

THE DECIDABILITY OF THE EQUIVALENCE PROBLEM
FOR DOL-SYSTEMS*

by

K. Culik II and I. Fris[†]
Department of Computer Science
University of Waterloo

CS-76-25

May 1976

(revised in August 1976)

* This research was supported by the National Research Council of Canada, Grant No. A7403.

† On leave from the University of New England, Armidale, N.S.W., Australia.

No handwritten symbols are used; in formulae

$\&$ is the letter 'e'

1 is the digit 'one'.

Number of pages : 35

Number of tables : 0

Number of figures: 2

The running head: DOL equivalence problem

Abstract

The language and sequence equivalence problem for DOL-systems is shown to be decidable. In an algebraic formulation the sequence equivalence problem for DOL-systems can be stated as follows: Given homomorphisms h_1 and h_2 on a free monoid Σ^* and a word σ from Σ^* , is $h_1^n(\sigma) = h_2^n(\sigma)$ for all $n \geq 0$?

0. Introduction

The DOL sequence equivalence problem can be stated algebraically as follows. Given two homomorphisms h_1, h_2 on a free monoid Σ^* and a word σ in Σ^* , is $h_1^n(\sigma) = h_2^n(\sigma)$ for all $n \geq 0$? This paper shows that this problem is decidable. The problem originated in Lindenmayer systems which are mathematical models of cellular development. In that context it can be restated as the problem of the developmental equivalence of two genetic encodings in filamental organisms developing deterministically without interaction. The Lindenmayer systems without interaction (OL-systems) were introduced in (Lindenmayer, 1971) and the equivalence problem for them was posed shortly afterwards in (Problem Book, 1973). Its undecidability for nondeterministic OL-systems has been shown, e.g. in (Salomaa, 1973). The same question for deterministic OL-systems (DOL-systems) was conjectured to be decidable but remained open. Some partial results were obtained in (Paz and Salomaa, 1973; Johansen and Meiling, 1974; Ehrenfeucht and Rozenberg, 1974; Nielsen, 1974; Culik, 1975; Valiant, 1975; and Karhumäki, 1976). Our full solution is based on the results and methods shown in (Culik, 1975). A part of these results, namely, the decidability of the equivalence problem for smooth DOL-systems, appeared independently and using different terminology in (Valiant, 1975).

Now, we explain intuitively the basic ideas of our approach. The technical terms which are not fully explained in the introduction are enclosed in quotation marks on first use.

We start by showing that, without loss of generality, the testing for equivalence may be restricted to "normal" systems. The essence of

this paper is to show that every pair of equivalent normal systems has "bounded balance". It has been shown in (Culik, 1975) that the equivalence problem is decidable for each family of DOL-systems in which the equivalence implies bounded balance.

Neglecting many technical details we will now informally describe the principal ideas of the proof that for normal systems the equivalence implies bounded balance. In (Culik, 1975) it has also been shown that "simple" systems have bounded balance. A normal system is simple iff it has no "subsystem" in the sense of general algebra. If a system has a subsystem, then the underlying set of the subsystem is called a "subalphabet".

For two equivalent systems which are not simple we find a common subalphabet and show that either all substrings of the language generated by the systems which are entirely in this subalphabet are "short" (such a subalphabet is called "limited") or the two systems "induced" by this subalphabet are equivalent. A second pair of normal systems is obtained by "removing" the subsystem (i.e. by omitting the symbols from the common subalphabet). As before, these "remainder"-systems are equivalent because the original systems are equivalent. Since both the subsystem and the remainder system are systems over a smaller alphabet we can use the boundedness as an induction hypothesis. The base of the induction deals (essentially) with systems over one letter so the claim is easy to verify. This allows us to assume that the remainder-pair and (in the case of a subalphabet which is not limited) also the induced-pair have bounded balance. As the case of limited subalphabets causes no problem, this allows us to construct a bound on the balance for the original pair.

Some of the more important technical details which were omitted above are as follows. In every step of the induction we have to consider the non-propagating systems and another singular case separately. Since a propagating system may have a non-propagating remainder system we cannot include the propagating property into the requirements for normality.

Finally, and independently of the main result, we discuss in section 6 an interesting property of pairs of equivalent DOL-systems which is equivalent to bounded balance. The property requires the existence of a regular set R such that:

- (i) R contains the language generated by either of the systems;
- (ii) The homomorphisms of the two systems are equal on every string in R .

An alternative algorithm for testing equivalence of DOL-systems can be based on this property. We conjecture that such a regular set exists for every pair of equivalent DOL-systems, i.e. every pair of equivalent systems has bounded balance. Note that although we solve the decision problem for all DOL-systems, the conjecture is shown correct for normal systems only.

1. Notation

Given an alphabet Σ , Σ^* denotes the free monoid generated by Σ , with unit (empty string) ε .

A DOL-system is a 3-tuple $G = (\Sigma, h, \sigma)$ consisting of alphabet Σ , homomorphism h and a starting string $\sigma \in \Sigma^*$. $L(G)$, the language generated

by G , is defined as $\{h^n(\sigma) : n \geq 0\}$. G is said to be reduced, if every symbol from Σ occurs in at least one $h^n(\sigma)$, $n \geq 0$. To reduce G means to omit from Σ all symbols which do not have this property.

For $w \in \Sigma^*$ and $a \in \Sigma$, $\#_a w$ denotes the number of occurrences of a in w . If (a_1, \dots, a_n) is an ordering of Σ , then $(\#_{a_1} w, \dots, \#_{a_n} w)$ is called the Parikh vector of w and is denoted by $[w]$. The matrix $M = (m_{ij})_{\substack{1 \leq i \leq n \\ 1 \leq j \leq n}}$, where $m_{ij} = \#_{a_j} h(a_i)$ is called the growth matrix for G .

If i is a number, $|i|$ denotes the absolute value of i ; if w is a string $|w|$ denotes the length of w ; later on $|A|$ is also used for length of a vector A or maximum characteristic value of a matrix A .

For $w \in \Sigma^*$, let $\min(w) = \{a : a \text{ occurs in } w\}$.

Given $G = (\Sigma, h, \sigma)$, we say that w is a G -prefix (G -substring, G -suffix) if w is a prefix (substring, suffix) of $h^n(\sigma)$ for some $n \geq 0$.

Two DOL-systems $G_i = (\Sigma, h_i, \sigma_i)$, $i = 1, 2$ are called (sequence) equivalent if $h_1^n(\sigma_1) = h_2^n(\sigma_2)$ for all $n = 0, 1, \dots$. Two DOL-systems G_1, G_2 are called Parikh equivalent if $[h_1^n(\sigma_1)] = [h_2^n(\sigma_2)]$ for all $n = 0, 1, \dots$. The balance (with respect to G_1, G_2) of a string w in Σ^* is defined as in (Culik, 1975) $\beta(w) = ||h_1(w)| - |h_2(w)||$. If there exists $c \geq 0$ so that $\beta(x) \leq c$ for all G_1 -prefixes, then the pair (G_1, G_2) is said to have bounded balance. In this case the smallest such c is called the balance of the pair (G_1, G_2) .

For two sets A, B , $A \cup B$ denotes their union. If A, B are disjoint, we stress this by writing $A+B$ for the union. Finally, we will often write a instead of $\{a\}$ for a one-element set.

2. The Normal Systems

Let $G = (\Sigma, h, \sigma)$ be a DOL-system. We define the function $m: \mathcal{P}(\Sigma) \rightarrow \mathcal{P}(\Sigma)$, where $\mathcal{P}(\Sigma)$ is the set of all subsets of Σ by putting

$$m(\phi) = \phi,$$

$$m(\{a\}) = \min(h(a)) \text{ for } a \in \Sigma,$$

$$m(A \cup B) = m(A) \cup m(B).$$

It is easy to see that $m^i(a) = \min(h^i(a))$ for all $i \geq 1$. We will write $m(a)$ for $m(\{a\})$ and use m_1, m_2, m_{12} etc. to denote similar functions based on h_1, h_2, h_1h_2 , etc.

Definition 1 A DOL-system $G = (\Sigma, h, \sigma)$ is called an ℓr -system if

$\Sigma = \Sigma_\ell + \Sigma_c + \Sigma_r$ is a decomposition of Σ into three non-empty disjoint sets such that $h(a) \in \Sigma_\ell \Sigma_c^*$ for $a \in \Sigma_\ell$, $h(a) \in \Sigma_c^*$ for $a \in \Sigma_c$, $h(a) \in \Sigma_c^* \Sigma_r$ for $a \in \Sigma_r$, and $\sigma \in \Sigma_\ell \Sigma_c^* \Sigma_r$. We call Σ_c the core of Σ , Σ_ℓ is called the left side, Σ_r the right side of Σ . The number of symbols in the core Σ_c of Σ is called the order of G .

Definition 2 A DOL-system $G = (\Sigma, h, \sigma)$ is called normal if

- (1) G is an ℓr -system,
- (2) G is reduced,
- (3) if $a \in m^j(b)$ for some $j > 0$ then $a \in m(b)$,

holds for every $a, b \in \Sigma_c$.

The following lemma, which is used to prove that we may consider normal systems only, is given in somewhat more general form as needed for Lemma 7.

Let $G_i = (\Sigma, h_i, \sigma)$, $i = 1, 2$ be two DOL-systems. Given $n \geq 1$ let $\iota = (\iota_1, \dots, \iota_n)$ be a sequence of length n of integers $\iota_1, \dots, \iota_n \in \{1, 2\}$. We denote $h^{(\iota)} = h_{\iota_1} \dots h_{\iota_n}$, a composition of homomorphisms h_1, h_2 , i.e. $h^{(\iota)}(x) = h_{\iota_1}(\dots h_{\iota_n}(x) \dots)$.

Lemma 1 Let $G_i = (\Sigma, h_i, \sigma)$, $i = 1, 2$, $n \geq 1$, $\iota_1 = (\iota_1, \dots, \iota_n)$, $\iota_2 = (j_1, \dots, j_n)$ be given. Denote $\sigma_j = h_1^j(\sigma)$ and let $i_1 = 1$, $j_1 = 2$. Under these assumptions G_1, G_2 are equivalent iff

$$(4) \quad G_1^j = (\Sigma, h^{(\iota_1)}, \sigma_j), G_2^j = (\Sigma, h^{(\iota_2)}, \sigma_j)$$

are equivalent for every $j = 0, 1, \dots, n-1$ and at the same time

$$(5) \quad h_1^j(\sigma) = h_2^j(\sigma)$$

also for every $j = 0, 1, \dots, n-1$.

Proof If G_1, G_2 are equivalent then (5) holds for every j and thus $h^{(\iota_1)}(\sigma) = h^{(\iota_2)}(\sigma)$ for all possible sequences ι_1, ι_2 . This means that (4) holds for all possible pairs.

Conversely, for each $\ell \geq 0$, $h_1^\ell(\sigma) = (h_1 h_{\iota_2} \dots h_{\iota_n})^k h_1^m(\sigma) = (h^{(\iota_1)})^k h_1^m(\sigma)$, $h_2^\ell(\sigma) = (h_2 h_{j_2} \dots h_{j_n})^k h_2^m(\sigma) = (h^{(\iota_2)})^k h_2^m(\sigma)$, where $\ell = kn+m$ and $0 \leq m < n$. Since G_1^j and G_2^j are equivalent and by (5) $h_1^m(\sigma) = h_2^m(\sigma)$ we have $h_1^\ell(\sigma) = h_2^\ell(\sigma)$, i.e. G_1, G_2 are equivalent. \square

Note: It is sometimes more convenient to write $\bar{G}_i^j = (\Sigma, h^{(\iota_i)}, h_i^j(\sigma))$ and instead (4) and (5) require that \bar{G}_1^j, \bar{G}_2^j be equivalent for $j = 0, 1, \dots, n-1$.

Lemma 2 Let $G = (\Sigma, h, \sigma)$. Then there is $k \geq 1$ such that in all the systems $G^j = (\Sigma, h^k, h^j(\sigma))$, $j = 0, 1, \dots, k-1$, (3) holds for all $a, b \in \Sigma$.

Proof As the validity of (3) does not depend on j we may consider any single j . For every $a \in \Sigma$ consider the sets $m(a), m^2(a), \dots$ where m is based on the original h of G . All the sets $m^j(a)$ are subsets of Σ , so we can find $r(a) > 0$, $d(a) > 0$ such that $m^{r(a)}(a) = m^{r(a)+d(a)}(a)$. From this $m^j(a) = m^\ell(a)$ for all $j, \ell \geq r(a)$ for which $j \equiv \ell \pmod{d(a)}$. Consider the least common multiple $d = \text{l.c.m.}(d(a) : a \in \Sigma)$ and let r be such that $r \geq r(a)$ for all $a \in \Sigma$ and $r \equiv 0 \pmod{d}$.

Obviously $m^r(a) = m^{rj}(a)$ for all $a \in \Sigma$ and all $j = 1, 2, \dots$.

It is thus sufficient to take $k = r$. □

Theorem 1 The testing whether or not a pair G_1, G_2 is equivalent may be restricted to normal systems.

Proof Given any pair $G_i = (\Sigma, h_i, \sigma_i)$, $i = 1, 2$ of DOL-systems we can effectively construct a finite set S of pairs of normal DOL-systems such that G_1, G_2 are equivalent iff each pair in S is a pair of equivalent systems.

By Lemma 2 we can find k_1, k_2 for which $h_1^{k_1}, h_2^{k_2}$ meet (3). The systems constructed for $k = \text{l.c.m.}(k_1, k_2)$ meet (3) and G_1, G_2 are equivalent, by Lemma 1, iff all G_1^j, G_2^j thus constructed are equivalent. Next, we reduce each G_i^j . Clearly G_1^j and G_2^j are equivalent iff the corresponding reduced systems are equivalent.

Finally, if G_i^j is not yet an ℓr -system we may create the sides "artificially". Let ℓ, r be two distinct symbols $\notin \Sigma$. Put $\Sigma' = \{\ell\} + \Sigma + \{r\}$ and $h'(a) = h(a)$ for $a \in \Sigma$, while $h'(\ell) = \ell$, $h'(r) = r$ in each G_i^j . The new G_i^j is normal and again G_1, G_2 are equivalent iff all G_1^j, G_2^j are equivalent. \square

Note that systems obtained using the construction above meet (3) even for $a, b \in \Sigma$. We will, however, need the more general case subsequent!

The following definitions and facts from linear algebra are needed.

A vector $x = (x_1, \dots, x_p)$ and a matrix $M = (m_{ij})_{\substack{1 \leq i \leq p \\ 1 \leq j \leq p}}$ will mean a vector and a matrix over real numbers. $|x| = \sum_{i=1}^p |x_i|$ is the length of x , $\|M\| = \sum_{j=1}^p \max_{1 \leq i \leq p} |m_{ij}|$ is the norm of M . $|M|$ will denote $\max_{1 \leq i \leq p} |r_i|$, where r_i are the (generally complex) characteristic numbers. A vector x and a matrix M are called positive (non-negative) and denoted by $x > 0$, $M > 0$ ($x \geq 0$, $M \geq 0$) if $x_i > 0$, $m_{ij} > 0$ ($x_i \geq 0$, $m_{ij} \geq 0$) for all $1 \leq i, j \leq p$. Finally, $\langle x, y \rangle$ will denote the scalar product $\sum_{i=1}^p x_i y_i$, while (x, y) will denote the direct sum of x and y .

It is easy to establish the following facts.

Proposition 1 Let M be a matrix and $q = |M|$, the absolute value of the largest characteristic value. Then for every vector x $|xM^n| < q_0^n |x|$ for all sufficiently large n and every $q_0 > q$.

Proposition 2 Let $M = \begin{pmatrix} A & B \\ 0 & C \end{pmatrix}$ be a decomposition of a matrix M where A and C are square matrices and 0 a zero matrix. Assume that C has a single characteristic vector \bar{u} with respect to the maximal characteristic value

$r = |C|$ which is real and positive. We will call such a vector the maximal characteristic vector. Let \bar{v} be the characteristic vector of C^T with respect to r . Denote by $u = (0, \bar{u})$ and $v = (0, \bar{v})$ the characteristic vectors of M and M^T respectively. Assume $|A| < r$ and $\bar{u} > 0, \bar{v} > 0$. From this $\langle u, v \rangle = \langle \bar{u}, \bar{v} \rangle > 0$, thus we may normalize them so that $\langle u, v \rangle = 1$. Finally, let $x = (y, z)$ be any vector decomposed also correspondingly to M . Now if $z \geq 0, z \neq 0$ then there exist constants a, b and r_0 such that $a > 0, r_0 < r$ and

$$(6) \quad |xM^n - ar^n u| < br_0^n \quad \text{for all sufficiently large } n.$$

Proof Let $x, \bar{u}, \bar{v}, u, v$ be as described. Writing $x = \langle x, v \rangle u + w_0$ we get $\langle w_0, v \rangle = 0$. Denote $a = \langle x, v \rangle = \langle z, \bar{v} \rangle > 0$. We have $xM^n = ar^n u + w_0 M^n$. Let $W = \{w | \langle w, v \rangle = 0\}$. By induction $w_0 M^n \in W$, thus W is a subspace invariant with respect to M . Obviously, $u \notin W$. The characteristic value r is simple, so all characteristic values of M on W are $< r$. Let $r_0 < r$ be any number larger than absolute values of all characteristic values of M on W . From Proposition 1 above we get (6) immediately. \square

Proposition 3 Let M, u, x be as in Proposition 2. Consider the space $X = [x, xM, xM^2, \dots]$, the space generated by the vectors $\{xM^i | i \geq 0\}$.

It is closed (as any subspace in a finite-dimensional vector space) and there is a sequence of vectors from X , namely, the sequence $\frac{1}{r^i} xM^i$ which converges to u . Consequently, the maximal characteristic vector lies in every space X generated by $\{xM^i\}$ starting with $x = (y, z)$ where $z \geq 0, z \neq 0$.

The following definitions and facts about non-negative matrices can be found in (Gantmacher, 1960).

A matrix $M \geq 0$ is called irreducible if M cannot be written in the form $M = \begin{pmatrix} A & B \\ 0 & C \end{pmatrix}$, with A, C square submatrices, 0 - a zero matrix, even after any permutation of rows and the same permutation of columns. If all M^i , $i = 1, 2, \dots$ are irreducible, we call M primitive.

Proposition 4 If M is irreducible, but some power M^d is reducible, then M^d is fully reducible - i.e. it can be written (after a suitable permutation of rows and columns) as $M = \begin{pmatrix} A & 0 \\ 0 & C \end{pmatrix}$.

Matrix M is primitive iff some power d of M is positive: $M^d > 0$. Such a d , if it exists divides the order m of M , i.e. in particular $d \leq m$.

A primitive matrix has a positive characteristic value r which is simple, and $r > |r_i|$ for all other characteristic values r_i of M . The characteristic vector belonging to r is positive.

Finally, if $M = (m_{ik})$ is irreducible, then for the maximum characteristic value r we have $r \geq \min_{1 \leq i \leq p} \sum_{k=1}^p m_{ik}$.

3. The $\mathfrak{L}r$ -Simple Systems

Definition 3 Let $G = \langle \Sigma_{\mathfrak{L}} + \Sigma_{\mathfrak{C}} + \Sigma_{\mathfrak{r}}, h, \sigma \rangle$ be an $\mathfrak{L}r$ -system. Homomorphism h is called $\mathfrak{L}r$ -simple if for every $a, b \in \Sigma_{\mathfrak{C}}$ and every $k > 0$ there is $j > 0$ such that $a \in m^{kj}(b)$. Equivalently, calling h $\mathfrak{L}r$ -irreducible if for every $a, b \in \Sigma_{\mathfrak{C}}$ there is $j > 0$ such that $a \in m^j(b)$, h is $\mathfrak{L}r$ -simple iff h^k is $\mathfrak{L}r$ -irreducible for all $k \geq 1$. We call G $\mathfrak{L}r$ -simple if h is $\mathfrak{L}r$ -simple.

If G is $\mathfrak{L}r$ -simple and normal, then from $a \in m^{kj}(b)$ we get $a \in m(b)$. Putting $a = b$ we get $a \in m(a)$, which implies in turn that $a \in m^k(b)$ for all $i \geq 1$. Thus if G is normal, G is $\mathfrak{L}r$ -simple iff $m(b) = \Sigma_{\mathfrak{C}}$ for all $b \in \Sigma_{\mathfrak{C}}$. However, the following lemma is needed for systems not necessarily normal.

Lemma 3 Let $G_i = (\Sigma, h_i, \sigma)$, $i = 1, 2$ be two DOL-systems, G_1 ℓr -simple, the order m of G_1 at least two. If G_1, G_2 are Parikh equivalent then for every $\varepsilon > 0$ there is $n_0 > 0$ such that for every $w \in \Sigma^*$, $w \notin (\Sigma_\ell + \Sigma_r)^*$

$$(7) \quad \beta(h_1^n(w)) \leq \varepsilon |h_1^n(w)| \quad \text{for all } n \geq n_0.$$

Proof Let M_1 be the growth matrix of G_1 . If Σ is suitable ordered we can write

$$M_1 = \begin{pmatrix} I_1 & 0 & A_1 \\ 0 & I_2 & A_2 \\ 0 & 0 & N \end{pmatrix},$$

where I_1, I_2 are matrices of the order $|\Sigma_\ell|, |\Sigma_r|$, respectively, with exactly one 1 in each row and all other elements zero. A_1, A_2 are rectangular matrices in general, and 0 denotes zero-matrices of appropriate orders. If the order of G is m , then N is $m \times m$ matrix which is primitive, in particular irreducible. Being primitive, N^d is positive, for some $d \leq m$. The elements of N , and so of $N^d = (n_{i,j}^{(d)})$ are integers. Thus $\min_{1 \leq i \leq m} \sum_{j=1}^m n_{ij}^{(d)} \geq m$. By Proposition 4, for the maximal characteristic value $r' = |N^d|$ we have $r' \geq m > 1$. Denoting $r = |N|$, we have $r' = r^d$, i.e. $r > 1$.

Let u be the characteristic vector of M_1 with respect to r . Since all the characteristic values of matrices I_1, I_2 are in absolute value smaller or equal to one, the assumptions of Proposition 2 are met for $A = \begin{pmatrix} I_1 & 0 \\ 0 & I_2 \end{pmatrix}$, $B = \begin{pmatrix} A_1 \\ A_2 \end{pmatrix}$, $C = N$. Let $\bar{\sigma}$ be the Parikh vector of σ . From Proposition 3 we get $u \in [\bar{\sigma}, \bar{\sigma}M_1, \bar{\sigma}M_1^2, \dots] = [\bar{\sigma}, \bar{\sigma}M_2, \bar{\sigma}M_2^2, \dots] = M$,

the first equality following from the Parikh equivalence of G_1 and G_2 .

For every vector $x \in M$ we have $xM_1 = xM_2$, thus, in particular, $u(M_1 - M_2) = 0$.

Let x be now the Parikh vector of w . As $w \notin (\Sigma_\ell + \Sigma_r)^*$, the conditions on x in Proposition 2 are met and (6) holds. That is, for suitable $a, b > 0, r_0$

we have $|xM_1^n - ar^n u| \leq br_0^n$. From this $|xM_1^n(M_1 - M_2)| \leq b \|M_1 - M_2\| r_0^n$. From

(6) we further get $|xM_1^n| \geq |ar^n u| - br_0^n \geq \frac{a|u|}{2} r^n$ - again for sufficiently

large n . These two inequalities combined give

$$\beta(h_1^n(w)) \leq |xM_1^n(M_1 - M_2)| \leq \frac{2b \|M_1 - M_2\|}{a|u|} \left(\frac{r_0}{r}\right)^n \cdot |xM_1^n|.$$

As $r_0 < r$, (7) can be met if n is large enough. \square

Lemma 4 Under the assumptions of Lemma 3

(8) for every $\varepsilon > 0$ there is $K > 0$ such that for every G_1 -prefix w , $|w| > K$ we have $\beta(w) \leq \varepsilon |w|$.

Proof Using Lemma 3, given $\frac{\varepsilon}{2}$ we find n_0 . Let w be any G_1 -prefix, i.e.

$h_1^n(\sigma) = wx$ for suitable n, x . Assume $|w| > 1$, if $n \geq n_0$, then denote

$u = h_1^{n-n_0}(\sigma)$. Let $u = u_1 a u_2$, where $a \in \Sigma$ be such that $h_1^{n_0}(u_1)$ is a prefix of w but w is a proper prefix of $h_1^{n_0}(u_1 a)$, i.e.

$w = h_1^{n_0}(u_1) x_1$, $h_1^{n_0}(u_1 a) = w x_2$, $x_1, x_2 \in \Sigma^*$. Now

$\beta(w) \leq \beta(h_1^{n_0}(u_1)) + \beta(x_1) \leq \frac{\varepsilon}{2} |h_1^{n_0}(u_1)| + B |x_1| \leq \frac{\varepsilon}{2} |w| + B H^{n_0}$, where

$B = \max_{a \in \Sigma} \{\beta(a)\}$, and $H = \max_{a \in \Sigma} |h_1(a)|$. To prove (8) it is sufficient to take

$\frac{H^{n_0} B}{|w|} \leq \frac{\varepsilon}{2}$, i.e. to take $K > H^{n_0} \max(\frac{2B}{\varepsilon}, 1)$. The second case in max-function

guarantees that $n \geq n_0$. \square

Theorem 2 Let $G_i = (\Sigma, h_i, \sigma)$ for $i = 1, 2$ be two $\&r$ -DOL-systems and let G_1 be $\&r$ -simple. Let G_1 and G_2 be sequence equivalent and let the order of G_1 be at least two. Then the pair (G_1, G_2) has bounded balance.

Proof This result is shown in (Culik, 1975), Theorem 3.2, for pairs of equivalent simple DOL-systems. However, in the proof of this result only the following properties are essential:

- (a) $h_1^n(a)$ is exponentially growing for each a in Σ , except possibly for symbols which occur only as a first or last symbol in any $h_1^n(\sigma)$ for $n \geq 0$.
- (b) (8) holds.

In our case for each a in Σ_c , $h_1^n(a)$ grows because G_1 is $\&r$ -simple and of order at least two, therefore (a) is satisfied. By Lemma 4 (b) is satisfied. Therefore, the proof of Theorem 3.2 from (Culik, 1975) also proves our Theorem 2. The only modification required is that when comparing formulae

(2) and (3) we may not say that without restriction of generality

$|h_1(u')| \geq |h_2(u')|$ since the assumptions of the theorem are not symmetric with respect to G_1 and G_2 here. However, the proof for the case

$|h_1(u')| \leq |h_2(u')|$ is fully analogical since only the equivalence of G_1 and G_2 is used and this is a symmetric property. \square

4. Subalphabets and Induced Systems

Given a DOL-system $G = \langle \Sigma, h, \sigma \rangle$, a set $\Pi, \phi \neq \Pi \not\subseteq \Sigma_c$ is called a subalphabet if $h(a) \in \Pi^*$ for each $a \in \Pi$. Denote $\Omega = \Sigma - \Pi$. If G is an

$\&r$ -system we will also use Ω_C for $\Sigma_C - \Pi$. For every $z \in \Sigma^*$ we denote by z^Ω the string z with all symbols from Π omitted, thus $z^\Omega \in \Omega^*$. We define G^Ω as $\langle \Omega, h^\Omega, \sigma^\Omega \rangle$ where $h^\Omega(x) = (h(x))^\Omega$ for $x \in \Omega$. If for a language L we write $L^\Omega = \{z^\Omega \mid z \in L\}$, then obviously

$$(9) \quad (L(G))^\Omega = L(G^\Omega).$$

Given two DOL-systems G_1, G_2 , Π is called their common subalphabet if Π is a subalphabet of G_i for $i = 1, 2$. From (9) we get immediately that if G_1, G_2 are equivalent and have a common subalphabet Π then G_1^Ω, G_2^Ω are equivalent. It is also obvious that if G is normal, so is G^Ω .

Lemma 5 Let $G_i = \langle \Sigma, h_i, \sigma \rangle$, $i = 1, 2$ be two normal propagating equivalent DOL-systems. Then G_1 and G_2 have a common subalphabet Π , or the composite homomorphism $h_1 h_2$ is $\&r$ -simple.

Proof First, we will show that if there is no common subalphabet then $h_1 h_2$ is $\&r$ -irreducible. For $a, b \in \Sigma_C$ we say that a immediately derives b , written $a \Rightarrow b$, if $b \in m_1(a) \cup m_2(a)$. (See Section 2 for the definition of m_1, m_2). Also, we say that a derives b using m_1 or m_2 if $b \in m_1(a)$ or $b \in m_2(a)$, respectively. Let \Rightarrow^* be the reflexive and transitive closure of binary relation \Rightarrow . Finally, for $a \in \Sigma_C$, let $\tilde{m}(a) = \{b \in \Sigma_C : a \Rightarrow^* b\}$. Obviously, $m_i(\tilde{m}(a)) \subseteq \tilde{m}(a)$ for $i = 1, 2$; so either $\tilde{m}(a) = \Sigma_C$ or $\tilde{m}(a)$ is a common subalphabet of G_1 and G_2 . This means that if there is no common subalphabet, then $a \Rightarrow^* b$ for any two $a, b \in \Sigma_C$.

Let Δ_i be the subset of Σ_C of symbols which occur in $h_i^n(\sigma)$ for infinitely many $n \geq 0$, $i = 1, 2$. Since G_1 and G_2 are equivalent $\Delta_1 = \Delta_2$.

$\&r$ -system we will also use Ω_C for $\Sigma_C - \Pi$. For every $z \in \Sigma^*$ we denote by z^Ω the string z with all symbols from Π omitted, thus $z^\Omega \in \Omega^*$. We define G^Ω as $\langle \Omega, h^\Omega, \sigma^\Omega \rangle$ where $h^\Omega(x) = (h(x))^\Omega$ for $x \in \Omega$. If for a language L we write $L^\Omega = \{z^\Omega \mid z \in L\}$, then obviously

$$(9) \quad (L(G))^\Omega = L(G^\Omega).$$

Given two DOL-systems G_1, G_2 , Π is called their common subalphabet if Π is a subalphabet of G_i for $i = 1, 2$. From (9) we get immediately that if G_1, G_2 are equivalent and have a common subalphabet Π then G_1^Ω, G_2^Ω are equivalent. It is also obvious that if G is normal, so is G^Ω .

Lemma 5 Let $G_i = \langle \Sigma, h_i, \sigma \rangle$, $i = 1, 2$ be two normal propagating equivalent DOL-systems. Then G_1 and G_2 have a common subalphabet Π , or the composite homomorphism $h_1 h_2$ is $\&r$ -simple.

Proof First, we will show that if there is no common subalphabet then $h_1 h_2$ is $\&r$ -irreducible. For $a, b \in \Sigma_C$ we say that a immediately derives b , written $a \Rightarrow b$, if $b \in m_1(a) \cup m_2(a)$. (See Section 2 for the definition of m_1, m_2). Also, we say that a derives b using m_1 or m_2 if $b \in m_1(a)$ or $b \in m_2(a)$, respectively. Let \Rightarrow^* be the reflexive and transitive closure of binary relation \Rightarrow . Finally, for $a \in \Sigma_C$, let $\tilde{m}(a) = \{b \in \Sigma_C : a \Rightarrow^* b\}$. Obviously, $m_i(\tilde{m}(a)) \subseteq \tilde{m}(a)$ for $i = 1, 2$; so either $\tilde{m}(a) = \Sigma_C$ or $\tilde{m}(a)$ is a common subalphabet of G_1 and G_2 . This means that if there is no common subalphabet, then $a \Rightarrow^* b$ for any two $a, b \in \Sigma_C$.

Let Δ_i be the subset of Σ_C of symbols which occur in $h_i^n(\sigma)$ for infinitely many $n \geq 0$, $i = 1, 2$. Since G_1 and G_2 are equivalent $\Delta_1 = \Delta_2$.

Assume that $\Delta_1 \not\subseteq \Sigma_C$. Since G_1 is propagating $\Delta_1 \neq \phi$ and thus clearly Δ_1 is a common subalphabet of G_1 and G_2 . Therefore, if G_1 and G_2 have no common subalphabet $\Delta_1 = \Delta_2 = \Sigma_C$.

Consider arbitrary $a, b \in \Sigma_C$. Since G_1 is propagating there exists $c \in \Sigma_C$ such that $c \in m_1(a)$. Since $\Delta_2 = \Sigma_C$ there exists $d \in \Sigma_C$ such that $b \in m_2(d)$. If there is no common subalphabet, then $c \Rightarrow^* d$. This means that a can derive b using m_1 in the first and m_2 in the last step of the derivation. From condition (3) of normality it follows that if $x \Rightarrow^* y$ for $x, y \in \Sigma_C$ using only m_1 (m_2) in all steps, then $x \Rightarrow y$ using m_1 (m_2). Therefore, a derives b using m_1 and m_2 alternately starting with m_1 and ending with m_2 . Thus we have shown that for every $a, b \in \Sigma_C$ there exist $n \geq 0$ and $c_1, \dots, c_n \in \Sigma_C$ so that $c_1 \in m_{12}(a)$; $c_{j+1} \in m_{12}(c_j)$ for $j = 1, 2, \dots, n-1$; and $b \in m_{12}(c_n)$. We used the fact that the function m_{12} as defined at the beginning of Section 2 is the composition of m_1 and m_2 .

Thus we have shown that $h_1 h_2$ is lr -irreducible and we proceed to show that $h_1 h_2$ is lr -simple. A system is lr -simple iff its growth matrix restricted to Σ_C is primitive. From results in (Gantmacher, 1960) it follows that if the growth matrix is not primitive, then there exist $q > 1$ and a partition P of Σ_C with q classes such that for every $a, b \in \Sigma_C$, if $a \in m_{12}^q(b)$, then a and b belong to the same class of P .

Claim Let $a, b \in \Sigma_C$. If $b \Rightarrow a$ then a and b belong to the same class of P .

Proof Suppose that $a \in m_1(b)$. Since G_1 and G_2 are propagating there exists $c \in m_1(a)$, and similarly there exists $d \in m_2(c)$. Therefore $d \in m_{12}(a)$ and since G_1 is normal $c \in m_1(b)$ (condition (3)), also $d \in m_{12}(b)$. This means that $m_{12}(a) \cap m_{12}(b) \neq \emptyset$ and thus, since G_1 and G_2 are propagating, also $m_{12}^q(a) \cap m_{12}^q(b) \neq \emptyset$. Therefore, a and b are in the same class of \mathcal{P} , namely, in the class including $m_{12}^{q-1}(d)$.

Similarly, suppose $a \in m_2(b)$. Since $\Delta_1 = \Delta_2 = \Sigma_c$ there exist $c, d \in \Sigma_c$ such that $b \in m_2(c)$ and $c \in m_1(d)$. Therefore, $b \in m_{12}(d)$ and using condition (3) of normality for G_2 we have $a \in m_2(c)$ and thus also $a \in m_{12}(d)$. Therefore, again a and b are in the same class of \mathcal{P} . \square

Having proven the claim let a, b be again any two elements of Σ_c . We know that $a \Rightarrow^* b$. From the claim and the definition of \Rightarrow^* through \Rightarrow it follows that a and b belong to the same class of \mathcal{P} . Since this holds for arbitrary a, b in Σ_c , partition \mathcal{P} has a single class, i.e. $q = 1$, which shows that $h_1 h_2$ is $\mathcal{L}r$ -simple. \square

Definition 4 Given $G = \langle \Sigma, h, \sigma \rangle$. A subalphabet $\Pi \subseteq \Sigma$ is called limited if there is a constant k such that for every substring $u \in \Pi^*$ of $L(G)$ we have $|u| < k$. Note that Π is limited with respect to every DOL-system equivalent to G .

Lemma 6 Let G_1, G_2 be two equivalent systems, with a common subalphabet Π . If Π is limited and if the pair (G_1^Ω, G_2^Ω) has a bounded balance, then the pair (G_1, G_2) has bounded balance.

Proof Let the balance of (G_1^Ω, G_2^Ω) be c and let k be such that $|u| \leq k$ for all G_1 -substrings u from Π^* . Then the balance of the pair (G_1, G_2) is clearly smaller or equal to $(c+1)k+c$. \square

Definition 5 Let G_1, G_2 be a pair of DOL-systems, $G_i = (\Sigma, h_i, \sigma)$. Given $k \geq 1$, the set $S = \{(G_1^j, G_2^j) : 0 \leq j < k\}$ of pairs of DOL-systems is called k -combination of (G_1, G_2) where $G_i^j = (\Sigma, \bar{h}_i, \sigma_{i,j})$, $\bar{h}_1 = h_1^k$, $\bar{h}_2 = h_2 h_1^{k-1}$, $\sigma_{i,j} = h_i^j(\sigma)$, $i = 1, 2$; $j = 0, 1, \dots, k-1$. Instead of 2-combination we will say just combination.

We will say that the set S has bounded balance if each pair $(G_1^j, G_2^j) \in S$ has bounded balance.

Lemma 7 Let (G_1, G_2) be a pair of DOL-systems. Let S be their k -combination for some $k \geq 1$. Then

- (i) G_1, G_2 are equivalent iff for all $(G_1^j, G_2^j) \in S$, G_1^j, G_2^j are equivalent.
- (ii) Let G_1 and G_2 be equivalent. Then (G_1, G_2) has bounded balance iff their k -combination S has bounded balance.

Proof (i) has already been proven in Lemma 1. Now, assume that (G_1^j, G_2^j) has bounded balance and let w be a G_1 -prefix, say, $ww' = h_1^n(\sigma)$ for some $n \geq 0$ and some $w' \in \Sigma^*$. When proving that the balance is bounded on a set of strings we may neglect finitely many strings, so, let $n \geq k$. Let ua with $u \in \Sigma^*$, $a \in \Sigma$ be a prefix of $h_1^{n-k+1}(\sigma)$ such that $h_1^{k-1}(u)$ is a prefix of w , but w is a proper prefix of $h_1^{k-1}(ua)$. (Such ua exists if w is a proper prefix, but if w is the whole string $h_1^n(\sigma)$

then $\beta(w) = 0$, so again we may ignore this), i.e. $h_1^{k-1}(u)x = w$ for some $x \in \Sigma^*$, and x is a prefix of $h_1^{k-1}(a)$, from which $|x| \leq H^{k-1}$ and $\beta(x) \leq BH^{k-1}$, i.e. $\beta(w) \leq \beta(h_1^{k-1}(u)) + BH^{k-1}$, where $H = \max_{a \in \Sigma} |h_1(a)|$ and

$B = \max_{a \in \Sigma} \beta(a)$. The boundedness of $\beta(w)$ follows from the fact that $\beta(h_1^{k-1}(u)) = ||h_1^k(u) - |h_2 h_1^{k-1}(u)|| = \beta_j(u)$, where we denoted by β_j the balance in (G_1^j, G_2^j) which is bounded, and j is chosen so that w is a G_1^j -prefix.

The converse, namely, that if (G_1, G_2) has bounded balance so has each (G_1^j, G_2^j) is obvious and is not in fact needed in our proofs. \square

Definition 6 Let $G = (\Sigma, h, \sigma)$ be a DOL-system and let $\Pi \subset \Sigma$ be a sub-alphabet, and assume that h^Ω is propagating. For every $avb \in \Omega\Pi^*\Omega$ we define an induced system $G^{avb} = (\Sigma^{a+\Pi^+b}, \hat{h}, \bar{a}\bar{v}\bar{b})$ as follows.

For $a \in \Omega$, we write $h(a) = xcv$, where $c \in \Omega$, $v \in \Pi^*$. (Note that such decomposition is possible because h^Ω is propagating, and is obviously unique.) We denote $\ell(a) = c$, $\ell'(a) = v$. Similarly, writing $h(a) = v'c'y$, where $c' \in \Omega$, $v' \in \Pi^*$, we define $r(a) = c'$, $r'(a) = v'$.

We define $\Sigma^a = \{\bar{c} : \text{there is } n \geq 0 \text{ and a sequence } c_0 = a, c_1, \dots, c_{n-1}, c_n = c, c_j \in \Omega \text{ such that } c_j = \ell(c_{j-1}), j = 1, 2, \dots, n\}$, where \bar{c} is one new symbol for each $c \in \Omega$. Similarly, we define ${}^b\Sigma$ starting with $c_0 = b$ and using r instead of ℓ : ${}^b\Sigma = \{\bar{c} : \text{there is } m \geq 0 \text{ and a sequence } c_0 = b, c_1, \dots, c_m = c, c_j \in \Omega \text{ and } c_j = r(c_{j-1}) \text{ for } j = 1, 2, \dots, m\}$, and where \bar{c} is another new symbol, one for each $c \in \Omega$. Let

$$\hat{h}(\bar{a}) = \overline{\ell(a)}\ell'(a) \quad \text{for } a \in \Omega,$$

$$\hat{h}(\bar{\bar{a}}) = r'(a)\overline{r(a)} \quad \text{for } a \in \Omega,$$

$$\hat{h}(d) = h(d) \quad \text{for } d \in \Pi.$$

Finally, Π' is the subset of Π of symbols actually used when the homomorphism \hat{h} is repeatedly applied to v . That completes the definition of G^{avb} . When starting with G_1 or G_2 we will, as usual, talk about \hat{h}_1 , \hat{h}_2 , G_1^{avb} , and G_2^{avb} .

Lemma 8 Let G_1, G_2 be two equivalent DOL-systems with a common sub-alphabet Π . Assume both h_1 and h_1^Ω are propagating and there exists a constant k such that for every G_1 -prefix of the form xav , where $a \in \Omega$, $x \in \Sigma^*$, and $v \in \Pi^*$ we have

$$(10) \quad \text{if } |v| > k, \text{ then } h_1^\Omega(xa) = h_2^\Omega(xa).$$

Then for every $avb \in \Omega\Pi^*\Omega$, $|v| > k$, avb a substring of $L(G_1)$ the systems $G_1^{\text{avb}}, G_2^{\text{avb}}$ are equivalent.

Proof As avb is a G_1 -substring, we can write $xavby = h_1^j(\sigma)$ for some $x, y \in \Sigma^*$ and some $j \geq 0$. From (10) we have $h_1(xa) = x'\ell_1(a)\ell_1'(a)$,

$h_2(xa) = x'\ell_2(a)\ell_2'(a)$, where ℓ_1, ℓ_1' and ℓ_2, ℓ_2' are the functions from definition 6 based here on h_1 and h_2 . Similarly,

$h_i(xavb) = x'\ell_i(a)\ell_i'(a)h_i(v)r_i'(b)r_i(b)x_i''$, for some $x', x_i'' \in \Sigma^*$, $i = 1, 2$. Strings $h_1(xa), h_2(xa)$ and $h_1(xavb), h_2(xavb)$ are prefixes of the same string

$h_1^{j+1}(\sigma) = h_2^{j+1}(\sigma)$, so $\ell_1(a) = \ell_2(a) \in \Omega$; $\ell_1'(a)h_1(v)r_1'(b)$ and

$\ell_2'(a)h_2(v)r_2'(b) \in \Pi^*$, but they are equal as the next symbol $r_1(b) = r_2(b) \in \Omega$.

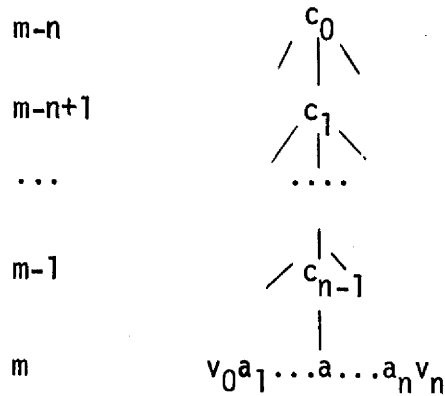
That is, $|v| > k$ implies (through $h_1^\Omega(xa) = h_2^\Omega(xa)$) that $\hat{h}_1(\bar{a}v\bar{b}) = \hat{h}_2(\bar{a}v\bar{b})$.

As h_1 - and thus \hat{h}_1 - are propagating, also $|h_1(v)| \geq |v| > k$. This proves that $G_1^{\text{avb}}, G_2^{\text{avb}}$ are equivalent. \square

Lemma 9 Let $G = \langle \Sigma, h, \sigma \rangle$ be a normal DOL-system. Denote $H = \max(|h(a)| : a \in \Sigma)$. Let $\Pi \subset \Sigma$ be a subalphabet and $v_0 a_1 \dots a_n v_n$ a decomposition of a substring of $h_1^m(\sigma)$, where $n \geq 1$; $a_1, \dots, a_n \in \Omega$; $v_0, \dots, v_n \in \Pi^*$. Assume that h^Ω is propagating. Assume further that $m \geq n$, and $|v_0|, |v_n| > H^n$. Then

$$h^\Omega(a_i) = a_i \quad \text{for all } i = 1, 2, \dots, n.$$

Proof Suppose that for some $a \in \{a_1, \dots, a_n\}$ $h^\Omega(a) \neq a$. Let c_0 be "the father of degree n of our a ", i.e. assume that the following picture is a part of the derivation tree in G



There are two possibilities :

(i) There exists $b \in \Omega$, $b \in m^\Omega(a)$, and $b \neq a$. As $a \in (m^\Omega)^j(c_{n-j})$ and G normal, we have $\{a, b\} \subseteq m^\Omega(c_j)$ for all $0 \leq j \leq n-1$. From this we get $|(h^\Omega)^n(c_0)| \geq n+1$.

(ii) $h^\Omega(a) = a^r$ for some $r \geq 2$. As before, from the normality and from $a \in (m^\Omega)^n(c_0)$ we get $a \in m^\Omega(c_0)$. From this

$$|(h^\Omega)^n(c_0)| \geq r^n \geq n+1 \quad \text{if } n \geq 1.$$

Thus in both cases $h_1^n(c_0)$ has at least $n+1$ occurrences of symbols from Ω .

In other words, either v_0 or v_n must be a substring of $h_1^n(c_0)$, but from this $|v_0|$ or $|v_n| \leq H^n$. \square

5. The Main Theorem

Theorem 3 Every pair of normal equivalent DOL-systems has bounded balance.

Proof Let $G_i = (\Sigma, h_i, \sigma)$ for $i = 1, 2$. Denote by r the order of G_1 (same as G_2). The proof will be by induction on r .

Base of induction, $r = 1$. Let $\Sigma_c = \{a\}$. For $i = 1, 2$ we have:

- (i) for each $b \in \Sigma_\ell$, $h_i(b) = ca^{\alpha_{i,b}}$ for some $c \in \Sigma_\ell$ and $\alpha_{i,b} \geq 0$;
- (ii) $h_i(a) = a^{\beta_i}$ for some $\beta_i \geq 0$;
- (iii) for each $b \in \Sigma_r$, $h_i(b) = a^{\alpha_{i,b}}c$ for some $c \in \Sigma_r$ and $\alpha_{i,b} \geq 0$.

Since G_1 and G_2 are equivalent, obviously, $\beta_1 = \beta_2$ and the balance of the pair (G_1, G_2) is at most $\max_{i=1,2; b \in \Sigma_\ell} \alpha_{i,b}$, i.e. the pair (G_1, G_2) has bounded balance.

We now make the induction hypothesis that the assertion holds for systems of order smaller than a fixed $r > 1$, and consider a pair of systems of order r , i.e. $|\Sigma_c| = r \geq 2$.

Case I: Assume that $h_1(a) = h_2(a) = \epsilon$ for some $a \in \Sigma_c$. Then $\Pi = \{a\}$ is a common subalphabet. Let $\Omega = \Sigma - \Pi$. Since G_1 and G_2 are equivalent also G_1^Ω and G_2^Ω are equivalent and since $|\Omega_c| < |\Sigma_c|$ the pair (G_1^Ω, G_2^Ω) has bounded balance by induction hypothesis. Subalphabet Π is clearly limited and therefore the pair (G_1, G_2) has bounded balance by Lemma 6.

Case II: Assume that $h_1(a) = \epsilon$ for some $a \in \Sigma_c$ but not necessarily $h_2(a) = \epsilon$. Consider the combination $\{(G_1^1, G_2^1), (G_1^2, G_2^2)\}$ of (G_1, G_2) .

We have $\bar{h}_1(a) = h_1^2(a) = \epsilon$, $\bar{h}_2(a) = h_2(h_1(a)) = \epsilon$, so by case I, (G_1^i, G_2^i) has bounded balance for $i = 1, 2$ and so has (G_1, G_2) by Lemma 7.

Case III: We may now assume that both G_1 and G_2 are propagating. By Lemma 5 either the combination of (G_1, G_2) is simple, this implies, using Theorem 2 and Lemma 7, that (G_1, G_2) has bounded balance, or there is a common subalphabet Π . Denote $\Omega = \Sigma - \Pi$ and $\Omega_c = \Sigma_c - \Pi$. We may assume that Π is maximal, i.e. there is no subalphabet Π' so that $\Pi \subsetneq \Pi' \subsetneq \Sigma_c$. We may further assume without loss of generality that either Ω_c has exactly one element or h_1^Ω and h_2^Ω are propagating. This is so for the following reasons. In view of Lemma 7, in order to prove that the pair (G_1, G_2) has bounded balance we may show this for the combination of (G_1, G_2) instead. Note also that every common subalphabet with respect to G_1, G_2 is also a common subalphabet with respect to the combination of (G_1, G_2) , i.e. with respect to each pair of systems from the combination. Suppose now that the assumption above is not valid, i.e. for some a in Ω_c either $h_1(a) = \varepsilon$ or $h_2(a) = \varepsilon$ and $\Omega_c - \{a\} \neq \emptyset$. Then for the homomorphisms \bar{h}_1, \bar{h}_2 from the combination of (G_1, G_2) (or (G_2, G_1)) we have $\bar{h}_1^\Omega(a) = \bar{h}_2^\Omega(a) = \varepsilon$. Therefore, $\Pi \cup \{a\}$ is also a common subalphabet with respect to the combination of (G_1, G_2) . It might not be a maximal one but can be enlarged to such. If this new subalphabet does not satisfy our assumption we repeat the above construction. After a finite number of steps we get a maximal subalphabet, which meets the assumption.

Since G_1 and G_2 are equivalent G_1^Ω and G_2^Ω are also equivalent, and since they are of order smaller than r and normal, the pair (G_1^Ω, G_2^Ω) has bounded balance by the induction hypothesis. For the rest of the proof we will use the following notation. The balance of (G_1^Ω, G_2^Ω) is denoted by c and $H = \max_{i=1,2} (\max_{a \in \Sigma} |h_i(a)|)$.

Now, as a part of Class III we formulate and prove the following.

Claim 1 Suppose that for every G_1 -prefix of the form wav , where $w \in \Sigma^*$, $a \in \Omega$ and $v \in \Pi^*$ with $|v| > H^c$

$$(11) \quad \beta^\Omega(wa) = 0.$$

Then the pair (G_1, G_2) has bounded balance.

Proof Let $Q = H^c$ and let $S = \{w \in \Omega\Pi^*\Omega : Q < |w| \leq HQ\}$. Now, consider the pairs of induced systems (cf. def.6) (G_1^w, G_2^w) for each $w \in S$. By (11) and Lemma 8 the systems G_1^w and G_2^w are equivalent for each $w \in S$. Clearly, G_i^w is normal for each $w \in S$ and $i = 1, 2$.

Hence, by the induction hypothesis the pair (G_1^w, G_2^w) has bounded balance for every $w \in S$. Let the balance of (G_1^w, G_2^w) be c_w , and let $c_\Pi = \max_{w \in S} c_w$, which is well defined since S is finite.

We now proceed in the proof of Claim 1 by considering all G_1 -prefixes, and show that their balances are bounded. Every G_1 -prefix x can be written uniquely in the form $x = a_d v_d a_{d-1} v_{d-1} \dots a_1 v_1$ for some $d \geq 1$, and $a_i \in \Omega$, $v_i \in \Pi^*$ for $i = 1, 2, \dots, d$. We will consider four cases. In the first three we assume that x is a prefix of $h_1^t(\sigma)$ for some $t \geq c$.

Case A Let $d \leq c$ and $|v_i| \leq Q$ for $i = 1, 2, \dots, d$. In this case we have $\beta(x) \leq dQ + dH \leq c(Q+H)$.

Case B Let $d > c$ and $|v_i| \leq Q$ for $i = 1, 2, \dots, c+1$. Without loss of generality we may assume that $h_1(x)$ is a prefix of $h_2(x)$, i.e. $h_2(x) = h_1(x)z$ for some $z \in \Sigma^*$. Since $\beta^\Omega(x) \leq c$, z contains at most c occurrences of symbols from Ω ; at the same time G_2 is propagating and therefore z is

a suffix of $h_2(v_{c+1}a_c v_c \dots a_1 v_1)$ (see Fig.1), thus

$$\beta(x) = |z| \leq H |v_{c+1}a_c v_c \dots a_1 v_1| \leq (c+1)(Q+1)H.$$

Case C Let there exists an m such that $1 \leq m \leq \min(d, c+1)$ and $|v_m| > Q$; assume that m is the smallest such index, i.e. $|v_j| \leq Q$ for $1 \leq j < m$. By (11) we have $\beta^\Omega(a_d v_d \dots v_{m+1} a_m) = 0$, this implies that $h_i(a_d v_d \dots v_{m+1} a_m) = z u_i$ for some $z \in \Sigma^* \Omega$ and $u_i \in \Pi^*$ where u_i is a suffix of $h_i(a_m)$, for $i = 1, 2$. Therefore $\beta(a_d v_d \dots v_{m+1} a_m) \leq H$. Also $\beta(v_m) \leq \beta'(a_m v_m) + 2H \leq c_{II} + 2H$, where β' is the balance with respect to the pair (G_1^W, G_2^W) for a suitable $w \in S$. Such a w exists since every G_1 -substring y such that $y \in \Omega \Pi^*$ and $|y| \geq Q+1$ is a G_1^W -prefix for some $w \in S$. Finally,

$$\beta(a_{m-1} v_{m-1} \dots a_1 v_1) \leq (m-1)H(Q+1) \leq c(Q+1)H. \text{ Since}$$

$\beta(x) \leq \beta(a_d v_d \dots v_{m+1} a_m) + \beta(v_m) + \beta(a_{m-1} v_{m-1} \dots a_1 v_1)$, $\beta(x)$ is bounded for all G_1 -prefixes belonging to Case C.

Case D There are only finitely many G_1 -prefixes not considered in the previous cases, thus we may conclude that the balance is bounded on all G_1 -prefixes. \square

We have completed the proof of Claim 1 and will continue with Case III of the proof of Theorem 3. We will consider four subcases.

Subcase IIIA. Let $\Sigma_c = \Pi \cup \{a\}$, i.e. $\Omega_c = \Sigma_c - \Pi = \{a\}$, and $h_1^\Omega(a) = h_2^\Omega(a) = a$. Let $p \geq 1$ be the smallest integer such that if $\sigma = bud$, then $h_1^p(bud) = bvd$, for some v in Σ^* . Then for all $n \geq 0$ the first (last) symbol of $h_1^n(\sigma)$ and of $h_1^{n+p}(\sigma)$ are the same.

Consider any pair of $\&r$ -systems from the p -combination of (G_1, G_2) , say (G_1^m, G_2^m) where $G_i^m = (\Sigma, \bar{h}_i, \sigma_m)$ for $i = 1, 2$. We proceed to show that (G_1^m, G_2^m) has bounded balance. Let $\sigma_m = bud$ for some $b, d \in \Omega$, clearly $\bar{h}_1^n(\sigma_m) \in b\Pi^*d$ for all $n \geq 0$.

Denote by ℓ_i, r_i the number of occurrences of a in $\bar{h}_i(b)$ and $\bar{h}_i(d)$, respectively, ($i = 1, 2$). As $\ell_i + r_i$ is the number by which the number of occurrences of a is increased when \bar{h}_i is applied to any string bwd with $w \in \Sigma_C^*$ we have $\ell_1 + r_1 = \ell_2 + r_2$. Without loss of generality we may assume that $\ell_1 \geq \ell_2$.

If $\ell_1 = \ell_2$, then also $r_1 = r_2$ and clearly $\beta^\Omega(x) = 0$ for every G_1^m -prefix. Therefore, by Claim 1 the pair (G_1^m, G_2^m) has bounded balance. Since this is true for every pair from the p -combination of (G_1, G_2) the pair (G_1, G_2) has also bounded balance by Lemma 7.

It remains to consider the case $\ell_1 > \ell_2$. For each $n \geq 0$ we can write $\bar{h}_1^n(\sigma) = bv_1^{(n)}av_2^{(n)} \dots av_{s_n}^{(n)}d$, where $v_j^{(n)} \in \Pi^*$ for $j = 1, \dots, s_n$. The number of occurrences of a in $h_1^n(b)$ is $n\ell_1$, thus $bv_1^{(n)}a \dots av_{n\ell_1}^{(n)}a$ is a prefix of $h_1^{n'}(b)$ for each $n' \geq n$. Therefore $v_j^{(n')} = v_j^{(n)}$ for all n, n' and $j = 1, 2, \dots, \min(n, n')\ell_1$. Symmetrically we get $v_{s_{n'}-j}^{(n')} = v_{s_n-j}^{(n)}$ for $j = 1, 2, \dots, \min(n, n')r_2$.

Let $q > (\ell_1 + r_1 + s_0) / (\ell_1 - \ell_2)$. Consider any $v_j^{(n)}$ for $n > q$. If $j \leq (n-1)\ell_1$, then

$$(12) \quad v_j^{(n)} = v_j^{(n-1)},$$

if $j \geq s_{n-1} - (n-1)r_2$, then

$$(13) \quad v_j^{(n)} = v_{s_{n-1}-j}^{(n-1)}.$$

Since $s_n = s_0 + n(\ell_1 + r_1)$ we have $s_{n-1} - (n-1)r_2 - (n-1)\ell_1 = s_0 + (n-1)(\ell_1 + r_1) - (n-1)r_2 - (n-1)\ell_1 = s_0 - (n-1)(r_2 - r_1) = s_0 - (n-1)(\ell_1 - \ell_2) < s_0 - (\ell_1 + r_1 + s_0) < 0$. The inequality follows from the choice of q and n above. Hence, all $j = 1, 2, \dots, s_n$ are considered in

either (12) or (13). Since this is so for all $n > q$ we conclude by induction that, for each $n > q$, all the substrings of $\bar{h}_1^n(\sigma)$ occurring between two consecutive a 's have already occurred in $\bar{h}_1^q(\sigma)$. Therefore, there is only a finite number of distinct substrings from Π , thus Π is limited and the pair (G_1^m, G_2^m) has bounded balance by Lemma 6. Since this is true for each pair in the p -combination of (G_1, G_2) the pair (G_1, G_2) also has bounded balance by Lemma 7. This concludes Subcase IIIA.

Subcase IIIB. Let $\Omega_c = \{a\}$ and $h_1^\Omega(a) = h_2^\Omega(a) = \varepsilon$. Since here the symbol a can occur only in $h_i(b)$ for $b \in \Sigma_\ell \cup \Sigma_r$, we can write the string $h_1^n(\sigma)$ for each $n \geq 1$ in the form $\ell u_1 a_1 u_2 \dots u_k a_k w b_m v_m \dots b_1 v_1 r$ where $\ell \in \Sigma_\ell$, $r \in \Sigma_r$, $a_j \in \Omega_c$, $u_j \in \Pi^*$, $|u_j| < H$, for $j = 1, \dots, k$, $b_j \in \Omega_c$, $v_j \in \Pi^*$, $|v_j| < H$, for $j \in 1, 2, \dots, m$ and $w \in \Pi^*$.

Since G_1 and G_2 are equivalent we have $h_1^\Omega(\ell') = \ell a_1 \dots a_k = h_2^\Omega(\ell')$ where ℓ' is the first symbol in $h_1^{n-1}(\sigma)$. Since $\beta^\Omega(u_1 a_1 \dots u_k a_k) = 0$, we have $\beta^\Omega(\ell u_1 a_1 \dots u_k a_k) = |\ell a_1 \dots a_k| - |\ell a_1 \dots a_k| = 0$. As w is the only maximal (i.e. with neighbors from Ω) substring over Π which can be longer than H^c we can apply Claim 1 and conclude that the pair (G_1, G_2) has bounded balance.

Subcase IIIC. Let $\Omega_c = \{a\}$, $h_1^\Omega(a) = \varepsilon$ and $h_2^\Omega(a) \neq \varepsilon$. We consider the combination of (G_1, G_2) . For the homomorphisms \bar{h}_1, \bar{h}_2 from the combination we have $\bar{h}_1(a) = \bar{h}_2(a) = \varepsilon$, which is the Subcase IIIB. Finally, the pair (G_1, G_2) has bounded balance by Lemma 7. Similarly for $h_1^\Omega(a) \neq \varepsilon$ and $h_2^\Omega(a) = \varepsilon$.

Subcase D. Let h_1^Ω and h_2^Ω be propagating and either Ω_c contains more than one symbol, or if $\Omega_c = \{a\}$, then $h_1^\Omega(a) \neq a$.

We show that the assumption of Claim 1 is satisfied. Let w be a G_1 -prefix, where $w \in \Sigma^*$, $a \in \Omega_c$ and $v \in \Pi^*$ with $|v| > H^c$. Denote

$\beta^{\Omega}(wa)$ by p and assume that $p > 0$, i.e. one of the strings $h_1(wa)$ and $h_2(wa)$ is a proper prefix of the other, say $h_2(wa) = h_1(wa)z$, where z contains p occurrences of symbols from Ω_c . We may write (see Fig.2)

$$(14) \quad h_2(wav) = h_1(wa)z \quad h_2(v) = h_1(wa)u_0b_1\dots b_p u_p$$

where $b_1, b_2, \dots, b_p \in \Omega_c$ and $u_0, u_1, \dots, u_p \in \Pi^*$. Note that $h_2(v)$ is a suffix of u_p and since G_2 is propagating we have $|u_p| > H^C$.

Now, we will show that

$$(15) \quad |u_j| \leq H^C, \quad \text{for } j = 0, \dots, p-1.$$

If (15) does not hold, there is s , $0 \leq s \leq p-1$, such that $|u_s| > H^C$ and, by Lemma 9, $h_i^{\Omega}(b_j) = b_j$ for all $j = s+1, \dots, p$ and $i = 1, 2$. This is in contradiction with the assumption that Π is a maximal subalphabet as we can add any one of the b_j ($j = s+1, \dots, p$) to Π to obtain a larger subalphabet. Note that since Ω_c does not consist of a single symbol a such that $h_1^{\Omega}(a) = h_2^{\Omega}(a) = a$, the enlargement of Π is properly contained in Σ_c , and therefore it is in fact a subalphabet. Hence (15) is established.

However, using (14) we see that $h_1(v)$ is a prefix of u_0 and since G_1 is propagating we have $|u_0| \geq |h_1(v)| \geq |v| > H^C$, which is in contradiction with (15). Thus the assumption $p > 0$ is false, and we have $\beta^{\Omega}(wa) = 0$. Finally, we conclude using Claim 1 that the pair (G_1, G_2) has bounded balance also in this last subcase. That completes the proof of Theorem 3. \square

Corollary 1 The sequence equivalence problem for DOL-system is decidable.

Proof Theorem 3 shows that the family of normal systems is smooth in the terminology of (Culik, 1975), therefore, the sequence equivalence problem is decidable for this family by Theorem 2.1 from (Culik, 1975). Thus, by Theorem 1, the problem is decidable for all DOL-systems. \square

Corollary 2 Given two DOL-systems G_1, G_2 , it is decidable whether $L(G_1) = L(G_2)$.

Proof By Corollary 1 and (Nielsen, 1974). \square

6. Regular Envelopes

We have shown that every pair of equivalent normal DOL-systems has bounded balance. This bounded balance was then used to construct a decision algorithms to test the equivalence. There is another property which is equivalent to bounded balance and which is quite interesting, but as the following facts are not needed for the main result we will state them without a proof.

Definition 7 Let $G_i = (\Sigma, h_i, \sigma)$, $i = 1, 2$ be two DOL-systems. We say that a set R is a true envelope for the pair (G_1, G_2) if

- (i) $L(G_1) \subseteq R$ and $L(G_2) \subseteq R$
- (ii) $h_1(x) = h_2(x)$ for all $x \in R$.

Obviously, if a pair (G_1, G_2) has a true envelope then G_1, G_2 are equivalent.

Theorem 4 Let $G_i = (\Sigma, h_i, \sigma)$, $i = 1, 2$ be two equivalent DOL-systems. Then the pair (G_1, G_2) has bounded balance iff there exists a regular set R which is a true envelope of (G_1, G_2) .

The proof is independent of Theorem 3 and the main idea is in the fact that the bound on the balance is also a bound on the number of states of an automaton which compares prefixes of $L(G_1)$ and $L(G_2)$. In more details, if x is an G_1 prefix then either

$$(16) \quad h_1(x) = h_2(x)z$$

or

$$(17) \quad h_2(x) = h_1(x)z$$

for some $z \in \Sigma^*$. The relations (16) or (17) enable us to introduce a congruence relation $x \equiv x'$ if (16) or (17) holds with the same z . If the congruence is finite, we have a finite automaton, but this also gives the bound on the balance as the maximum length of z . \square

The existence of a regular true envelope gives also an alternative, but essentially the same construction for the algorithm which decides a possible equivalence.

Theorem 5 If every pair of equivalent DOL-systems has a regular true envelope, then the sequence equivalence problem for DOL-systems is recursively decidable.

Proof Let $R_1, R_2, \dots, R_k, \dots$ be any effective enumeration of regular sets (more precisely their representatives, say finite automata), which of course exists. For each $k = 1, 2, \dots$ check whether R_k is a true envelope of

(G_1, G_2) . Condition (i) is equivalent to $L(G_1) \cap \bar{R} = \emptyset$, \bar{R} is again regular and for a DOL-system and a regular set we can effectively find EOL-system G' so that $L(G') = L(G_1) \cap \bar{R}$. Finally, emptiness problem is decidable for EOL-systems. Condition (ii) can clearly be checked since it is enough to check it for a finitely many strings, e.g. only for simple paths and loops of a finite automaton representing R . From our assumption we know that if G_1, G_2 are equivalent then there exists a true envelope for (G_1, G_2) and we will find this true envelope in our enumeration, therefore our procedure will always halt in that case, and gives a semi-decision procedure for equivalence. Since a semi-decision procedure for non-equivalence obviously exists we have completed the proof. \square

Acknowledgements

The authors are grateful to H. Jürgensen, J. Karhumäki, K. Ruohonen and A. Salomaa for helpful comments to the earlier version of this paper.

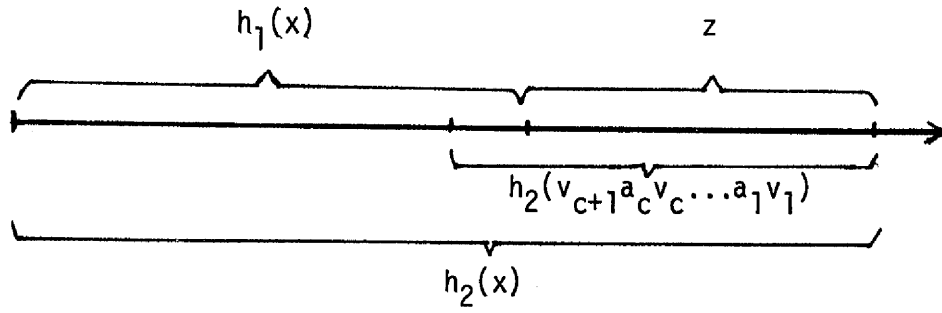


Figure 1

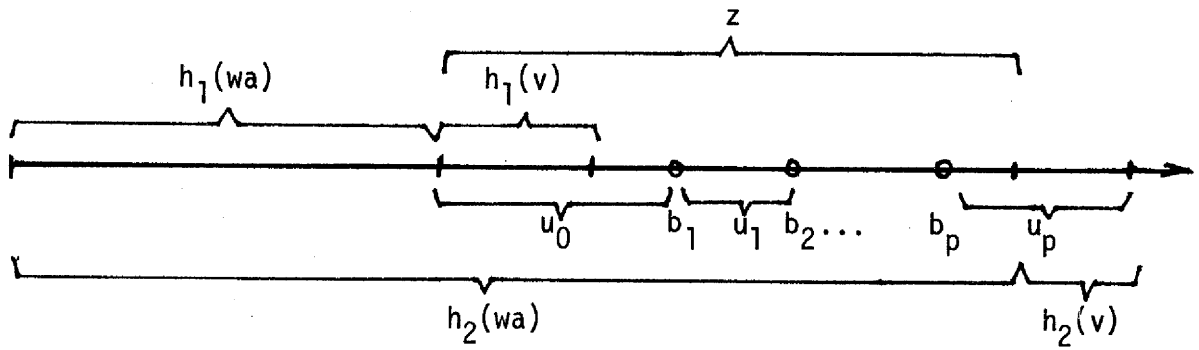


Figure 2

References

- Culik II, K. (1975), On the decidability of the sequence equivalence problem for DOL-systems, *Theoretical Computer Science*, to appear, also Res. Rep. CS-75-24, Dept. of Computer Science, University of Waterloo.
- Ehrenfeucht, A. and Rozenberg, G. (1974), Private communication.
- Gantmacher, F.R. (1960), *The Theory of Matrices*, vol.2, Chelsea, New York.
- Johansen, P. and Meiling, E. (1974), Free groups in Lindenmayer systems, in L-systems edited by G. Rozenberg and A. Salomaa, *Lecture Notes in Computer Science*, Springer-Verlag, vol.15.
- Karhumäki, J. (1976), The decidability of the equivalence problem for polynomially bounded DOL sequences. Preprint series, Dept. of Mathematics, University of Turku.
- Lindenmayer, A. (1971), Developmental systems without cellular interaction, their languages and grammars, *J. of Theoretical Biology* 30, 455-484.
- Nielsen, M. (1974), On the decidability of some equivalence problems for DOL-systems, *Information and Control* 25, 166-193.
- Paz, A. and Salomaa, A. (1973), Integral sequential word functions and growth equivalence of Lindenmayer systems, *Information and Control* 23, 313-343.
- Problem Book (1973), Unusual Automata Theory January 1972, Dept. of Computer Science, University of Aarhus Techn. rep. DAIMI PB-15, 14-26.
- Salomaa, A. (1973), On sentential forms of context-free grammars, *Acta Informatica* 2, 40-49.
- Valiant, L.G. (1975), The equivalence problem for DOL-systems and its decidability for binary alphabets, Techn. rep. No.74, University of Leeds.