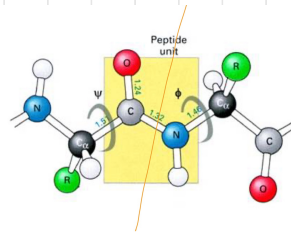


Review

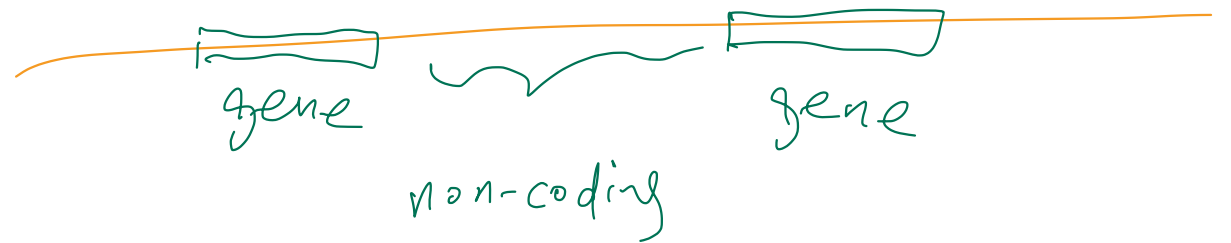
- protein structure prediction
- Torsion angles



- Free energy
- Co-evolution
- Contact map
- ResNet
- AlphaFold2

Hidden Markov Model

gene prediction:



HMM

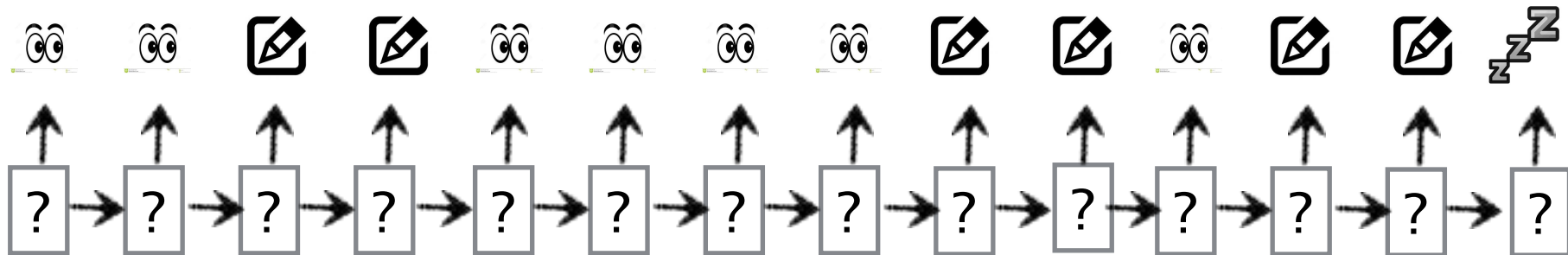
- Hidden Markov model was first invented in speech recognition. But are widely used in many other areas including bioinformatics.
- An automata that has “hidden states”. At each time point, it emits a symbol, and change a state with certain probability.
- We want to derive the hidden states by the emitted symbols.

Classroom example

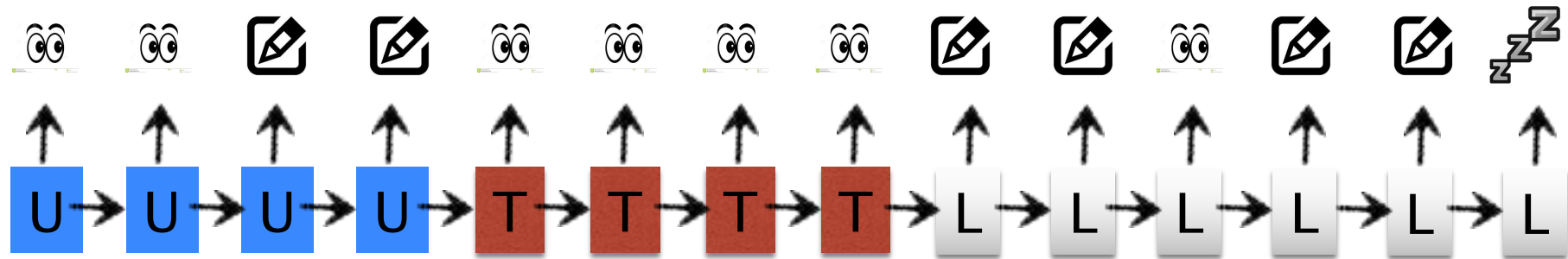
- Think of a student in classroom.
- At any minute, a student is in one of 3 hidden *states* that I try to figure out:
 - U: understands
 - T: does not understand but tries to understand
 - L: is lost completely and does not try to understand
- Meanwhile, the student emits one of 3 *symbols* that I can observe
 - Look at me
 - Write/Type
 - Sleep

Classroom Example

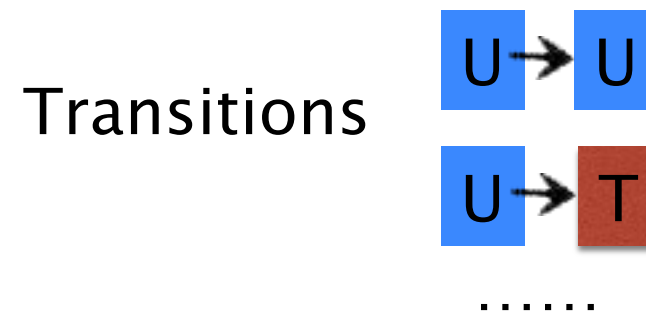
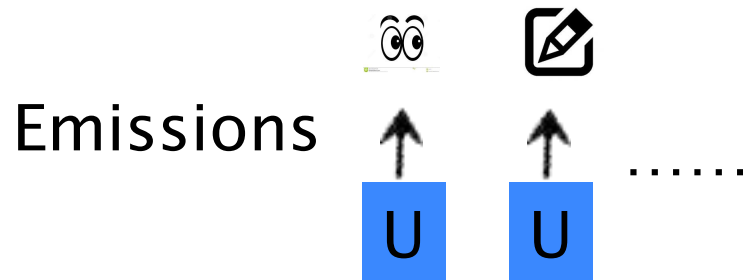
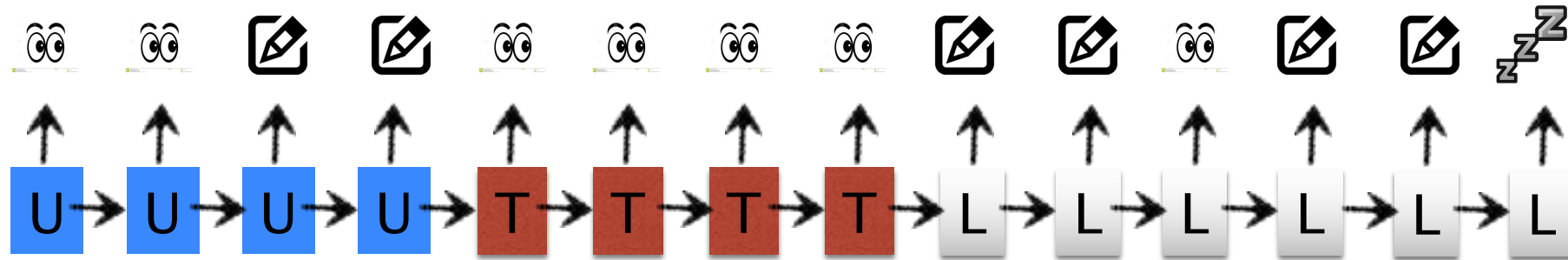
- Now suppose I see a student's behavior is the following in the past several minutes. What is his internal states at each minute?



Classroom Example

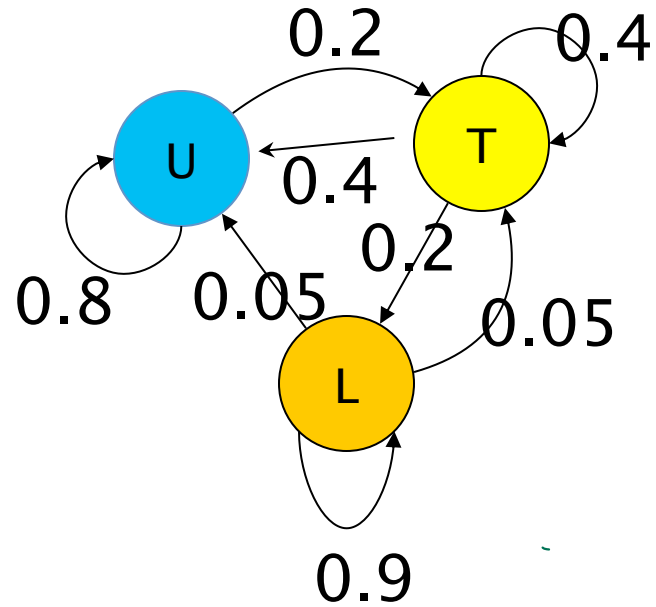


Classroom Example



Typically, HMM assumes that emission probability depends only on current state; and current state only depends on previous state. We want to find the most likely path of states given the symbols (observations).

Classroom Example



U: Understands
 T: Tries to understand
 L: Lost completely

(T) Transition matrix

	U	T	L
U	0.8	0.2	0
T	0.4	0.4	0.2
L	0.05	0.05	0.9

add up to 1

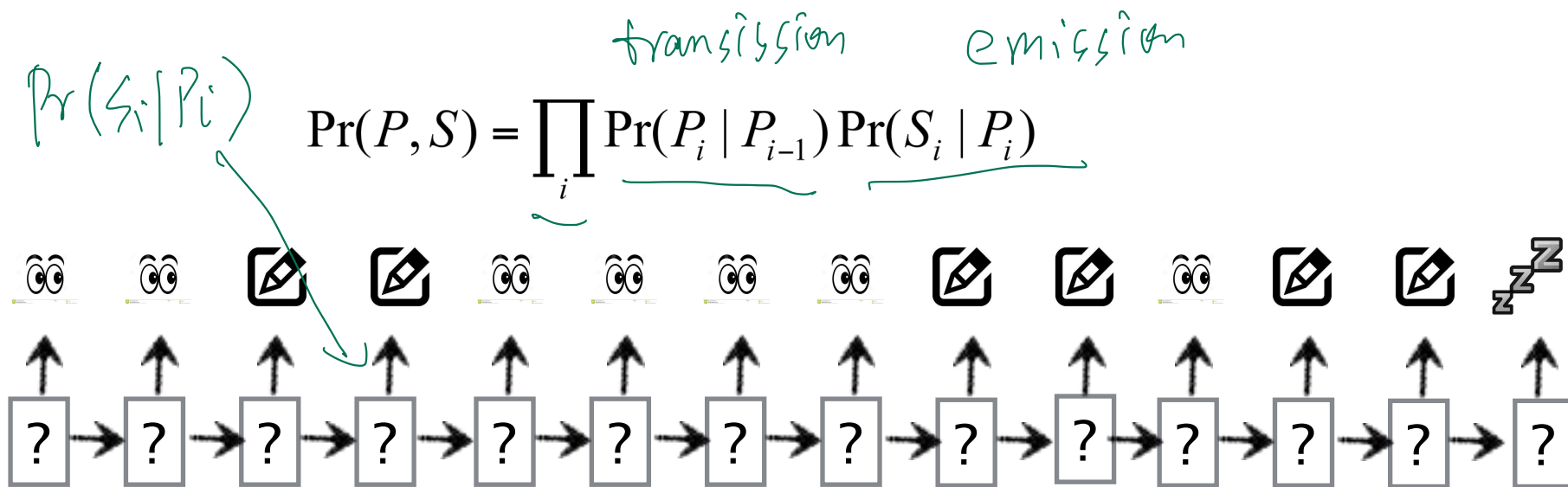
(E) Emission matrix

	Look	Write	Sleep
U	0.6	0.35	0.05
T	0.9	0.1	0
L	0.1	0.6	0.3

add up to 1

Classroom Example

- $S=S_1S_2\dots S_n$: sequence of symbols;
- $P=P_1P_2\dots P_n$: path of states.
- We want to maximize $\Pr(P|S) = \Pr(P,S) / \Pr(S)$.
- Therefore, we want to maximize

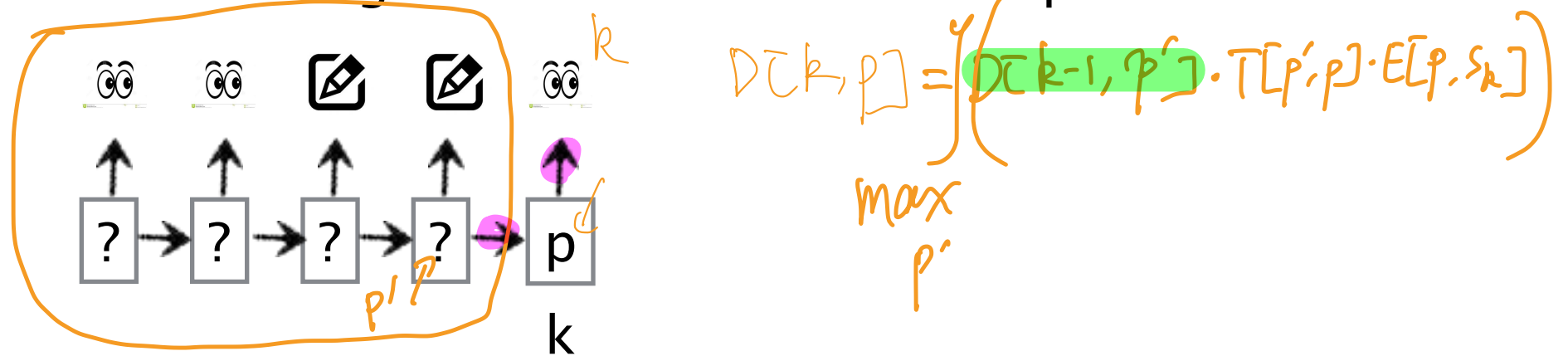


$\Pr(P_i|P_{i-1})$

* Note: To deal with the first state, we can define $\Pr(P_1|P_0) = 1$ in above formula.

Solving HMM

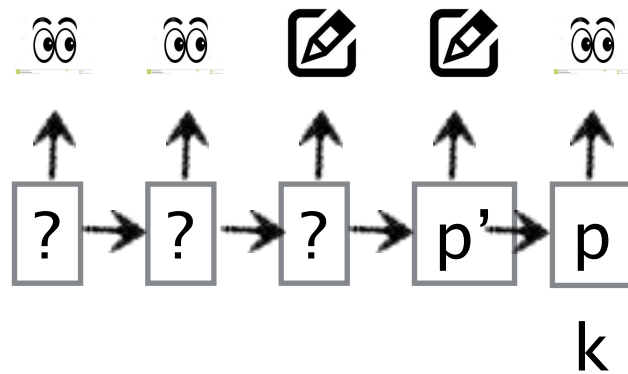
- We use dynamic programming again. Define $D[k,p]$ be the maximum probability achieved by first k states given that the last state is p .



- Then $\max_p D[n,p]$ is the maximum probability achieved by the complete path, which is what we want to compute.
- It is not hard to obtain a recurrence Relation:

Definition of $D[k, p]$ \rightarrow
$$D[k, p] = \max_{P[1..k]; P[k]=p} \prod_{1 \leq i \leq k} T[P_{i-1}, P_i] E[P_i, S_i]$$

Solving HMM

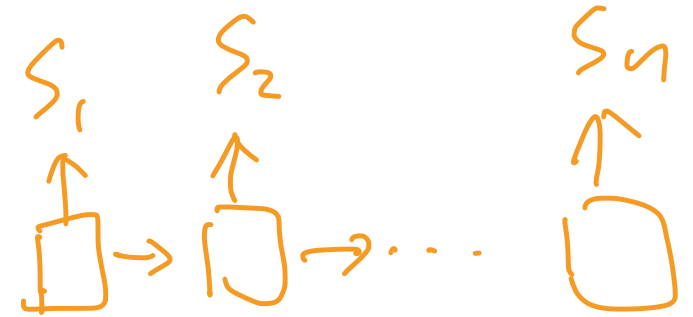


$$D[k, p] = \max_{p'} \underbrace{D[k-1, p']}_{T[p', p]} \underbrace{\Pr(p|p')}_{E[p, s_i]} \underbrace{\Pr(S_i|p)}$$

k

Solving HMM

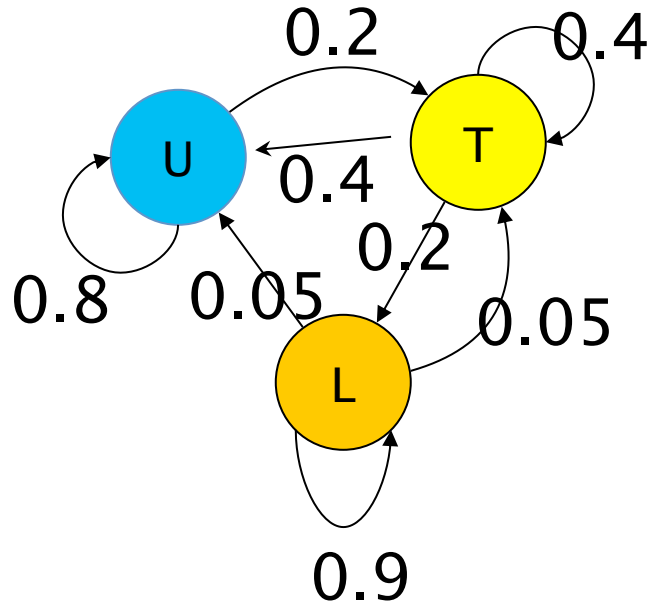
- The algorithm:
- Input: $S = S_1S_2\dots S_n$
- Output: $P = P_1P_2\dots P_n$
- 1. for every state p , let $D[1,p] = \Pr(S_1|p)$.
- 2. for k from 2 to n ,
- 2.1 for every state p ,
- 2.1.1 let $D[k,p] = \max_{p'} D[k-1,p'] \Pr(p|p') \Pr(S_i|p)$
- 3. backtrack to compute the optimal path.



$$D[k,p] = \max_{p'} D[k-1,p'] \Pr(p|p') \Pr(S_i|p)$$

length of sequence.

Example



(E) emission matrix

	Look	Write	Sleep
Understand	0.6	0.35	0.05
Try	0.9	0.1	0
Lost	0.1	0.6	0.3

$$D[k, p] = \max_{p'} D[k-1, p'] \Pr(p|p') \Pr(S_i|p)$$

$D[2, u]$

case 1: $p' = u$

$$D[2, u] = D[1, u] \cdot T[u, u] \cdot E[u, u]$$

$$= 0.6 \times 0.8 \times 0.6$$

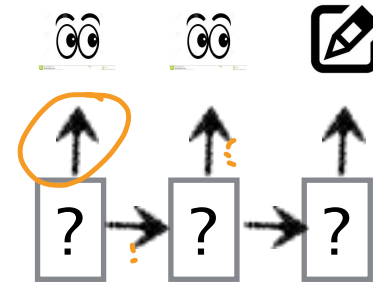
$$= 0.288$$

case 2: $p' = T$

$$0.9 \times 0.4 \times 0.6 = 0.216$$

case 3: $p' = L$

$$0.1 \times 0.05 \times 0.6 = 0.003$$



		→ 0.288	
U	0.6	0.216	
T	0.9	0.003	
L	0.1		

Notes

- Do not multiply
 - because soon the numbers become so small that the double precision will give you value 0.
 - Do a logarithm and use additions instead.

$$D[k, p] = \max_{p'} D[k - 1, p'] \Pr(p|p') \Pr(S_i|p)$$



$$\log D[k, p] = \max_{p'} (\log D[k - 1, p'] + \log \Pr(p|p') + \log \Pr(S_i|p))$$

Parameter Estimation

- All of our computation depends on the transition probabilities and emission probabilities. How do we estimate these parameters?

Parameter Estimation

- If we have an annotated sequence with both symbols and states, then these can be trained by counting.
- If we do not, then we can start with a reasonable guess of the parameters and annotate the sequence.
- Then we use the annotation to train a new set of probabilities. Repeat until converge.
- There is some guarantee to the convergence. But does not guarantee this will converge to the right solution.

Pseudocounts

- If the training data include no cases of a particular emission from a particular state, then its probability will be 0 in this model.
- That's no good.
- So we add pseudocounts to make the probabilities not zero when an event should be able to happen.

Higher Order HMM

- Think again the classroom example:

U: Understands
T: Tries to understand
L: Lost

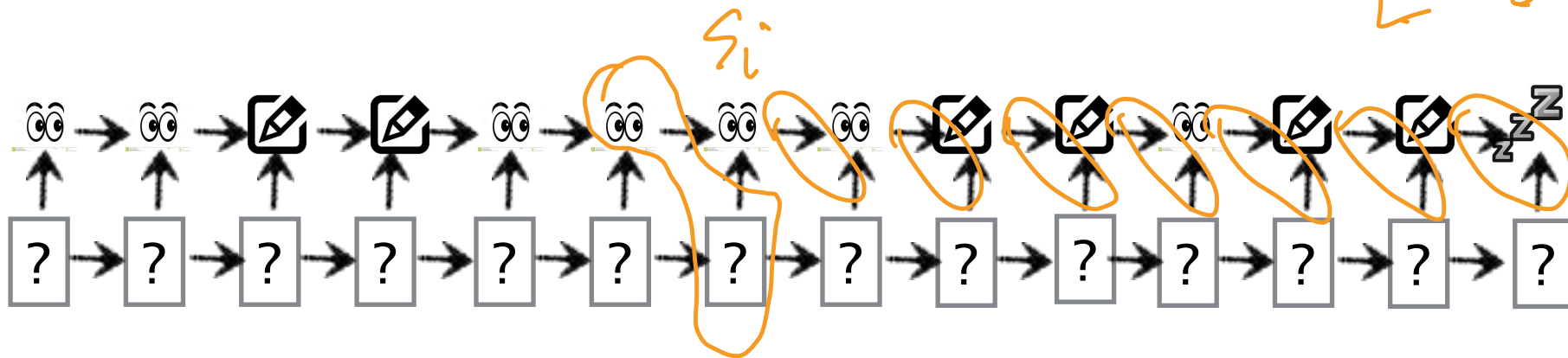
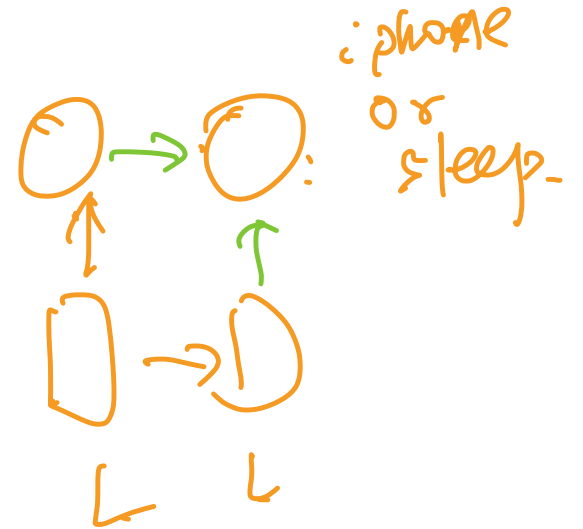
(E) Emission matrix

	Look	Write	Sleep
U	0.6	0.35	0.05
T	0.9	0.1	0
L	0.1	0.6	0.3

- The emission of a symbol should not only depend on current state, but sometimes also the previous symbol.
 - E.g. Sleeping at previous moment leads to a higher probability of sleeping now.

1st Order HMM

- To accommodate the correlation between the adjacent symbols, the emission matrix needs to be expanded.
- The emission matrix becomes $\Pr(S_i | P_i, S_{i-1})$.



1st Order HMM

- Before

$$\Pr(P, S) = \prod_i \underbrace{\Pr(P_i | P_{i-1})}_{\text{transition}} \underbrace{\Pr(S_i | P_i)}_{\text{emission}}$$

2nd order

- Now

$$\Pr(P, S) = \prod_i \underbrace{\Pr(P_i | P_{i-1})}_{\text{same}} \underbrace{\Pr(S_i | P_i, S_{i-1})}_{\text{different}}$$

$\rightarrow \Pr(S_i | P_i, S_{i-1}, S_{i-2})$

- To find the path P to maximize, we let $D[k, p]$ be the maximum probability obtained by the first k states ending at p. We can obtain the following recurrence relation similarly as before.

$\Pr(S_i | P)$

$$D[k, p] = \max_{p'} D[k-1, p'] \Pr(p | p') \Pr(S_i | p, S_{i-1})$$

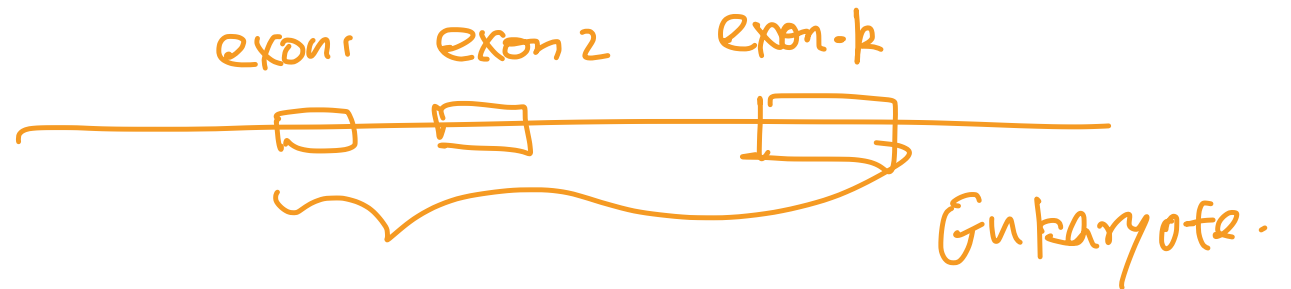
- We can still do dynamic programming.

Higher Order HMM

- To generalize, we can let the current emission depend on the current state, and previous k symbols.
- Then this is called the k -th order HMM.
- Solving such a HMM is similar as before. Running time not changed.
- The only difficulty is the parameter training because the emission matrix has many more parameters for larger k .

Prokaryote Gene Finding

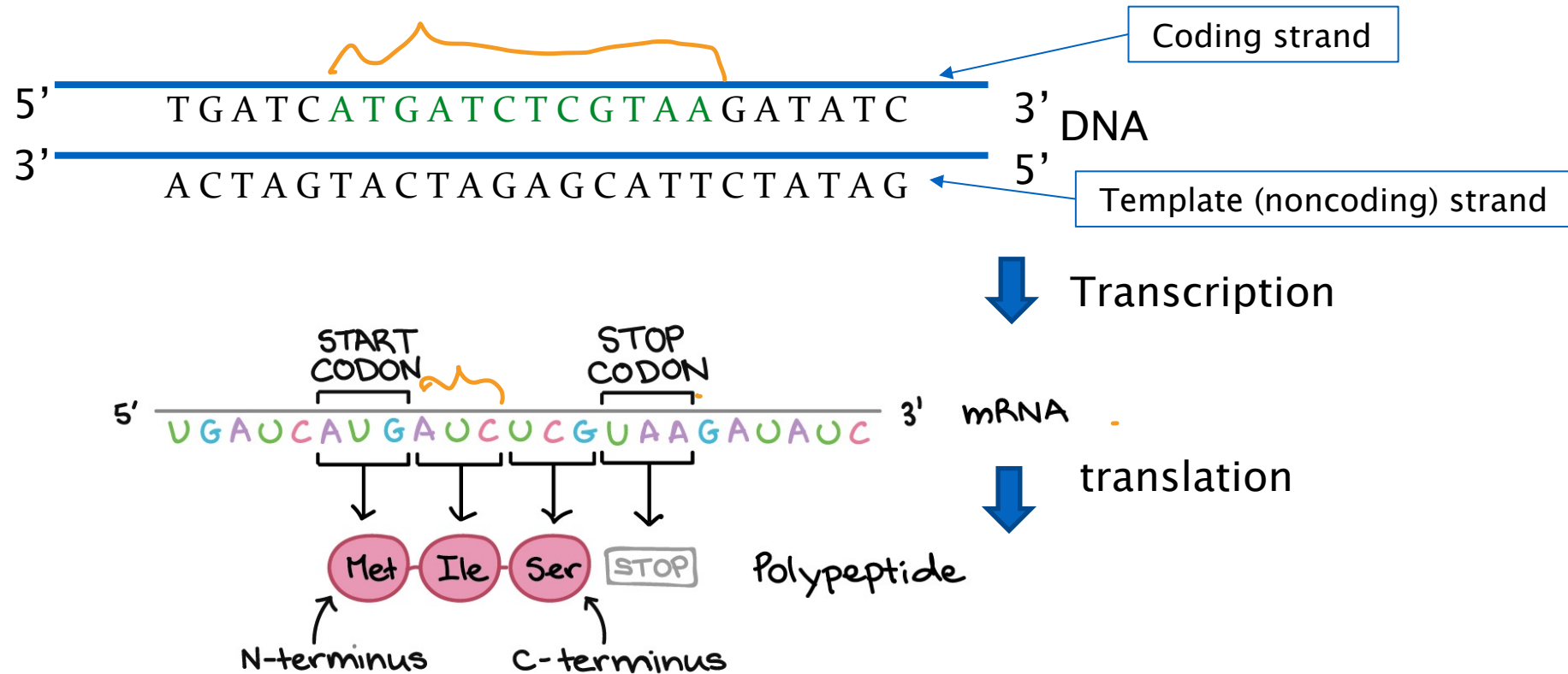
- The **prokaryotes** (pronounced /prɒʊ'kæriɔʊts/; singular **prokaryote** /prɒʊ'kæriət/) are a group of organisms that lack a cell nucleus (= karyon).
 - The opposite is the **eukaryotes**.
- Most of prokaryotes are unicellular.
- Prokaryote genes do not have introns. So their genes is a linear structure.



Intron video:

<http://www.youtube.com/watch?v=o0BQJbLNYSg>

From Gene to Protein (in *Prokaryotes*)



Genetic code

$4^3 = 64$
codons

		Second letter				
		U	C	A	G	
First letter	U	UUU Phenyl-alanine UUC	UCU Serine UCC UCA UCG	UAU Tyrosine UAC UAA Stop codon UAG Stop codon	UGU Cysteine UGC UGA Stop codon UGG Tryptophan	U C A G
	C	CUU Leucine CUC CUA CUG	CCU Proline CCC CCA CCG	CAU Histidine CAC CAA CAG	CGU Arginine CGC CGA CGG	U C A G
	A	AUU Isoleucine AUC AUA AUG Methionine; start codon	ACU Threonine ACC ACA ACG	AAU Asparagine AAC AAA AAG	AGU Serine AGC AGA AGG	U C A G
	G	GUU Valine GUC GUA GUG	GCU Alanine GCC GCA GCG	GAU Aspartic acid GAC GAA GAG	GGU Glycine GGC GGA GGG	U C A G

·
·
A T T } I
·
C A C } H
·
A G T } S
·
C G A } G
·
·

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codons

Codon bias

- A codon XYZ occurs with different frequencies in coding regions and non-coding regions
 - different amino acids have different freq.
 - Diff. codons for the same amino acid have diff. freq.
 - In random regions approx. $p(X)*p(Y)*p(Z)$

Codon Bias Tables
(% of codons used
for each residue)



Amino Acid	Codon		
Gly	GGG	2	25
Gly	GGA	0	25
Gly	GGU	59	16
Gly	GGC	39	34