Module 10: Query Evaluation Spring 2022

Cheriton School of Computer Science

CS 348: Intro to Database Management

Reading Assignments and References

To be read during the Week of May 2-6:0.

- Section 2.6 of Chapter 2 of course textbook.¹
- Chapter 15 of course textbook.
- Sections 16.1 through 16.4 of Chapter 16 of course textbook.

¹Silberschatz, Korth and Sudarshan, *Database Systems Concepts*, 7th edition

Outline

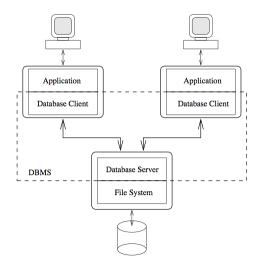
Unit 1: Overview

Unit 2: Relational Algebra

Unit 3: Query Optimization

Unit 4: Cost Estimation

The Two-Tier Architecture



Also called the client/server architecture.

The Two-Tier Architecture (cont'd)

Application:

- User interaction: query input, presentation of results.
- Application-specific tasks.

Database Server:

- DDL evaluation.
- > DML compilation: selection of a query plan for a query.
- DML execution.
- Concurrency control.
- Buffer management: rollback and failure recovery.

File System:

Storage and retrieval of unstructured data.

Query Evaluation

Steps in evaluating a query Q:

- 1. Parsing, view expansion, and type and authorization checking of Q.
- 2. Translation of Q to a formulation E_Q in the relational algebra.
- 3. Optimization of E_Q .
 - \Rightarrow generates an efficient query plan P_Q from E_Q
 - \Rightarrow uses statistical metadata about the database instance
- 4. Execution of query plan P_Q .
 - \Rightarrow uses access methods to access stored relations
 - ⇒ uses physical relational operators to combine relations

Considerations:

- How relations are stored, that is, *physically represented*.
- Choice of physical relational operators to answer to complex queries.
- How intermediate results are managed.

Outline

Unit 1: Overview

- Unit 2: Relational Algebra
- Unit 3: Query Optimization
- Unit 4: Cost Estimation

Relational Algebra: Overview

Idea

Define a relational algebra (RA) consisting of a set of operations on the universe \mathcal{U} of finite relations over an underlying universe of values **D** of a database instance **DB**.

$$(\mathcal{U}; \mathbf{R}_0, \ldots, \mathbf{R}_k, \times, \sigma, \pi, \cup, -, \mathsf{elim}, \mathbf{c}_1, \mathbf{c}_2, \ldots)$$

Constants:

 R_i relation name (one for each relation name in a signature ρ)

*c*_i constant (one for each constant in **D**)

Unary operators:

- σ selection (removes rows)
- π duplicate preserving projection (removes columns)
- elim duplicate elimination

Binary operators:

- \times cross product
- U multiset union
- multiset difference

Relational Algebra: Syntax

Definition

Given a database signature $\rho = (R_1/k_1, ..., R_n/k_n)$ and a set of constants $\{c_1, c_2, ...\}$, a *relational algebra* (RA) query is an expression *E* given as follows:

$$E ::= R_{i}
| c_{j}
| \sigma_{\#i=\#j}(E_{1})
| \pi_{\#i_{1},...,\#i_{m}}(E_{1})
| elim E_{1}
| E_{1} \times E_{2}
| E_{1} \cup E_{2}
| E_{1} - E_{2}$$

We write Eval(E, DB) to denote the table computed by evaluating the RA query *E*, and Cnum(E) to denote its arity.

Relational Algebra: Semantics

The semantics of Eval(E, DB) is given by appeal to the range restricted relational calculus with multiset semantics defined in Module 4, in particular, we write

Answers(Q, DB)

to denote the answers to RC query Q over DB.

- We also assume the following, where arity n and RA subquery E_i will be clear from context:
 - 1. S_i is a table with arity $Cnum(E_i)$ and extension $Eval(E_i, DB)$, and
 - 2. \bar{x} is short for variables x_1, \ldots, x_n .

relation name (for $R_i/n \in \rho$)

```
Eval(R_i, DB) = Answers(\{(\bar{x}) | R_i(\bar{x})\}, DB), where Cnum(R_i) = n.
```

constant

$$Eval(c) = Answers(\{(x) | x = c\}, DB), where Cnum(R_i) = 1.$$

Relational Algebra: Semantics (cont'd)

selection

Eval $(\sigma_{\#i=\#j}(E_1), \mathbf{DB}) = \text{Answers}(\{(\bar{x}) \mid S_1(\bar{x}) \land (x_i = x_j)\}, \mathbf{DB}),$ where $\text{Cnum}(\sigma_{\#i=\#j}(E_1)) = \text{Cnum}(E_1).$

projection

Eval $(\pi_{\#i_1,...,\#i_m}(E_1), DB) = Answers(\{(x_{i_1},...,x_{i_m}) \mid \exists x_{i_{m+1}},...,x_{i_n}.S_1(\bar{x})\}, DB),$ where Cnum $(\pi_{\#i_1,...,\#i_m}(E_1)) = m$ and $(i_1,...,i_n)$ is a permutation of (1,...,n).

duplicate elimination

Eval(elim E_1), **DB**) = Answers({ $(\bar{x}) | {S_1(\bar{x})}$, **DB**), where Cnum(elim E_1) = Cnum(E_1).

cross product

 $\begin{aligned} & \mathsf{Eval}(E_1 \times E_2, \mathsf{DB}) = \mathsf{Answers}(\{(\bar{x}, \bar{y}) \mid S_1(\bar{x}) \land S_2(\bar{y})\}, \mathsf{DB}), \\ & \textit{where } \mathsf{Cnum}(E_1 \times E_2) = \mathsf{Cnum}(E_1) + \mathsf{Cnum}(E_2). \end{aligned}$

Relational Algebra: Semantics (cont'd)

multiset union

 $\begin{aligned} & \mathsf{Eval}(E_1 \cup E_2, \mathbf{DB}) \ = \ \mathsf{Answers}(\{(\bar{x}) \mid S_1(\bar{x}) \lor S_2(\bar{x})\}, \mathbf{DB}), \\ & \textit{where } \mathsf{Cnum}(E_1 \cup E_2) = \mathsf{Cnum}(E_1). \end{aligned}$

multiset difference

 $\begin{aligned} & \mathsf{Eval}(E_1 - E_2, \mathsf{DB}) = \mathsf{Answers}(\{(\bar{x}) \mid S_1(\bar{x}) \land \neg S_2(\bar{x})\}, \mathsf{DB}), \\ & \textit{where } \mathsf{Cnum}(E_1 - E_2) = \mathsf{Cnum}(E_1). \end{aligned}$

multiset difference (an alternative semantics)

 $\begin{aligned} & \mathsf{Eval}(E_1 - E_2, \mathsf{DB}) = \mathsf{Answers}(\{(\bar{x}) \mid S_1(\bar{x}) \land \neg (S_1(\bar{x}) \land \{S_2(\bar{x})\})\}, \mathsf{DB}), \\ & \textit{where } \mathsf{Cnum}(E_1 - E_2) = \mathsf{Cnum}(E_1). \end{aligned}$

NOTE: Multiset difference with the alternative semantics can be used when translating subqueries in SQL conditions.

Relational Algebra: Examples

(data) $\mathbf{DB} = (\mathbb{STR} \uplus \mathbb{Z}, \approx,$

	anum	type	balance	bank	bnum	cnt	
	1234	СНК	\$1000	TD	1	1	
	1235	SAV	\$20000	TD	2	1	
ACCOUNT =	1236	CHK	\$2500	CIBC	1	1	,
	1237	CHK	\$2500	Royal	5	1	
	2000	BUS	\$10000	Royal	5	1	
	2001	BUS	\$10000	TD	3	1	

	name	address	cnt
BANK =	TD	TD Centre	1
	CIBC	CIBC Tower	1

relation name

Example: All account information.

	anum	type	balance	bank	bnum	cnt
	1234	СНК	\$1000	TD	1	1
	1235	SAV	\$20000	TD	2	1
Eval(ACCOUNT, DB) =	1236	CHK	\$2500	CIBC	1	1
	1237	CHK	\$2500	Royal	5	1
	2000	BUS	\$10000	Royal	5	1
	2001	BUS	\$10000	TD	3	1

constant

Example: \$10000.

cross product

Example: Every pair of accounts and banks.

Eval(ACCOUNT × BANK, DB)

	anum	type	balance	bank	bnum	name	address	cnt
	1234	CHK	\$1000	TD	1	TD	TD Centre	1
	1234	CHK	\$1000	TD	1	CIBC	CIBC Tower	1
	1235	SAV	\$20000	TD	2	TD	TD Centre	1
	1235	SAV	\$20000	TD	2	CIBC	CIBC Tower	1
	1236	CHK	\$2500	CIBC	1	TD	TD Centre	1
=	1236	CHK	\$2500	CIBC	1	CIBC	CIBC Tower	1
	1237	CHK	\$2500	Royal	5	TD	TD Centre	1
	1237	CHK	\$2500	Royal	5	CIBC	CIBC Tower	1
	2000	BUS	\$10000	Royal	5	TD	TD Centre	1
	2000	BUS	\$10000	Royal	5	CIBC	CIBC Tower	1
	2001	BUS	\$10000	TD	3	TD	TD Centre	1
	2001	BUS	\$10000	TD	3	CIBC	CIBC Tower	1

selection

Example: All account information, including bank addresses.

$Eval(\sigma_{\#4=\#6}(ACCOUNT \times BANK), DB)$

	anum	type	balance	bank	bnum	name	address	cnt
	1234	СНК	\$1000	TD	1	TD	TD Centre	1
=	1235	SAV	\$20000	TD	2	TD	TD Centre	1
	1236	CHK	\$2500	CIBC	1	CIBC	CIBC Tower	1
	2001	BUS	\$10000	TD	3	TD	TD Centre	1

Example: All account information for accounts with a \$10000 balance.

$Eval(\sigma_{\#3=\#6}(ACCOUNT \times \$10000), DB)$

	anum	type	balance	bank	bnum		cnt
=	2000	BUS	\$10000	Royal	5	\$10000	1
	2001	BUS	\$10000	TD	3	\$10000	1

duplicate preserving projection

Example: The type and balance of all accounts.

$$Eval(\pi_{\#2,\#3}(ACCOUNT), DB) =$$

type	balance	cnt
CHK	\$1000	1
SAV	\$20000	1
CHK	\$2500	2
BUS	\$10000	2

duplicate elimination

Example: All account types.

Eval(elim $\pi_{\#2}$ (ACCOUNT), **DB**)

multiset union

Example: The type and balance of all checking and savings accounts.

 $Eval(\sigma_{\#1=\#3}(\pi_{\#2,\#3}(ACCOUNT) \times CHK) \cup \sigma_{\#1=\#3}(\pi_{\#2,\#3}(ACCOUNT) \times SAV), DB)$

= CHK \$1000 CHK 1 SAV \$20000 SAV 1 CHK \$2500 CHK 2	

multiset difference

Example: Banks that do not have addresses.

$$\mathsf{Eval}((\mathsf{elim} \ \pi_{\#4}(\mathsf{ACCOUNT})) - \pi_{\#1}(\mathsf{BANK}), \mathsf{DB}) = \begin{array}{|c|c|} \mathsf{bank} & \mathsf{cnt} \\ \hline \mathsf{Royal} & \mathsf{I} \end{array}$$

Exercise: Express this with only one use of elim at the top level.

Expressiveness

Range restricted RC queries *with multiset semantics* have at least the expressiveness of RA queries. For the other direction, we have the following.

Theorem (Codd)

For every domain independent RC query there is an equivalent RA expression. Thus, RA is a relationally complete query language.

An outline of translating range restricted RC queries to RA queries:

 $\begin{aligned} &\mathsf{RCmap}(R_i(x_1,\ldots,x_k)) &= R_i \\ &\mathsf{RCmap}(\varphi \wedge x_i = x_j) &= \sigma_{\mathsf{Vmap}(x_i) = \mathsf{Vmap}(x_j)}(\mathsf{RCmap}(\varphi)) \\ &\mathsf{RCmap}(x_i = c_j) &= c_j \\ &\mathsf{RCmap}(\exists x_i.\varphi) &= \pi_{\mathsf{Vmap}(\mathsf{Fv}(\varphi) - \{x_i\})}(\mathsf{RCmap}(\varphi)) \\ &\mathsf{RCmap}(\varphi_1 \wedge \varphi_2) &= \mathsf{RCmap}(\varphi_1) \times \mathsf{RCmap}(\varphi_2) \\ &\mathsf{RCmap}(\varphi_1 \vee \varphi_2) &= \mathsf{RCmap}(\varphi_1) \cup \mathsf{RCmap}(\varphi_2) \\ &\mathsf{RCmap}(\varphi_1 \wedge \neg \varphi_2) &= \mathsf{RCmap}(\varphi_1) - \mathsf{RCmap}(\varphi_2) \end{aligned}$

1. Must ensure $Fv(Q_1) \cap Fv(Q_2) = \emptyset$ for \wedge case, and ...;

- 2. Must define Vmap, an appropriate mapping of variables to column positions; and
- 3. Need to add a top-level elim and projection to the RA expression.

Relational Algebra: Implementation

The multiset semantics of RA enables implementations of its operators that mostly avoids the need to store intermediate results.

Idea

An implementation for an RA operator provides a cursor OPEN/FETCH/CLOSE interface.

In particular, any implementation of an RA operator:

- 1. implements the cursor interface to produce answers, and
- 2. uses the *same* interface to get answers from its children.

Providing at least one *physical implementation* for this protocol for each operator enables evaluating RA queries.

Example: An implementation of selection in an object-oriented language could be as follows.

```
// select_{#i=#j}(Child)
  OPERATOR child;
  int i, j;
public:
  OPERATOR selection (OPERATOR c, int i0, int j0)
                { child = c; i = i0; j = j0; };
  void open() { child.open(); };
  tuple fetch() { tuple t = child.fetch();
                  if (t==NULL || t.attr(i) = t.attr(j))
                       return t;
                  return this.fetch();
                };
  void close() { child.close(); }
```

This implementation is *fully pipelined* since it requires a constant space overhead.

A fully pipelined implementation exists for most of the other operators as well. constant

first fetch returns the constant; next fetch fails

cross product

simple nested loops algorithm

duplicate preserving projection eliminate unwanted attributes from each tuple

multiset union

simple concatenation

multiset difference

nested loops algorithm that checks for a tuple in the inner loop

WARNING: The multiset difference implementation only works with the alternative semantics.

relation name

a simple file scan of the primary index[†] for the relation

duplication elimination

remember tuples that have been returned

Exercise: Consider how an implementation of multiset difference with the original semantics might work. Is full pipelining possible?

[†]An artifact of standard physical design; see following.

The implementation just sketched will work, but plans will be inefficient.

Efficiency can be improved in a number of ways.

- 1. Use concrete (usually disk based) data structures for efficient searching, e.g., choosing a Btree for the primary index (more on this following).
- 2. Use better algorithms to implement the operators based on SORTING or HASHING.
- 3. Rewrite the RA expression to an equivalent expression enabling a more efficient implementation (topic of next section):
 - \Rightarrow remove unnecessary operations such as duplicate elimination
 - \Rightarrow apply "always good" transformations, heuristics that commonly work
 - \Rightarrow perform cost-based join order selection
 - ⇒ introduce STORE operations using memory to factor computation of common subexpressions

Standard Physical Design

A *standard physical design* for a relational schema defines the following for each relation name *R*:

- 1. a primary index for R materializing its extension as a concrete data structure, and
- 2. zero or more secondary indices for *R* materializing *projections* of the primary index for *R* as concrete data structures.

A materialization of a relation adds an additional *record identifier* (RID) attribute to the relation.

Secondary indices usually include the RID attribute of the primary index in their projection of *R*.

We add an index scan operation to RA: $\sigma_{\varphi}(\leq \text{index})$, where φ is a condition supplying search values for the underlying data structure.

Assuming $k = \text{Cnum}(\langle \text{index} \rangle)$ and φ is the condition "#i = c", an index scan is equivalent to

$$\pi_{\#1,\ldots,\#k}(\sigma_{\#i=\#k+1}(<\texttt{index}>\times C)).$$

Relation Names and Indexing (cont'd)

Example: Assume relation name PROF/ (pnum, lname, dept) has the following physical design:

- 1. a Btree primary index on pnum called PROF-PRIMARY (see next slide), and
- 2. a Btree secondary index on lname called PROF-SECONDARY (see slide following next slide).
- A visualization of the indices as relations is as follows:

PROF-PRIMARY					
RID-P	pnum	lname	dept		
@1.1 @1.2 @2.1	10 14 17	Davis Smith Taylor	CS C&O CS		
:	:		÷		

PROF-SECONDARY

RID-S	lname	RID-P
@12.1 @12.2 @12.3	Ashton Davis Dawson	@5.1 @1.1 @2.3
: :		:

Example (cont'd): The last name and department of professor number 14:

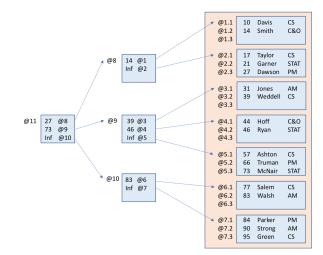
 $\pi_{\#3,\#4}(\sigma_{\#2=14}(\text{PROF-PRIMARY}))$

Example (cont'd): The last names of all professors:

elim $\pi_{\#2}$ (PROF-SECONDARY)

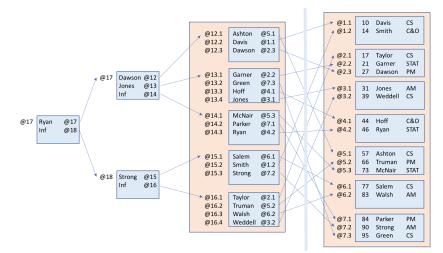
Relation Names and Primary Indices

Example (cont'd): Btree index PROF-PRIMARY on pnum:



Relation Names and Secondary Indices

Example (cont'd): Btree index PROF-SECONDARY on lname:



Outline

Unit 1: Overview

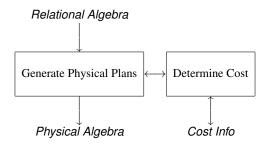
- Unit 2: Relational Algebra
- Unit 3: Query Optimization
- Unit 4: Cost Estimation

Query Optimization

- There can be thousands of possible query plans for a given query that differ by orders of magnitude in their performance:
 - 1. alternative plans that derive from equivalences in RA; and
 - 2. alternative plans that choose different implementations of RA operations.
- How is the best plan found?
 - 1. review basic "always good" transformations; and
 - 2. cost-based join order selection in next unit.
- Finding an optimal plan is computationally not feasible; an optimizer looks for reasonable query plans.

Query Optimization: General Approach

- Generate all physical plans equivalent to the query.
- Choose the plan having the lowest cost.



... all physical plans equivalent to the query?

Cannot be done in general:

 \Rightarrow undecidable if a query is (un-)satisfiable (equivalent to an empty plan)

- Very expensive for even conjunctive queries:
 - \Rightarrow selecting the best join order
- In practice:
 - 1. consider only plans of a certain form (restrictions on the search space); and
 - 2. focus on eliminating really bad query plans.

... the plan having the lowest cost?

- How do we determine which plan is the best one?
 - \Rightarrow not possible to run the plan to find out

Instead, estimate the cost based on statistical metadata collected by the DBMS on database instances.

The next unit reviews a simple cost model based on disk I/O, and assumes:

uniformity all possible values of an attribute are equally likely to appear in a relation; and

independence the likelihood that an attribute has a particular value (in a tuple) does not depend on values of other attributes.

Outline

Unit 1: Overview

- Unit 2: Relational Algebra
- Unit 3: Query Optimization
- Unit 4: Cost Estimation

A Simple Cost Model

For a materialized relation *R* with an attribute *A* we keep:

|R| the cardinality of R (the number of tuples in R)

b(R) the blocking factor for index R

 $\min(R, A)$ the minimum value for A in R

 $\max(R, A)$ the maximum value for A in R

distinct(R, A) the number of distinct values of A

Based on these values, we try to estimate the *cost* of physical plans.

Cost of Retrieval

Example: Consider the following case:

R has the signature:

MARK/(studnum,course,assignnum,mark).

E is the query:

 $\pi_{\#1,\#4}(\sigma_{\#2=\#7}(\sigma_{\#1=\#6}(\sigma_{\#4>\#5}(MARK \times 90) \times 100) \times PHYS))$

The query is obtained by a translation of the following SQL query.

select studnum, mark from MARK
where course = 'PHYS' and studnum = 100 and mark > 90

Note: the result of the query can be a multiset.

Cost of Retrieval (cont'd)

- The physical design for MARK:
 - a Biree primary index on course: MARK-PINDEX/(RID-P, studnum, course, assignnum, mark)
 - 2. a Btree secondary index on studnum:

MARK-SINDEX/(RID-S, studnum, RID-P)

- The following statistical metadata:
 - 1. |MARK| = 10000
 - b(MARK-PINDEX) = 50
 - distinct(MARK, studnum) = 500 (number of different students)
 - distinct(MARK, course) = 100 (number of different courses)
 - 5. distinct(MARK, mark) = 100 (number of different marks)

Strategy 1: Use Primary Index

Query plan:

 $\pi_{\#2,\#5}(\sigma_{\#2=\#7}(\sigma_{\#5>\#6}(\sigma_{\#3="PHYS"}(MARK-PINDEX) \times 90) \times 100))$

Cost in number of block reads:

- Assuming a uniform distribution of tuples over the courses, there will be about |MARK|/100 = 100 tuples with course = PHYS.
- Searching the MARK-PINDEX Btree has a cost of 2, and retrieving the 100 matching tuples adds a cost of 100/b(MARK-PINDEX) data blocks.[†]
- The total cost is therefore 4 block reads.

[†]Selection of *N* tuples from relation *R* using a *clustered* primary index has a cost of 2 + N/b(R).

Strategy 2: Use Secondary Index

Query plan:

 $\pi_{\#5,\#8}(\sigma_{\#6=\#10}(\sigma_{\#8>\#9}(\sigma_{\#2=100}(MARK-SINDEX) \times \sigma_{\#1=\#3\ell}(MARK-PINDEX)) \times 90) \times PHYS))$

NOTE: Part in red expresses a nested index join: "#3ℓ" refers to column 3 of the ℓeft argument of the nested cross product operator "×".

Cost in number of block reads:

- Assuming a uniform distribution of tuples over student numbers, there will be about |MARK|/500 = 20 tuples for each student.
- Searching the MARK-SINDEX Btree has a cost of 2. Since this is not a clustered index, we will make the pessimistic assumption that each matching record in the MARK-PINDEX Btree is on a separate data block, i.e., 20 blocks will need to be read.[†]
- The total cost is therefore 22 block reads.

[†] Selection of *N* tuples from relation *R* using an *unclustered* secondary index has a cost of 2 + N.

Strategy 3: Scan the Primary Index

Query plan:

 $\pi_{\#2,\#5}(\sigma_{\#2=\#8}(\sigma_{\#5>\#7}(\sigma_{\#3=\#6}(\text{MARK-PINDEX} \times \text{PHYS}) \times 90) \times 100))$

Cost in number of block reads:

- There are 10,000/50 = 200 MARK-PINDEX Btree data pages.[†]
- The total cost is therefore 200 block reads.

[†] Selection of *N* tuples from relation *R* by an exhaustive scan of its primary index has a cost of |R|/b(R).

Cost of other Relational Operations

Costs of physical operations in block reads and writes:

selection

$$\operatorname{cost}(\sigma_{\varphi}(E)) = (1 + \epsilon_{\varphi}) \operatorname{cost}(E).$$

nested loop join (*R* is the outer relation):

$$cost(R \times S) = cost(R) + (|R|/b) cost(S)$$

nested index join (*R* is the outer relation, *S* is the inner relation, and Btree has depth *d_S*):

$$\cos(\mathbf{R} imes \sigma_{\varphi}(\mathbf{S})) = \cos(\mathbf{R}) + \mathbf{d}_{\mathbf{S}}|\mathbf{R}|$$

sort-merge join:

$$cost(R \bowtie_{\varphi} S) = cost(sort(R)) + cost(sort(S))$$

where

$$\operatorname{cost}(\operatorname{sort}(E)) = \operatorname{cost}(E) + (|E|/b) \log(|E|/b).$$

Size Estimation

Cost estimation requires an estimate of the size of results of operations.

Use selectivity estimates, defined, for a condition $\sigma_{\varphi}(R)$, as:

$$\operatorname{sel}(\sigma_{\varphi}(R)) = rac{|\sigma_{\varphi}(R)|}{|R|}$$

An optimizer will estimate selectivity using simple rules based on its statistics:

$$\operatorname{sel}(\sigma_{A=c}(R)) \approx \frac{1}{\operatorname{distinct}(R,A)}$$
$$\operatorname{sel}(\sigma_{A \leq c}(R)) \approx \frac{c - \min(R,A)}{\max(R,A) - \min(R,A)}$$
$$\operatorname{sel}(\sigma_{A \geq c}(R)) \approx \frac{\max(R,A) - c}{\max(R,A) - \min(R,A)}$$

Size Estimation (cont.)

For joins:

general join (where φ is an equality on column with attribute name A of R and column with attribute name B of S):

$$|\mathbf{R} \bowtie_{\varphi} \mathbf{S}| \approx |\mathbf{R}| \frac{|\mathbf{S}|}{\operatorname{distinct}(\mathbf{S}, \mathbf{B})}$$

or as

$$|R \bowtie_{\varphi} S| \approx |S| \frac{|R|}{\operatorname{distinct}(R,A)}$$

• foreign key join (e.g., ACCOUNT and BANK where φ is "bank=name"):

$$|\pmb{R} \Join_{arphi} \pmb{S}| = |\pmb{R}| rac{|\pmb{S}|}{|\pmb{S}|} = |\pmb{R}|$$

Many joins are foreign key joins, like this one.

More Advanced Statistics

We have presented a very simple model for cost estimation. Much more complex models are used in practice:

- histograms to approximate non-uniform distributions;
- correlations between attributes;
- uniqueness (keys) and containment (inclusions);
- sampling methods;
- etc.

"Always good" Transformations

Push selections:

$$\sigma_{\varphi}(E_1 \bowtie_{\theta} E_2) = \sigma_{\varphi}(E_1) \bowtie_{\theta} E_2$$

for φ involving columns of E_1 only (and vice versa).

Push projections:

$$\pi_V(R \bowtie_\theta S) = \pi_V(\pi_{V_1}(R) \bowtie_\theta \pi_{V_2}(S))$$

where V_1 is the set of all columns of *R* involved in θ and *V* (similarly for V_2).

Replace products by joins:

$$\sigma_{\varphi}(\boldsymbol{R} \times \boldsymbol{S}) = \boldsymbol{R} \bowtie_{\varphi} \boldsymbol{S}$$

These rewrites also reduce the space of plans to search.

Example

- Assume the following.
 - 1. There are |S| = 1000 students,
 - 2. enrolled in |C| = 500 classes.
 - 3. The enrollment table is |E| = 5000,
 - 4. and, on average, each student is registered for five courses.
- Then:

$$cost(\sigma_{name='Smith'}(S \bowtie (E \bowtie C)))$$

greatly exceeds

 $cost(\sigma_{name='Smith'}(S) \bowtie (E \bowtie C)).$

Join Order Selection

- ► Joins are associative $R \bowtie S \bowtie T \bowtie U$ can be equivalently expressed as
 - 1. $((R \bowtie S) \bowtie T) \bowtie U$
 - 2. $(R \bowtie S) \bowtie (T \bowtie U)$
 - 3. $R \bowtie (S \bowtie (T \bowtie U))$
 - \Rightarrow try to minimize the intermediate result(s).
- Moreover, we need to decide which of the subexpressions is evaluated first.
 - \Rightarrow e.g., cost of nested loop join is *not* symmetric.

Example

Consider choosing one of the following two join orders:

1. $\sigma_{\text{name}='\text{Smith}'}(S) \bowtie (E \bowtie C)$

This order evaluates $E \bowtie C$, which has one tuple for each course registration (by any student) \sim 5000 tuples.

2. $(\sigma_{\text{name}='\text{Smith}'}(S) \bowtie E) \bowtie C$

This join order produces an intermediate relation which has one tuple for each course registration by a student named Smith.

If there are only a few Smith's among the 1,000 students (say there are 10), this relation will contain about 50 tuples.

Summary

Relational algebra is the basis for efficient implementation of SQL.

- Provides a connection between conceptual and physical level;
- Expresses query execution in (easily) manageable pieces;
- Allows the use of efficient algorithms/data structures
- Provides a mechanism for *query optimization* based on logical transformations (including simplifications based on integrity constraints, etc.)

Performance of database operations depends on the way queries and updates are executed against a particular physical database design.

Understanding the *basics* of query evaluation is necessary to good *physical design decisions*.

Performance also depends a great deal on transaction management (next module)