

Department of Applied Analysis
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DATA COMMUNICATIONS SUPPORT
ROUTINES FOR THE NETWORKS LABORATORY

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This report in the University of Waterloo Computer Science Departmental Series is also available under separate cover, for the benefit of readers in the Computer Communications area who do not receive the Computer Science Series.

NAME DCI:

DESCRIPTION - DCI: is a non-terminal input device driver for the DC11 asynchronous interface. Binary data blocks are accepted by DCI: and sent to the system address. In detail DCI: when it is ready to accept a 256 word block sends a request to the sending end of the network. The other end will then begin sending the data byte by byte. The first byte is for indicating an end of file. The next 512 bytes are data. If the first byte indicates end, DCI will tell the system and a normal CLOSE will initiate. DCI: is the counterpart to DCO:

USES - together with DCO:, DCI: provides hands off file transfer between any two PDP-11 DOS systems. The transfer can take place in the same room with NULL MODEMS or across the country over a single telephone line. Also, other machines could support this type of transfer with a program to simulate these routines.

PROGRAMMING: DCI: is an input device with 4 units which map into the DC11 speeds. (See DCT: for a better explanation). Otherwise it can be used as any other DOS device.

ERRORS: no errors will evolve from DCI but the handler will loop until the line is connected.

NOTE DCO: and DCI: are being combined into one file DCF.

.TITLE DCI

```

174000 RCSR=174000
174002 RBUF=174002
174004 TCSR=174004
174006 TBUF=174006
000000 RZ=%0
000001 R1=%1
000006 SP=%6
000005 R5=%5
000007 PC=%7

```

DCI1 INPUT HANDLER

```

000000 000000 DCI: .WORD 0 ;DVR VECTOR
000002 000002 .WORD 334 ;INPUT,ASCII,BIN
000004 000004 .BYTE 27 ;256 WORD BUFFER
000006 000006 .BYTE 240
000008 000008 .BYTE DC.OPN-DCI
000010 000010 .BYTE DC.TRN-DCI
000012 000012 .BYTE DC.CLS-DCI
000014 000014 .WORD 2
000016 014601 DC.DEV: .RAD50 /DCI/
;
; OPEN ROUTINE
;
000016 012737 DC.OPN: MOV #1,@#RCSR ;SET READY
000018 000001
000020 174000
000022 012737 MOV #1,@#TCSR
000024 000001
000026 174004
000028 016700 MOV DCI,R0
000030 177742
000032 116001 MOVB 13(R0),R1 ;GET UNIT #
000034 000013
000036 042701 BIC #177774,R1 ;DROP GARBAGE
000038 177774
000040 006101 ROL R1
000042 006101 ROL R1
000044 006101 ROL R1
000046 050137 BIS R1,@#RCSR ;CONVERT TO SPEEDS AND SET IN CSR
000048 174000
000050 050137 BIS R1,@#TCSR
000052 174004
000054 005726 DCOPN1: TST (SP)+
000056 000170 JMP @14(R0) ;FINISHED OPEN OR CLOSE
000058 000014
;
;
; CLOSE ROUTINE CLEAR CSR
;
000060 005037 DC.CLS: CLR @#RCSR
000062 174000
000064 005037 CLR @#TCSR
000066 174004

```

```

000102 016700      MOV DCI,R0
000106 177672
000106 020766      BR DCOPN1
;
;      TRANSFER START ROUTINE SET ADDRESSES AND WAIT FOR
;      CARRIER DETECT TO BEGIN RECEIVING
;
000110 016700 DC.TRN: MOV DCI,R0
000110 177664
000114 016067      MOV 6(R0),WHERE ;SYSTEM BUFFER ADDRESS
000114 000006
000114 020150
000122 016021      MOV 10(R0),R1   ;GET WORD COUNT
000122 000010
000126 026321      ASL R1          ;NOW BYTE COUNT
000130 010167      MOV R1,WHEN     ;STORE
000130 000150
000134 032737      BIT #4,@#RCSR  ;CARRIER?
000134 000024
000134 174000
000142 021774      BEQ .-6         ;NO
000144 012737      MOV #6,@#TBUF
000144 000026
000144 174006
000152 105267      INCB SW
000152 072132
000156 052737      BIS #100,@#RCSR ;EN INTERRUPT
000156 000100
000156 174000
000164 000207      RTS PC         ;RETURN WAIT
;
;
000166 105767 RXINT: TSTB SW          ;FIRST CHAR
000166 000116
000172 001410      BEQ RXINT1     ;NO NORMAL
000174 105737      TSTB @#RBUF   ;END OF FILE CHAR
000174 174002
000200 100421      BMI RXINT2     ;YES FINISH
000222 105037      CLRB @#RBUF
000222 174002
000206 105267      CLRB SW
000206 000276
000212 022022      RTI
000214 025737 RXINT1: TST @#RCSR   ;LOOK FOR ERROR
000214 174000
000220 102411      BMI RXINT2
000222 113777      MOVB @#RBUF,@WHERE
000222 174002
000230 000052
000230 105267      INC WHERE
000230 000746
000234 005267      INC WHEN
000234 022044
000240 022021      BGE RXINT2     ;END OF LINE
000242 022022      RTI
;

```

```

;          ERROR OR END
;
200244 242737 RXINT2: BIC #100,@#RCSR ;DISABLE DEV
          200100
          174000
000252 013746          MOV @#44,-(SP)
          000044
000256 204536          JSR R5,@(SP)+
000260 016700          MOV DCI,R0
          177514
000264 016701          MOV WHEN,R1
          000014
000270 006201          ASR R1
000272 210160          MOV R1,16(R0)
          000016
000276 000170          JMP @14(R0)
          000014

```

```

;
000302 000000 WHERE: .WORD 0
000304 000000 WHEN: .WORD 0
000306 000000 ERRORC: .WORD 0
000310 000000 SW: .BYTE 0
          000001 .END

```

NAME - DCO:

DESCRIPTION - DCO: is a non-terminal output device driver for the DC11 interface unit. DCO: sends out 256 word data blocks at the request of the receiving end of the line. This is the counterpart or complement of DCI: In detail DCO: waits for an ACK character from the receiving end. Upon receipt of it a block of data is shipped out preceded by a null block indicating data. If DCO: is in an end of file state, the character 100 will be sent instead. This will turn off the receiving end.

USES - see DCI:

PROGRAMMING - DCO: also has 4 speeds which are mapped into unit numbers 0-3. Otherwise DCO: works as any other DOS device.

ERRORS - no errors will occur from DCO.

NOTE - DCO: and DCI: are being combined into one name DCF:

.TITLE DCO

174224 TCSR=174224
 174228 RCSR=174228
 174232 RBUF=174232
 174236 TBUF=174236
 222220 R2=%0
 222221 R1=%1
 222226 SP=%6
 222225 RS=%5
 222227 PC=%7

;
 ; DC11 OUTPUT HANDLER
 ;

200200 222228 DCO: .WORD 2 ;DVR VECTOR
 200202 222332 .WORD 332 ;OUTPUT,ASCII,BIN,TERMINAL
 200204 222 .BYTE 20 ;256 WORD BUF
 222225 240 .BYTE TXINT-DCO
 222226 242 .BYTE 240
 222227 216 .BYTE DC.OPN-DCO
 222210 140 .BYTE DC.TRN-DCO
 222211 276 .BYTE DC.CLS-DCO
 222212 200220 .WORD 2
 222214 214627 DC.DEV: .RAD50 /DCO/

;
 ; OPEN ROUTINE
 ;

222216 212737 DC.OPN: MOV #1,@#TCSR ;SET REQUEST TO SEND
 200221 174224
 222224 225267 CLR SW
 222226 222270
 222230 212737 MOV #1,@#RCSR ;ENABLE RECEIVER
 222221 174228
 222236 215720 MOV DCO,R0
 177736
 222242 116221 MOVB 13(R0),R1 ;GET UNIT #
 222213
 222246 242721 BIC #177774,R1 ;DROP GARBAGE
 177774
 222250 226121 ROL R1
 222254 226121 ROL R1
 222256 226121 ROL R1
 222260 252137 BIS R1,@#TCSR ;CONVERT TO SPEEDS AND SET IN CSR
 174224
 222264 252137 BIS R1,@#RCSR ;ALSO REC.
 174220
 222270 225726 DCOPN1: TST (SP)+
 222272 222170 JMP @14(R0) ;FINISHED OPEN OR CLOSE
 222214

;
 ;
 ; CLOSE ROUTINE CLEAR CSR
 ;

222276 125737 DC.CLS: TSTB @#RCSR
 174220

```

000102 100375 BPL .-4
000104 113705 MOV3 @#RBUF,R5 ;GET THE CHAR
      174042
000110 120527 CMPB R5,#6
      000276
000114 011370 BNE DC.CLS ;IF NNT ACK THEN IGNORE
000116 015075 CLR R5
000120 116737 MOV3 STOP,@#TBUF
      000173
      174046
000126 005067 CLR WHEN
      000162
000130 005067 INC SW
      000162
000136 000227 RTS PC
;
;
;
;
000140 016730 DC.TRN: MOV DC0,R0
      177634
000144 016467 MOV 6(R0),WHERE ;SYSTEM BUFFER ADDRESS
      000006
      000140
000152 016371 MOV 10(R0),R1 ;GET WORD COUNT
      000210
000156 006371 ASL R1 ;NOW BYTE COUNT
000160 012167 MOV R1,WHEN ;STORE
      000130
000164 006367 DEC WHEN
      000124
000170 030737 BIT #2,@#TCSR ;CLEAR TO SEND ?
      000002
      174044
000176 001774 BEQ .-6 ;NO
000200 125737 DCTRN1: TSTB @#RCSR ;OTHER END READY ?
      174046
000204 100375 BPL .-4 ;NO WAIT
000206 113705 MOV3 @#RBUF,R5
      174042
000212 120527 CMPB R5,#6
      000276
000216 011370 BNE DCTRN1 ;UNLESS 5 IGNORE
000220 005075 CLR R5
000222 052737 BIS #100,@#TCSR ;EN INTERRUPT
      000173
      174074
000230 116737 MOV3 START,@#TBUF ;SEND START CODE FIRST
      000262
      174076
000236 000227 RTS PC ;WAIT FOR DONE
;
;
;
000240 005067 TXINT: INC WHEN
      000250

```



```

070244 072076 BGE TXEND
070246 117737 MOV3 @WHERE,@#TBUF
      072040
      174076
070254 085267 INC WHERE
      072032
070260 072072 RTI
070262 076767 TXEND: TST SW ;CLOSE OR TRAN
      072032
070266 071402 BEQ TXEND1 ;TRAN
070270 075037 CLR @#TCSR
      174074
070274 013746 TXEND1: MOV @#44,-(SP)
      089044
070300 104036 JSR R5,@(SP)+
070302 016770 MOV DCO,R0
      177472
070306 070177 JMP @14(R0)
      073014
;
070310 080070 WHERE: .WORD 0
070314 100070 WHEN: .WORD 0
070316 070 START: .BYTE 0
070317 070 STOP: .BYTE 200
070320 070 SW: .WORD 0
      073071
      .END

```

NAME DCT:

DESCRIPTION: DCT is an ASCII terminal handler for the DC11 asynchronous interface on the PDP-11. Both terminal output and echo input are supported by DCT: All speeds supported by the DC11 are available without any special control functions.

On OUTPUT - Character lines of ASCII are put onto the terminal device until either the end of file or a Control X is typed on the keyboard. To continue from a Control X simply type another one. Tabs are converted to spaces, Rubout is ignored as are all illegal control characters.

On INPUT - The character '>' is typed on the device to indicate that it is ready to receive one line. Each input character is checked and echoed if valid. Tabs are converted to spaces. A control U will restart the current line. A rubout deletes the previous character in the line. Any valid terminator, LF, VT or FF will disable the input until the system has received the current line. Then the whole sequence recommences. DCT: has its own internal line buffer for input. All operations are done on it until a terminator initiates the transfer to the system.

USES - DCT: can replace the teletype for both input and output applications. There are many terminal devices that can operate at speeds up to 1800 BAUD. DCT: can operate these devices, whereas the KB: driver cannot.

- The DC11 can operate through any standard modem device. With DCT: one could remotely access the PDP-11 from any distance through telephone lines.

- DCT: could become the console handler for the PDP-11 DOS system. With this the user could access DOS from his home or another computer could initiate jobs on the remote PDP-11.

PROGRAMMING - DCT is a DOS compatible driver for terminal devices. It can be employed where KB: is used with one exception: DCT requires a unit number 0 to 3. This unit number maps into the speed setting for the DC11.

Eg. if one has a DC11 AA wired for speeds

0	-	110	BAUD
1	-	134.5	"
2	-	150	"
3	-	300	"

DCT:	or	DCT0:	will	drive	the	DC11	at	110	BAUD
DCT1:		DCT0:	will	drive	the	DC11	at	134.5	"
DCT2:		DCT0:	will	drive	the	DC11	at	150	"
DCT3:		DCT0:	will	drive	the	DC11	at	300	"

DCT: expects the DC11 to start at address 174000 and interrupt vector at 300. Any other configuration requires alteration of DCT.

- Other than the speed setting, DCT can be used as any other system I/O device.

ERRORS - no errors occur directly from DCT: .

- A listing of DCT follows: -

R0=%0
R1=%1
R2=%2
R3=%3
R4=%4
R5=%5
SP=%6
PC=%7
S202=0

```
;
; DC11 TERMINAL DEVICE DRIVER
;
; .TITLE DCT
; .GLOBL DCT
;
; DESIGNED TO DRIVE ANY ASCII TERMINAL DEVICE
;
; FROM DOS 11 , ALSO COULD BE USED FOR A
;
; CONSOLE DEVICE UNDER DOS
;
; ---DEVICE VECTOR---
;
DCT: .WORD 0 ;BUSY IND. AND DDB POINTER
      .WORD 427 ;TERM,IN,OUT,ASCII,MULTI USER
      .BYTE 6 ;120 OCTAL BYTES BUFFER
      .BYTE TRNXX-DCT ;RCVR INT ADDRESS DISP
      .BYTE 240 ;PRIORITY = 5
      .BYTE 0
      .BYTE DCTRN-DCT ;TRAN ROUTINE
      .BYTE 0,0,0
DCTDEV: .RAD50 /DCT/ ;NAME OF DEVICE
;
TRNXX: JMP TRANR ;INT ROUTINE ENTRY
;
; --- TRAN ROUTINE ---
;
; 1- SET SPEED , DATA ADDRESSES , I/O SWITCH
;
DCTRN: MOV DCT,R0 ;GET DDB ADDR
        MOVB 13(R0),R1 ;GET UNIT #
        BIC #177774,R1
        ASL R1
        ASL R1
        ASL R1 ;CONVERT TO SPEED FOR DC11
        INC R1 ;ADD ENABLE BIT
        MOV R1,DCENAB ;KEEP FOR LATER
        MOV PC,R1
        ADD #TRANX-.,R1
        MOV R1,@#304 ;SET TX INT VECTOR
        MOV #240,@#306
        MOV PC,R1
        ADD #BUFR-.,R1
        MOV R1,PBUFR ;GENERATE ADDRESSES FOR LATER USE
        ADD #117,R1
        MOV R1,PBUFRE
```

```
MOV PC,R1
ADD #BUFCR--,R1
MOV R1,PBUFCR
;
; SET SYSTEM BUFFER AND COUNT
;
MOV 6(R0),WHERE ;ADDRESS
MOV 10(R0),R1
ASL R1
MOV R1,WHEN ;BYTE COUNT
CLRB SWITCH
BIT #4,12(R0) ;IN OR OUT
BEQ .+6 ;OUT SW=0
INCR SWITCH
;
; INIT VARIABLES AND SWITCHES
;
INITIT: MOV R0,-(SP)
MOV PBUFR,R0
CLRB (R0)+
CMP R0,PBUFRE
BLT .-6
MOV (SP)+,R0
MOV DCT,R0
CLRB ECHOSW
CLRB WAITSW
CLRB STOPSW
CLRB TABSW
CLRB TABCNT
CLRB DONESW
MOV PBUFR,START ;INIT INPUT BUFFER PTRS
MOV START,ECHO
DEC ECHO
;
; START DC 11
;
MOV DCENAB,@#174000
MOV DCENAB,@#174004
;
; WAIT FOR CARRIER BEFORE GOING ON
;
INITT1: MOV @#174000,TEMP0
BIT #4,TEMP0
BEQ INITT1
BIS #100,@#174000
;
; CHECK DIRECTION SWITCH AND BRANCH IF OUTPUT
;
TSTB SWITCH
BEQ TRNX00 ;OUTPUT BRANCH
;
; INIT INPUT SEQUENCES
;
INCR ECHOSW
MOVB #'+',@#174006
BIS #100,@#174004
RTS PC
```

```
;
;
; --- END OF TRAN SETUP ---
;
; INIT OUTPUT BY FAKING INTERRUPT AND DROPPING TO INT TRN
;
TRNX00: MOV (SP),-(SP)
        MOV @#177776,2(SP)
;
; TRANSMITTER INTERRUPT ROUTINE
;
; FIRST DETERMINE DIRECTION
;
TRANX:  BIC #100,@#174004          ;DROP INT ON ENTRY
        TSTB TABSW                ;TAB IN PROG.?
        BEQ TRANX0                ; NO ! GO ON
;
; OUTPUT ANOTHER SPACE UNTIL TABCNT GIVES OUT
;
TRANX4: MOVB #40,@#174006
        INCB TABCNT                ;ONE LESS
        BPL TRANX3                ;DONE !
TRANX9: BIS #100,@#174004          ;EN INT.
        RTI
TRANX3: CLRB TABSW                 ;RESET WHEN DONE
        INC WHEN
        BR .-20
TRANX5: INCB TABSW                 ;ENTRY FOR INIT TABS
        BISB #370,TABCNT
        BR TRANX4                 ;SEND FIRST SPACE
;
;
; NEXT LOOP POSITION - LOOK FOR DIR.
;
TRANX0: TSTB SWITCH                ;IN OR OUT ?
        BNE TRANE                 ;IN ! GO TO ROUTINE
;
; OUTPUT ONLY SECTION OF TX INTERRUPT RTN
;
        TSTB STOPSW                ;DO WE STOP OUTPUTTING ?
        BEQ TRANX8                ;NO !!
;
; STOP CURRENT LINE BY FORCING CR LF
;
        MOV PBUF CR,WHERE
        MOV #-2,WHEN
        CLRB STOPSW
;
; CHECK FOR END OF LINE, GET CHAR , OUTPUT SAME
;
; UNLESS TAB OR TERMINATOR INWHICH CASE WAIT
;
; IF USER HAS TYPED *X.
;
TRANX8: TST WHEN                    ;DONE ?
        BPL DCEND                 ;YES !!!
;
```

```

;
TRANX1: MOV B @WHERE, TCHAR
        INC WHERE                ;UP OND NOW !
        BIC B #200, TCHAR       ;GET CHAR AND DROP PARITY
        CMP B TCHAR, #177      ;RUB OUT ?
        BEQ TRANX7              ;YES IGNORE !
        CMP B TCHAR, #40        ;VALID ?
        BLT TRANX2              ;MAYBE NOT
;
; SEND OUT CHARACTER
;
TRANX6: INC B TABCNT
        INC WHEN
        MOV B TCHAR, @#174006   ;SEND IT
        JMP TRANX9
;
; CHECK FOR TAB , CR , AND TERMINATOR
;
TRANX2: CMP B TCHAR, #11        ;TAB ?
        BEQ TRANX5              ;YES GO INIT TAB
        BLT TRANX7              ;IGNORE IF <
        CMP B TCHAR, #15        ;CR ?
        BEQ TRANX6              ;YES SEND IT
        BGT TRANX7              ;IGNORE IF >
;
; TERMINATOR FOUND WAIT IF USER HAS INDICATED
;
        MOV @#-2, -(SP)
        CLR @#-2                ;DROP PRIORITY FOR POS +C
        TST B WAITSW           ;WAIT UNTIL WAITSW = 0
        BNE .-4
        MOV (SP)+, @#-2        ;RESTORE PRIORITY
        CLR B TABCNT
        CMP B TCHAR, #12       ;LINE FEED ?
        BNE TRANX7             ;DO NOT WRITE IF NOT
        BR TRANX6+4
;
; IGNORE CHAR
;
TRANX7: INC WHEN
        BR TRANX8              ;GO GET ANOTHER CHAR
;
; END OF LINE REACHED RETURN TO SYSTEM
;
DCEND:  MOV @#44, -(SP)
        JSR R5, @(SP)+
        MOV DCT, R0
        JMP @14(R0)           ;END
;
; ECHO PORTION OF TRANSMIT INTERRUPT ROUTINE
;
;
TRANE:  INC ECHO                ;BUMP ECHO POINTER
        CMP ECHO, START        ;UP TO END YET ?
        BLT TRANE0             ;NO ! CONTINUE
;
; CHECK TO SEE IF A COMPLETE LINE YET

```

```

;
;   IF NOT - JUST RETURN
;
;   CLRB ECHOSW           ;ECHO DISABLE
;   TSTB DONESW         ;COMPLETE LINE
;   BNE TRANFL          ;YES GO FILL BUFFER
;   TSTB STOPSW         ;+U MATBE ???
;   BNE TRANE3          ;YES - RESET LINE
;   RTI                 ;OTHERWISE RETURN
;
;
;   ECHO CHARACTER AFTER CHECKING FOR SPECIALS
;
;   SUCH AS RUBOUT,CR,TAB,LF ETC.
;
;
;   TRANE0:  MOVB @ECHO,TCHAR           ;GET CHAR
;            RLCB #200,TCHAR
;            CMPB TCHAR,#177           ;RUBOUT ???
;            BEQ RUBOUT                ;YES !! SPECIAL PROCESSING
;            CMPB TCHAR,#40            ;VALID CHAR
;            BLT .+20                  ;IGNORE ECHO IF NOT!
;
;   TRANE1:  MOVB TCHAR,@#174006       ;ECHO CHAR
;            INCB TABCNT                ;AND SET TAB UP
;            JMP TRANX9
;
;
;   CONTROL CHAR CHECK FOR +U,ETC
;
;
;   CMPB TCHAR,#25                   ;+U ???
;   BEQ TRANE2                         ;YES ! GO AWAY
;   CMPB TCHAR,#11                    ;TAB ?
;   BEQ TRANX5                         ;YES INIT TAB SPACING
;   BLT TRANE                          ;IGNORE IF LESS
;   CMPB TCHAR,#15                     ;C R ??
;   BGT TRANE                          ;IGNORE IF GREATER
;   BNE TRANE1                         ;TERM CHAR - OK.
;   MOVB #12,@START                    ;END OF LINE
;   INC START                           ;C.R. ADD LINE FEED
;   BR TRANE1                           ;NOW ECHO C.R.
;
;
;   CONTROL U - RESET LINE AND ECHO '+U' ETC
;
;
;   TRANE2:  INCB STOPSW                ;TELL US ABOUT IT
;            MOV PBUFCR,START           ;SET TO +U PRINT
;            MOV START,ECHO
;            INC START
;            DEC ECHO
;            DEC ECHO
;            BR TRANE0                  ;START IT
;
;
;   AFTER +U DONE COME HERE
;
;
;   TRANE3:  CLRB STOPSW                ;RESET SWITCH
;            MOV 2(SP),@#177776         ;SET FOR RTS NOT RTI
;            MOV (SP)+,(SP)
;            JMP INITIT                 ;RESET
;
;

```

```

; RUBOUT ROUTINE BACK UP ONE DELETED CHARACTER
;
RUBOUT: MOV R0,TEMP0 ;KEEP R0
MOV ECHO,R0 ;WHERE WERE WE
DEC ECHO
DEC ECHO ;THIS IS WHERE WE END
CMP ECHO,PBUFR ;UNLESS BACKED TOO FAR
RLT RUB2 ;WE DID !
;
; MOV CHARS UNTIL END REACHED
;
RUB0: CMP R0,START ;END /
BGE RUB1 ;YES STOP
MOVB (R0)+,-2(R0) ;GRAB NEXT CHAR
BR RUB0
;
; END CLEAN UP POINTERS
;
RUB1: DEC R0
DEC R0 ;NOW POINTS TO NEW END
MOV R0,START
MOV TEMP0,R0 ;RESTORE R0
MOV #'/,@#174006 ;OUTPUT *
JMP TRANX9
;
; JUST RESET AND RETURN
;
RUB2: MOV PBUFR,ECHO
MOV ECHO,START
CLRB ECHOSW
RTI
;
; SEND A LINE TO THE SYSTEM
;
TRANFL: MOV @#44,-(SP)
JSR R5,@(SP)+ ;STORE REGS
MOV WHERE,R1
MOV WHEN,R2
MOV PBUFR,R3
FIL1: MOVB (R3)+,(R1)+ ;MOVE CHAR
CMP R3,PBUFRE ;END ?
BLT FIL1
;
; RETURN TO SYSTEM
;
FIL2: MOV OCT,R0
JMP @14(R0)
;
; RECEIVER INTERRUPT ROUTINES
;
; KEEP DATA AND CHECK DIRECTION
;
TRANR: MOV @#174000,TEMP0 ;GET CSR
BMI DCERR ;IF ERROR GO THERE
MOVB @#174002,RCHAR ;GET DATA
BICB #200,RCHAR ;MAKE POSITIVE
TSTB SWITCH ;IN OR OUT

```



```

BNE .+6 ;NO !
INCB UCASE ;SET UPPER CASE ONLY SWITCH
CMPB RCHAR,#2 ;CONTROL B ?
BNE TRANRØ
CLRB UCASE
RR TRANRØ

;
; ERROR STOP
;
DCERR: MOV TEMPØ,-(SP)
      MOV #S2Ø2,-(SP)
      IOT

;
; DATA BUFFER
;
BUFR:  .=.+122
PBUR:  .WORD Ø ;POINTER TO BUFFER
PBURF: .WORD Ø ;POINTER TO ITS END
      .ASCII /↑U/
BUFCR: .BYTE 15,12
PBUCR: .WORD Ø

;
; SWITCHES
;
STOPSW: .BYTE Ø
WAITSW: .BYTE Ø
SWITCH: .BYTE Ø
ECHOSW: .BYTE Ø
TABSW:  .BYTE Ø
TABCNT: .BYTE Ø
DONESW: .BYTE Ø
TCHAR:  .BYTE Ø
RCHAR:  .BYTE Ø
UCASE:  .BYTE Ø
      .EVEN

;
; DATA AREAS
;
TEMPØ: .WORD Ø
DCENAB: .WORD Ø
START: .WORD Ø
ECHO:  .WORD Ø
WHERE: .WORD Ø
WHEN:  .WORD Ø

;
;
;
      .END
```

NAME DV:

DESCRIPTION - DV: is a device driver for the DIVA 2314 Disk Unit and Controller. Handling up to 4 drives (UNITS 0-3) DV: reads and writes data blocks of 512 PDP-11 words onto the diskpack. DV: works under the DOS I/O system and has valid blocks from 0 to 56677 octal or (24000)10 blocks of 512 words for its storage per unit. At the present DV: is a non-system device but in the near future DV: will be used as a system disk with its own DOS system on unit 0.

USES - DV: provides DOS with a huge random storage area of 24000 blocks of 512 words. Under the file system as many as 125 users may be enabled on a single unit as opposed to 14 users on a DF: system or 62 users on a DK: system.

PROGRAMMING - DV: is another DOS device after running a zeroing program. Any valid I/O operation is valid except the zero switch in PIP. However, due to the 512 word buffers required for transfers, 12K of core should be the minimum configuration. For initialization two steps are necessary. The first step is to format the diskpack to 512 word blocks using the DIVA supplied format routine.

WORDSIZE	=	1000	Octal
#PHYSICAL SECTORS/LOGICAL SECTORS	=	4	"
#LOGICAL SECTORS/TRACK	=	6	"
#CYL	=	313	"
#HEADS	=	24	"

Step 2 is to run the program DVFMAT.LDA.

DVFMAT.LDA - this program initializes a file system on the disk pack on unit 0. MFD blocks #1 & #2 are written. All bitmaps are then written out. The file system uses the first 37 octal blocks. This program should only be used once per pack as PIP can now take care of file deletions etc.

After step 2 the pack is ready for use. Note that [1,1] and [200,200] do not exist after formatting and initialization.

ERRORS - only 3 possible errors can be generated directly from DV:

F035 xxxxxx - illegal block number. The block #xxxxxx is too big for the disk.

F044 xxxxxx - disk interface error. xxxxxx is the CSR of the interface.

F045 xxxxxx - device not ready i.e. wrong unit #.

- A listing of DV: follows: -

R0=%0
R1=%1
R2=%2
R3=%3
R4=%4
R5=%5
SP=%6
PC=%7

;
; DISK DRIVER FOR DIVA DISK UNIT
;
; VERSION ONE
;
; FEATURES SINGLE USER
; 512 WORD BLOCKS / DISK
; 4 UNITS HANDLED
;

.TITLE DV
.GLOBL DV

; DEVICE ASSIGNMENTS

DCSR=164000
DNBR=164002
DMAR=164004
DWCR=164006
DCBR=164010
DSSR=164012
DAIR=164014
DUSR=164016

; CBR COMMAND BITS

DIR=0
READ=40000
WRITE=100000
SPEC=140000
MOD0=0
MOD1=10000
MOD2=20000
MOD3=30000

; CONTROL FUNCTIONS

INCHAD=1
RECAL=2
RESETH=20
SEEK=40
CLRHDA=100

; DEVICE VECTOR

DV: .WORD 0 ;DDB POINTER
.WORD 102037 ;FACILITIES
.BYTE 40 ;512 WORD BLOCKS
.BYTE DV.INT-DV ;IN ROUTINE

```

.BYTE 240      ;PR = 5
.BYTE 0
.BYTE DV.TRN-DV ;TRA ROUTINE
.BYTE 0
.WORD 0
DV.DEV: .RAD50 /DV/
        .WORD 1      ;FIRST MFD BLOCK POINTER
        .WORD 0,0,0,0 ;4 DRIVES/DEVICE
;
;
; INTERRUPT HANDLER FOR DV:
;
DV.INT: MOV @#DCSR,TEMP0      ;KEEP STATUS REG
        BMI OVERR           ;IF NEG THEN ERROR
        TSTB TEMP0         ;R/W
        BPL DVSEEK         ;NO !
        BIS #200,@#DCSR ;GET RID OF DONE BIT
        BIC #100,@#DCSR    ;DROP INT
        MOV @#44,-(SP)
        JSR R5,@(SP)+
        MOV DV,R0
        JMP @14(R0)        ;RETURN DONE
;
; CHECK SEEK OPERATION
;
DVSEEK: MOV #DIR+MOD3+CLRHDA,@#DCBR ;RESET ATTN
        BIT #4000,@#DSSR ;DRIVE READY ?
        BNE OVERR
        MOV PTRCFM,@#DMAR ;SET C BUF IN MAR
        MOV BCOUNT,@#DWCR
        MOV COMND0,@#DCBR ;LOAD HEAD NOW!
        MOV COMND1,@#DCBR ;READ OR WRITE CONFIRM
        INC @#DCSR ;GO !!!
        RTI
;
; CALL ERROR ROUTINE WITH F44
;
OVERR:  MOV TEMP0,-(SP) ;SHOW CSR
        MOV #1444,-(SP) ;F 44
        IOT
;
; TRANSFER ROUTINE
;
; TWO STEPS 1-SEEK POSITION
;           2-INITIATE R/W
;
DV.TRN: MOV #DIR+MOD3+CLRHDA+RESETH,@#DCBR ;DROP POS INT
        MOV DV,R0 ;GET DDB
DECODE: MOV 4(R0),R1 ;GET BLOCK #
        CMP R1,#56677 ;CHECK SIZE
        BLE DCODE0 ;O.K.
;
; ILLEGAL BLOCK # FOR DEVICE
;
        MOV R1,-(SP)
        MOV #1435,-(SP)
        IOT
;

```

; DECODE CYLINDER, TRACK AND SEGMENT ADDRESSES

```

;
;
DCODE0: MOV CNT1,R3           ;FIRST DIVISOR
        MOV DIV1,R2         ;
        CLR R4
DCODE1: CMP R2,R1           ;DOES IT DIVIDE ?
        BGT DCODE2         ;NO
        SUB R2,R1
        INC R4
DCODE2: CLC
        INC R3
        BPL DCODE6         ;DONE FIRST #
        RDR R2
        ROL R4
        BR DCODE1

```

; STORE SEGMENT

```

;
DCODE6: ASL R1
        MOV R1,SEGMT

```

; START NEXT

```

;
        MOV R4,R1
        MOV CNT2,R3         ;SECOND DIVISOR
        MOV DIV2,R2         ;
        CLR R4
DCODE3: CMP R2,R1           ;DOES IT DIVIDE ?
        BGT DCODE4         ;NO
        SUB R2,R1
        INC R4
DCODE4: CLC
        INC R3
        BPL DCODE7
        RDR R2
        ROL R4
        BR DCODE3
DCODE7: MOV R1,TRACK
        MOV R4,CYLNR
        JMP SEEKIT

```

```

SEGMENT: .WORD 0
TRACK:   .WORD 0
CYLNR:   .WORD 0
DIV1:    .WORD 30000
CNT1:    .WORD 177765
DIV2:    .WORD 50000
CNT2:    .WORD 177765
TEMP0:   .WORD 0
BCOUNT:  .WORD 0
UNIT:    .WORD 0
COMND0:  .WORD 0
COMND1:  .WORD 0
PTRCFM:  .WORD 0
CFMBUF:  .WORD 0,0,0,0

```

; SET UP SEEK AND CONFIRM BUFFER

```

;
;   ALSO SET UP ALL R/W COMMANDS NOW !
;
SEEK1: MOV @#DSSR,TEMP0           ;GET HDWR STATUS
      BIC #143777,TEMP0         ;DROP SOME OF IT
      BNE DVERR                 ;ERROR IF NOT READY
;
;   SET UNIT # AND SELECT
;
      MOV B 13(R0),R1
      BIC #177770,R1
      MOV R1,R3
      CLR R2
      INC R2
SEEK1: DEC R1
      BLE .+6
      ASL R2
      BR SEEK1
      MOV R2,UNIT               ;UNIT SET
      MOV R3,R2
      ADD #SPEC+MOD0,R2
      MOV R2,@#DCBR             ;SELECT UNIT
      BIT #2000,@#DSSR         ; SELECT OK ?
      BNE SEEK2                 ;YES
      MOV DV.DEV,-(SP)
      MOV #1445,-(SP)
      IOT
;
;   RESET HEAD
;   SET CYLINDER AND HEAD REGISTERS
;
SEEK2: MOV CYLNDR,R1
      MOV TRACK,R2
      ADD #DIR,R2
      ADD #DIR+MOD2,R1
      MOV R1,@#DCBR
      MOV R2,COMND0             ;SET TRACK AND CYLINDER
;
;   BUILD UP CONFIRM BUFFER FOR I/O
;
      MOV PC,R1
      ADD #CFMBUF-.,R1
      MOV R1,PTRCFM             ;GENERATE ABS ADDRESS
;
;   CHECK DIRECTION AND GENERATE READ OR WRITE
;
      MOV #READ,R1              ;START WITH READ
      BIT #4,12(R0)             ;IN OR OUT
      BNE .+6                    ;IN ! O.K.
      MOV #WRITE,R1
      ADD #MOD3,R1               ;+CONFIRM
      ADD SEGMT,R1              ;+PHYSICAL SEG.
      MOV R1,COMND1             ;STORE INSTRUCTION FOR R/W
;
;   NOW FINISH CONFIRM BUFFER
;
      MOV PTRCFM,R2             ;GET POINTER

```

```
MOV TRACK,R1      ;GET TRACK PT
SWAB R1           ;PUT IN UPPER BYTE
ADD CYLND,R1      ;ADD IN CYL PTR
MOV R1,(R2)+      ;FIRST ENTRY
MOV 10(R0),R3     ;GET WORD COUNT
ASL R3
MOV R3,BCOUNT     ;SAVE FOR READ / WRITE
MOV #177000,R1    ;GET WORD COUNT
ASL R1            ;CONVERT TO WORD COUNT FIRST
ASL R1
ASL R1
ASL R1
MOV SEGMENT,R3    ;DIVIDE SEGMENT BY 2 AND ADD TO R1
CLC
ASR R3
ADD R3,R1
MOV R1,(R2)+      ;SECOND WORD
CLR R1
SUB -4(R2),R1
SUB -2(R2),R1
MOV R1,(R2)+      ;THIRD WORD IS CHECKSUM
MOV 6(R2),(R2)    ;LAST WORD IS DATA BUFFER
MOV UNIT,@#DAIR  ;ENABLE UNIT IN AIR
BIS #100,@#DCSR  ;AND INTERRUPT
MOV #DIR+MOD3+SEEK+RESETH,@#DCBR ;START SEEK
RTS PC           ;GO WAIT FOR DONE
.END
```


Name DV: Version 2

DV: - Device driver and file system for 2314 type disk systems, version 2.

DESCRIPTION - DV: provides the PDP-11 with large scale random access storage. The disk pack is divided into 2 logical units each with 24000 blocks of 256 words. The even unit (i.e. 0,2,4, or 6) is physically the first 100 cylinders. The odd unit becomes the last 100 cylinders. The file system designed for this unit will permit full DOS access for 125 users per logical unit. DV: will permit up to 4 drives without modification.

USES - A large scale storage area for PDP-11s. One disk will hold the equivalent of 12 RK05 disks at a cost of only 4 RK packs.

PROGRAMMING - DV: is the logical name of the device and may be used in the same manner as any other DOS file storage device except for initialization. DV: must first have a formatted disk before any transfers take place. The necessary procedure follows:

- 1) Format the disk pack to 400g words per logical sector, 28 physical sectors per logical, 14g logical sectors per track.
- 2) Run the program DVFMAT.LDA. This program writes all Master File blocks and the bitmaps.

In particular after formatting the disk will have the following following blocks written on both logical units.

- BLOCK 0 reserved for possible bootstrap
- BLOCK 1 Master File Directory #1
- BLOCK 56645 Master File Directory #2
- BLOCK 56646 Master File Directory #3
- BLOCKS 56647 - 56677 BIT MAPS 1-25

From this point on, PIP may be used to enable users etc., as any other DOS device.

NOTE 1 - DV: must be added to DOS with a new system generation using the DEC supplied program MODS.

NOTE 2 - DV: does not yet support a DOS system stand alone. The ideal system device for use with DV: would be the RF11 dixed head disk.

ERRORS - Two possible errors stem from DV:

- F035 - illegal block number
- F044 - disk interface error
- F045 - device not ready

These errors were made fatal because the DOS system recovery methods are not applicable to this device.

- A listing of DV: and DUFMAT follows -

R0=%0
R1=%1
R2=%2
R3=%3
R4=%4
R5=%5
SP=%6
PC=%7

; DISK DRIVER FOR DIVA DISK UNIT

; VERSION TWO

; FEATURES SINGLE USER
; 256 WORD BLOCKS / DISK
; 8 UNITS HANDLED

; .TITLE DV
; .GLOBL DV

; DEVICE ASSIGNMENTS

; DCSR=164000
; DDBR=164002
; DMAR=164004
; DWCR=164006
; DCBR=164010
; DSSR=164012
; DAIR=164014
; DUSR=164016

; CBR COMMAND BITS

; DIR=0
; READ=40000
; WRITE=100000
; SPEC=140000
; MOD0=0
; MOD1=10000
; MOD2=20000
; MOD3=30000

; CONTROL FUNCTIONS

; INCHAD=1
; RECAL=2
; RESETH=20
; SEEK=40
; CLRHDA=100

; DEVICE VECTOR

DV: .WORD 0 ;DDB POINTER
.WORD 102037 ;FACILITIES
.BYTE 20 ;256 WORD BLOCKS

```

        .BYTE DV.INT-DV ;IN ROUTINE
        .BYTE 240      ;PR = 5
        .BYTE 0
        .BYTE DV.TRN-DV ;TRA ROUTINE
        .BYTE 0
        .WORD 0
DV.DEV: .RAD50 /DV/
        .WORD 1          ;FIRST MFD BLOCK POINTER
        .WORD 0,0,0,0    ;4 DRIVES/DEVICE
        .WORD 0,0,0,0    ;PLUS 4 MORE FOR VERSION 2
;
;   INTERRUPT HANDLER FOR DV:
;
DV.INT: MOV @#DCSR,TEMP0      ;KEEP STATUS REG
        BMI DVERR            ;IF NEG THEN ERROR
        TSTB TEMP0          ;R/W
        BPL DVSEEK          ;NO !
        BIS #200,@#DCSR ;GET RID OF DONE BIT
        BIC #100,@#DCSR ;DROP INT
        MOV @#44,-(SP)
        JSR R5,@(SP)+
        MOV DV,R0
        JMP @14(R0)          ;RETURN DONE
;
;   CHECK SEEK OPERATION
;
DVSEEK: MOV #DIR+MOD3+CLRHDA,@#DCBR ;RESET ATTN
        BIT #4000,@#DSSR ;DRIVE READY ?
        BNE DVERR
        MOV PTRCFM,@#DMAR ;SET C BUF IN MAR
        MOV BCOUNT,@#DWCR
        MOV COMND0,@#DCBR ;LOAD HEAD NOW!
        MOV COMND1,@#DCBR ;READ OR WRITE CONFIRM
        INC @#DCSR ;GO !!!
        RTI
;
;   CALL ERROR ROUTINE WITH F44
;
DVERR:  MOV TEMP0,-(SP) ;SHOW CSR
        MOV #1444,-(SP) ;F 44
        IOT
;
;   TRANSFER ROUTINE
;
;   TWO STEPS          1-SEEK POSITION
;                       2-INITIATE R/W
;
DV.TRN: MOV #DIR+MOD3+CLRHDA+RESETH,@#DCBR ;DROP POS INT
        MOV DV,R0 ;GET DDB
DECODE: MOV 4(R0),R1 ;GET BLOCK #
        CMP R1,#56677 ;CHECK SIZE
        BLE DCODE0 ;O.K.
;
;   ILLEGAL BLOCK # FOR DEVICE
;
        MOV R1,-(SP)
        MOV #1435,-(SP)

```

```
      IOT
;
;      DECODE CYLINDER, TRACK AND SEGMENT ADDRESSES
;
;
DCODE0: MOV CNT1,R3          ;FIRST DIVISOR
        MOV DIV1,R2        ;
        CLR R4
DCODE1: CMP R2,R1          ;DOES IT DIVIDE ?
        BGT DCODE2        ;NO
        SUB R2,R1
        INC R4
DCODE2: CLC
        INC R3
        BPL DCODE6        ;DONE FIRST #
        ROR R2
        ROL R4
        BR DCODE1
;
;      STORE SEGMENT
;
DCODE6: ASL R1
        MOV R1,SEGMENT
;
;      START NEXT
;
        MOV R4,R1
        MOV CNT2,R3      ;SECOND DIVISOR
        MOV DIV2,R2      ;
        CLR R4
DCODE3: CMP R2,R1          ;DOES IT DIVIDE ?
        BGT DCODE4        ;NO
        SUB R2,R1
        INC R4
DCODE4: CLC
        INC R3
        BPL DCODE7
        ROR R2
        ROL R4
        BR DCODE3
DCODE7: MOV R1,TRACK
        MOV R4,CYLNDR
        JMP SEEKIT
SEGMENT: .WORD 0
TRACK:   .WORD 0
CYLNDR: .WORD 0
DIV1:   .WORD 30000
CNT1:   .WORD 177765
DIV2:   .WORD 50000
CNT2:   .WORD 177765
TEMP0:  .WORD 0
BCOUNT: .WORD 0
UNIT:   .WORD 0
COMND0: .WORD 0
COMND1: .WORD 0
PTRCFM: .WORD 0
CFMBUF: .WORD 0,0,0,0
```

```

;
; SET UP SEEK AND CONFIRM BUFFER
;
; ALSO SET UP ALL R/W COMMANDS NOW !
;
SEEK1: MOV @#DSSR,TEMP0 ;GET HDWR STATUS
      BIC #143777,TEMP0 ;DROP SOME OF IT
      BNE DVERR ;ERROR IF NOT READY
;
; SET UNIT # AND SELECT
;
      MOVB 13(R0),R1
      CLC ;CLEAR CARRY IF ANY
      ROR R1 ;GET EVEN UNIT ONLY
      BCC .+10 ;NO CARRY = EVEN UNIT
      ADD #144,CYLNR ;ODD UNIT DISPLACE UNIT
      BIC #177774,R1 ;DROP GARB.
      MOV R1,R3
      CLR R2
      INC R2
SEEK1: DEC R1
      BLE .+6
      ASL R2
      BR SEEK1
      MOV R2,UNIT ;UNIT SET
      MOV R3,R2
      ADD #SPEC+MOD0,R2
      MOV R2,@#DCBR ;SELECT UNIT
      BIT #2000,@#DSSR ;SELECT OK ?
      BNE SEEK2 ;YES
      MOV DV.DEV,-(SP)
      MOV #1445,-(SP)
      IOT
;
; RESET HEAD
; SET CYLINDER AND HEAD REGISTERS
;
SEEK2: MOV CYLNR,R1
      MOV TRACK,R2
      ADD #DIR,R2
      ADD #DIR+MOD2,R1
      MOV R1,@#DCBR
      MOV R2,COMND0 ;SET TRACK AND CYLINDER
;
; BUILD UP CONFIRM BUFFER FOR I/O
;
      MOV PC,R1
      ADD #CFMBUF--,R1
      MOV R1,PTRCFM ;GENERATE ABS ADDRESS
;
; CHECK DIRECTION AND GENERATE READ OR WRITE
;
      MOV #READ,R1 ;START WITH READ
      BIT #4,12(R0) ;IN OR OUT
      BNE .+6 ;IN ! O.K.
      MOV #WRITE,R1
      ADD #MOD3,R1 ;+CONFIRM

```

```
ADD SEGMT,R1          ;+PHYSICAL SEG.
MOV R1,COMND1        ;STORE INSTRUCTION FOR R/W
;
;
NOW FINISH CONFIRM BUFFER
MOV PTRCFM,R2        ;GET POINTER
MOV TRACK,R1         ;GET TRACK PT
SWAB R1              ;PUT IN UPPER BYTE
ADD CYLNR,R1         ;ADD IN CYL PTR
MOV R1,(R2)+         ;FIRST ENTRY
MOV 10(R0),R3        ;GET WORD COUNT
ASL R3
MOV R3,BCOUNT        ;SAVE FOR READ / WRITE
MOV #177400,R1       ;GET WORD COUNT
ASL R1               ;CONVERT TO WORD COUNT FIRST
ASL R1
ASL R1
ASL R1
MOV SEGMT,R3         ;DIVIDE SEGMT BY 2 AND ADD TO R1
CLC
ASR R3
ADD R3,R1
MOV R1,(R2)+         ;SECOND WORD
CLR R1
SUB -4(R2),R1
SUB -2(R2),R1
MOV R1,(R2)+         ;THIRD WORD IS CHECKSUM
MOV 6(R0),(R2)       ;LAST WORD IS DATA BUFFER
MOV UNIT,@#DAIR      ;ENABLE UNIT IN AIR
BIS #100,@#DCSR      ;AND INTERRUPT
MOV #DIR+MOD3+SEEK+RESETH,@#DCBR ;START SEEK
RTS PC               ;GO WAIT FOR DONE
.END
```

R0=%0
SP=%6
PC=%7

.TITLE DVFMAT

; INIT DIVA DISK FOR PDP 11 FILE SYSTEM

; START: MOV #LINK, -(SP)
EMT 6 ;INIT DV:

; WRITE OUT MFD #1 AT BLOCK 1

; MOV #TRAN, R0
MOV #1, (R0)+
MOV #MFD1, (R0)
TST -(R0)
JSR PC, TRA

; WRITE OUT MFD #2

; MOV #56645, (R0)+
MOV #MFD2, (R0)
TST -(R0)
JSR PC, TRA

; WRITE OUT MFD #3

; MOV #56646, (R0)
CLR MFD2 ;END OF CHAIN
JSR PC, TRA
MOV #MAP, TRAN+2

; NOW BIT MAPS ONE AT A TIME

; LOOP: INC MAP
INC MAP+2
INC TRAN ;BL 56647 FIRST
CMP TRAN, #56677 ;LAST ONE
BEQ LOOP2 ;YES
JSR PC, TRA
CLR MAP+10 ;DROP BLOCK 0,1
BR LOOP

; WRITE OUT LAST MAP

; LOOP2: MOV #177777, MAP+174
MOV #177777, MAP+176
CLR MAP ;LAST IN CHAIN
JSR PC, TRA
EMT 60

; TRA: MOV #TRAN, -(SP)
MOV #LINK, -(SP)
EMT 10

```
MOV #LINK, -(SP)
EMT 1
RTS PC
```

```
;
```

```
LINK: .WORD 0,0,1
      .RAD50 /DV/
```

```
;
```

```
TRAN: .WORD 0,0,400,2,0
```

```
;
```

```
MFD1: .WORD 56645
      .WORD 5,56647
      .WORD 56647,56650,56651,56652,56653,56654,56655,56656
      .WORD 56657,56660,56661,56662,56663,56664,56665,56666
      .WORD 56667,56670,56671,56672,56673,56674,56675,56676
      .WORD 56677
      . =MFD1+2004
```

```
;
```

```
MFD2: .WORD 56646
      . =MFD2+2004
```

```
;
```

```
MAP: .WORD 56647,0,74,56647,3
      . =MAP+2004
      .END START
```


NAME MTS:

DESCRIPTION: MTS: is a device driver for the AMPEX 9 track tape unit and custom interface connected to our 11/20. MTS: handles all I/O operations and file system functions for the tape unit. Since magnetic tape is sequential with no central directory, the file system is different to that of any other DEC device. The file system is comprised of a sequence of files followed by 2 tape marks. Each file has as its first record a 7 word label similar to that of the file block used in all file operations. All successive records are 256 words long. The last record of the file is followed by a tape mark. So tape marks separate each file and 2 tape marks end the tape.

An OPEN command searches the tape labels for a match. Each request for data transfers a complete block of 256 words. CLOSE will write the 2 tape marks if a new file were created.

USES - MTS: permits DOS file operations onto magnetic tape. Thus, the tape unit becomes another bulk storage for DOS. Because of its nature, only one file is allowed open at any time. MTS: is another DOS device and may be used in the same way as DT:,DK:, DF:, etc.

PROGRAMMING - MTS: operates files outside of the regular DOS file system. This means that PIP commands such as /DI, /DE will not work. To overcome this deficiency 2 small programs are available to assist.

MTFMAT.LDA - reformats the tape with 2 tape marks, essentially cleaning the tape.

MTDIR.LDA - reads the tape labels and lists the directories onto a logical device DEV: which must be assigned prior to running MTDIR:

Otherwise MTS: can be programmed as any other single user file - oriented device.

ERRORS - 2 errors will occur in MTS:

F012 - means that either a file exists when it shouldn't or that no file exists for input.

F032 xxxxxx - indicates a hardware error on the tape. xxxxxx is the CSR status of the device. All errors are normally unrecoverable.

- A listing of MTS follows: -

R0=%0
R1=%1
R2=%2
SP=%6
PC=%7
R5=%5
MTCSR=177540
MTDBR=177542
MTMAR=177544
MTBCR=177546
MTBLK=177550

INPUT OUTPUT HANDLER FOR AMPEX UNIT

```

;
;
;
.MTITLE MTS
.GLOBL MTS
MTS: .WORD 0 ;DVR VECTOR START
      .WORD 336 ;OPEN CLOSE, ASCII BIN, INPUT OUTPUT
      .BYTE 20 ;256 WORD BUFFER
      .BYTE MT.INT-MTS ;START OF INT ROUTINE
      .BYTE 300 ;PR =6
      .BYTE MT.OPN-MTS ;OPEN OFFSET
      .BYTE MT.TRN-MTS ;TRANSFER OFFSET
      .BYTE MT.CLS-MTS ;CLOSE OFFSET
      .WORD 0 ;NO SPEC FUNCTIONS
MT.DEV: .RAD50 /MTS/ ;NAME OF DEVICE
;
; OPEN ROUTINE INITIATE
;
; GET FILE NAME EXT ETC. SEARCH TAPE FOR SUCH OR END OF TAPE
; WHICHEVER COMES FIRST
;
; CALL APPROPRIATE ERRORS IF NECESSARY
;
MT.OPN: MOV MTS,R0 ;GET ADDRESS OF DOB VECTOR
        MOV @#177776,PRSAVE ;KEEP CALLING STATUS FOR ERROR
        MOV #400,BLOCK ;RESET BLOCK COUNTER
        MOV #1,OPEN ;SIGNAL OPEN
        CLR CLOSE ;MAKE SURE OF NO CLOSE
        MOV PC,R1 ;GENERATE ADDRESS OF LABEL AREA
        ADD #FILE2-.,R1
        MOV R1,PFILE2 ;STORE IT FOR LATER USE
        MOV 4(R0),R1 ;GET POINTER TO FILBLK
        MOV R1,PFILE1 ;STORE FOR LATER USE
        MOVB -2(R1),OPENCD ;KEEP OPEN CODE
;
; CHECK FILE NAME FOR UIC AND PROTECT CODES
;
OPNA: TST 6(R1) ;CHECK UIC FOR ZEROS
      BNE TAG1 ;NOT DEFAULT
      MOV @#440,6(R1) ;REPLACE ZERO WITH CURRENT UIC
TAG1: TST 10(R1) ;CHECK PROTECT CODE
      BNE TAG2
      MOV #233,10(R1) ;REPLACE ZERO WITH 233
TAG2: CLR OPNCDE ;SET FIRST JMP CODE
      CLR @#MTBLK ;ZERO BLOCK ADDRESS

```

```
MOV #102,@#MTCSR      ;REWIND TAPE FUNCTION
RTS PC                ;RETURN UNTIL ACTION
;
; CLOSE INITIATE ROUTINE
;
; IF OPENI THEN STRAIGHT RETURN
;
; ELSE WRITE 2 TAPE MARKS AND FINISH
;
MT.CLS: CMP OPENC0,#2      ;OPENO ?
        BEQ TAG3          ;YES CONTINUE
        TST (SP)+        ;CLEAR CALL FROM STACK
        MOV MTS,R0       ;GET DDB ADDRESS
        JMP @14(R0)      ;RETURN DONE
TAG3:   MOV #1,CLOSE     ;SIGNAL CLOSE
        CLR CLSCDE      ;SET JUMP CODE
        MOV #105,@#MTCSR ;WRITE TAPE MARK
        RTS PC          ;WAIT
;
; INTERRUPT ROUTINE START CHECK FOR OPEN ERROR CLOSE
; IN THAT ORDER THEN JUMP TO APPROPRIATE ROUTINE
;
MT.INT: BIT #2000,@#MTCSR ;BUSYEADY ???
        BNE .-6         ;YES WAIT
        CMP #300,@#MTCSR ;LOOK FOR READY NOT POSITIONED
        BNE TAG40      ;GO ON IF NOT
        INCB BLOCK      ;SET ONE BLOCK ON
        BIS #400,BLOCK  ;KEEP BIT 8 UP
        MOV BLOCK,@#MTBLK ;GIVE IT TO REG
        MOV #106,@#MTCSR ;SEARCH TO IT
        RTI
TAG40:  TST OPEN        ;IF OPEN GO TO SPECIAL PART
        BEQ TAG4
        JMP MTIOPN
TAG4:   TST @#MTCSR     ;LOOK FOR ERROR
        BPL TAG5       ;NO ERROR
        JMP HERROR
TAG5:   TST CLOSE      ;SAME AS OPEN
        BEQ TAG6
        JMP MTICLS
;
; INCREMENT BLOCK COUNTER AND TAKE SYSTEM EXIT
;
TAG6:   JMP OPN3       ;EXIT FINISHED
;
;
; TRANSFER ROUTINE LOAD VARIABLES AND POINTERS
; AND INITIATE BLOCK TRANSFER.
;
MT.TRN: MOV MTS,R0     ;GET DDB ADDRESS
        MOV 6(R0),@#MTMAR ;GET DATA ADDRESS INTO MAR
        MOV 10(R0),R1    ;GET WORD COUNT
        COM R1          ;MAKE POSITIVE
        ADD #1,R1       ;INCREASE BY ONE WORD
        ASL R1          ;MULTIPLY BY TWO
        MOV R1,@#MTBCR  ;STORE BYTE COUNT IN DEV
        MOV 12(R0),R1   ;GET FUNCTION BITS
```

```

ROR R1
ROR R1
ROR R1
BMI MT.OUT ;OUTPUT BIT ON
MOV #101,@#MTCSR ;READ DATA
RTS PC ;WAIT FOR ACTION
MT.OUT: MOV @6(R0),@#MTDBR ;SET FOR WRITE BY MOVING UP ONR
ADD #2,@#MTMAR ;WORD IN MEMORY
MOV #104,@#MTCSR
RTS PC ;WRITE AND WAIT
; ***** OPEN SERVICE ROUTINES *****
;
;
; JUMP TO OPEN ROUTINES
;
MTIOPN: TST @#MTCSR ;CHECK FOR ERROR
BPL MTIPN1 ;NO ERROR
CMP OPNCDE,#4 ;WHAT WERE WE DOING --
BEQ TAG7 ;WE WERE READING A LABEL
JMP HERROR ; ERROR IN STATUS
TAG7: CMPB @#MTDBR,#23 ;END OF TAPE ???
BEQ TAG8
JMP HERROR ;STILL ERROR
TAG8: CLR FIND ;SET INDICATOR
JMP OPN6 ;GO TO FINISH ROUTINE
;
; NOW EXECUTE JUMP
;
MTIPN1: MOV R0,SAVE ;KEEP R0
MOV PC,R0
ADD #OPNJMP-.,R0 ;GENERATE JUMP ADDRESS
ADD OPNCDE,R0
MOV R0,JMP
MOV SAVE,R0
JMP @JMP
OPNJMP: JMP OPN0
JMP OPN1
JMP OPN2
JMP OPN3
JMP: .WORD 0
;
; TAPE REWOUND READ FIRST LABEL
;
OPN0: MOV #4,OPNCDE ;NEXT JUMP
MOV #16,@#MTBCR ;7 WORD LABEL
MOV PFILE2,@#MTMAR ;LABEL BUFFER ADDRESS
MOV #101,@#MTCSR ;READ LABEL
RTI ;RETURN TO WAIT
;
; CHECK LABEL I MATCH JUMP OUT ELSE INITIATE
; SEARCH TO TAPE MARK TO GET NEXT LABEL
;
OPN1: CLR OPNCDE ;JUMP CODE
MOV R0,SAVE
MOV R1,SAVE+2
MOV PFILE1,R0
MOV PFILE2,R1

```

```

CMP (R0)+,(R1)+ ;CHECK LABEL
BNE OPN11
CMP (R0)+,(R1)+
BNE OPN11
CMP (R0)+,(R1)+
BNE OPN11
CMP (R0)+,(R1)+
BNE OPN11
JMP ERROR2 ;CHECK PROTECT CODE NOW
;
; LABEL NOT A MATCH RESUME SEARCHING
;
OPN11: CLR @#MTBLK
MOV #400,BLOCK ;RESET BLOCK COUNT
MOV #107,@#MTCSR ;SEARCH TO TAPE MARK
MOV SAVE,R0
MOV SAVE+2,R1
RTI
;
; FOUND LABEL OR EDN OF TAPE
;
OPNFND: MOV #1,FIND ;SIGNAL MATCH
MOV SAVE,R0
MOV SAVE+2,R1
;
;
OPN6: TST FIND
BEQ OPNO ; L END OF TAPE BRANCH
;
; MUST BE OPENI OR ELSE ERROR
;
CMP OPENCD,#4 ;OPENI?
BEQ TAG9
JMP ERROR1 ;ERROR IF NOT
TAG9: JMP OPN3 ;FINISHED OPENI
;
; CHECK FOR OPENO IF NOT - ERROR
;
OPNO: CMP OPENCD,#2 ;OPENO ?
BEQ TAG10
JMP ERROR1 ;ERROR IF NOT
;
; BACKSPACE ONE BLOCK BEFORE WRITING NEW LABEL
;
TAG10: MOV #10,OPNCDE ;JMP POINTER
MOV #400,BLOCK ;RESET BLOCK COUNT
CLR @#MTBLK ;BACK UP ONE BLOCK
MOV #106,@#MTCSR ;SEARCK BACK ONE BLOCK
RTI
;
;
; WRITE NEW LABEL
;
OPN2: MOV #14,OPNCDE ;LAST JUMP POINTER
MOV #16,@#MTBCR ;16 BYTES OUT
MOV @PFILE1,@#MTDBR ;SEND FIRST WORD OF LABEL
MOV PFILE1,@#MTMAR

```

```

ADD #2,@#MTMAR ;GET CORRECT ADDRESS
MOV #104,@#MTCSR ;WRITE
RTI

```

```

;
; END OF OPENO
;

```

```

OPN3: CLR OPEN ;DISABLE OPEN
      MOV @#44,-(SP) ;REG SAVE ROUTINE
      JSR R5,@(SP)+ ;CALL IT
OPN20: MOV MTS,R0 ;DDB USED
      JMP @14(R0) ;TAKE RETURN IN DDB VECTOR

```

```

; *****CLOSE SERVICE ROUTINES *****
;

```

```

; JMP TO ROUTINES
;

```

```

MTICLS: MOV R0,SAVE ;REQUIRE R0
        MOV PC,R0 ;MAKE UP JMP ADDRESS
        ADD #CLSJMP-.,R0
        ADD CLSCDE,R0
        MOV R0,JMP
        MOV SAVE,R0
        JMP @JMP

```

```

CLSJMP: JMP CLS0
        JMP CLS1

```

```

; WRITE SECOND TAPE MARK ON TAPE
;

```

```

CLS0: MOV #4,CLSCDE
      MOV #105,@#MTCSR ;WRITE TAPE MARK
      RTI

```

```

; FINISHED CLOSING ON OPENO FILE
;

```

```

CLS1: CLR CLOSE
      JMP OPN3 ;END CALL

```

```

; DATA FOR HANDLER
;

```

```

SAVE: .WORD 0,0 ;T STORE FOR REGS.
FILE2: .WORD 0,0,0,0
      .WORD 0,0,0,0 ;TAPE FILE NAME
PFILE1: .WORD 0 ;POINTER TO FILBLK
PFILE2: .WORD 0 ;POINTER TO FILE2
FIND: .WORD 0
BLOCK: .WORD 0 ;BLOCK COUNTER
OPNCDE: .WORD 0
OPENCD: .WORD 0
OPEN: .WORD 0
CLSCDE: .WORD 0
CLOSE: .WORD 0
PRSAVE: .WORD 0 ;PRIORITY SAVE
ERRORC: .BYTE 0
PRCT2: .BYTE 0

```

```

; ERROR ROUTINES FOR HANDLER
;

```

```

;
;   INVALID OPEN   IE END OF TAPE WHEN OPENI
;                   OR FILE FOUND ON OPENO
;
;
;   USER PROTECT CODE INVALID FOR READ
;
;
;   HARDWARE ERROR IN TAPE UNIT
;
;
;   END OF FILE ENCOUNTERED ON READ
;
;   IF THE ERROR JUMP IN USERS FILBLK IS NOT ZERO
;   THEN CONTROL IS PASSED THERE ON OPEN ERRORS .
;
;
;   AN END OF FILE BHT IS SET IN THE LINKBLK WHEN
;   ENCOUNTERED .
;
;
;   ---INVALID OPEN---
;
ERROR1:  MOVB #2,ERRORC           ;ERROR CODE 2
ERROR4:  DEC PFILE1              ;POINT TO ERROR CODE BYTE
        MOVB ERRORC,@PFILE1     ;GIVE IT ERROR CODE
        DEC PFILE1              ;NOW POINTS TO ERROR RET
        DEC PFILE1
        DEC PFILE1
        DEC PFILE1
        TST @PFILE1             ;IF ZERO FATAL ERROR
        BNE ERRJMP
        ADD #4,PFILE1           ;RESET PFILE1
        MOV PFILE1,-(SP)        ;GIVE ADDRESS
        MOV #1412,-(SP)        ;FATAL 12 ERROR
        IOT
;
;   JUMP TO USER DESTINATION IN CORE
;
ERRJMP:  CLR @MTS                ;FREE DDB
        MOV PRSAVE,@#177776     ;USER PRIORITY
        CMP (SP)+,(SP)+        ;CLEAR INTERRUPT FROM STACK
        MOV @PFILE1,PFILE1     ;POINT TO USER ROUTINE
        JMP @PFILE1            ;EXIT TO USER ROUTINE
;
;   ---PROTECT CODE ERROR ROUTINE---
;
;   IF OPENO IN PROGRESS IGNORE SINCE ERROR ANYWAY
;
;   IF UIC IN CORE AND UIC IN R1 MATCH IGNORE ALSO
;
;   OTHERWISE CHECK FOR VIOLATION IF NONE GO TO
;   OPNFND
;   ELSE CALL ERROR ROUTINE ABOVE WITH CODE 6
;
ERROR2:  CMPB #2,OPENCD         ; OPENO
        BNE .+6
        JMP OPNFND              ;YES EXIT
        CMP -(R1),@#440        ;DO UICS MATCH
        BNE .+6
        JMP OPNFND              ;YES EXIT
;
;   CHECK UIC DIFFERENCES
;

```

```
MOV B 2(R1),PRCT2 ;GET CODE
CMP B 1(R1),@#440 ;DO GROUPS MATCH
BNE ERRNSA ;NO !
ASRB PRCT2
ASRB PRCT2
ASRB PRCT2 ;SHIFT GROUP CODE TO RIGHT
ERRNSA: BIC B #370,PRCT2 ;CHECK IT
CMP B PRCT2,#3
BGT .+6 ;PROTECT CODE OK
JMP OPNFND ;ERROR 6 IN FILBLK
MOV B #6,ERRORC
JMP ERROR4
;
; HARDWARE ERROR ENCOUNTERED
;
; LOOK FOR END OF FILE MARK
;
HERROR: CMP B #23,@#MTDBR ;END OF FILE ?
BNE HERR1 ;NO--REAL ERROR
HERR2: MOV @#44,-(SP) ;SET TO END
JSR R5,@(SP)+
MOV MTS,R0 ;GET DDB ADDR
MOV 10(R0),16(R0) ;NO DATA TO R/W
JMP OPN20 ;EXIT
;
; UNRECOVERABLE ERROR FATAL 32
;
HERR1: MOV @#MTCSR,-(SP)
MOV #1432,-(SP)
IOT
.END
```


.TITLE MTDIR

LIST DIRECTORY OF MAG TAPE ONTO DEV: ASSIGNED BEFORE RUNNING

MTCSR=177540
MTDBR=177542
MTMAR=177544
MTBCR=177546
MTBLK=177550
SP=%6

.GLOBL CVT

; ; ;
START: MOV #LINK,-(SP) ;INIT DEV:
 EMT 6
 CLR @#MTBLK ;BLOCK ADDRESS 0 ON DRIVE
 MOV #FILE,-(SP) ;OPEN DEV:
 MOV #LINK,-(SP)
 EMT 16
 MOV #LINK,-(SP)
 EMT 1
 MOV #2,@#MTCSR ;REWIND TAPE TO LOAD POINT
 TSTB @#MTCSR
 BPL .-4
 TST @#MTCSR
 BMI ERROR
 ; ; ;
 READ A LABEL OR END OF TAPE
 ; ; ;
 CONVERT IT TO COMPLETE ASCII CHARACTERS
 TO BE OUTPUT ONTO
 WHATEVER DEVICE THE USER HAS DEFINED
 ; ; ;
 START1: BIT #2000,@#MTCSR ;WAIT UNTIL NOT BUSY
 BNE .-6
 MOV #14,@#MTBCR ;READ LABEL
 MOV #BUFFER,@#MTMAR
 MOV #1,@#MTCSR
 TSTB @#MTCSR
 BPL .-4
 TST @#MTCSR ;EXIT ON ANY ERROR
 BMI ERROR
 MOV #7,@#MTCSR ;SEARCH TO NEXT TAPE MARK
 MOV @#BUFFER,-(SP) ;CONVERT FILENAME EXT TO ASCII
 MOV #BUFF,-(SP)
 MOV #1,-(SP)
 EMT 42
 MOV @#BUFFER+2,-(SP)
 MOV #BUFF1,-(SP)
 MOV #1,-(SP)
 EMT 42
 MOV @#BUFFER+4,-(SP)
 MOV #BUFF2,-(SP)
 MOV #1,-(SP)
 EMT 42

```

MOV @#BUFFER+6,-(SP)           ;CONVERT UIC TO ASCII
MOV #BUFF3,-(SP)
MOV #5,-(SP)
EMT 42
MOV @#BUFFER+10,-(SP)         ;AND PROTECT CODE
MOV #BUFF4,-(SP)
MOV #5,-(SP)
EMT 42
MOV #BUFOUT,-(SP)            ;WRITE OUT LINE OF LABEL
MOV #LINK,-(SP)
EMT 2
MOV #LINK,-(SP)
EMT 1
BR START1

```

```

ERROR: EMT 60
        .WORD 0
LINK:   .WORD 0           ;LINK BLOCK1
        .RAD50 /DEV/
        .WORD 0,0
        .WORD 0,2
FILE:   .WORD 0,0,0,0,0
BUFFER: .WORD 0,0,0,0
        .WORD 0,0,0,0
BUFOUT: .WORD 36
        .WORD 0
        .WORD 34
BUFF:   .BYTE 0,0,0
BUFF1:  .BYTE 0,0,0,56
BUFF2:  .BYTE 0,0,0,40,40
BUFF3:  .WORD 0,0,0
        .BYTE 40,40
BUFF4:  .WORD 0,0,0
        .BYTE 15,12,0,0
        .END START

```

.TITLE MTFMAT

```
;
;
;
START:  MOV #2,@#177540
        CLR @#177550
        TSTB @#177540
        BPL .-4
        MOV #5,@#177540
        TSTB @#177540
        BPL .-4
        MOV #401,@#177550
        MOV #5,@#177540
        EMT 60
        .END START
```

NAME: SO:

DESCRIPTION - SO: is a device driver capable of sending information to a storage tube display unit hooked to a DR11-A interface unit. The information may be either text or graphics. For text output data lines are drawn until either 38 lines are output or a form feed is encountered. To continue the user must push the 'PAGE' button on the display. The screen is erased and the next line of characters started. In text mode tabs are converted to spaces and illegal characters are ignored. For graphics output the user must set a special function code to 1. This causes SO: to ignore any normally illegal characters.

USES - SO: replaces the teletype in most look and see applications, i.e. when a hard copy is not required. The effective character speed, being about 50 K.Baud, allows more effective use of the DOS system for development purposes. In particular, the Editor and PIP programs almost require SO: as an extension of the keyboard service.

PROGRAMMING - SO: is just another device in the system library and can be employed in the same manner as KB:, PP:, etc. Its one limitation is that only one dataset can be opened at a time. For graphics SO: must be called from a user program. This is because the setting of a function code is not possible from the system programs. For further information on DOS I/O programming and special function codes, the reader should consult Chapter 2 of the DOS Users Guide. However, the function code of SO: is initialized to 0 for text mode and the user normally would not change it.

ERRORS - no errors are generated by SO:

- A listing of SO: follows: -

R0=%0
R1=%1
R5=%5
SP=%6

.GLOBL SO
.TITLE SO

; ASCII OUTPUT DISPLAY HANDLER

; ALLAYS 32 LINES THEN WAITS FOR ACTION ON CONSOLE

SO: .WORD 0 ;START OF DRIVER TABLE
.WORD 672 ;TERMINAL,ASCII,BIN,OUTPUT,OPEN,SPECIAL
.BYTE 4 ;128 BYTE BUFFER
.BYTE SO.INT-SO
.BYTE 200 ;PRI =4
.BYTE SO.OPN-SO
.BYTE SO.TRN-SO
.BYTE 0
.BYTE SO.SPC-SO ;SPECIAL FUNCTIONS
.BYTE 0
.RAD50 /SO/ ;NAME OF DEVICE

; DATA AREA

BYTCNT: .WORD 0
NBYTE: .WORD 0
LENGTH: .BYTE 0
LINES: .BYTE 0
STORE2: .WORD 0
SWITCH: .BYTE 0
.EVEN

; SPECIAL FUNCTION 0 CHECK FOR SPACES AND FORM FEEDS
1 NO CHECKS

SO.SPC: MOV SO,R0 ;GET DDB ADDRESS
MOV @2(R0),CODE ;GET SPECIAL CODE
TST (SP)+
JMP @14(R0)

CODE: .WORD 0

; OPEN ROUTINE RESET AND HOME ERASE

SO.OPN: MOV #14,@#177532
CLR @#177534 ;CLEAR INPUT BUFFER
MOVB #332,LINES ;SET LINE COUNTER NOW
SOT10: TSTB @#177530
BPL SOT10
MOV SO,R0 ;GET ADDRESS OF DDB
TST (SP)+ ;GET RID OF CALL IN STACK
JMP @14(R0) ;COMPLETED RETURN CALL

; TRANSFER ROUTINE SET UP EVERYTHING
; LINE COUNT
; WORD COUNT AND BYTE POINTERS
; AND SET DISPLAY IN MOTION

```
;
SO.TRN: MOV SO,R0 ;GET DDB POINTER
        MOV 6(R0),NBYTE ;GET POINTER TO DATA
        MOV 10(R0),R1 ;AND WORD COUNT
        ASL R1 ;MULTIPLY BY TWO
        MOV R1,BYTCNT ;KEEP IT
;
; ALTER STACK SETUP TO FAKE AN INTERRUPT
; THIS PERMITS A RETURN "RTI" LATER ON
;
        MOV (SP),-(SP) ;MOVE UP 1 WORD
        MOV @#177776,2(SP) ;SET "INTERRUPTED" PS
;
; INTERRUPT ROUTINE
;
SO.INT: BIC #100,@#177530 ;DISABLE INTERRUPT
        TST BYTCNT ;TEST COUNT FOR END
        BPL SO.DUN ;FINISHED
        TST CODE
        BNE SOT1 ;NO TAB OR FF CHECK
        TSTB SWITCH ;TAB IN PROGRESS ?
        BNE SOT20 ;YES BRANCH
        CMPB #177,@NBYTE ;IGNORE RUBOUT
        BEQ SOT2
        BITB #140,@NBYTE ;CONTROL ???
        BNE SOT1 ;NO WRITE
        CMPB #13,@NBYTE ;V TAB ?
        BEQ SOT3 ; YES !
        CMPB #15,@NBYTE ;CARRIAGE RETURN ?
        BEQ SOT1
        CMPB #14,@NBYTE ;FORM FEED?
        BEQ SOT3 ;YES WAIT
        CMPB #12,@NBYTE ;LINE FEED
        BEQ SOT4 ;YES
        CMPB #11,@NBYTE ;NEXT CHAR A TB?
        BNE SOT2 ;NO TAB
        INCB SWITCH ;SET TAB SWITCH
SOT20: MOVB #40,@#177532
        INCB LENGTH ;END
        BITB #7,LENGTH ;TEST TO SEE IF FIRST
        BEQ SOT21 ;3 BITS ARE ZERO
        BIS #100,@#177530 ;NOT ZERO
        RTI
SOT21: CLRB SWITCH ;FINISHED TAB RESET SWITCH
        BR SOT50
SOT1: MOVB @NBYTE,@#177532 ;SEND CHAR
        INCB LENGTH ;ONE LESS TAB SPACE
SOT50: BIS #100,@#177530 ;ENABLE INTERRUPT
SOT5: INC NBYTE
        INC BYTCNT
        RTI
;
;
SO.DUN: MOV @#44,-(SP) ;R.RSAV ADDRESS POINTER
        JSR R5,@(SP)+ ;SAVE REGISTERS FOR RETURN
        MOV SO,R0 ;GET DDB POINTER INTO R0
        JMP @14(R0) ;RETURN TASK DONE
```

```

;
; FORM FEED INSERT LINE FEED AND BOMB LINE COUNTER
; THEN DROP TO LINE FEED ROUTINE
;
SOT3:  MOVB #12,@NBYTE
      CLR B LINES
;
; LINE FEED FOUND CHECK FOR END OF PAGE
; AND RESET VARIOUS PLACES
;
SOT4:  MOVB #377,LENGTH          ;RESET LENGTH
      INCB LINES
      BMI SOT1                  ;NOT FULL PAGE YET
;
; END OF PAGE WAIT FOR "PAGE" FROM CONSOLE
;
      MOV B #332,LINES
SOT12: MOV #140, @ #177776      ;LOWER PRIORITY TO ALLOW TTY IN
      TST @ #177530           ;ANY ACTION
      BPL SOT12               ;NO
      CMP B #14, @ #177534
      BNE SOT12               ;NOT CORRECT CHAR WAIT
      CLR B @ #177534
      MOV #200, @ #177776     ;RESET PRIORITY
      MOV #14, @ #177532     ;ERASE SCREEN
SOT13: TST B @ #177530
      BPL SOT13
      CLR B LENGTH
SOT2:  INC NBYTE
      INC BYTCNT
      JMP SO.INT             ;CONTINUE ON
      .END

```

TR: Pseudo-Device Driver for the shared ² memory between
2 PDP-11 Processors.

DESCRIPTION - TR: passes information between 2 DOS systems using a shared memory block. 256 words are transferred between the CPU's at memory speeds. One extra memory word at the start of the buffer controls the transfers. This word is initially zero but is set when data is available. Reading of the data will then occur with this word being cleared. An end of file bit controls the final transfer.

USES - Immediate file transfers between 2 CPU'S.

PROGRAMMING - A common core box is required. TR: is programmed as any other non-file DOS device. 257 words are needed from the common core.

ERRORS - no errors are generated from TR:

- A listing of TR follows -


```
R0=%0
R1=%1
R2=%2
R3=%3
R4=%4
R5=%5
SP=%6
PC=%7
TRCSR=140000
TRBUF=140002
;
;   TRANSFER ROUTINE FOR COMMON CORED CPU'S
;
;   .TITLE TR
;   .GLOBL TR
TR:  .WORD 0
     .WORD 336           ;IN OUT BIN ASC ONLY
     .WORD 4 ;NO INT ROUTINE-64 WORDS XFER
     .BYTE 0
     .BYTE TR.OPN-TR
     .BYTE TR.TRN-TR
     .BYTE TR.CLS-TR
     .WORD 0
     .RAD50 /TR /
;
;   TRAN ROUTINE NO INTS
;
TR.TRN: MOV TR,R0
        MOV 10(R0),R2
        BIT #4,12(R0)
        BNE TRIN
;
;   SET VALUES FOR OUTPUT
;
TROUT:  MOV 6(R0),R1
        MOV #TRBUF,R3
        CLR R4
        MOV #1,R5
        TST    @#TRCSR           ;WAIT FOR CLEAR CSR
        BNE   TROUT    ;BEFORE CONTINUING
        BR LOOP
;
;   SET VALUES FOR INPUT
;
TRIN:   MOV 6(R0),R3
        MOV #TRBUF,R1
        CLR R5
        MOV #1,R4
;
;   LOOP HERE FOR DONE
;
LOOP:   TST @#TRCSR
        BMI TREND
        CMP R4,@#TRCSR
        BNE LOOP
;
```

```
; TRANSFER DATA IN OR OUT
;
LOOP1: MOV (R1)+,(R3)+
      INC R2
      BMI LOOP1
      MOV R5,@#TRCSR
LOOP3: MOV (SP)+,R5
      MOV @#177776,-(SP)
      MOV R5,-(SP)
      SUB #14,SP
      JMP @14(R0)
;
;
TREND: MOV 10(R0),16(R0)
      CLR @#TRCSR ;CLEAR FOR FURTHER OUTPUT
      BR LOOP3
;
; CLOSE ROUTINE IGNORE IF INPUT MODE
;
TR.CLS: BIT #4,12(R0)
      BNE LOOP3
      TST @#TRCSR ;WAIT FOR CLEAR CSR
      BNE TR.CLS ;BEFORE CLOSING
      MOV #100000,@#TRCSR
      BR LOOP3
TR.OPN: MOV #TRCSR,R1 ;TRCSR ADDR
      BIC #100001,(R1) ;CLEAR UNWANTED
      ADD #100,(R1)
      TSTB (R1) ;MAKE SURE BOTH HERE
      BPL .-2
      SUB #100,(R1) ;CLEAR
      BR LOOP3
      .END
```