0}^{i-1} d_k + d$$

where for $s_i = \langle l_i, \nu_i \rangle$ and $d \geq 0$, we have $s_i + d = \langle l_i, \nu_i + d \rangle$

Semantics of TCTL (cont'd)

Definition (TCTL Semantics for Timed Automata)

A timed automaton TA **satisfies** a TCTL formula Φ iff $s_0 \models \Phi$ for each initial state s_0 of TA .

Presentation outline

1 Timed Computation Tree Logic (TCTL)

2 TCTL Model Checking

Reduction to CTL Model Checking

Idea

Given a time automaton TA and a TCTL formula Φ , our goal is to find a finite transition system S and an CTL formula $\hat{\Phi}$, such that

$$TA \models_{TCTL} \Phi \quad \text{iff} \quad R(TA, \Phi) \models_{CTL} \hat{\Phi}$$

Input: timed automaton TA and TCTL formula Φ (both over propositions AP and clocks C).

Output: $TA \models \Phi$

- 1 $\hat{\Phi} :=$ eliminate the timing parameters from Φ ;
- 2 determine the clock equivalence classes under \cong ;
- 3 construct the region transition system $TS = R(TA, \Phi)$;
- 4 apply the CTL model checking algorithm to check $TS \models \hat{\Phi}$
- 5 $TA \models \Phi$ if and only if $TS \models \hat{\Phi}$

Algorithm 1: A recipe for TCTL model checking

Elimination of Timing Parameters

Notation

For clock evaluation ν , $z \notin C$, and $d \in \mathbb{R}_{\geq 0}$, let $\nu\{z := d\}$ denote the clock valuation for $C \cup \{z\}$ that extends ν by setting z to d while keeping the value of all other clocks unchanged:

$$\nu\{z := d\}(x) = \begin{cases} \nu(x) & \text{if } x \in C \\ d & \text{if } x = z \end{cases} \quad (1)$$

Elimination of Timing Parameters

Notation

For clock evaluation ν , $z \notin C$, and $d \in \mathbb{R}_{\geq 0}$, let $\nu\{z := d\}$ denote the clock valuation for $C \cup \{z\}$ that extends ν by setting z to d while keeping the value of all other clocks unchanged:

$$\nu\{z := d\}(x) = \begin{cases} \nu(x) & \text{if } x \in C \\ d & \text{if } x = z \end{cases} \quad (1)$$

Notation

Let TA be a timed automaton over clocks C . For state $s = \langle l, \nu \rangle$ in $TS(TA)$ let $s\{z := d\}$ denote the state, $\nu\{z := d\}$. Note that $s\{z := d\}$ is a state in $TS(TA \oplus z)$ where $TA \oplus z$ is the timed automaton TA with the set of clocks $C \cup \{z\}$.

Elimination of Timing Parameters

Theorem

Let TA be timed automaton $(L, \Sigma, C, E, L^0, I)$, and $\Phi \mathbf{U}^J \Psi$ a TCTL formula over C and AP . For clock $z \notin C$ and for any state s of $TS(TA)$ it holds that

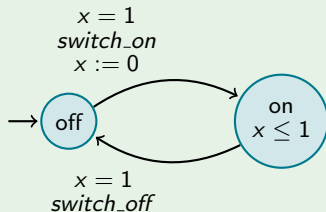
$$\textcircled{1} \quad s \models_{TCTL} \mathbf{E}(\Phi \mathbf{U}^J \Psi) \quad \text{iff} \quad s\{z := 0\} \models_{CTL} \mathbf{E}((\Phi \vee \Psi) \mathbf{U}((z \in J) \wedge \Psi)).$$

$$\textcircled{2} \quad s \models_{TCTL} \mathbf{A}(\Phi \mathbf{U}^J \Psi) \quad \text{iff} \quad s\{z := 0\} \models_{CTL} \mathbf{A}((\Phi \vee \Psi) \mathbf{U}((z \in J) \wedge \Psi)).$$

Example

Example

Light Switch Consider the following timed automaton TA and the TCTL formula $\Phi = \mathbf{E}\Diamond^{\leq 1}on$.

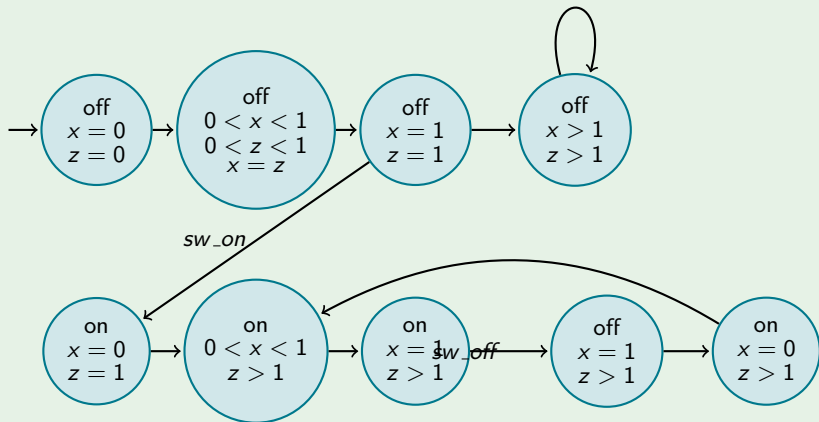


As a first step, Φ is replaced by $\hat{\Phi} = \mathbf{E}\Diamond((z \leq 1) \wedge on)$ and TA is equipped with an additional clock z . The maximal constants for the clocks x and z are $c_x = 1$ and $c_z = 1$. The region transition system $TS = R(TA \oplus z, \Phi)$ is on the next slide.

Example (con'd)

Example

Light Switch (cont'd)



Example (con'd)

Example

Light Switch (cont'd) The state region

$$\langle on, [x = 0, z = 1] \rangle \models (z \leq 1) \wedge on$$

and is reachable from the initial state region. Therefore,

$$TS \models_{CTL} \mathbf{E} \diamond ((z \leq 1) \wedge on)$$

and thus

$$TA \models \mathbf{E} \diamond^{\leq 1} on$$

Handling Multiple Clocks

Eliminating Multiple Clocks

A simple way of treating formulae with nested time bounds is to introduce a fresh clock for each subformula.

Example

For example, the following TCTL formula

$$\Phi = \mathbf{A}\Box^{\geq 3}\mathbf{E}\Diamond^{[1,2]}on$$

is transformed into:

$$\hat{\Phi} = \mathbf{A}\Box((z_1 \geq 3) \Rightarrow \mathbf{E}\Diamond(z_2 \in]1, 2]) \wedge on))$$