

Linear Programming

“program” as in “exercise program” or “spending program”, not “C program”

optimization problem with linear inequalities

variables $x_1 \dots x_d$ in d -dimensions.

$$\max \quad c_1 x_1 + c_2 x_2 + \dots + c_d x_d$$

$$\text{s.t.} \quad a_{11} x_1 + a_{12} x_2 + \dots + a_{1d} x_d \leq b_1$$

$$\vdots$$

$$a_{n1} x_1 + \dots + a_{nd} x_d \leq b_n$$




i.e.

$$\max \quad c x$$

$$A x \leq b$$

c $1 \times d$ vector
 x $d \times 1$ vector
 A $n \times d$ matrix
 b $n \times 1$

An application: planning

d foods	apple  1	broccoli  2	...	milk  d
each with cost	c_1	c_2	...	c_d
n nutrients	protein 1	vitamin D 2	...	n
each with daily requirement	b_1	b_2	...	b_n
a_{ij} — amount of nutrient i in food j				

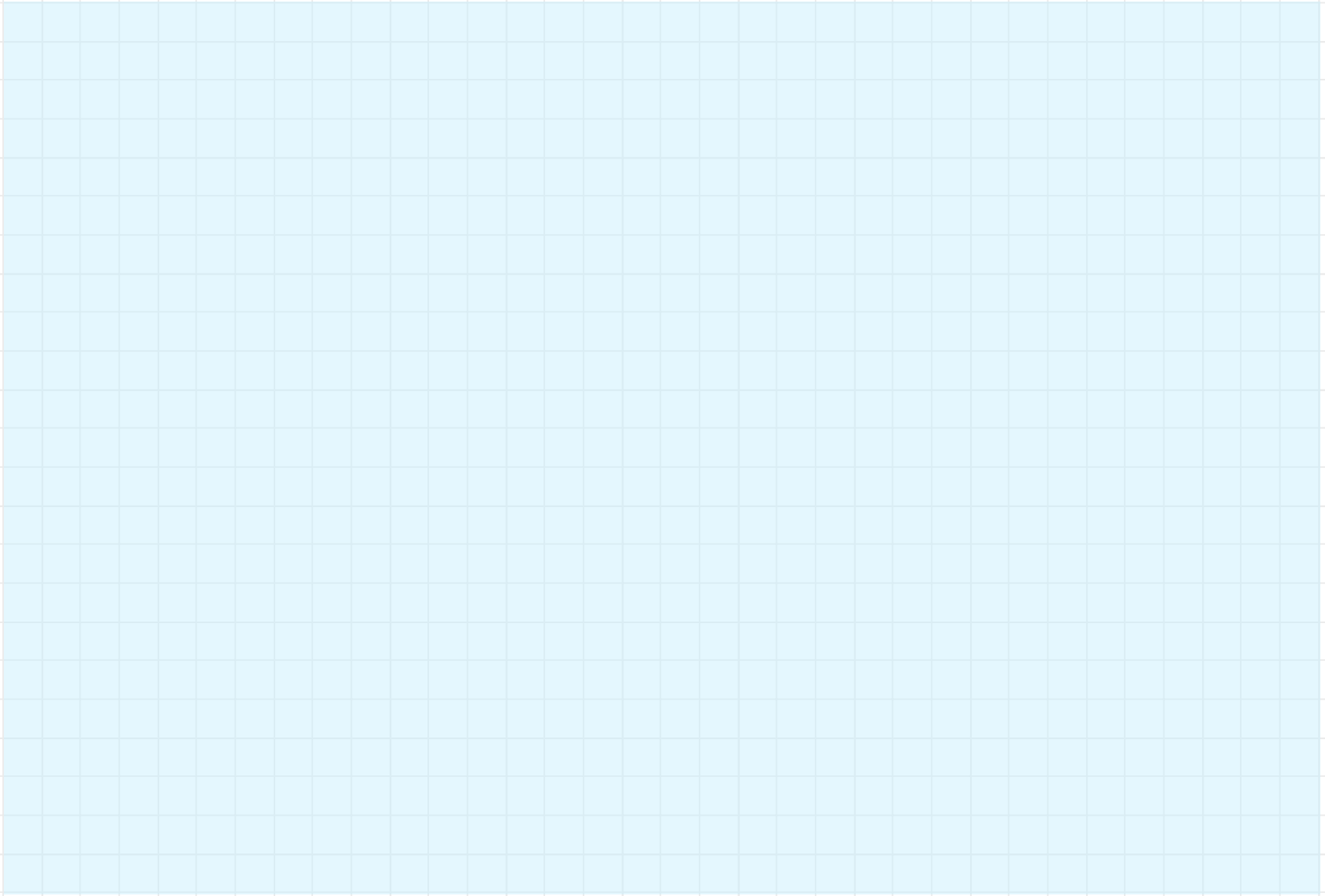
Buy food to
meet daily
requirements,
min cost

$$\min c x$$

$$A x \geq b$$

variables $x_1 \dots x_d$
 $x_j =$ amount of
food j to buy.

picture in 2D



Straightforward algorithm:

try all vertices, see which gives max

From last day: this is the dual problem to Convex Hull and can be solved by same algorithms

$O(n \log n)$ in 2D, 3D

$O(n^{\lfloor d-1/2 \rfloor})$ for $d \geq 4$

History

early history 40's, 50's

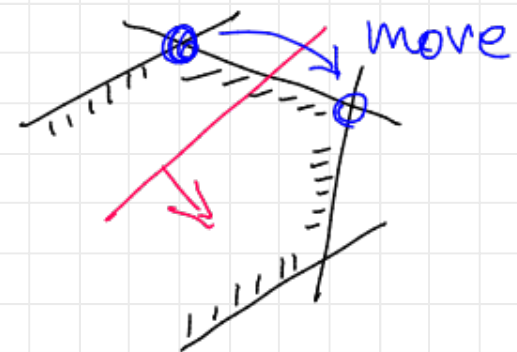
Dantzig - simplex method in '40's

- spurred development of computers

Simplex Method

- geometrically - walk from one vertex of the feasible region to an adjacent one

- Simplex Pivot Rule:
which inequality to remove,
which one to add



History

But the simplex rule is very good in practice.

OPEN: is there some pivot rule that gives poly. time?

Related question:

Given initial vertex s and final vertex t ,
how many edges on best path $s \rightarrow t$?

diameter of polyhedron = worst case over s, t .

Hirsch conjecture: diameter of convex polyhedron
is $\leq n - d$ $n = \# \text{ inequalities}$

Disproved in 2012, $d = 43$ $d = \text{dimension}$

But there could still be polynomial (even linear) bounds

History

Polynomial time algorithms for Linear Programming:

180 - Katchian - ellipsoid method

184 - Karmarkar - interior point method

These operate on bit representations of numbers

OPEN: an algorithm that uses

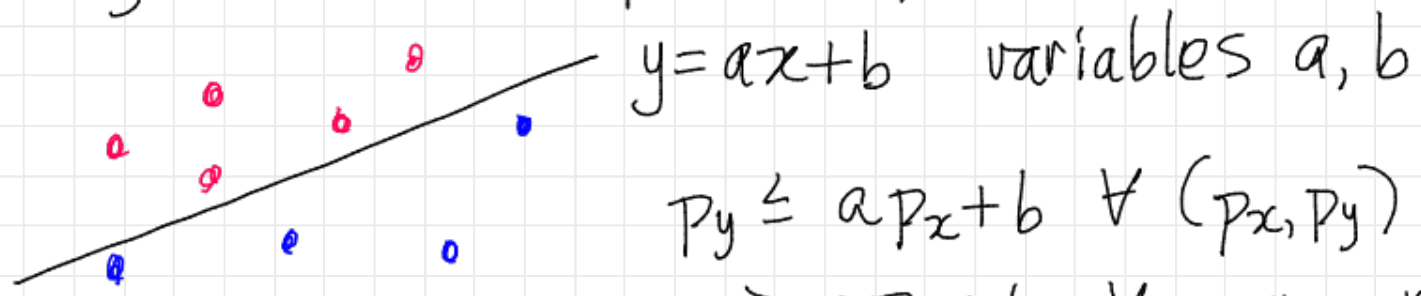
arithmetic operations polynomial in n, d

"strongly polynomial time"

Linear Programming in Small Dimensions

Applications

1. Separating red and blue points by a line



$y = ax + b$ variables a, b

$$p_y \leq a p_x + b \quad \forall (p_x, p_y) \text{ blue}$$

$$p_y \geq a p_x + b \quad \forall \text{ red}$$

Solve for a, b (just feasibility, no max.)

... and can check red below, blue above... vertical line..

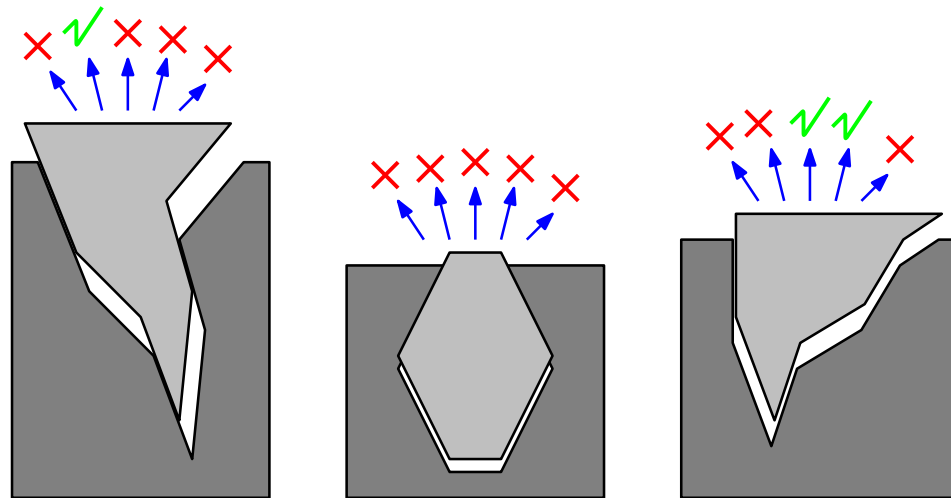
Can also ask for strict separation

$$p_y < a p_x + b \quad \Rightarrow \quad p_y \leq a p_x + b + \delta$$

δ a variable, $\delta \geq 0$
maximize δ .

2. Casting (from de Berg et al.)
 Make a 3D object in a mold

picture
 in 2D



Alper Ungor

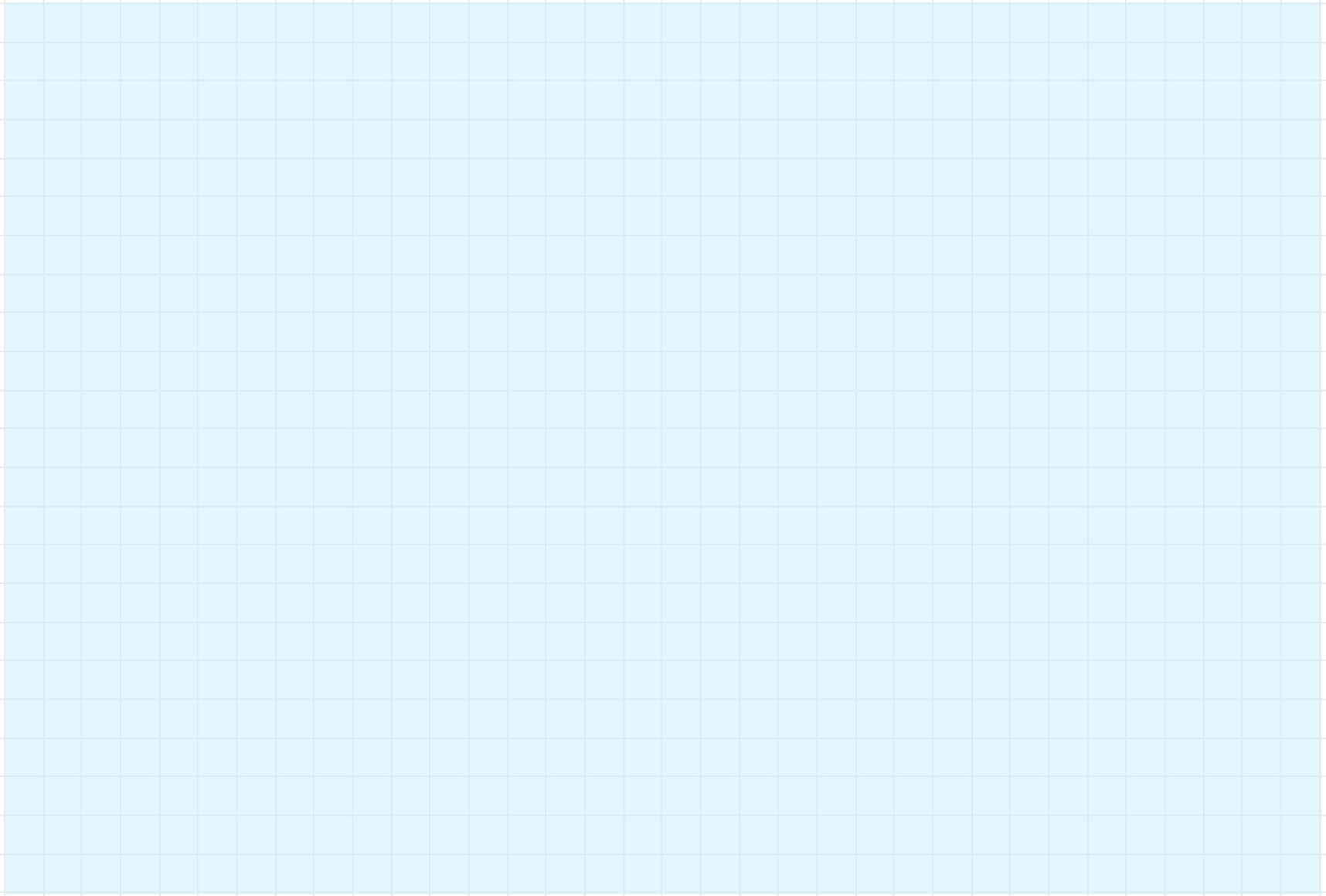
Pour liquid into a mold, harden,
 then remove by straight line motion in some direction.
 Find a direction that works
 For given top face — can express as LP.
 Try all top faces.

Linear programming in fixed dimension
can be done in time $O(n)$

Megiddo 1984

but dependence on d is bad $O(2^{2^d} n)$

Randomized Incremental Algorithm in 2D, Seidel



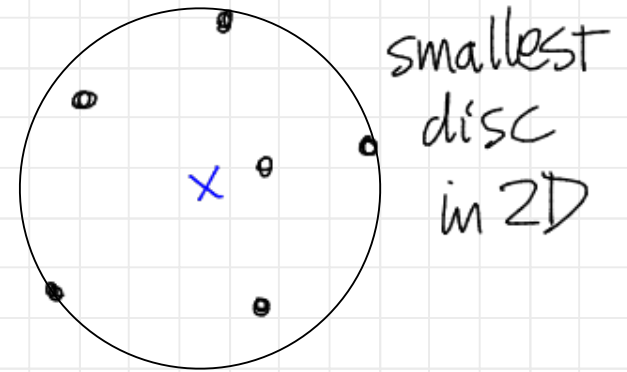
Smallest enclosing disc

Not a linear programming problem, but amenable to the same approach

Given points $p_1 \dots p_n$ in \mathbb{R}^d
find smallest enclosing sphere.

This is a facility location problem—
the center of the disc

minimizes the max distance to all points.



Quadratic programming.

Megiddo's approach gives $O(n)$ but bad constant

Randomized Incremental Approach, Welzl